

# ÒSCAR LORENTE COROMINAS

📍 Martorell 08760, Barcelona 📞 (+34) 684 083 678 📅 20 February 1998, Driving License B  
✉ oscar.lorente.co@gmail.com in linkedin.com/in/lorenteoscar 🐙 github.com/oscar-lorente

## EDUCATION

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CURRENT	<b>Master's Degree, Computer Vision</b>
OCT 2020	Universitat Autònoma de Barcelona (UAB) in collaboration with UPC, UPF, UOC
JULY 2020	<b>Bachelor's Degree, Telecommunications Technologies and Services Engineering</b>
SEPT 2016	ETSETB - Universitat Politècnica de Catalunya (UPC), Barcelona <i>Majored in AUDIOVISUAL SYSTEMS</i>

## WORK EXPERIENCE

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CURRENT	<b>Research Intern</b> at CENTRE FOR SENSORS, INSTRUMENTS AND SYSTEMS DEVELOPMENT (CD6 - UPC), Terrassa, Barcelona
OCT 2020	<i>Researching deep learning techniques to improve 3D object detection using RGB and LIDAR fusion architectures</i>
JULY 2020	<b>Computer Vision Intern</b> at BEAMAGINE S.L., Terrassa, Barcelona
FEB 2020	<i>Designing and implementing pedestrian detection architectures in 3D point clouds</i> Developed the ability to identify, formulate and solve engineering problems related to the computer vision field. Highly improved C++, Python, OPENCV and PCL skills.
NOV 2018	<b>SQL Developer</b> at ACCENTURE, Sant Cugat del Vallès, Barcelona
JULY 2018	<i>Succeed in developing and managing SQL databases of bank clients</i> Improved analysis and problem-solving skills, learned the importance of teamwork, organization and discipline, through the constant communication and feedback between project team members.

## PROJECTS

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JULY 2020	<b>Pedestrian Detection in 3D Point Clouds using Deep Neural Networks</b>
FEB 2020	State-of-the-art deep learning architecture based on <b>PointNet++</b> to detect pedestrians in 3D point clouds obtained from BEAMAGINE L3CAM LIDAR (registered with RGB video sequences). Workflow: apply YOLOv3 for pedestrian detection in the RGB video data, transfer annotations onto the point clouds generating a pedestrian labeled point cloud dataset, and train the designed DNN architecture using the labeled point clouds.
DEC 2019	<b>Ultrasound-Machine Simulator for Medical purposes</b>
SEPT 2019	Project proposed by Fetal Medicine Barcelona: Ultrasound-Machine Simulator for medical personnel training purposes using a smartphone to emulate the ultrasound probe and a computer for processing (MATLAB) and visualization of DICOM images.
MAY 2019	<b>Speaker Recognition, Classification and Verification System</b>
APR 2019	Speaker recognition, classification and verification system (C++) based on the MFCC cepstral coefficients and the use of the Gaussian Mixture Models (GMM). A Deep Learning algorithm based on a multilayer perceptron for speaker classification was also implemented.

## SKILLS

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**Software:** OPENCV, PCL (POINT CLOUD LIBRARY), ROS (ROBOT OPERATING SYSTEM)  
**Technical:** C++, Python, MATLAB, C, Java, SQL, MongoDB, L<sup>A</sup>T<sub>E</sub>X  
**Languages:** Spanish, Catalan, English (C1 ADVANCED)