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path.py
              Sun Sep 25 08:51:25 2016
File that handles paths and stuff
import json
class Path:
    ....
        Handles the path the robot should follow
       Also passes information to the draw-object
    def __init__(self, pathName):
        self.pathName = pathName
        self.path = self.load(pathName)
        self.currentIndex = 0
    def load(self, fileString):
        :param fileString: the name of the file
        :return: the path
        with open(fileString, 'r') as data file:
            data = json.load(data_file)
        return data
    # returns the position of the given point
    def position(self, index):
        return self.path[index]['Pose']['Position']['X'], self.path[index]['Pose']['Positio
n']['Y']
    def length(self):
        .....
        :return: the number of poses in the path
        return len(self.path)
    def getCurrentIndex(self):
        return self.currentIndex
    def setCurrentIndex(self, currentIndex):
        self.currentIndex = currentIndex
    def getLast(self):
        :return: the position of the last point on the path
        return self.position(self.length()-1)
```