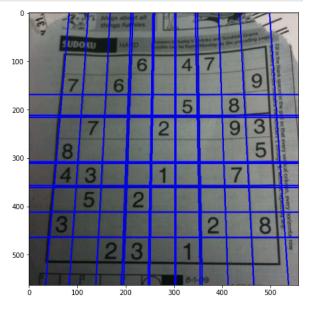
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```
In [ ]:
        #001
         import cv2 as cv
         import matplotlib.pyplot as plt
         import numpy as np
         fig,ax = plt.subplots(1,2,figsize =(16,8))
         im = cv.imread("sudoku.png",cv.IMREAD_COLOR)
         ax[0].imshow(im)
         assert im is not None
         gray = cv.cvtColor(im,cv.COLOR BGR2GRAY)
         edged = cv.Canny(gray,20,120,apertureSize = 3)
         lines = cv.HoughLines(edged,1,np.pi/180,230)
         for line in lines:
             rho,theta =line[0]
             a = np.cos(theta)
            b = np.sin(theta)
            x0, y0= a*rho, b*rho
            x1, y1 = int(x0+1000*(-b)), int(y0+1000*(a))
            x2, y2=int(x0-1000*(-b)),int(y0-1000*(a))
             cv.line(im,(x1,y1),(x2,y2),(0,0,255),2)
             ax[1].imshow(im)
```





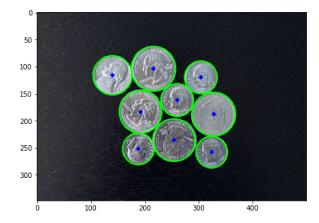
```
#Q02
In [ ]:
        import cv2 as cv
        import matplotlib.pyplot as plt
        import numpy as np
        fig,ax = plt.subplots(1,2,figsize =(16,8))
        im = cv.imread("coins.jpg",cv.IMREAD_COLOR,).astype(np.uint16)
        ax[0].imshow(im)
        assert im is not None
        gray = cv.cvtColor(im,cv.COLOR BGR2GRAY).astype(np.uint8)
        circles = cv.HoughCircles(gray,cv.HOUGH_GRADIENT,1,50,param1=180,param2=80,minRadius=1
        circles = np.uint16(np.around(circles))
        for i in circles[0,:]:
            # draw the outer circle
            cv.circle(im,(i[0],i[1]),i[2],(0,255,0),2)
            # draw the center of the circle
```

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```
cv.circle(im,(i[0],i[1]),2,(0,0,255),3)
ax[1].imshow(im)
```

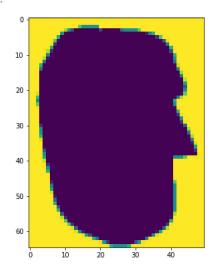
Out[]: <matplotlib.image.AxesImage at 0x1f8c2c7ee30>

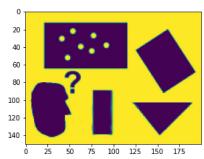


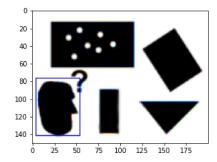


```
#Q03
In [ ]:
                        import cv2 as cv
                        import matplotlib.pyplot as plt
                        import numpy as np
                        fig,ax = plt.subplots(1,3,figsize =(16,8))
                        img=cv.imread(r'pic1.png',cv.IMREAD_REDUCED_GRAYSCALE_2)
                        assert img is not None
                        temp=cv.imread(r'templ.png',cv.IMREAD REDUCED GRAYSCALE 2)
                        assert temp is not None
                        im_edges = cv.Canny(img,50,250)
                        temp1 edges = cv.Canny(temp,50,250)
                        alg = cv.createGeneralizedHoughGuil()
                        im_edges=cv.Canny(img,50,250)
                        temp edges=cv.Canny(temp,50,250)
                        alg=cv.createGeneralizedHoughGuil()
                        alg.setTemplate(temp edges)
                        alg.setAngleThresh(100000)
                        alg.setScaleThresh(40000)
                        alg.setPosThresh(1000)
                        alg.setAngleStep(1)
                        alg.setScaleStep(0.1)
                        alg.setMinScale(0.9)
                        alg.setMaxScale(1.1)
                        positions,votes = alg.detect(im_edges)
                        out = cv.cvtColor(img,cv.COLOR BAYER BG2BGR)
                        for x,y,scale,orientation in positions[0]:
                                   halfHeight = temp.shape[0]/2.*scale
                                   halfWidth = temp.shape[1]/2.*scale
                                   p1 = (int(x-halfWidth),int(y-halfHeight))
                                   p2 = (int(x+halfWidth),int(y+halfHeight))
                                   print("x = {},y = {}, orientation = {}, p1 = {}, p2 = {}".format(x,y,scale,orientation = {}, p1 = {}, p2 = {}".format(x,y,scale,orientation = {}, p3 = {}, p4 = {}, p4
                                   cv.rectangle(out,p1,p2,(0,0,255))
                        ax[0].imshow(temp)
                        ax[1].imshow(img)
                        ax[2].imshow(out)
```

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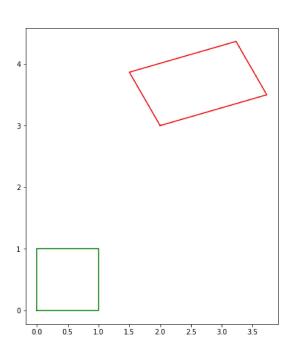


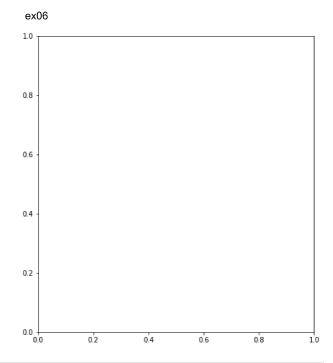


In []:

None

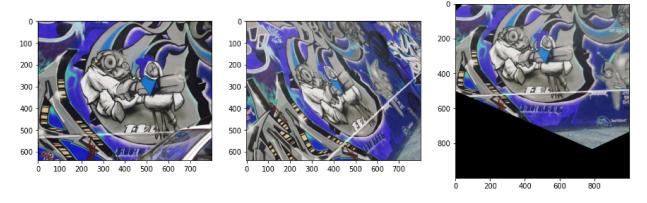
```
#004
In [ ]:
        import cv2 as cv
         import matplotlib.pyplot as plt
         import numpy as np
        a,b,c,d = [0,0,1],[0,1,1],[1,1,1],[1,0,1]
        X = np.array([a,b,c,d]).T
        theta = np.pi*30/180
        s=1
        tx, ty = 2,3
        H = np.array([[2*np.cos(theta),-s*np.sin(theta),tx],[s*np.sin(theta),s*np.cos(theta),t
        Y = H@X
        x = np.append(X[0,:],X[0,0])
        y = np.append(X[1,:],X[1,0])
        fig,ax = plt.subplots(1,2,figsize =(16,8))
         ax[0].plot(x,y,color = 'g')
        ax[0].set_aspect('equal')
        x = np.append(Y[0,:],Y[0,0])
        y = np.append(Y[1,:],Y[1,0])
        ax[0].plot(x,y,color = 'r')
         ax[0].set_aspect('equal')
         plt.show()
```





```
#Q05
In [ ]:
        import cv2 as cv
        import matplotlib.pyplot as plt
        import numpy as np
        %matplotlib inline
        img1=cv.imread(r'graffity/img1.ppm',cv.IMREAD_ANYCOLOR)
        assert img1 is not None
        img4=cv.imread(r'graffity/img4.ppm',cv.IMREAD_ANYCOLOR)
        assert img4 is not None
        H=[]
        with open(r'graffity/H1to4p') as f:
            H=np.array([[float(h) for h in line.split()] for line in f])
        img4to1=cv.warpPerspective(img4,np.linalg.inv(H),(1000,1000))
        fig,ax=plt.subplots(1,3,figsize=(15,15))
        ax[0].imshow(img1)
        ax[1].imshow(img4)
        ax[2].imshow(img4to1)
```

Out[]: <matplotlib.image.AxesImage at 0x245159054e0>



In []: