# Osher Azulay

#### Passionate Roboticist

Sep 2020 – Present | Ph.D., Mechanical Engineering, Tel Aviv University

Research Area: Robotic In-Hand Learning, Perception and Manipulation

Advisor: Dr. Avishai Sintov

Sep 2018 – Jul 2020 M.Sc., Mechanical Engineering, Ben Gurion University

Outstanding students program (93.8 GPA)

Thesis: Wheel Loader Scooping Controller Using Deep Reinforcement Learning

Advisor: Prof. Amir Shapiro

Sep 2015 – Jul 2019 | B.Sc., Mechanical Engineering, Ben Gurion University

Graduated with honors (90.1 GPA)

*Certificate of achievement: 2017-2018, 2018-2019* 

Final Project: Development of Autonomous Robot for Soil Manipulation

## **Work Experience**

## **Teaching Experience**

Fall 2020, Fall 2021 | Intro to control theory, Teaching Assistant, Mech Eng., Tel-Aviv University

Spring 2020 | Robotics and control lab, Designed and created course material, Mech Eng., Tel-Aviv University

Spring 2019 | Intro to Electrical Engineering, Teaching Assistant, Mech Eng., Ben-Gurion University

Fall 2019 | C Programming, Teaching Assistant, Mech Eng., Ben-Gurion University

Fall 2018 | Intro to Mechanical Engineering, Lab Instructor, Mech Eng., Ben-Gurion University

#### **Publications**

1. **Azulay, O.** & Shapiro, A. Wheel Loader Scooping Controller Using Deep Reinforcement Learning. *IEEE Access* **9,** 24145–24154 (2021).

#### **Skills**

2021

Programming | Python, Matlab, C/C++

Tools | ROS, PyTorch and TensorFlow

Engineering | Solidworks, Microcontrollers and Mechatronics