view_frames Result Recorded at time: 5182.602 map Broadcaster: /slam_gmapping Average rate: 20.522 Hz Most recent transform: 5182.632 (-0.030 sec old) Buffer length: 1.608 sec odom Broadcaster: /ekf_localization Average rate: 42.593 Hz Most recent transform: 5182.580 (0.022 sec old) Buffer length: 1.620 sec base_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (5182.602 sec old) Buffer length: 0.000 sec chassis_link Broadcaster: /robot_state_publisher Average rate: 48.780 Hz Average rate: 48.780 Hz Average rate: 10000.000 Hz Average rate: 48.780 Hz Average rate: 48.780 Hz Most recent transform: 0.000 (5182.602 sec old) Most recent transform: 5182.589 (0.013 sec old) Most recent transform: 0.000 (5182.602 sec old) Buffer length: 1.640 sec Buffer length: 1.640 sec Buffer length: 1.640 sec Buffer length: 1.640 sec Buffer length: 0.000 sec rear_left_wheel_link front_right_wheel_link rear_right_wheel_link front_fender_link imu_link rear_fender_link front_left_wheel_link mid_mount navsat_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (5182.602 sec old) Most recent transform: 0.000 (5182.602 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec front_mount rear_mount Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (5182.602 sec old) Buffer length: 0.000 sec front_laser_mount Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (5182.602 sec old) Buffer length: 0.000 sec front_laser