

OSCAR BURGA

Senior Game Developer

I consider myself to be a fun, laid-back, yet disciplined person who's passionate about technology and computer science. Algorithms, problem-solving and optimizations are the core components that keep me enjoying my profession.

CONTACT



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<u>oscarburga</u>



oscar-burga

EDUCATION

Peruvian University of Applied Sciences Bachelor in Computer Science

Five-year program (2018-2022)

LANGUAGES

- Spanish (native)
- English (advanced)
- **French** (basic-intermediate)

ACADEMIC ACHIEVEMENTS



IEEExtreme 14.0 (2020) Team ranked #41 world-wide



IEEExtreme 13.0 (2019) Team ranked #194 world-wide.



ACM ICPC South America -South Finals 2019

Placed #39 in the region.

SOFT SKILLS

- Avid teamworker, but can also thrive alone.
- Enjoy teaching and sharing knowledge with others
- Quick learner and eager to research more.

WORK EXPERIENCE

Senior Game Developer (Unreal Engine 4) Bamtang Games (Aug. 2021 - Current)

- Developed systems for quests, dialogues, cinematics, story progression and voice-overs for the game Avatar: The Last Airbender: Quest for Balance 🚱.
- Worked on the online system used in Nickelodeon Kart Racers 3 and **Avatar**.



- Currently in charge of implementing online features and network gameplay mechanics for the game DreamWorks All-Star Kart Racers 8
- Developed automation tools to ease and optimize the art team's workflow in Unreal Engine.

Algorithmic Complexity Tutor (part-time) Peruvian University of Applied Sciences (Aug. 2020 - July 2021)

• Prepared and taught complementary lessons on algorithms and data structures for groups of up to 30 students.

TECHNICAL SKILLS

Game Engines

- Unreal Engine 4: 2 years professional experience
- **Unity:** 1 year experience (university / recreational)

Programming languages

- C++: 6 years experience. Also comfortable with C.
- **Python:** 4 years experience.
- Go: 1 year experience.

CONTRIBUTION TO PROJECTS

MrMime2 (thesis project) - 2022

• Designed and developed an image-based human-to-robot motion imitation solution for the NAO robot using 3D-human pose estimation and analytical geometry methods.

E-Maxx-Eng (cp-algorithms) - 2021

• Wrote an article on half-plane intersection algorithms for the geometry section of the cp-algorithms website.

