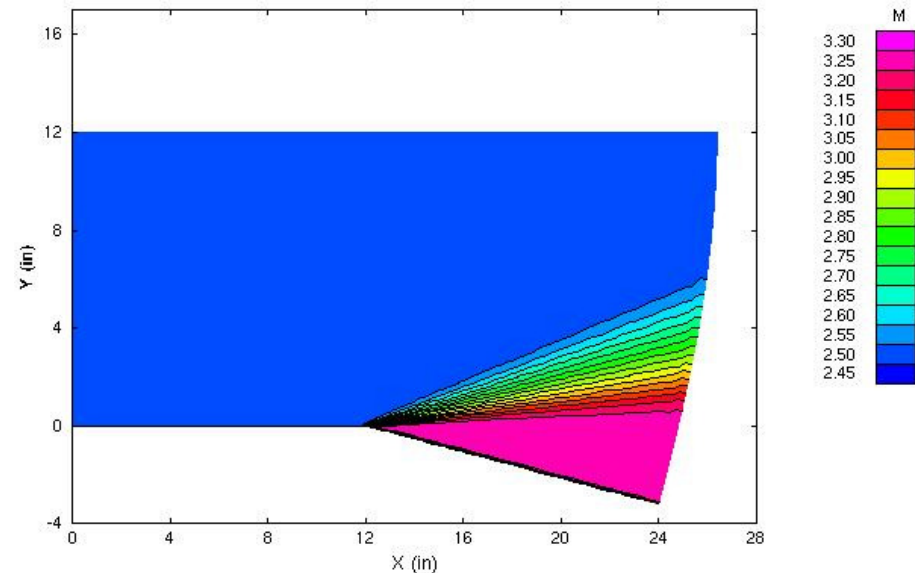
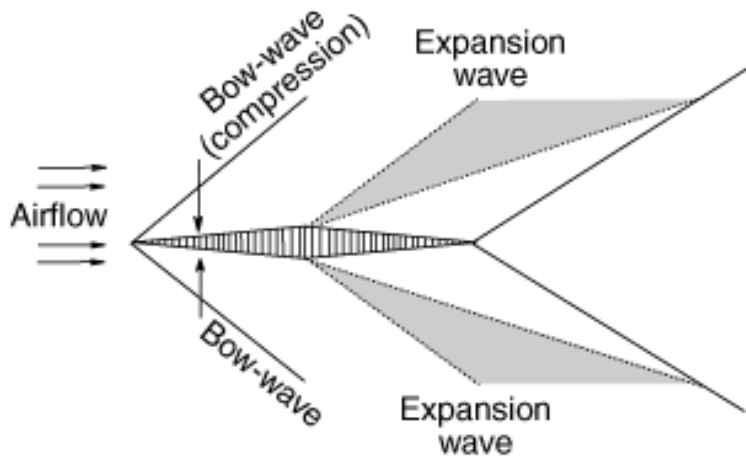


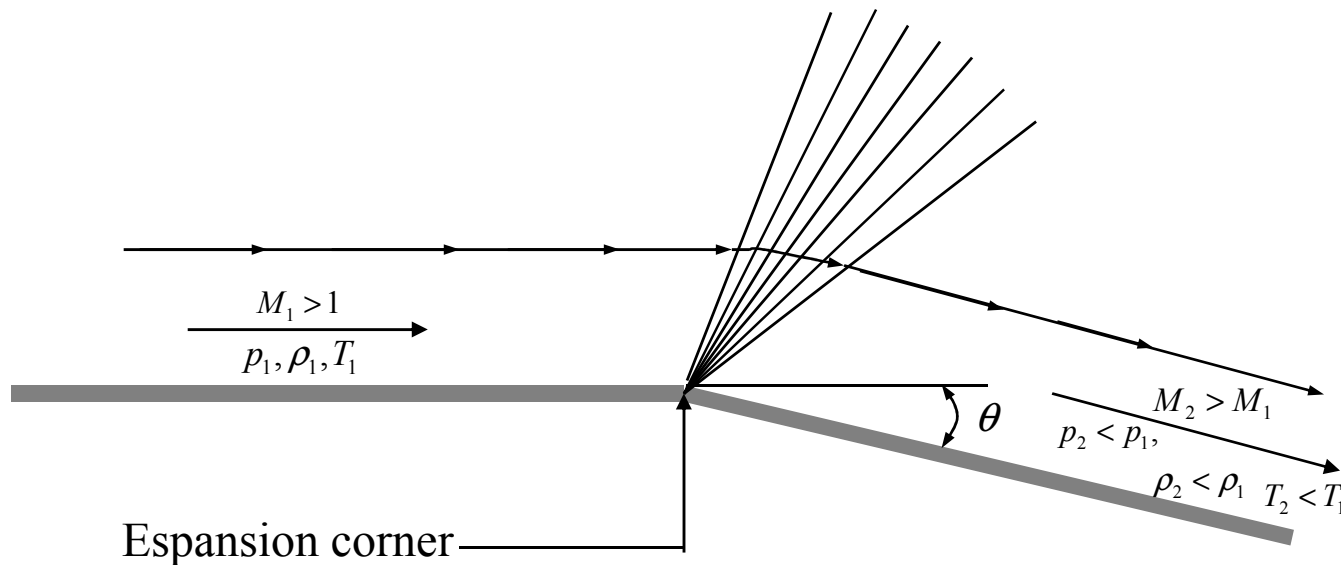
THE SOLUTION OF A PRANDTL-MEYER EXPANSION WAVE FLOW FIELD

- Supersonic flows turn through convex corners of airfoils by means of expansion waves
- A Prandtl-Meyer expansion wave is an idealized expansion wave



THE SOLUTION OF A PRANDTL-MEYER EXPANSION WAVE FLOW FIELD

2D inviscid supersonic flow moving over a surface



MacCormack's space marching (or downstream marching) technique

Exact analytical solution of this problem exist, which helps to obtain a reasonable feeling for the accuracy of the numerical technique

THE GOVERNING EQS OF A TWO-DIMENSIONAL SUPERSONIC FLOW (I)

The governing equations:

Euler equations (inviscid flow) for a steady 2D flow in strong conservation form, for adiabatic flow and no body forces ($f=0$)

$$\frac{\partial F}{\partial x} = -\frac{\partial G}{\partial y} \quad G = \left\{ \begin{array}{l} \rho v \\ \rho uv \\ \rho v^2 + p \\ \rho v \left(e + \frac{V^2}{2} \right) + pv \end{array} \right\} \quad F = \left\{ \begin{array}{l} \rho u \\ \rho u^2 + p \\ \rho uv \\ \rho u \left(e + \frac{V^2}{2} \right) + pu \end{array} \right\}$$

This strong conservation form allows us to apply a downstream marching solution

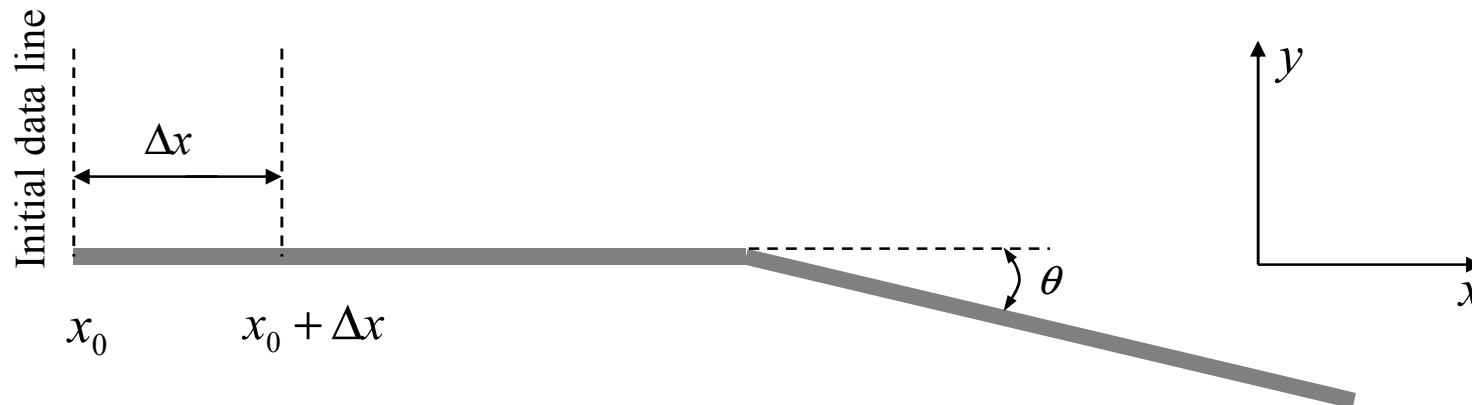
THE GOVERNING EQS OF A TWO-DIMENSIONAL SUPERSONIC FLOW (II)

Downstream marching solution:

$$\frac{\partial F}{\partial x} = -\frac{\partial G}{\partial y} \quad \frac{\partial G}{\partial y} \rightarrow \frac{\partial F}{\partial x} \rightarrow F$$

If the flow field variables are given at x_0 as a function of y (initial data line), then the y derivative of G is known along this line \rightarrow the x derivative of F can be calculated \rightarrow we can advance the flow field variables to the next vertical line located at $x_0 + \Delta x$

Solution can be carried out by marching in steps of Δx along the x direction



THE GOVERNING EQS OF A TWO-DIMENSIONAL SUPERSONIC FLOW (III)

We denote:

$$F_1 = \rho u$$

$$F_2 = \rho u^2 + p$$

$$F_3 = \rho uv$$

$$F_4 = \rho u \left(e + \frac{u^2 + v^2}{2} \right) + pu = \rho u \left(\frac{1}{\gamma - 1} \frac{p}{\rho} + \frac{u^2 + v^2}{2} \right) + pu = \frac{1}{\gamma - 1} pu + \rho u \frac{u^2 + v^2}{2} + pu$$

$$e = c_v T = \frac{RT}{\gamma - 1} = \frac{1}{\gamma - 1} \frac{p}{\rho}$$

$$F_4 = \frac{\gamma}{\gamma - 1} pu + \rho u \frac{u^2 + v^2}{2}$$

$$G_1 = \rho v$$

$$G_2 = \rho uv$$

$$G_3 = \rho v^2 + p$$

$$G_4 = \rho v \left(e + \frac{u^2 + v^2}{2} \right) + pv$$

$$G_4 = \frac{\gamma}{\gamma - 1} pv + \rho v \frac{u^2 + v^2}{2}$$

THE GOVERNING EQS OF A TWO-DIMENSIONAL SUPERSONIC FLOW (IV)

Extra work to do:

solving the eq. $\frac{\partial F}{\partial x} = -\frac{\partial G}{\partial y}$ we get F_1, F_2, F_3, F_4 and we need G_1, G_2, G_3, G_4 .

(1) Decode the primitive variables (u, v, p, T) from the flux variables F_1, F_2, F_3, F_4

$$\begin{aligned} \rho &= \frac{-B + \sqrt{B^2 - 4AC}}{2A} & \text{where} & & A &= \frac{F_3^2}{2F_1} - F_4 \\ u &= \frac{F_1}{\rho} & & & B &= \frac{\gamma}{\gamma-1} F_1 F_2 \\ v &= \frac{F_3}{F_1} & & & C &= -\frac{\gamma+1}{2(\gamma-1)} F_1^3 \\ p &= F_2 - F_1 u \\ T &= \frac{p}{\rho R} \end{aligned}$$

THE GOVERNING EQS OF A TWO-DIMENSIONAL SUPERSONIC FLOW

(V)

(2) Elements G_1, G_2, G_3, G_4 are more desirably expressed in terms of F_1, F_2, F_3, F_4 than in terms of the primitive variables.

$$G_1 = \rho v = \rho \frac{F_3}{F_1}$$

$$G_2 = F_3$$

$$G_3 = \rho v^2 + p = \rho \left(\frac{F_3}{F_1} \right)^2 + p = \rho \left(\frac{F_3}{F_1} \right)^2 + F_2 - \frac{F_1^2}{\rho}$$

$$p = F_2 - \rho u^2 = F_2 - \frac{F_1^2}{\rho}$$

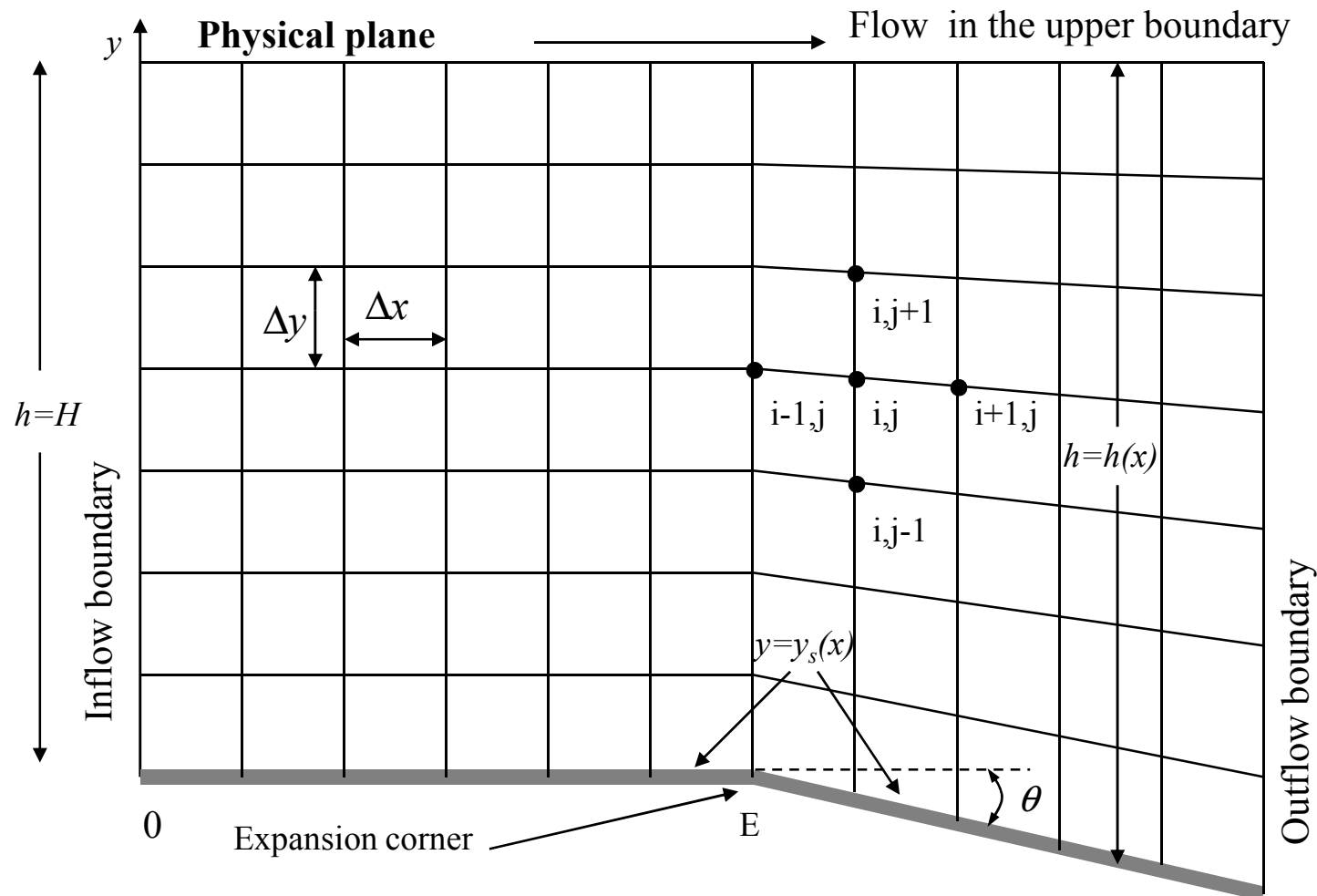
$$G_4 = \frac{\gamma}{\gamma-1} p v + \rho v \frac{u^2 + v^2}{2} = \frac{\gamma}{\gamma-1} \left(F_2 - \frac{F_1^2}{\rho} \right) \frac{F_3}{F_1} + \frac{\rho}{2} \frac{F_3}{F_1} \left[\left(\frac{F_1}{\rho} \right)^2 + \left(\frac{F_3}{F_1} \right)^2 \right]$$

We get F_1, F_2, F_3, F_4 at a point and we need G_1, G_2, G_3, G_4 to calculate $\frac{\partial G}{\partial y} \rightarrow \frac{\partial F}{\partial x} \rightarrow F$ in the next point.

← Obtention of G's as a function of the F's

THE GOVERNING EQS OF A TWO-DIMENSIONAL SUPERSONIC FLOW

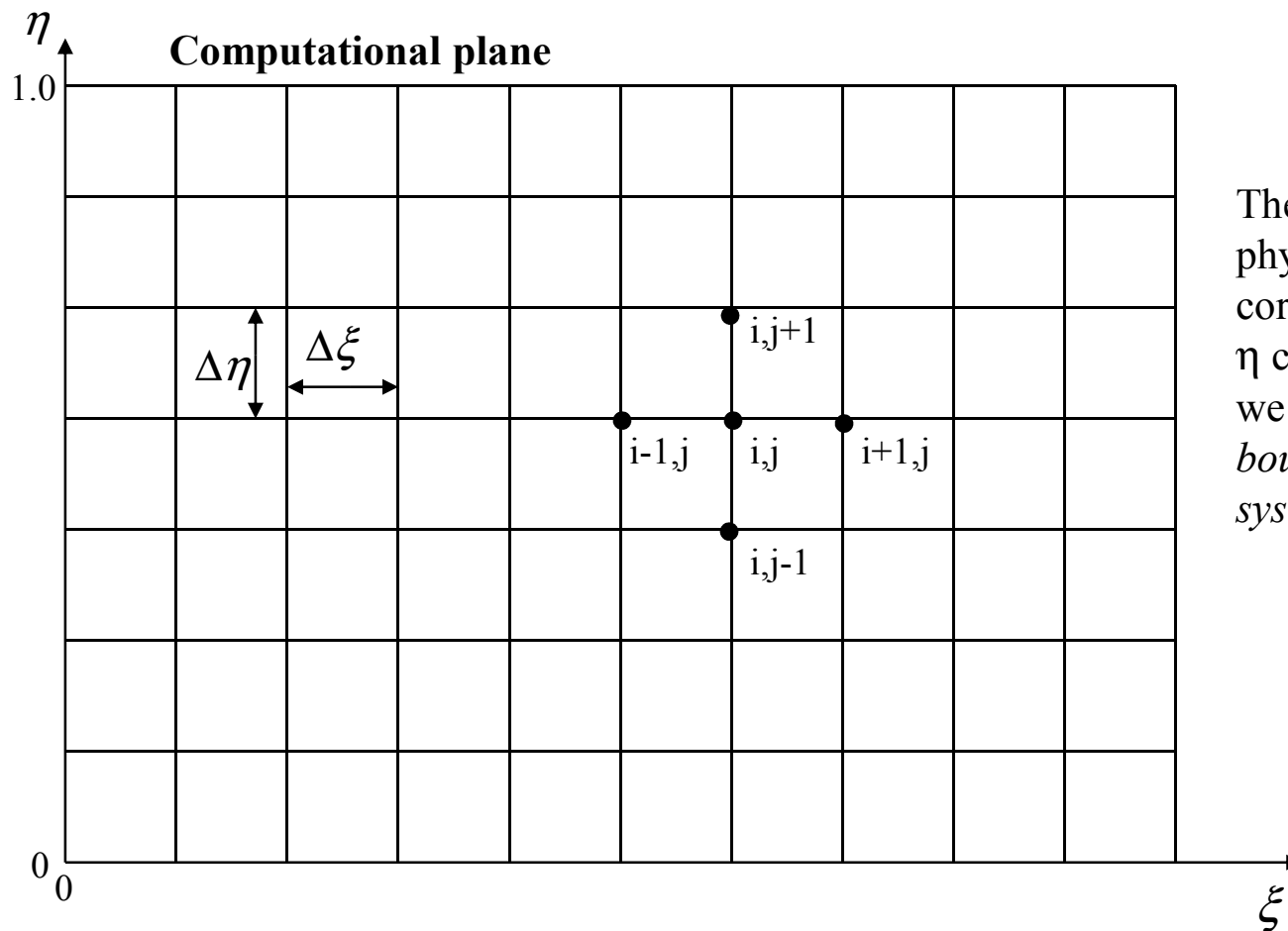
The transformation: grid generation, (VI)
equation transformation



Not a completely rectangular grid.

Physical plane must be transformed to a computational plane where the finite-difference grid is rectangular

THE GOVERNING EQS OF A TWO-DIMENSIONAL SUPERSONIC FLOW (VII)



The bottom surface in the physical plane should correspond to a constant η coordinate curve; i.e. we need to establish a *boundary-fitted coordinate system*.

THE GOVERNING EQS OF A TWO-DIMENSIONAL SUPERSONIC FLOW (VIII)

The transformation:

$y_s(x)$ - y location of the lower surface

$h(x)$ - local height from the lower to the upper boundary in the physical plane

$$\xi=x \quad \eta=\frac{y-y_s(x)}{h(x)}$$

We can carry out the finite-difference calculations on the rectangular grid in the ξ - η plane.

The partial differential equations for the flow are numerically solved in the transformed space and therefore must be appropriately transformed for use in the transformed,

computational plane: $\frac{\partial F}{\partial x} = -\frac{\partial G}{\partial y}$ must be transformed into terms dealing with η and ξ .

$$\begin{aligned} \frac{\partial}{\partial x} &= \frac{\partial}{\partial \xi} \left(\frac{\partial \xi}{\partial x} \right) + \frac{\partial}{\partial \eta} \left(\frac{\partial \eta}{\partial x} \right) & \frac{\partial \xi}{\partial x} &= 1 & \frac{\partial \xi}{\partial y} &= 0 & \frac{\partial \eta}{\partial x} &= -\frac{1}{h} \frac{dy_s}{dx} - \frac{\eta}{h} \frac{dh}{dx} & \frac{\partial \eta}{\partial y} &= \frac{1}{h} \\ \frac{\partial}{\partial y} &= \frac{\partial}{\partial \xi} \left(\frac{\partial \xi}{\partial y} \right) + \frac{\partial}{\partial \eta} \left(\frac{\partial \eta}{\partial y} \right) \end{aligned}$$

THE GOVERNING EQS OF A TWO-DIMENSIONAL SUPERSONIC FLOW (IX)

A faster calculation of $\frac{\partial \eta}{\partial x}$

From the physical plane and denoting the x location of the expansion corner by $x=E$:

$$\text{For } x \leq E : \quad \begin{aligned} y_s &= 0 \\ h &= H \end{aligned}$$

$$\text{For } x \geq E : \quad \begin{aligned} y_s &= -(x - E) \tan \theta \\ h &= H + (x - E) \tan \theta \end{aligned}$$

Differentiating these expressions:

$$\text{For } x \leq E \quad \begin{aligned} \frac{dy_s}{dx} &= 0 \\ \frac{dh}{dx} &= 0 \end{aligned}$$

$$\text{For } x \geq E \quad \begin{aligned} \frac{dy_s}{dx} &= -\tan \theta \\ \frac{dh}{dx} &= \tan \theta \end{aligned}$$

$$\text{Result: } \frac{\partial \eta}{\partial x} = \begin{cases} 0 & \text{for } x \leq E \\ (1 - \eta) \frac{\tan \theta}{h} & \text{for } x \geq E \end{cases} \quad \begin{matrix} (8.25a) \\ (8.25b) \end{matrix}$$

THE GOVERNING EQS OF A TWO-DIMENSIONAL SUPERSONIC FLOW (X)

$$\frac{\partial}{\partial x} = \frac{\partial}{\partial \xi} + \left(\frac{\partial \eta}{\partial x} \right) \frac{\partial}{\partial \eta}$$

$$\frac{\partial}{\partial y} = \frac{1}{h} \frac{\partial}{\partial \eta}$$

$$\frac{\partial F}{\partial x} = - \frac{\partial G}{\partial y}$$

Substituting $\frac{\partial \xi}{\partial x}, \frac{\partial \xi}{\partial y}, \frac{\partial \eta}{\partial x}, \frac{\partial \eta}{\partial y}$ into $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$
where $\frac{\partial \eta}{\partial x}$ is given by equations in previous page.

$$\frac{\partial F}{\partial \xi} + \left(\frac{\partial \eta}{\partial x} \right) \frac{\partial F}{\partial \eta} = - \frac{1}{h} \frac{\partial G}{\partial \eta}$$

$$\frac{\partial F}{\partial \xi} = - \left[\left(\frac{\partial \eta}{\partial x} \right) \frac{\partial F}{\partial \eta} + \frac{1}{h} \frac{\partial G}{\partial \eta} \right]$$

$$\text{Continuity: } \frac{\partial F_1}{\partial \xi} = - \left[\left(\frac{\partial \eta}{\partial x} \right) \frac{\partial F_1}{\partial \eta} + \frac{1}{h} \frac{\partial G_1}{\partial \eta} \right]$$

$$x \text{ momentum: } \frac{\partial F_2}{\partial \xi} = - \left[\left(\frac{\partial \eta}{\partial x} \right) \frac{\partial F_2}{\partial \eta} + \frac{1}{h} \frac{\partial G_2}{\partial \eta} \right]$$

$$y \text{ momentum: } \frac{\partial F_3}{\partial \xi} = - \left[\left(\frac{\partial \eta}{\partial x} \right) \frac{\partial F_3}{\partial \eta} + \frac{1}{h} \frac{\partial G_3}{\partial \eta} \right]$$

$$\text{Energy: } \frac{\partial F_4}{\partial \xi} = - \left[\left(\frac{\partial \eta}{\partial x} \right) \frac{\partial F_4}{\partial \eta} + \frac{1}{h} \frac{\partial G_4}{\partial \eta} \right]$$

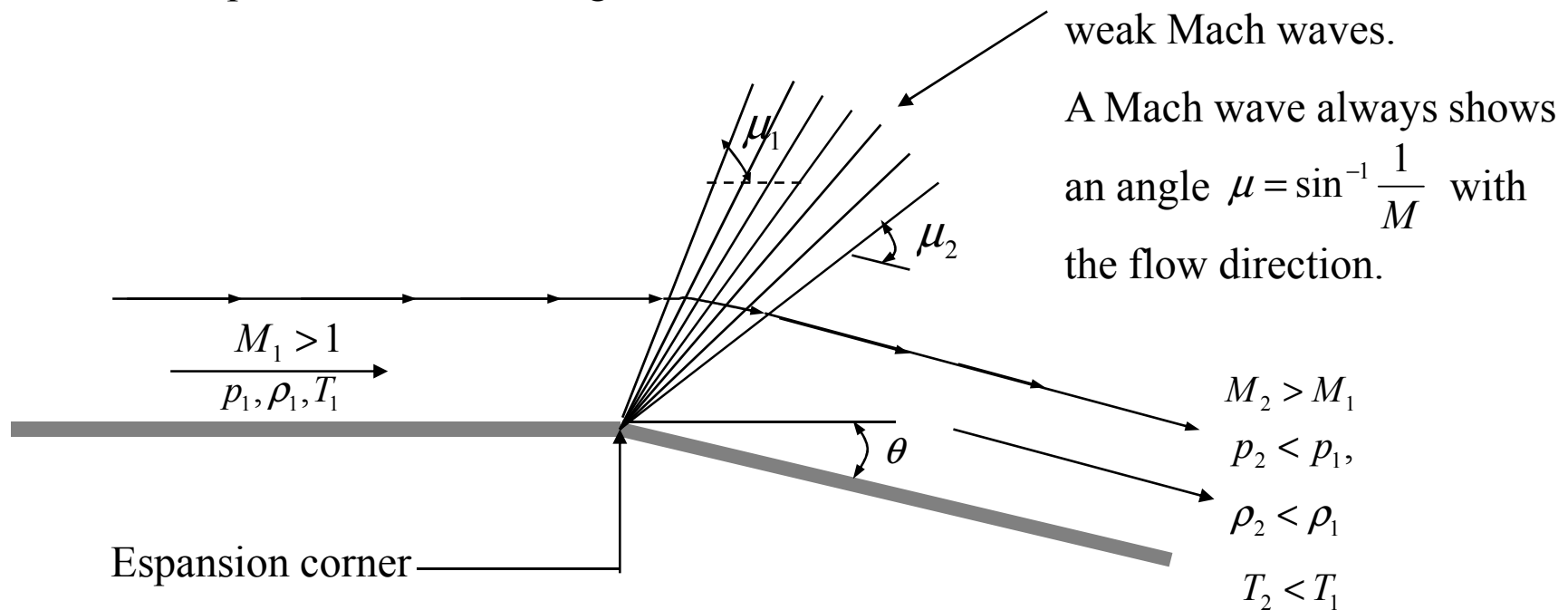
Governing equations in dimensional form to be solved numerically in the computational plane.

PRANDTL-MEYER EXPANSION WAVE

SOME PHYSICAL CHARACTERISTICS

(I)

2D inviscid supersonic flow moving over a surface



We will now obtain the analytical solution of this problem:

M_2, p_2, ρ_2 and T_2 will be calculated analitically from M_1, p_1, ρ_1 and T_1 .

PRANDTL-MEYER EXPANSION WAVE

SOME PHYSICAL CHARACTERISTICS

(II)

μ_1 Angle between the leading Mach wave and the upstream flow direction

μ_2 Angle between the trailing Mach wave and the downstream flow direction

$$\mu_1 = \sin^{-1} \frac{1}{M_1} \quad \text{and} \quad \mu_2 = \sin^{-1} \frac{1}{M_2}$$

Flow through a expansion wave is isentropic. As the flow passes through the expansion wave: M increases, p , T and ρ decrease. Inside the wave, the flow is 2D

The analytical solution of the flow across a centered expansion waves depends on the simple relation:

$$f_2 = f_1 + \theta$$

$$f = \sqrt{\frac{\gamma+1}{\gamma-1}} \tan^{-1} \sqrt{\frac{\gamma-1(M^2-1)}{\gamma+1}} - \tan^{-1} \sqrt{M^2-1}$$

Prandtl-Meyer function for a calorically perfect gas
(FoA, p. 532-537)

PRANDTL-MEYER EXPANSION WAVE

SOME PHYSICAL CHARACTERISTICS

(III)

Analytical solution: $M_1 \rightarrow f_1 \xrightarrow{\theta} f_2 \rightarrow M_2 \rightarrow p_2, T_2, \rho_2$
 | isentropic flow relations

$$p_2 = p_1 \left\{ \frac{1 + [(\gamma - 1)/2] M_1^2}{1 + [(\gamma - 1)/2] M_2^2} \right\}^{\gamma/(\gamma - 1)}$$

$$T_2 = T_1 \frac{1 + [(\gamma - 1)/2] M_1^2}{1 + [(\gamma - 1)/2] M_2^2}$$

$$\rho_2 = \frac{p_2}{RT_2}$$

With all these equations,
flow in 2 is determined

At the corner itself, there is a singular point at which the streamline at the wall experiences a discontinuous change in direction and where the flow properties are discontinuous. This will have an impact in the numerical method.

PROJECT 3: PRANDTL-MEYER EXPANSION WAVE

MacCormack's predictor-corrector explicit finite difference method.

Courant condition: $\Delta\xi = C\Delta\eta / |\tan(\theta \pm \mu)|_{\max}$ (the maximum obtained for each x -step)

Lower boundary condition: velocity tangent to the wall

Suggested values:

$$C=0.5 \quad \Delta\eta=0.1$$

$$h = \begin{cases} 40 \text{ m} & 0 \leq x \leq 10 \text{ m} \\ 40 + (x-10)\tan\theta & 10 \leq x \leq 65 \text{ m} \end{cases}$$

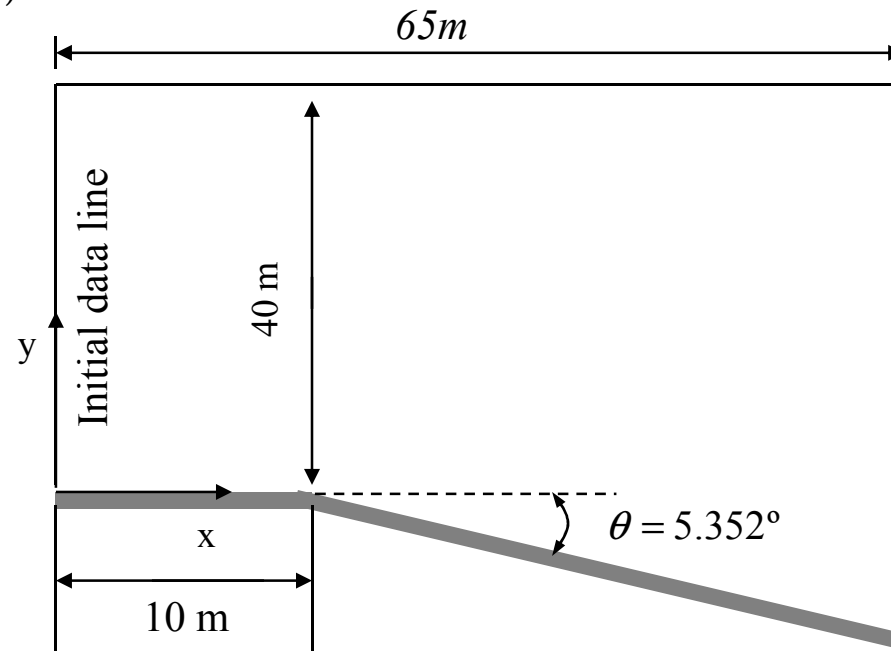
$$M_1 = 2$$

$$p_1 = 1.10 \times 10^5 \frac{\text{N}}{\text{m}^2}$$

$$\rho_1 = 1.23 \frac{\text{kg}}{\text{m}^3}$$

$$T_1 = 286.1 \text{ K}$$

Physical plane,
drawn to scale



Tricks:

- Each x -step, numerical viscosity must be added due to the discontinuity in the sharp corner (CFD, p.391-392).
- Read carefully how to apply the lower boundary condition (CFD, p.392-395).