



# Image Analysis

Rasmus R. Paulsen

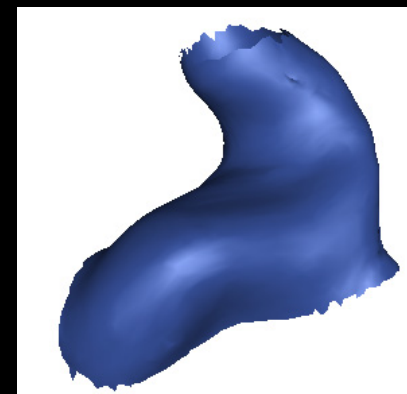
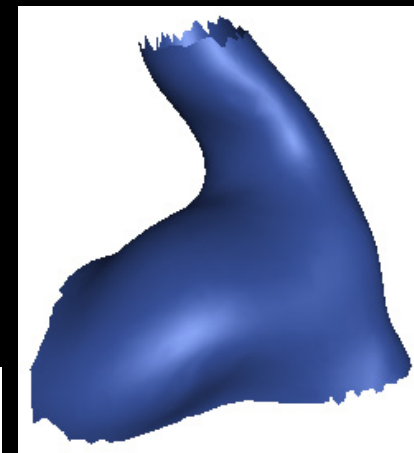
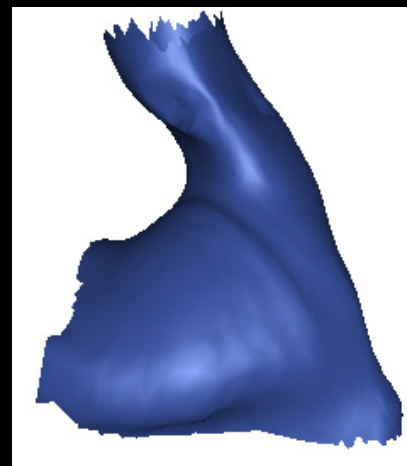
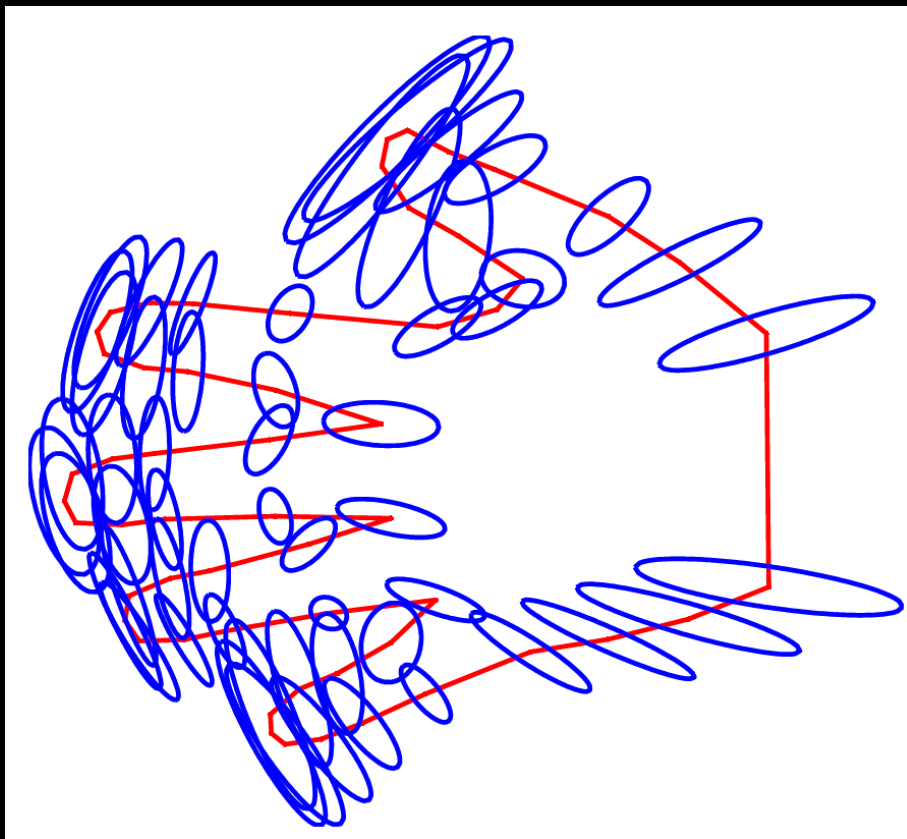
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# Lecture 9 – Statistical models of shape and appearance





## Today's Learning Objectives

- Describe the concept of shape models
- Define the shape of an object using landmarks
- Describe point correspondence
- Describe and use the vector representation of a shape
- Describe how a shape can be seen as a point in high-dimensional space
- Explain how shapes can be aligned
- Describe how principal component analysis can be used to model shape variation
- Explain the similarity between Eigenfaces and shape and appearance models

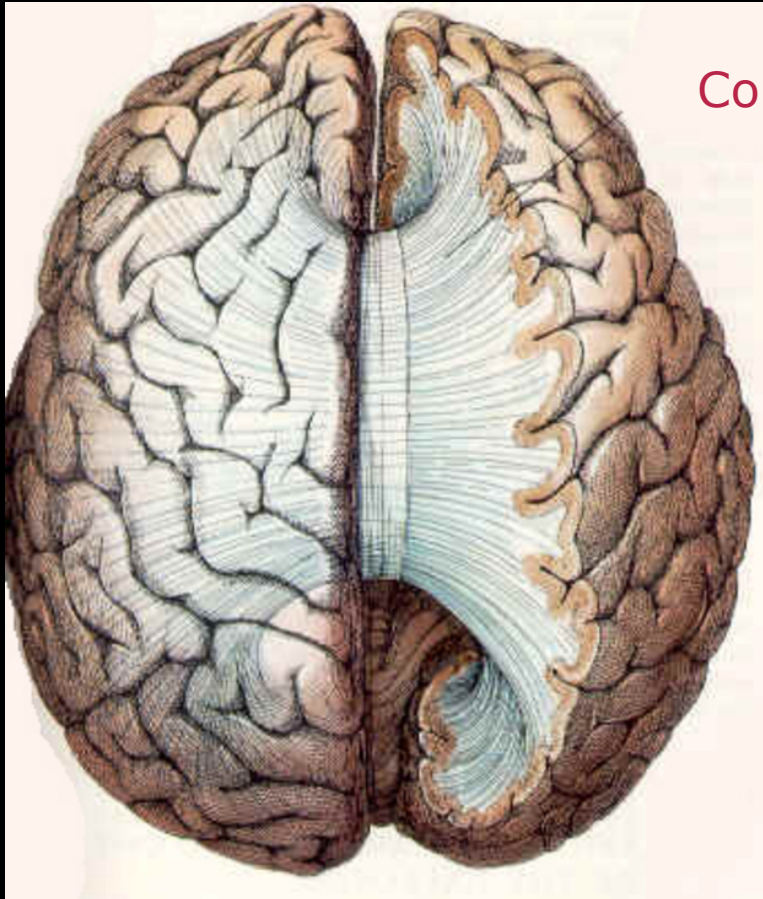
## A typical scenario



- Doctor X believes that he can “see” on a hand X-ray if the patient is in risk of arthritis!
- Specifically Doctor X is sure that the *shape of the joints* is an estimator for arthritis!

Can we verify that?

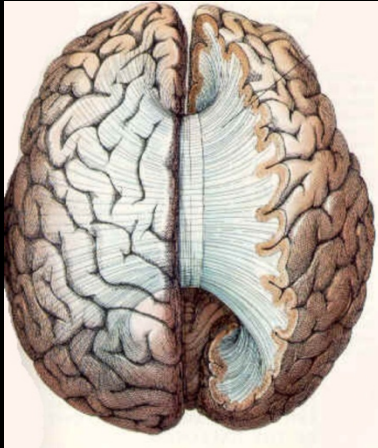
## Scenario II



Corpus Callosum

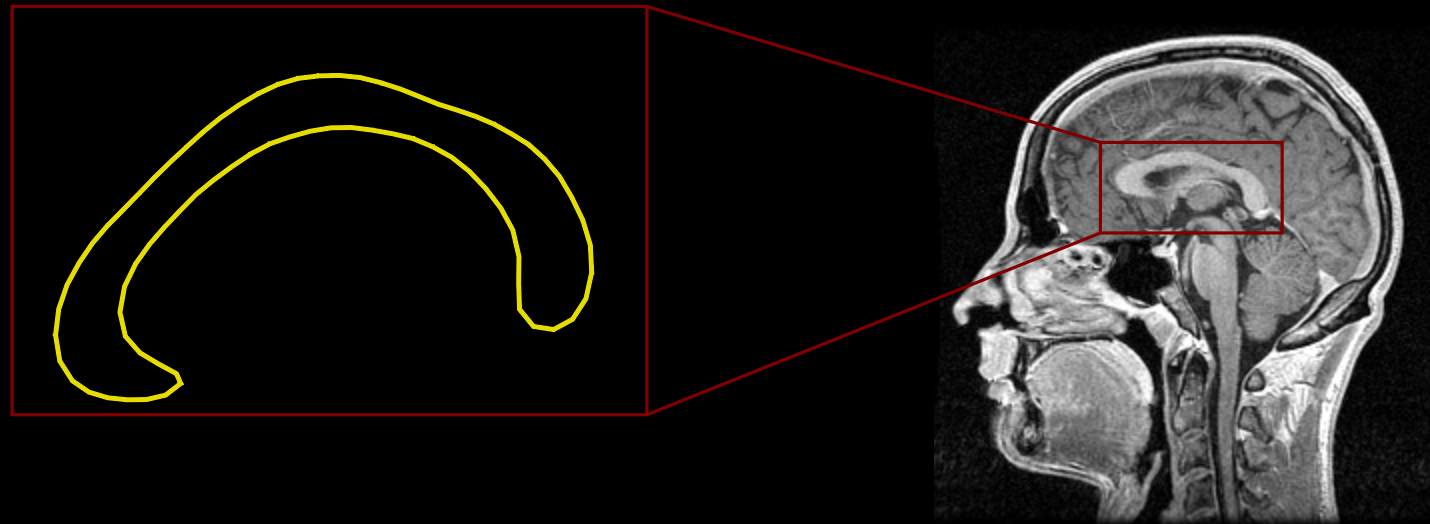
- MR images have been captured of a large group of people
- Cognitive abilities measured as well
- Is there a correlation between *how the brain looks* and how we behave?
- Does the shape of corpus callosum tell us something?

## Scenario II



Corpus Callosum

- We can get the MR slice with the corpus callosum from all the patients





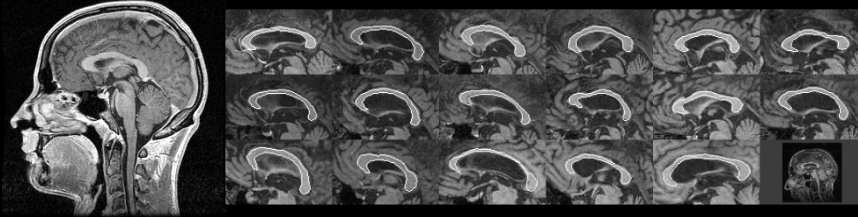
## Scenario III



- An experienced hearing aid fitter has seen a lot of ears!
- Some hearing aid users are very difficult to fit. Why?
- Large variation in the shape of ears
- Ear canals change shape when people chews
- Is it possible to learn about the shape and use it?



# Shape Analysis



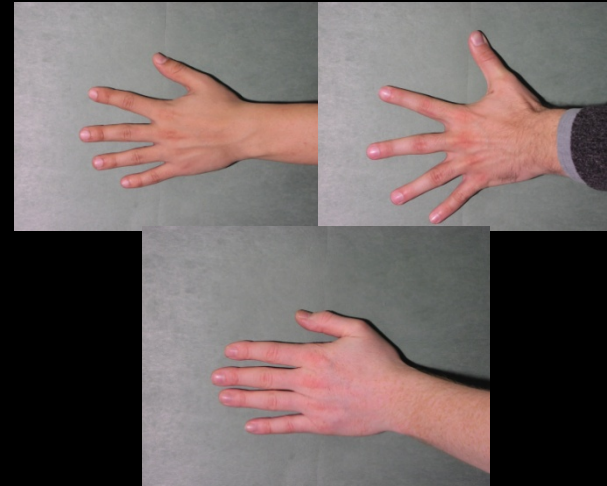
600 MR scans and  
behavioural data



1000 historical X-rays



A boxful of something  
that look like ear canals

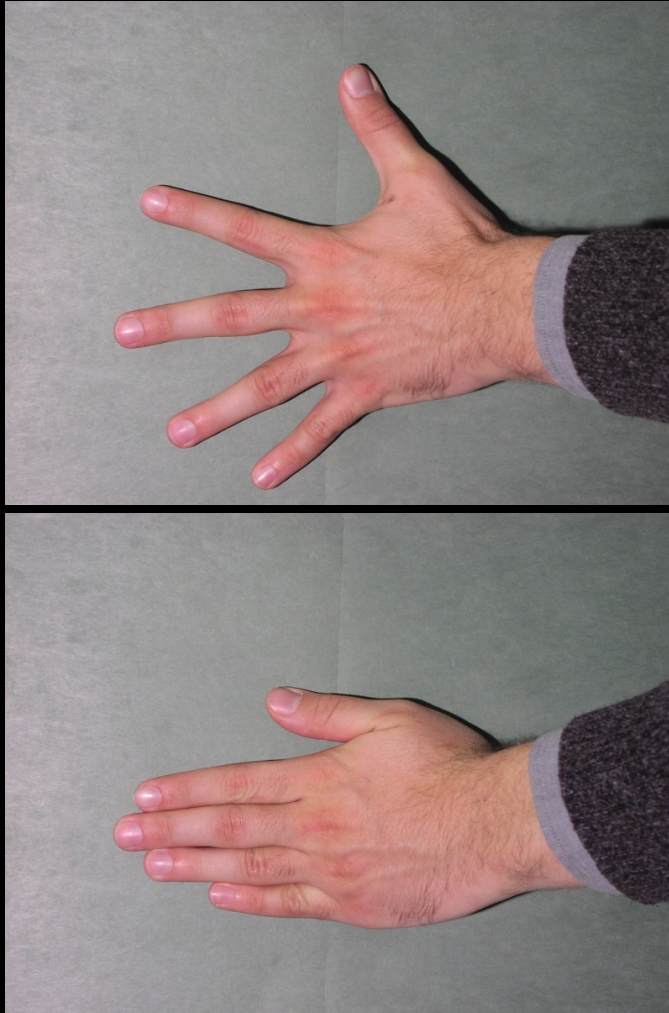


A set of hand  
photographs

- What can we learn from shape?
- What can we use it for?
- How do we do it?

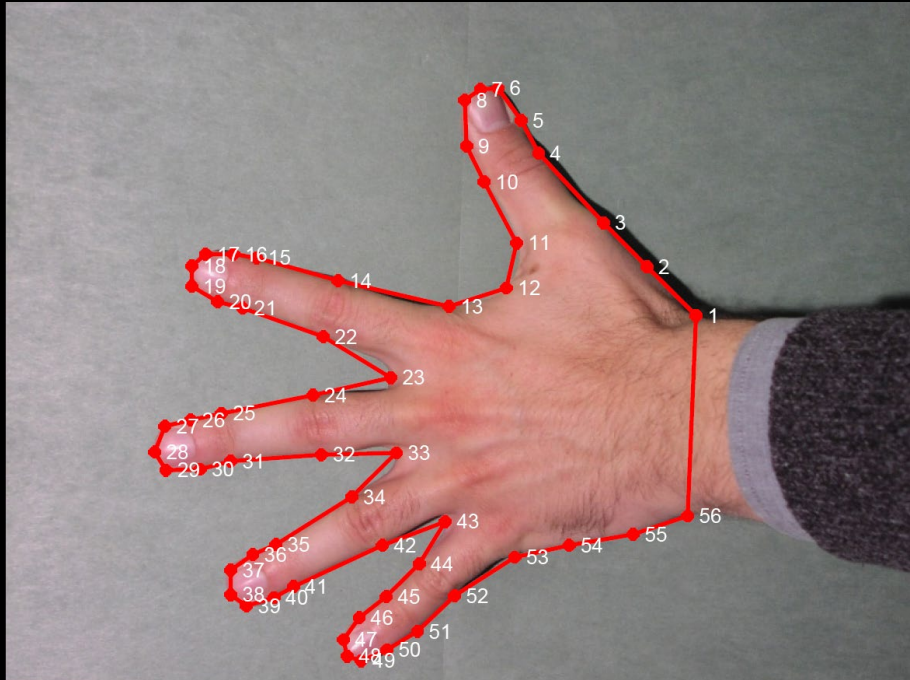


# What is shape?



- How do we define the *shape* of this hand?
- What is the shape difference between the two hands?

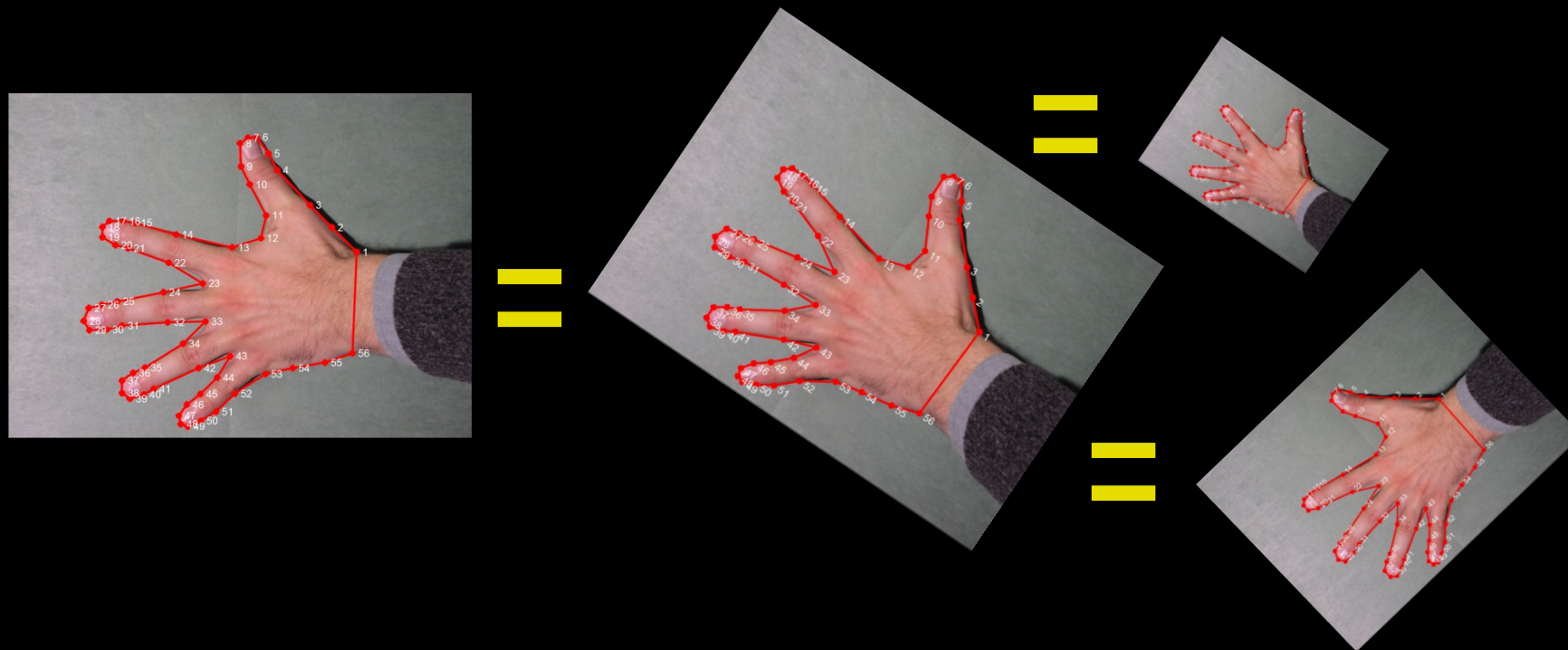
# Shape definition



- Shape is defined using landmarks
  - Placed by an expert
- In this case the outer contour of the hand
- Just one of many ways!

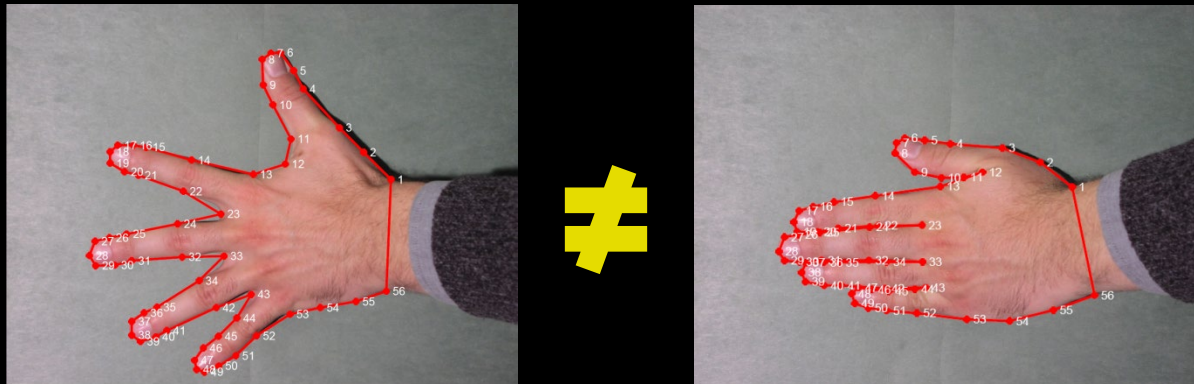
# Shape definition

Shape is all geometrical information that remains when location, scale, and rotational effects are removed



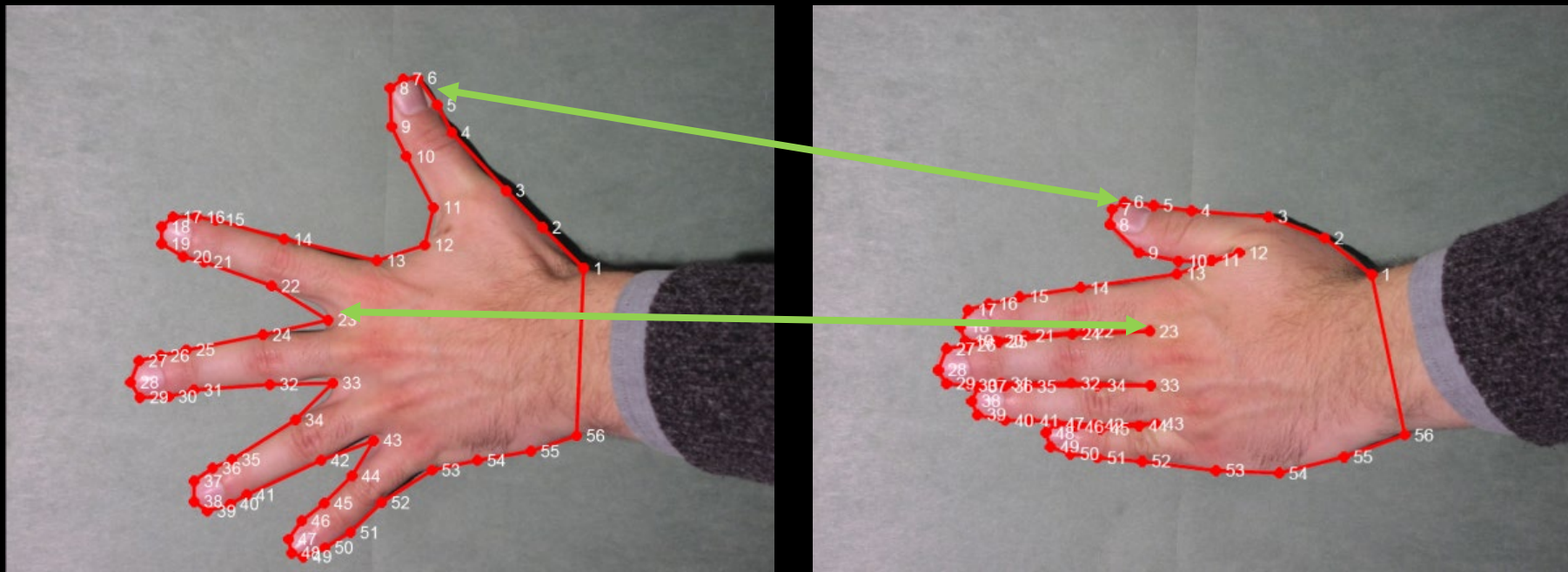
# Shape definition

Shape is all geometrical information that remains when location, scale, and rotational effects are removed



# Landmarks and point correspondence

Landmarks are placed on the same place on all shapes in the training set





# Shape as a vector

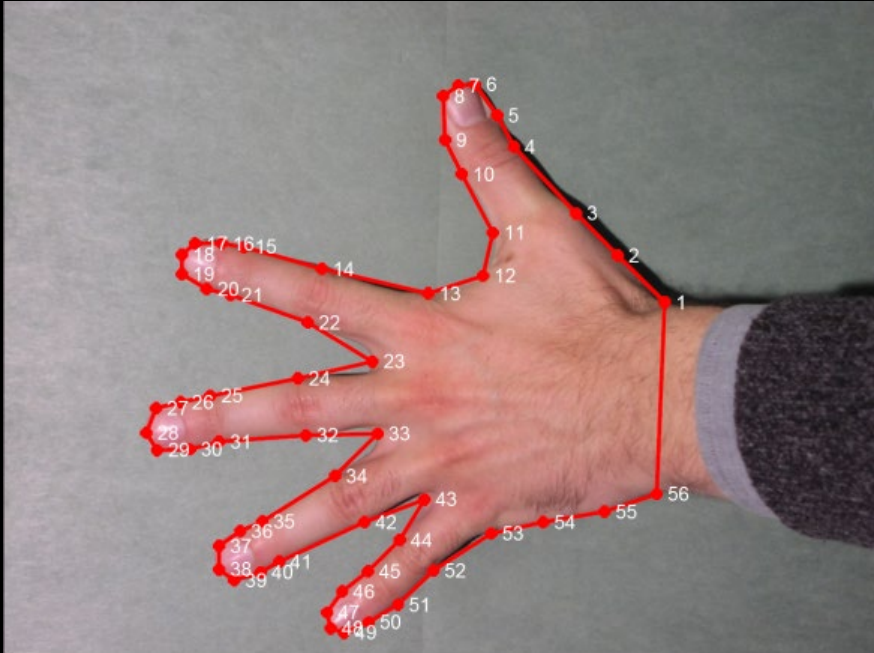
$$\begin{aligned} 1 &: (x_1, y_1) \\ 2 &: (x_2, y_2) \\ &\vdots \\ N &: (x_n, y_n) \end{aligned}$$



- The shape is represented as an array of (x,y) coordinates
- Trick number one!  
All coordinates are put into one vector!
- n=56 points
  - Vector with 112 elements!

$$\mathbf{x} = [x_1, x_2, \dots, x_n, y_1, y_2, \dots, y_n]^T$$

# Shapes in high-dimensional space

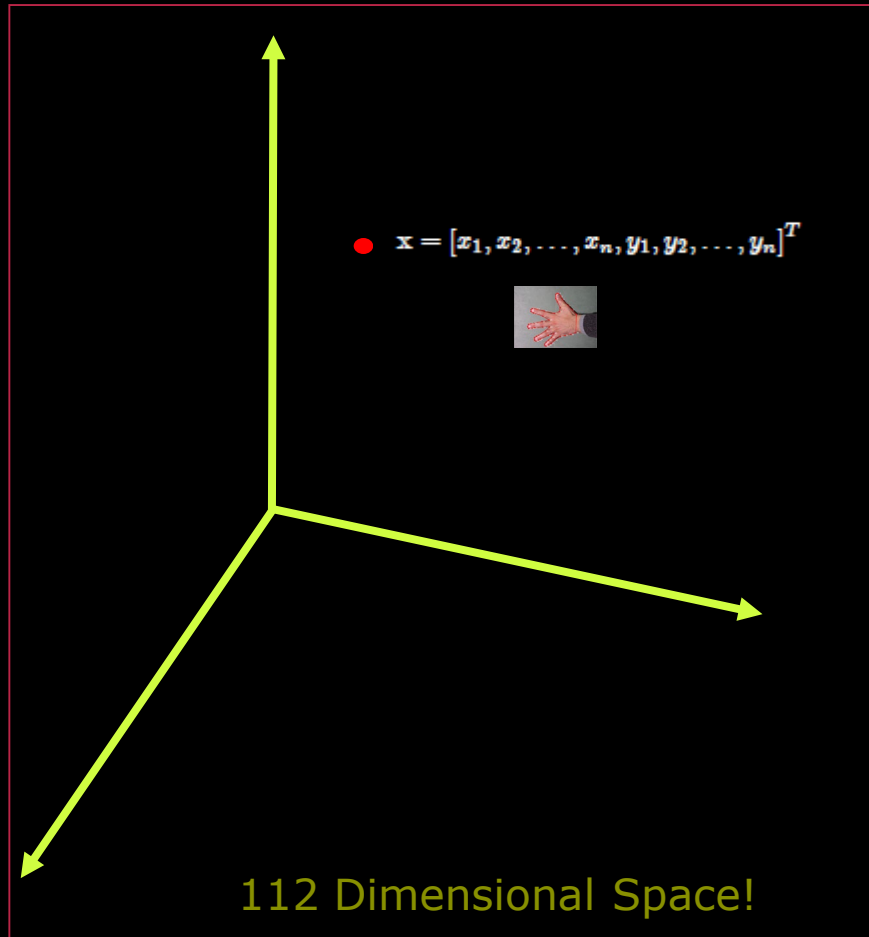


$$\mathbf{X} = [x_1, x_2, \dots, x_n, y_1, y_2, \dots, y_n]^T$$

- One hand is now described using one vector
- A vector can also be seen as a point in space!

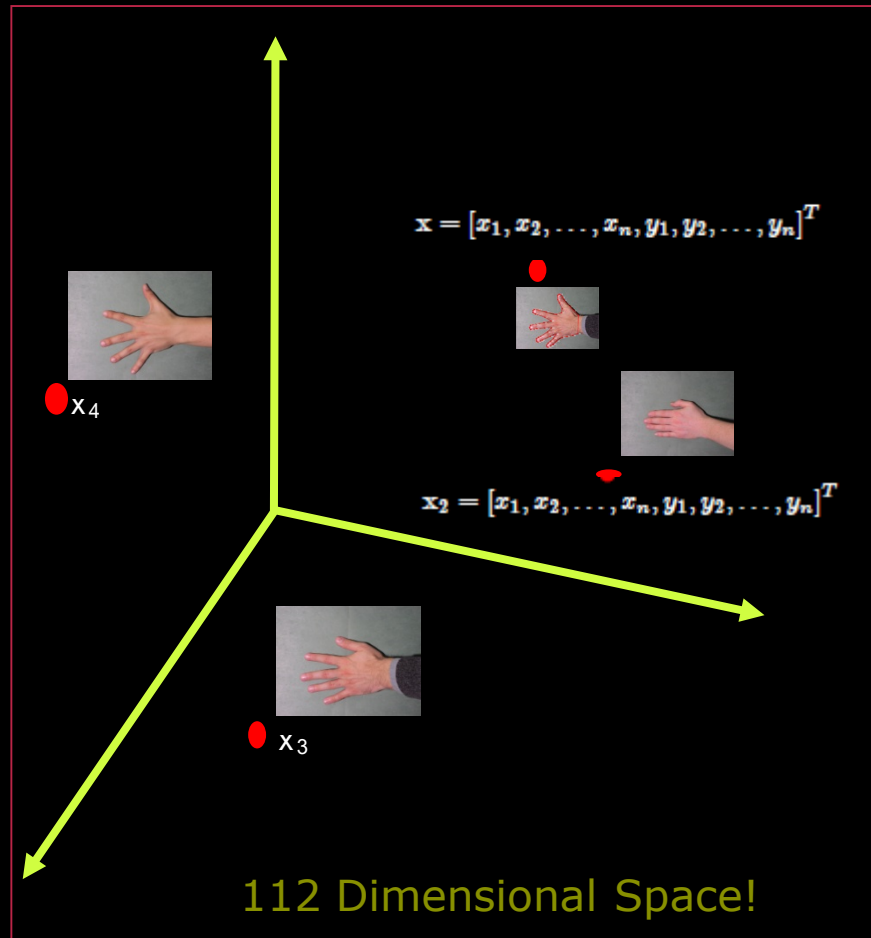
Trick number  
two!

# Coordinates in space



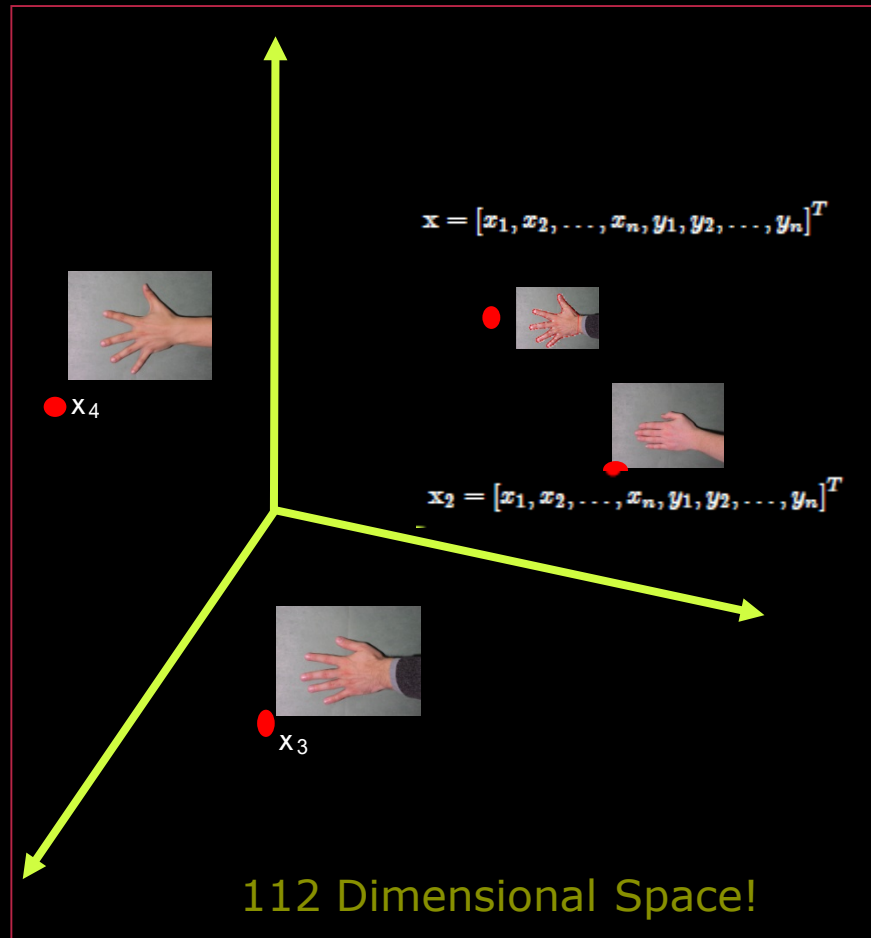
- On hand is now described using one vector
- A vector can also be seen as a coordinate in space!
- Not 2D space, not 3D space, not 4D space...
- 112 Dimensional Space!
- A hand has a position in this space!

# Hands in Space



- A hand has a position in space!
- Another hand appears
  - in the same space
  - different position = different shape
- All hands have a place in this space!

# Shape Analysis

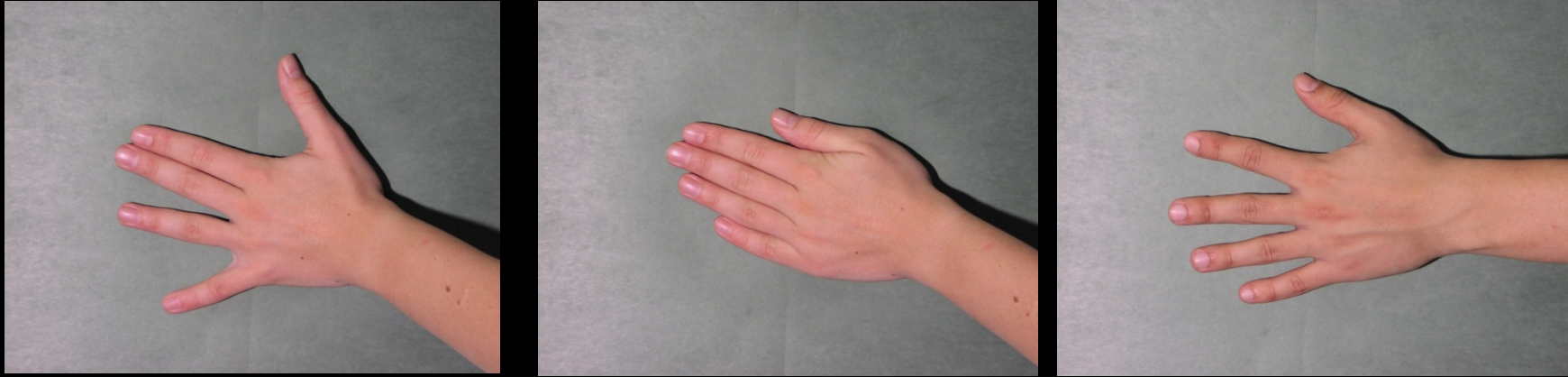


## ■ Shape analysis

- Similar shapes are placed on “planes” in the shape-space
- Also called a manifold

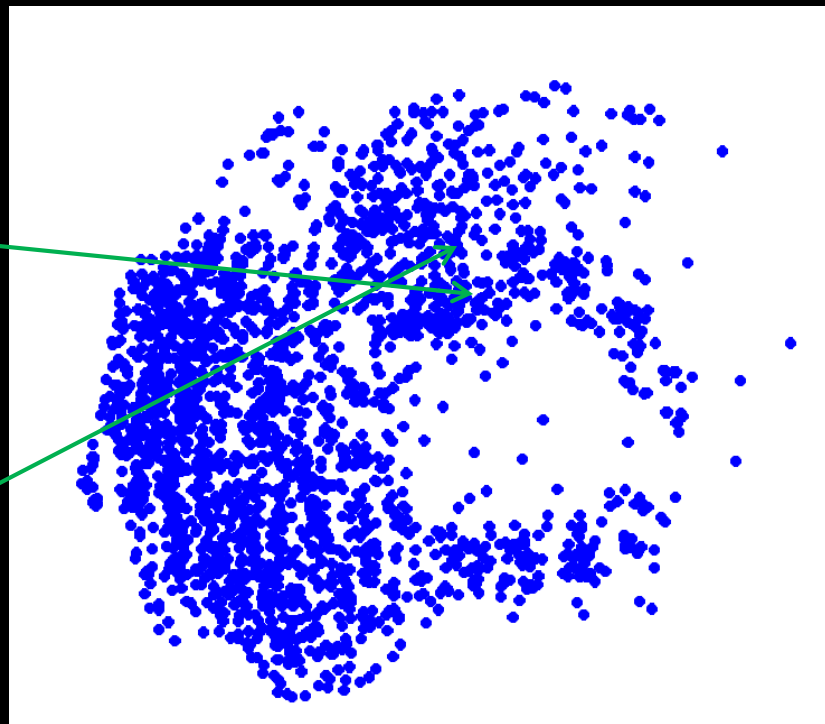
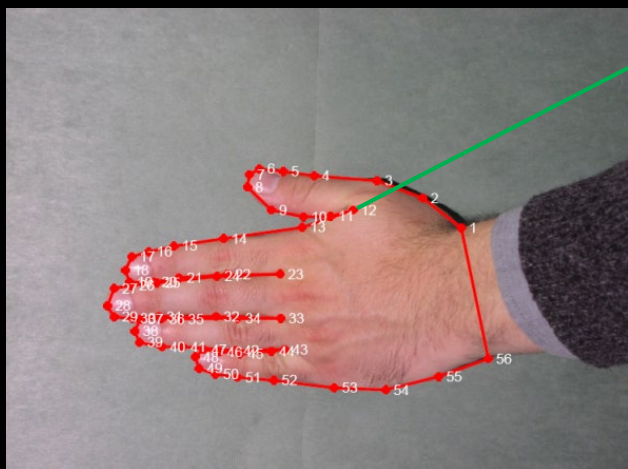
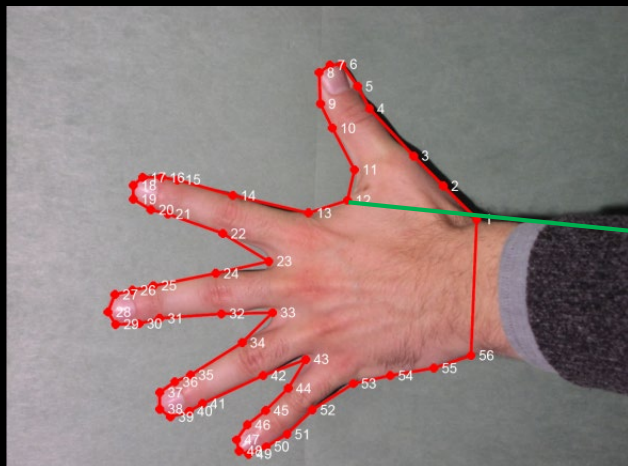


# Shape alignment



- 40 training images of hands
- 56 landmarks on each
- Placed in random location (translation+rotation)

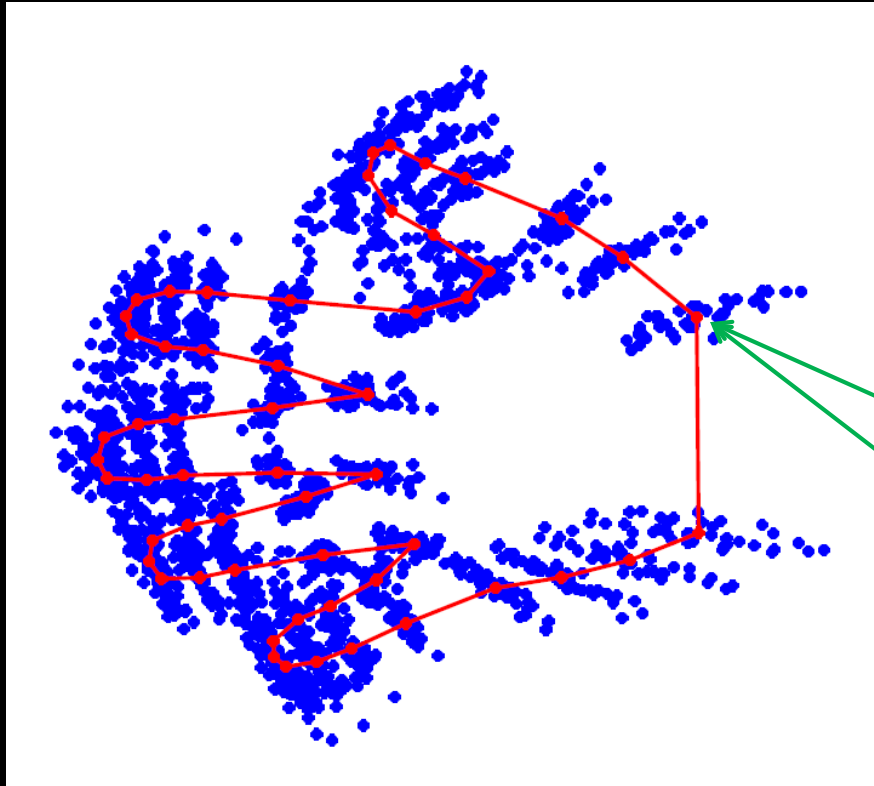
# Shape alignment



Landmarks from all hands

Needs alignment!

# What is alignment?



Average shape

## ■ Group wise registration

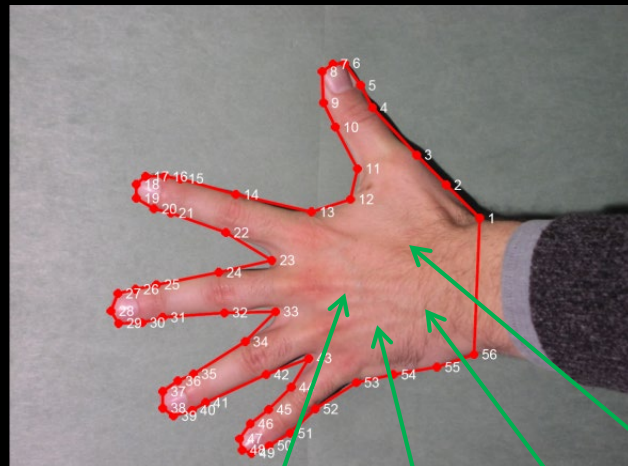
- Not one-to-one
- All to the average shape

$$\bar{\mathbf{x}} = \frac{1}{N} \sum_{i=1}^N \mathbf{x}_i$$

$$\bar{\mathbf{x}} = [\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n, \bar{y}_1, \bar{y}_2, \dots, \bar{y}_n]^T$$

But hey! We do not have an average shape?

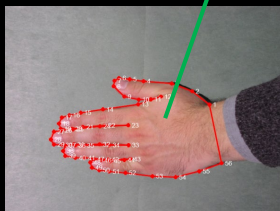
# Procrustes Analysis (alignment)



"Average shape"

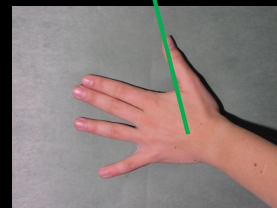
- We start by defining
  - Average shape = Shape #1
- Align shape #2 to shape #1
- Align all shapes to shape #1

Registration

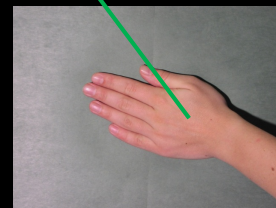


Shape #2

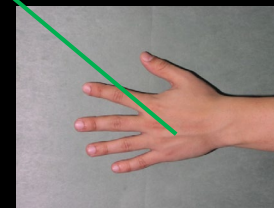
Registration



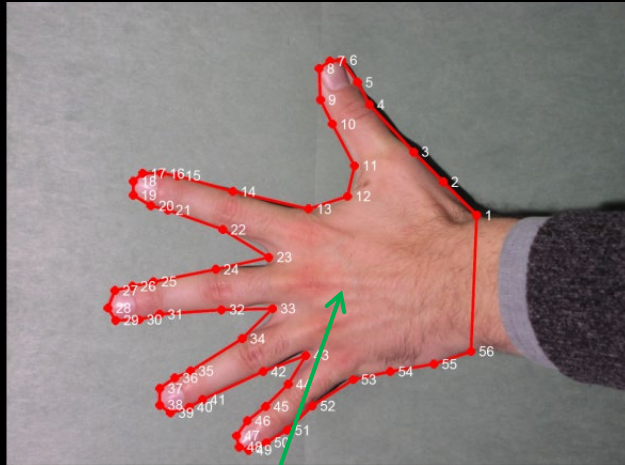
Registration



Registration

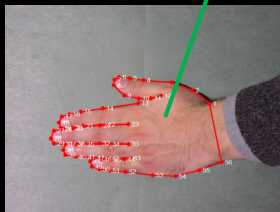


# Landmark based registration



"Average shape"

Registration



Shape #2

- Shape #2 is transformed to fit the average shape

- Translation
- Rotation
- Scaling
- = Similarity Transform

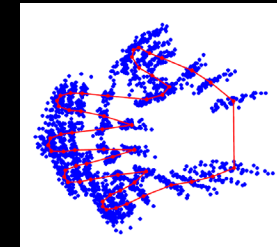
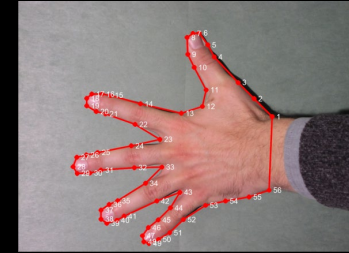
- Result

- Shape #2 is placed *on top of* the average shape



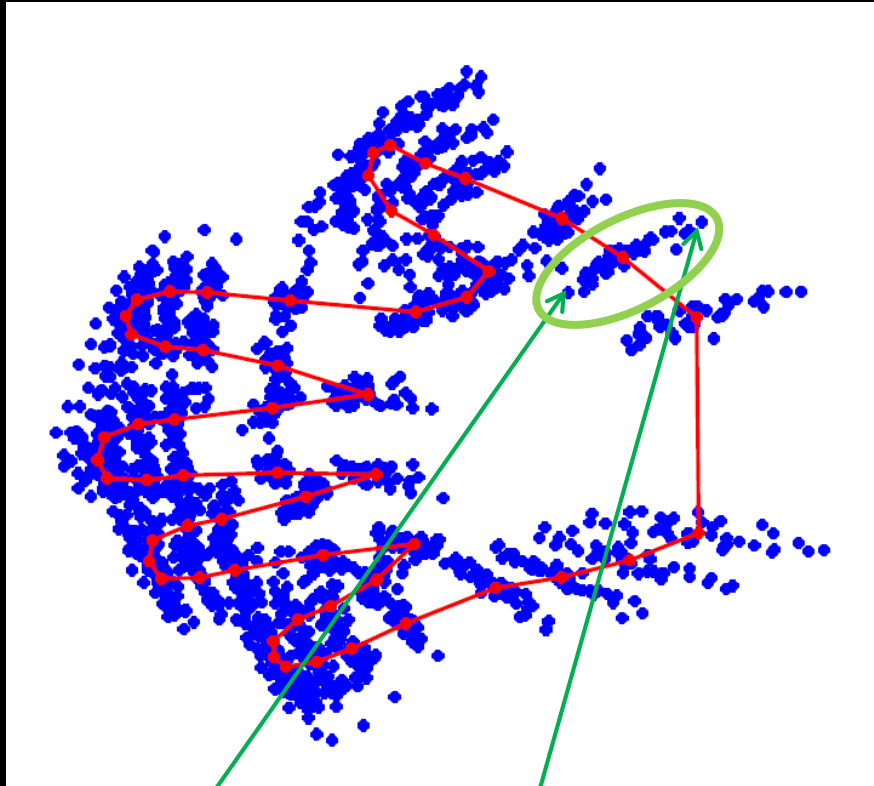
## Procrustes Analysis

1. Average shape is set to shape #1
2. Register all shapes to the average shape
  - Landmark based registration
3. Recompute the average shape
4. If average shape changed return to step 2.



$$\bar{\mathbf{x}} = \frac{1}{N} \sum_{i=1}^N \mathbf{x}_i$$

## Aligned shapes – what now

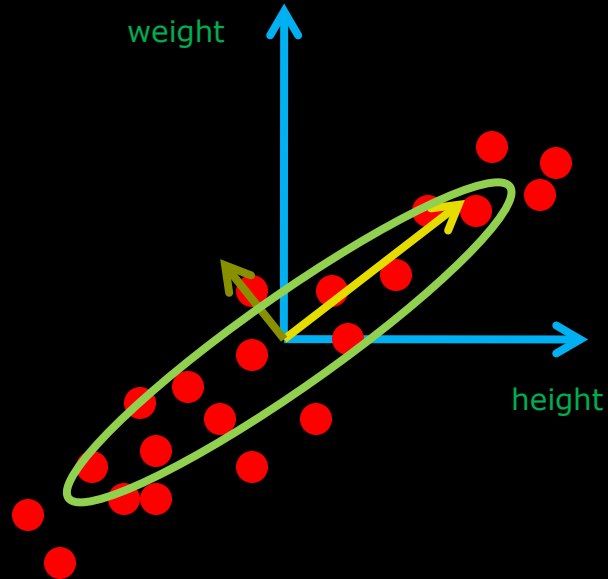


Shape #16

Shape #27

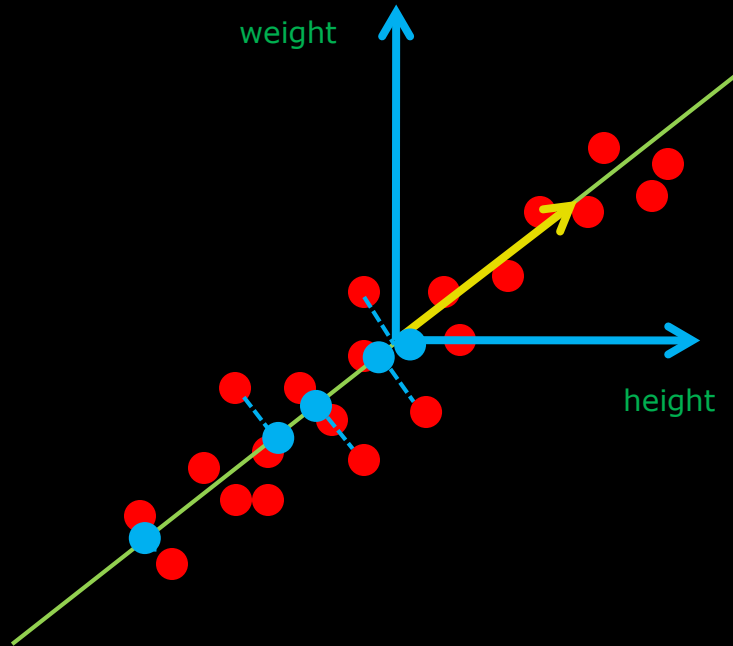
- Individual landmark variation
  - Over the training set
- What shape is the variation?

# Principal Component Analysis (PCA)



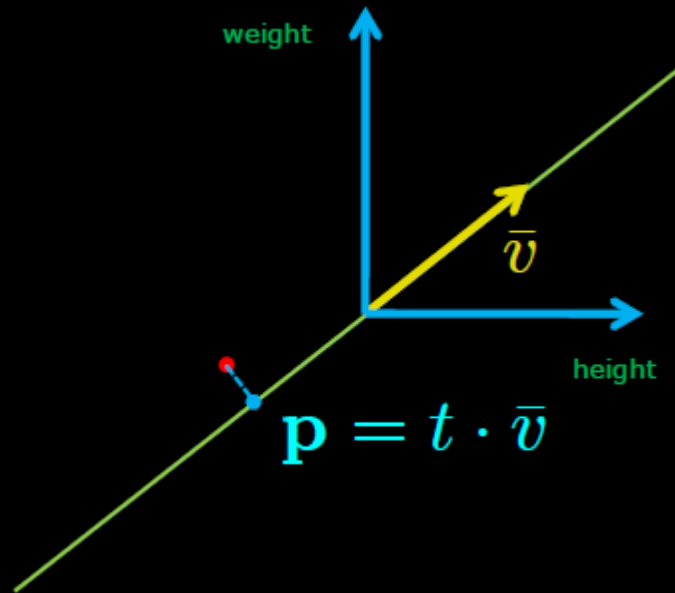
- PCA
  - Main axis in data
  - Eigenvectors
  - Eigenvalues
- Size of Eigenvalues describe explained variance

# Principal Component Analysis (PCA)



- We throw away the *noise dimensions*
- Points projected to the line

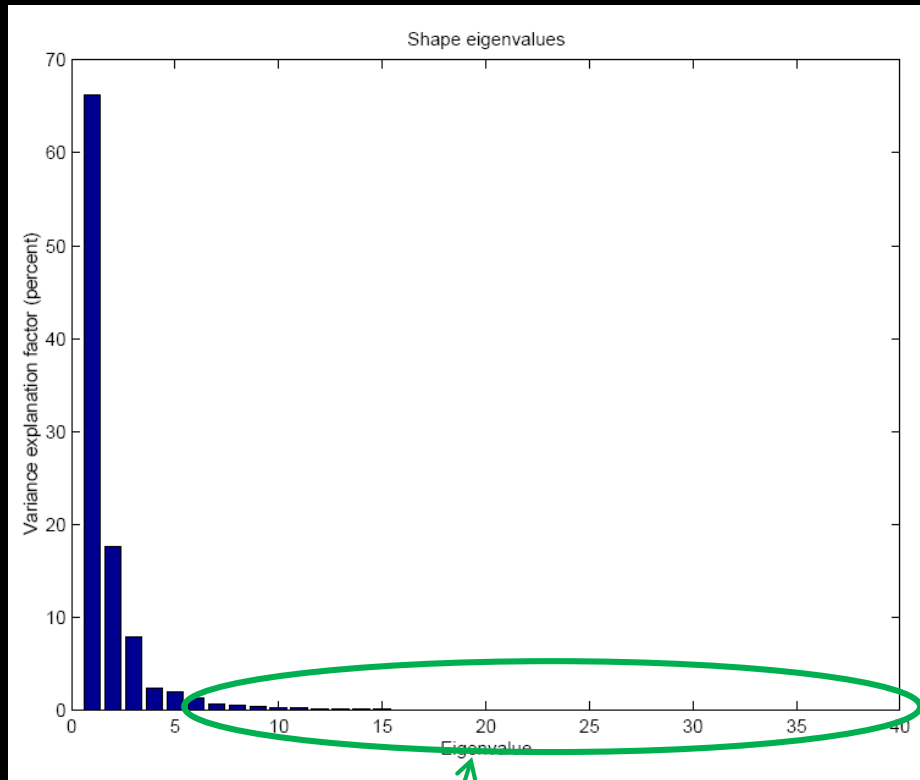
# Principal Component Analysis (PCA)



- We throw away the *noise dimensions*
- Points projected to the line
- A point can now be described by one parameter  $t$
- We have reduced the number of dimensions

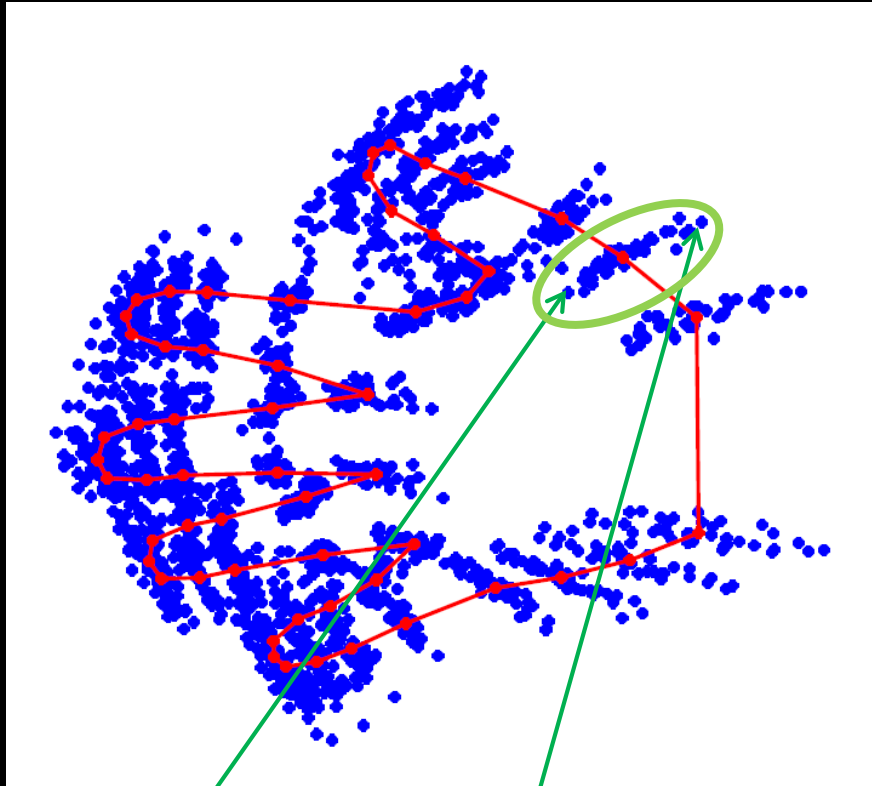


# How many dimensions should we keep?



- Plot the Eigenvalues
- Explains how *important* each dimension is
- Cut away noise dimensions

## Aligned shapes – what now

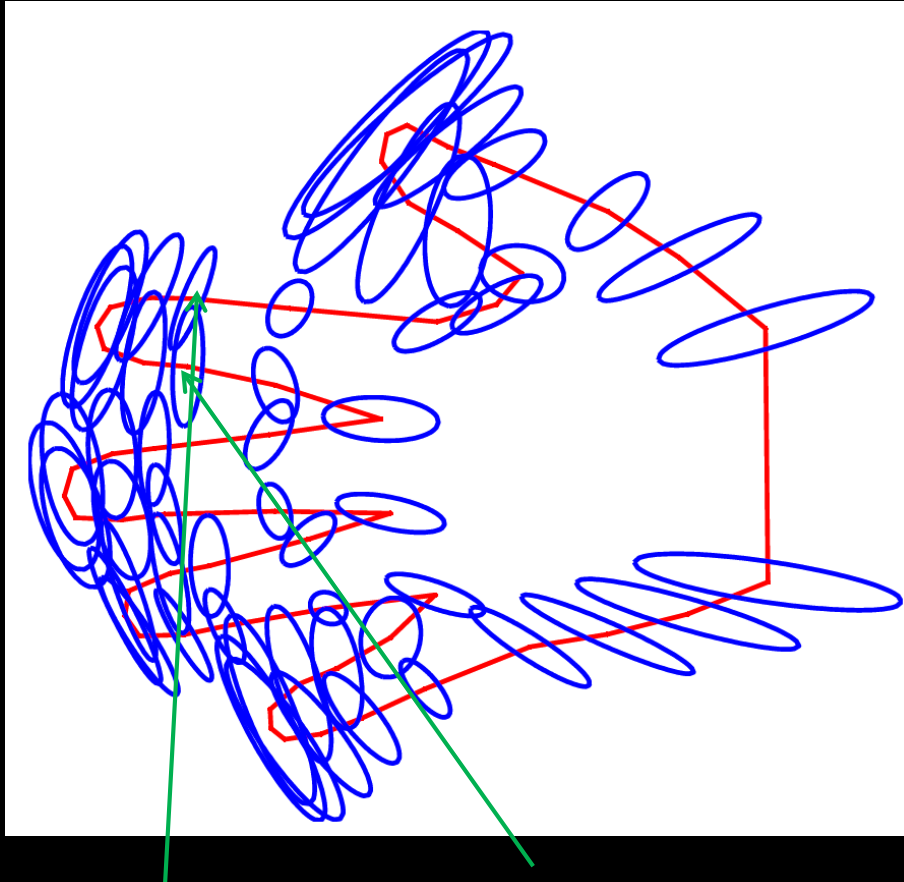


Shape #16

Shape #27

- Individual landmark variation
  - Over the training set
- What shape is the variation?

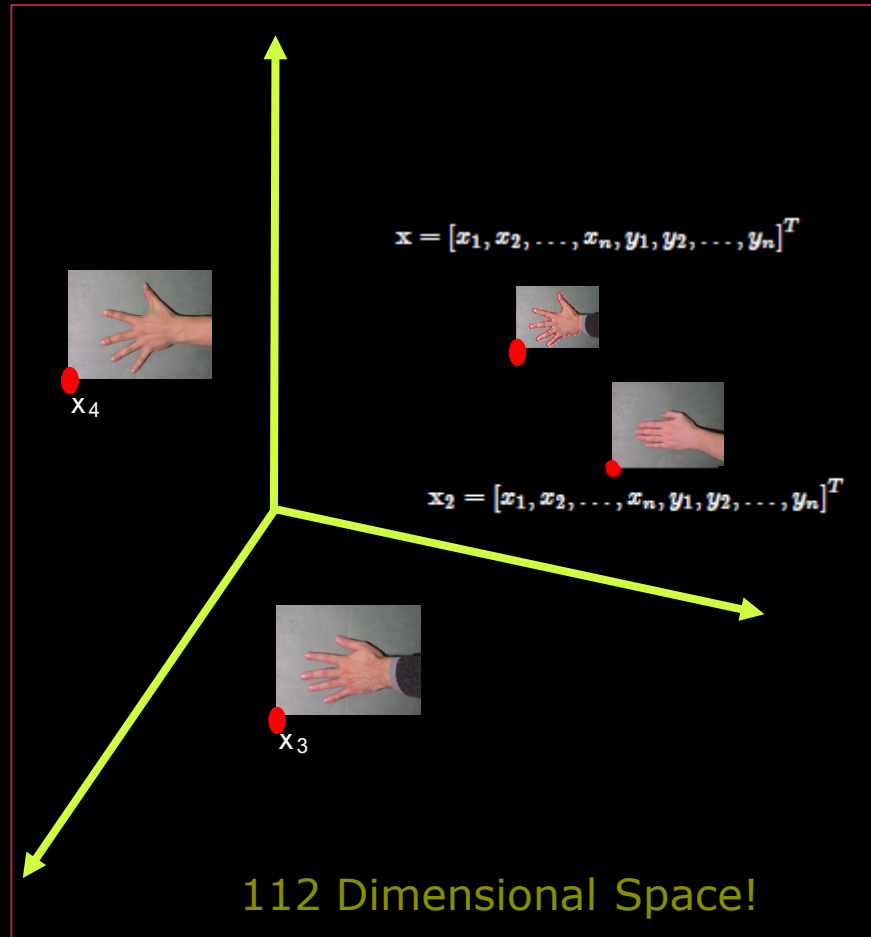
## PCA Analysis



Landmark #14    Landmark #22

- PCA analysis on individual landmarks
- Describes the major direction of variation
- Landmarks are correlated!
- The movement over the shape is connected
- Return to shape space

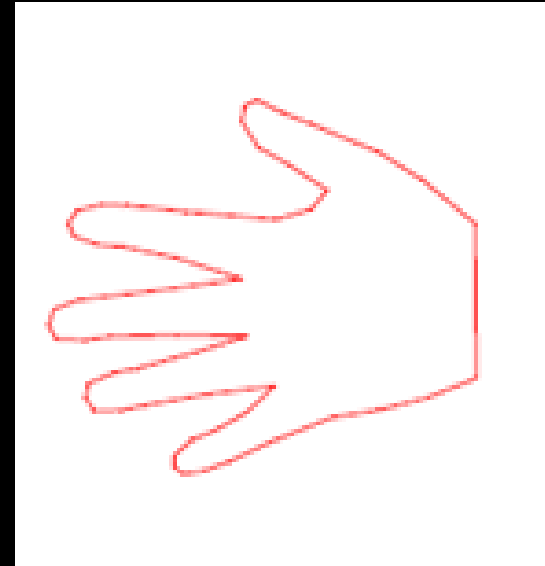
# PCA in shape space



- Instead of doing PCA on 2D points we do it on 112D points
- Examine if our 40 *shapes is lying on a plane* in 112D space
- We find the directions that spans the maximum variation in shape space

# Start by computing the shape average

$$\bar{\mathbf{x}} = \frac{1}{s} \sum_{i=1}^s \mathbf{x}_i$$



## Do the eigenvector analysis

$$S = \frac{1}{s-1} \sum_{i=1}^s (\mathbf{x}_i - \bar{\mathbf{x}})(\mathbf{x}_i - \bar{\mathbf{x}})^T$$

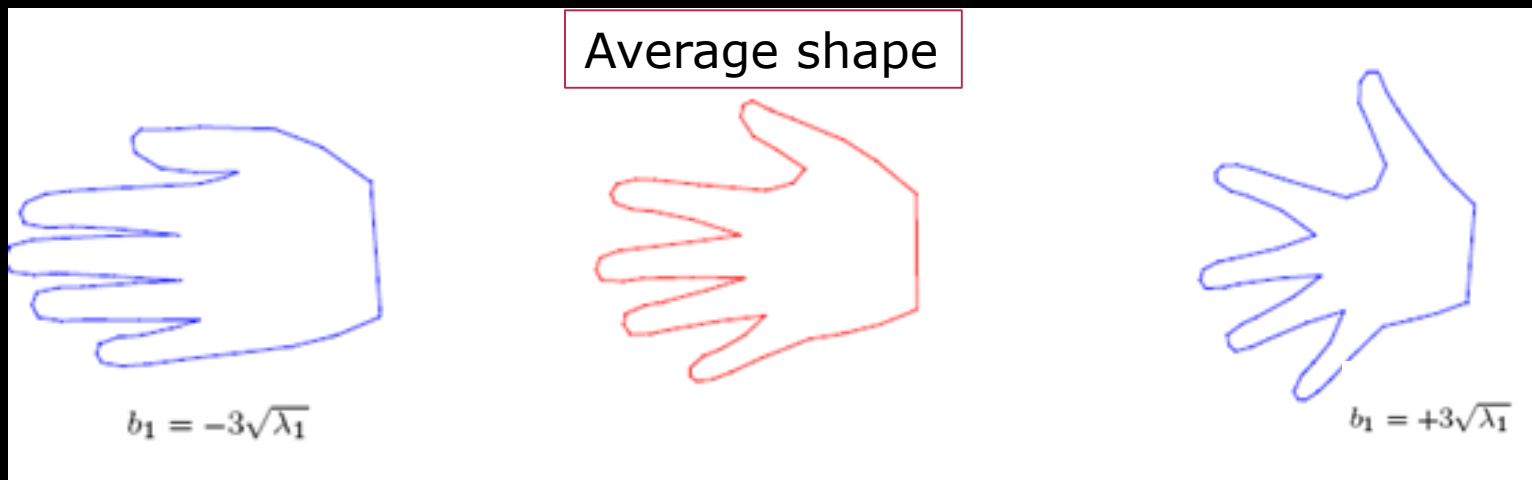
- Computing the covariance of the shape data



Average shape

Shape number  $i$  in the training set

# Visualizing variation

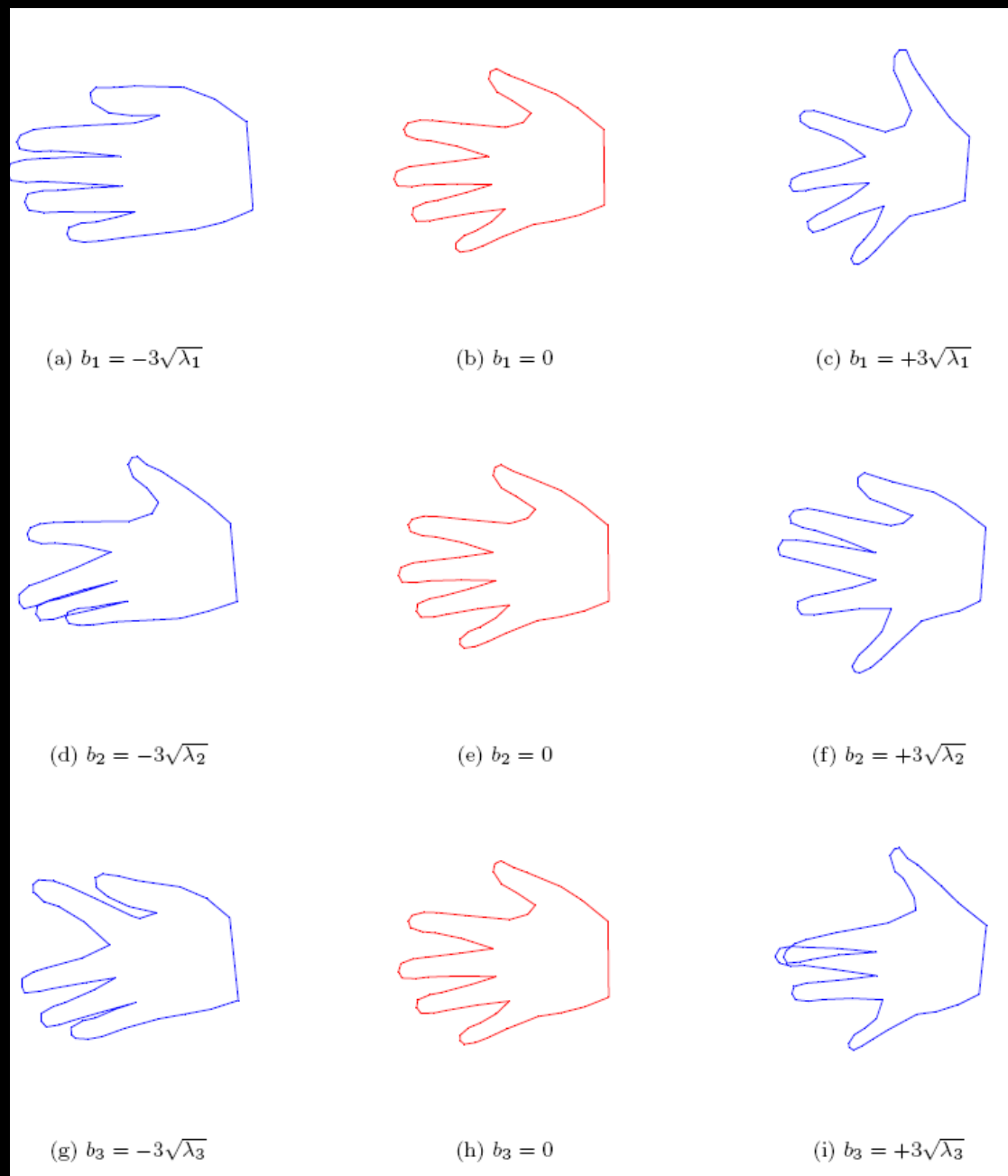


Visualizing the first principal component

$$\mathbf{x} \approx \bar{\mathbf{x}} + \Phi \mathbf{b}$$

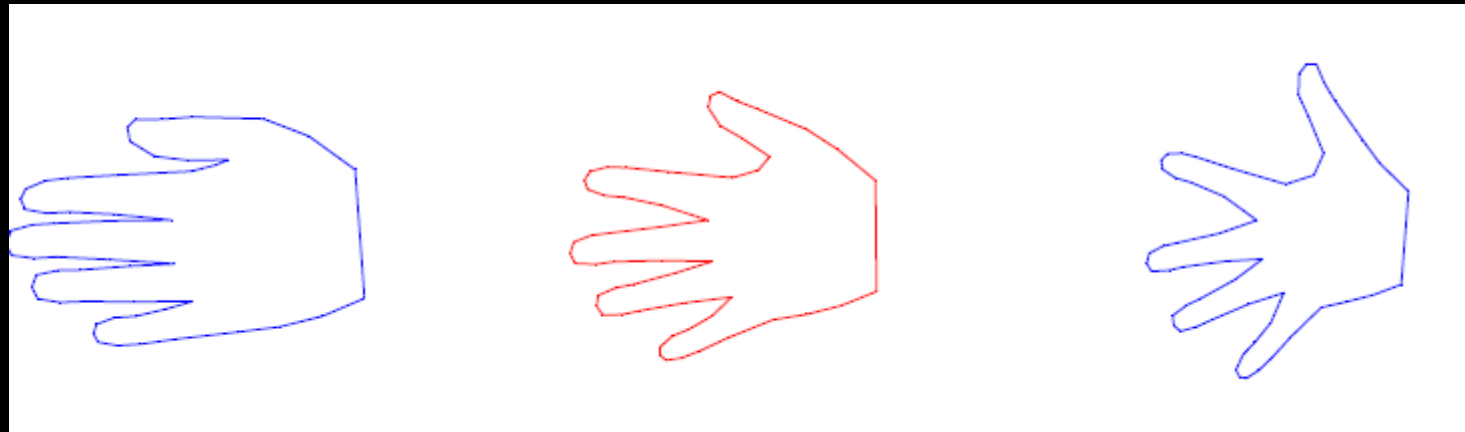
$\Phi$  contains the  $t$  eigenvectors





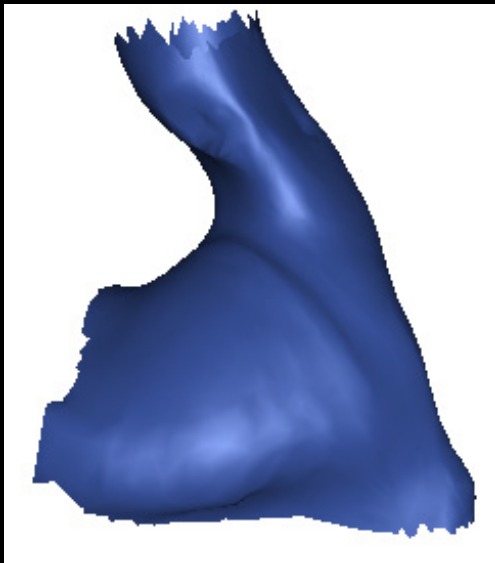
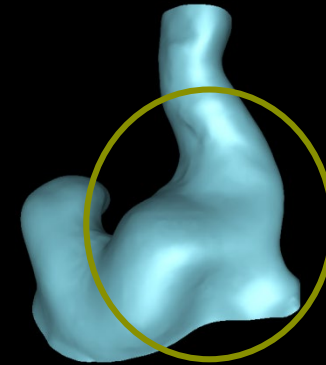
## Results of Shape Analysis

- Visualisation of the major variation of the shape over a population

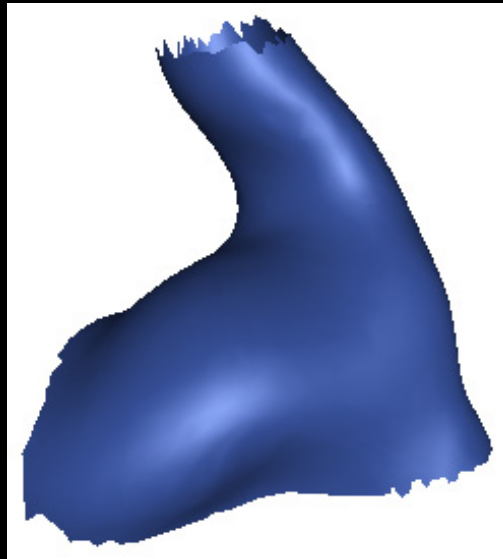


# Hearing Aid Design

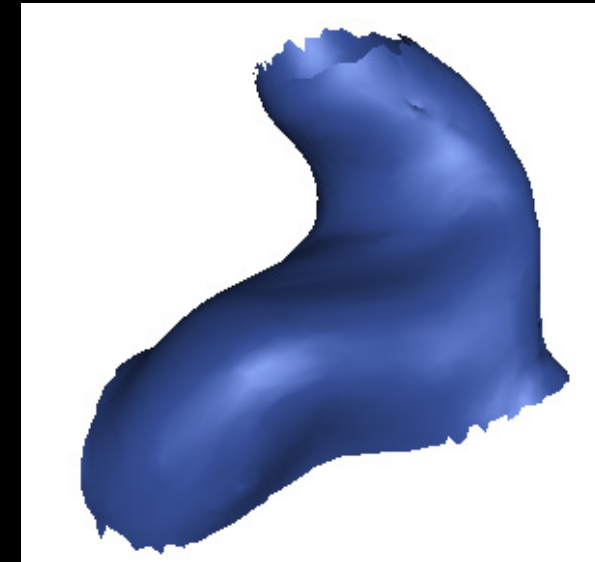
- Main variation of the shape of the ear canal
- Found using principal component analysis
- First mode of variation
- 7 modes explain 95% of the total variation



Average-1. mode



Average



Average+1. mode

## Modelling shape and appearance

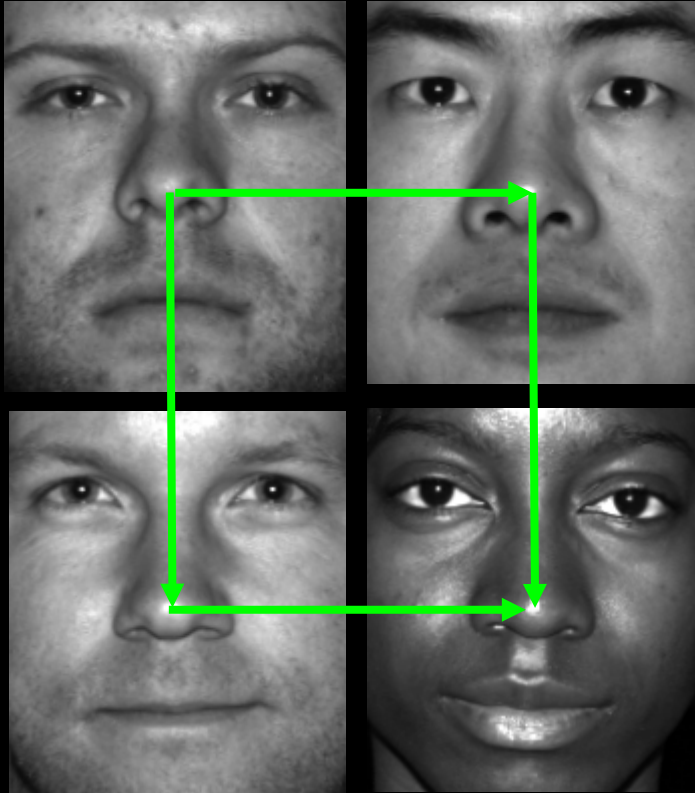
- A model that can both model the shape of an object and the appearance (the texture)
- **Texture:** The pattern of intensities (or colors) across an image patch





## Back to lecture 3: Eigenfaces

## Face data



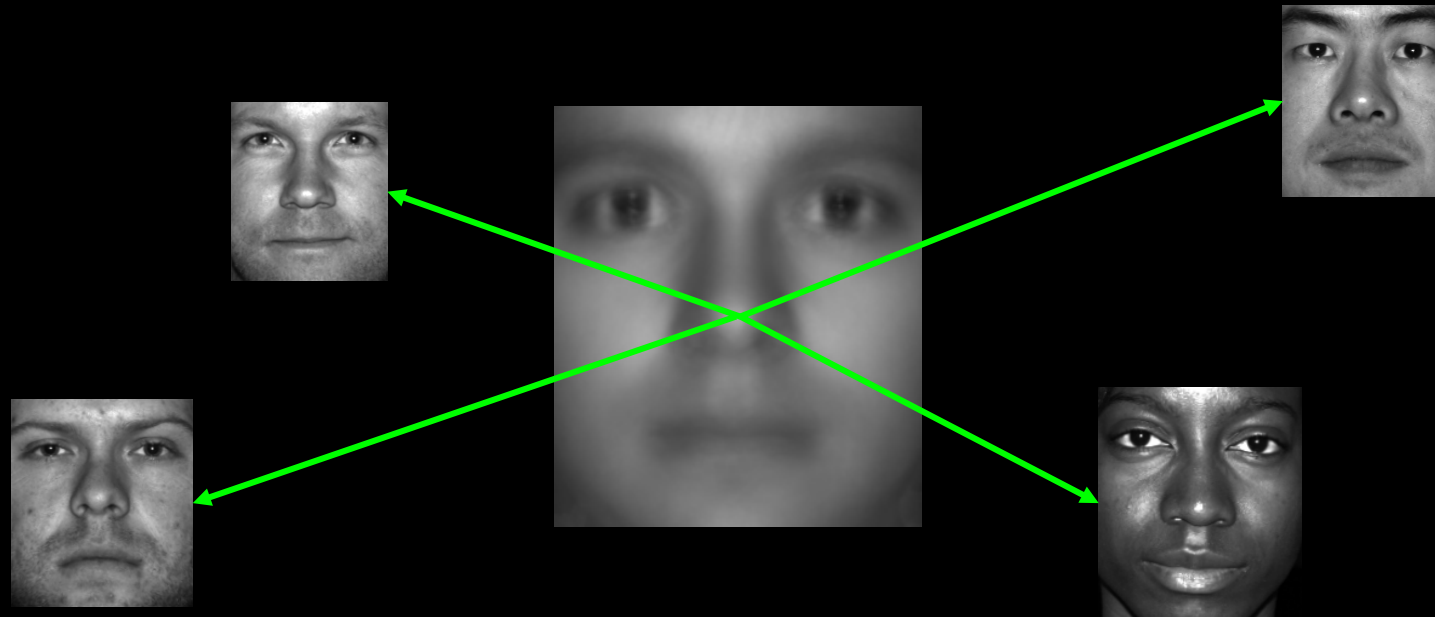
- 38 face images
  - 168 x 192 grayscale
- Aligned
  - The anatomy is placed "in the same position in all image"
- Same illumination conditions on the images we use

The Extended Yale Face Database B

<http://vision.ucsd.edu/~leekc/ExtYaleDatabase/ExtYaleB.html>

# Analyzing the deviation from the mean face

- We want to do the principal component analysis on the *deviations from the average face*





# Visualizing the PCA faces

*Main deviations from the average face*



First PC – 40% of variation



Second PC – 8% of variation

A tool to see major variations –  
brow lifting

-PC

Average face

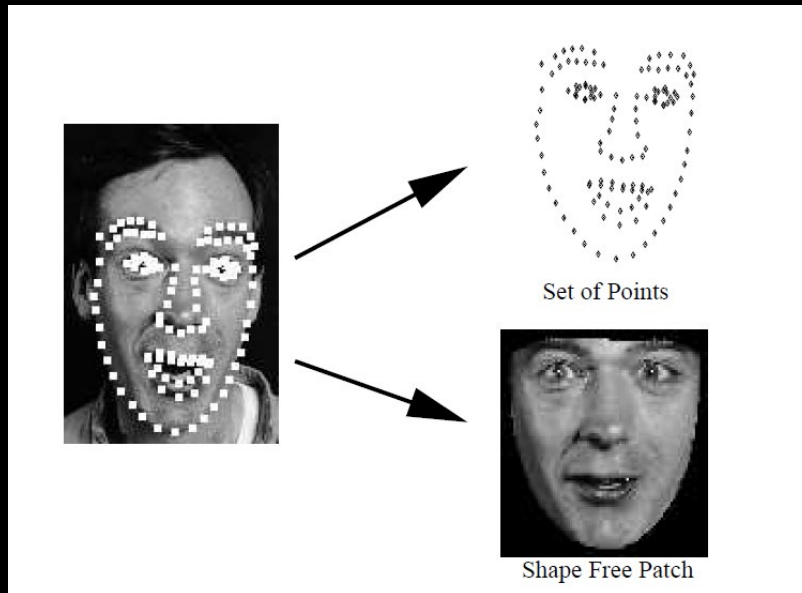
+PC

## Eigenfaces: Modelling texture

- The modelling of the pure appearance
- Without removing variation in shape
- No *decoupling* of shape and appearance

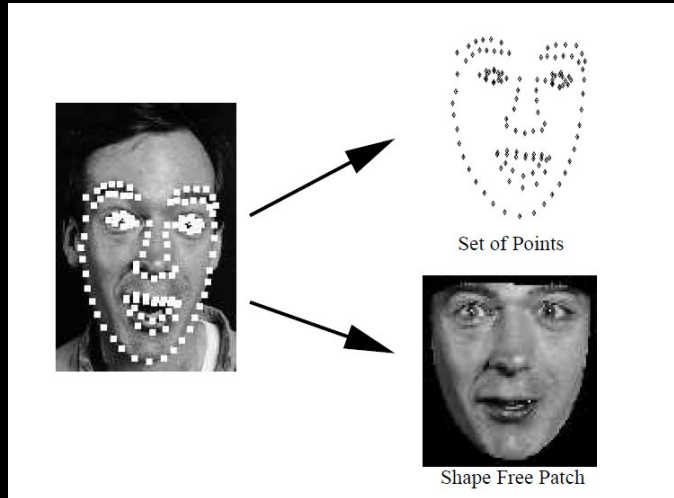


# Decoupling shape and texture



- Warp each face to average shape using the landmarks
- Non-linear geometrical transformation
- Sample the texture from the warped face

# Eigenfaces on warped faces



- Same PCA modelling as in the Eigenfaces approach
- Just slightly different notation



$$\mathbf{g} = \bar{\mathbf{g}} + \mathbf{P}_g \mathbf{b}_g$$

## Combined shape and appearance model

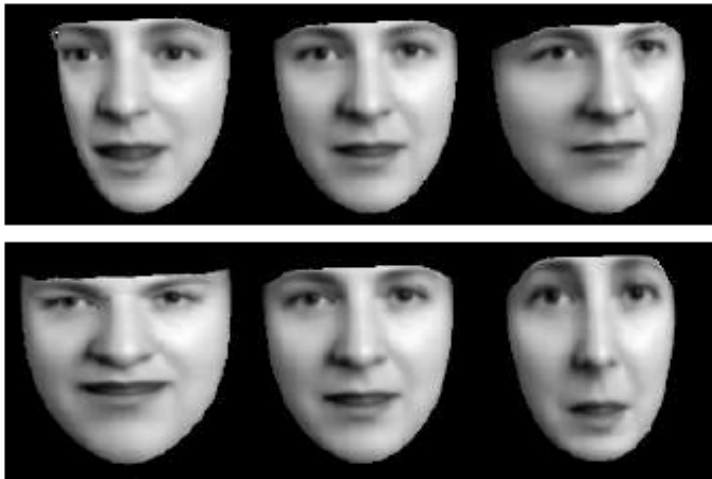


Figure 5.2: First two modes of shape variation ( $\pm 3$  sd)

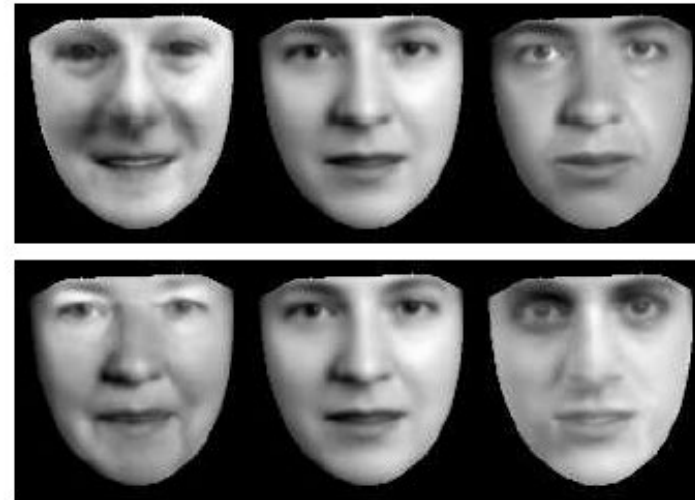


Figure 5.3: First two modes of grey-level variation ( $\pm 3$  sd)



# Facial Analysis

- Demo of AAM explorer