

BELLMAN-FORD ALGORITHM

The **Bellman-Ford algorithm** is a [graph](#) search algorithm that finds the shortest path between a given source vertex and all other vertices in the graph. This algorithm can be used on both weighted and unweighted graphs.

Like [Dijkstra's shortest path algorithm](#), the Bellman-Ford algorithm is guaranteed to find the shortest path in a graph. Though it is slower than Dijkstra's algorithm, Bellman-Ford is capable of handling graphs that contain negative edge weights, so it is more versatile. It is worth noting that if there exists a negative cycle in the graph, then there is no shortest path. Going around the negative cycle an infinite number of times would continue to decrease the cost of the path (even though the path length is increasing). Because of this, Bellman-Ford can also detect negative cycles which is a useful feature.

The Bellman-Ford algorithm, like [Dijkstra's algorithm](#), uses the principle of [relaxation](#) to find increasingly accurate path length. Bellman-Ford, though, tackles two main issues with this process.

- 1.If there are negative weight cycles, the search for a shortest path will go on forever.
- 2.Choosing a bad ordering for relaxations leads to exponential relaxations.

The detection of [negative cycles](#) is important, but the main contribution of this algorithm is in its ordering of relaxations. Dijkstra's algorithm is a [greedy algorithm](#) that selects the nearest vertex that has not been processed. Bellman-Ford, on the other hand, relaxes *all* of the edges.

Algorithm Psuedo-code

The pseudo-code for the Bellman-Ford algorithm is quite short.

This is high level description of Bellman-Ford written with pseudo-code, not an implementation

for v in V:

```
    v.distance = infinity
    v.p = None
source.distance = 0
for i from 1 to |V| - 1:
    for (u, v) in E:
        relax(u, v)
```

The first `for` loop sets the distance to each vertex in the graph to infinity. This is later changed for the source vertex to equal zero. Also in that first `for` loop, the `p` value for each vertex is set to nothing. This value is a pointer to a predecessor vertex so that we can create a path later.

The next `for` loop simply goes through each edge `(u, v)` in `E` and [relaxes](#) it. This process is done `|V| - 1` times.

Relax Equation

`relax(u, v):`

```
    if v.distance > u.distance + weight(u, v):  
        v.distance = u.distance + weight(u, v)  
        v.p = u
```

Detecting Negative Cycle

`for v in V:`

```
    v.distance = infinity  
    v.p = None  
    source.distance = 0  
    for i from 1 to |V| - 1:  
        for (u, v) in E:  
            relax(u, v)  
    for (u, v) in E:  
        if v.distance > u.distance + weight(u, v):  
            print "A negative weight cycle exists"
```

Implementation in C++

```

siddharth@siddharth-Inspiron-3541: ~/Desktop/4th SEMESTER (WINTER 2016-17)/CSE100
4 - NETWORK AND COMMUNICATION/PROJECT$ g++ bell.cpp
siddharth@siddharth-Inspiron-3541:~/Desktop/4th SEMESTER (WINTER 2016-17)/CSE100
4 - NETWORK AND COMMUNICATION/PROJECT$ ./a.out
Enter the Number of Vertices -
4
Enter the Number of Edges -
5
Enter the Edges V1 -> V2, of weight W
1 2 1
2 3 5
3 1 4
2 4 2
4 3 6

The Adjacency List-
adjacencyList[1] -> 2(1)
adjacencyList[2] -> 3(5) -> 4(2)
adjacencyList[3] -> 1(4)
adjacencyList[4] -> 3(6)

Enter a Start Vertex -
1
No Negative Cycles exist in the Graph -

```

```

siddharth@siddharth-Inspiron-3541: ~/Desktop/4th SEMESTER (WINTER 2016-17)/CSE100
4 - NETWORK AND COMMUNICATION/PROJECT$
1 2 1
2 3 5
3 1 4
2 4 2
4 3 6

The Adjacency List-
adjacencyList[1] -> 2(1)
adjacencyList[2] -> 3(5) -> 4(2)
adjacencyList[3] -> 1(4)
adjacencyList[4] -> 3(6)

Enter a Start Vertex -
1
No Negative Cycles exist in the Graph -

Vertex      Shortest Distance to Vertex 1      Parent Vertex-
1           0                               0
2           1                               1
3           6                               2
4           3                               2
siddharth@siddharth-Inspiron-3541:~/Desktop/4th SEMESTER (WINTER 2016-17)/CSE100
4 - NETWORK AND COMMUNICATION/PROJECT$

```

Implementation in Scilab

```
function [ v_weight, predecessor ] = bellman_ford ( v_num, e_num, source, e,  
e_weight )
```

```
    r8_big = 1.0E+30;  
    v_weight = [];  
    predecessor = [];  
    v_weight(1:v_num) = r8_big;  
    v_weight(source) = 0;  
  
    predecessor(1:v_num) = -1;  
  
    for i = 1 : v_num  
        for j = 1 : e_num  
            u = e(j,2);  
            v = e(j,1);  
            t = v_weight(u) + e_weight(j);  
            if ( t < v_weight(v) ) then  
                v_weight(v) = t;  
                predecessor(v) = u;  
            end  
        end  
    end
```

```
    for j = 1 : e_num  
        u = e(j,2);  
        v = e(j,1);  
        if ( v_weight(u) + e_weight(j) < v_weight(v) )  
            mprintf ( '\n' );  
            mprintf ( 'BELLMAN_FORD - Fatal error!\n' );  
            mprintf ( ' Graph contains a cycle with negative weight.\n' );  
            error ( 'BELLMAN_FORD - Fatal error!' );  
        end  
    end
```

```
    return  
endfunction
```

```
function i4vec_print ( n, a, ti )
```

```
    mprintf ( '\n' );  
    mprintf ( '%s\n', ti );
```

```

mprintf ( '\n' );

for i = 1 : n
    mprintf ( '%6d: %6d\n', i, a(i) );
end

return
endfunction

```

```

function r8vec_print ( n, a, ti )

mprintf ('\n' );
mprintf ( '%s\n', ti );
mprintf ( '\n' );
for i = 1 : n
    mprintf ( '%6d: %12g\n', i, a(i) );
end

return
endfunction

```

```

function bellman_ford_test01 ( )

e_num = 5;
v_num = 4;

e = [ 2, 1; 3, 2; 1, 3; 3, 4; 4, 2];
e_weight = [ 1;5;4;6;2];

source = 1;

mprintf ( 'Bellman-Ford shortest path algorithm\n' );

mprintf( 'Number of vertices = %d\n', v_num);
mprintf ( 'Number of edges = %d\n', e_num);
mprintf( 'The reference vertex is = %d\n', source);

r8vec_print ( e_num, e_weight, ' The edge weights:' );

[ v_weight, predecessor ] = bellman_ford ( v_num, e_num, source, e,e_weight );

r8vec_print ( v_num, v_weight, ' The shortest distances:' );

```

```
i4vec_print ( v_num, predecessor, ' The vertex predecessor parents for the shortest paths:');
```

```
return
endfunction
```

```
function bellman_ford_test ( )
```

```
bellman_ford_test01;
mprintf ( 'BELLMAN_FORD_TEST\n' );
mprintf ( 'Normal end of execution\n' );
```

```
return
endfunction
bellman_ford_test;
```

