```
ALGORITHM UniqueElements (A[0...n-1])
                  //Determines whether all the elements in a given array are distinct.
                  //Input: An array A[0..n - 1]
                  //Output: Returns "true" if all the elements in A are distinct.
                  // and "false" otherwise.
                  for i \leftarrow 0 to n - 2 do
                      for j \leftarrow i + 1 to n - 1 do
                           if A[i] = A[j] return false
def unique_element(arr):
     for i in range(0, len(arr)-2):
          for j in range(i+1, len(arr)):
               if arr[i] == arr[j]:
                    return False
     return True
               ALGORITHM Binary (n)
               //Input: A positive decimal integer n
               //Output: The number of binary digits in n's binary representation
               count ← 1
               while n > 1 do
                    count \leftarrow count + 1
                    n \leftarrow \lfloor n/2 \rfloor
               return count
def binary(n):
     count = 1
     while n > 1:
          count += 1
          n /= 2
```

return count

```
ALGORITHM BinRec(n)

//Input: A positive decimal integer n

//Output: The number of binary digits in n's binary representation

if n = 1 return 1

else return BinRec([n/2]) + 1

def binary_rec(n):
    if n == 1: return 1

return binary_rec(n//2) + 1
```

```
def merge(my_list, aux, lo, mid, hi):
       # copy items from my_list to aux list
        aux[lo:hi+1] = my_list[lo:hi+1]
        i = lo
        j = mid + 1
        for k in range(lo, hi+1):
            if i > mid: # i cross mid, copy from j half
                my_list[k] = aux[j]
                j += 1
            elif j > hi: # j cross hi, copy from i half
                my_list[k] = aux[i]
                i += 1
            elif aux[j] < aux[i]:</pre>
                my_list[k] = aux[j]
                j += 1
            else:
                my_list[k] = aux[i]
                i+= 1
```

```
def merge_sort(my_list, aux, lo, hi):
    if hi <= lo: return

mid = (hi + lo) // 2

divide(my_list, aux, lo, mid)  # first half lo --> mid
    divide(my_list, aux, mid + 1, hi)  # second half mid+1 --> hi

merge(my_list, aux, lo, mid, hi)  # sort lo --> hi
```

```
def swap(numbers, i, j):
     temp = numbers[i]
     numbers[i] = numbers[j]
     numbers[j] = temp
                      \textbf{ALGORITHM Quicksort} \ (A[l\mathinner{\ldotp\ldotp} r])
                      //Sorts a subarray by quicksort.
                      //Input: Subarray of array A[0..n - 1], defined by its left and right
                      // indices l and r.
                      //Output: Subarray A[l..r] sorted in nondecreasing order.
                      if l < r
                          s \leftarrow Partition(A[l..r])
                                                 //s is a split position.
                          Quicksort(A[l..s - 1])
                          Quicksort(A[s + 1..r])
def quick_sort(numbers, lo, hi):
     if lo < hi:</pre>
          # choose partition type
           s = partition(numbers, lo, hi)
          quick_sort(numbers, lo, s - 1)
           quick_sort(numbers, s + 1, hi)
           return numbers
```

```
ALGORITHM LomutoPartition (A[l..r])
                  //Partitions subarray by Lomuto's algorithm using first element as pivot.
                  //Input: A subarray A[l..r] of array A[0..n - 1], defined by its left and
                   right indices l and r (l \le r).
                  //Output: Partition of A[l..r] and the new position of the pivot.
                  p \leftarrow A[l]
                  s \leftarrow l
                  for i \leftarrow l + 1 to r do
                     if A[i] < p
                       s \leftarrow s + 1
                       Swap (A[s], A[i])
                  Swap (A[l], A[s])
                  return s
11 11 11
Partitions subarray by Lomuto's algorithm using first element as pivot.
Output: Partition of numbers and the new position of the pivot.
def lomuto_partition(numbers, lo, hi):
     pivot = numbers[lo]
     s = 1o
     for i in range(lo+1, hi):
          # If current element is smaller than or equal to pivot
          if numbers[i] <= pivot:</pre>
               # increment index of smaller element
               s += 1
               swap(numbers, s, i)
     swap(numbers, lo, s)
```

return s

```
ALGORITHM HoarePartition (A[l..r])
                //Partitions subarray by Hoare's algorithm using first element as pivot.
                //Input: A subarray A[l..r] of array A[0..n - 1], defined by its left and
                 right indices l and r (l \leq r).
                //Output: Partition of A[l..r], with the split position returned as this
                 function's value.
                p \leftarrow A[l]
                i \leftarrow l; j \leftarrow r + 1
                repeat
                     repeat i \leftarrow i + 1 until A[i] \ge p
                     repeat j \leftarrow j - 1 until A[j] \leq p
                     swap(A[i], A[j])
                until i \geq j
               swap(A[i], A[j])
                                           //undo last swap when i \geq j
                swap(A[l], A[j])
                return j
Partitions subarray by Hoare's algorithm using first element as pivot.
Output: Partition of numbers with the split position returned as this
function's value
.....
def hoare_partition(numbers, lo, hi):
     p = numbers[lo]
     i = lo+1
     j = hi
     while i < j:
          while numbers[i] < p:
               i += 1
          while numbers[j] > p:
               j -= 1
          swap(numbers, i, j)
     swap(numbers, i, j)
     swap(numbers, lo, j)
```

return j

```
ALGORITHM Prim(G)

// Prim's algorithm for constructing a minimum spanning tree.

// Input: A weighted connected graph G = (V, E).

// Output: E_T, the set of edges composing a minimum spanning tree of G.

V_T \leftarrow \{v_0\} //the set of tree vertices can be initialized with any vertex.

E_T \leftarrow \emptyset

for i \leftarrow 1 to |V| - 1 do

find a minimum-weight edge e^* = (v^*, u^*) among all the edges (v, u) such that v is in V_T and u is in V - V_T.

V_T \leftarrow V_T \cup \{u^*\}

E_T \leftarrow E_T \cup \{e^*\}

return E_T

from collections import defaultdict

import heapq
```

```
import heapq
def prims(graph, s):
    mst = defaultdict(set)
    visited = set([s])
    edges = [
        (cost, s, w)
        for w, cost in graph[s]
    heapq.heapify(edges)
    while edges:
        cost, v, w = heapq.heappop(edges)
        if w not in visited and w in graph:
            visited.add(w)
            mst[v].add(w)
            for adj, cost in graph[w]:
                if adj not in visited:
                    heapq.heappush(edges, (cost, w, adj))
    return mst
graph = {
 'A': {('C', 31)},
 'B': {('C', 15)},
 'C': {('G', 77), ('H', 40)},
 'E': {('C', 17), ('I', 3)},
 'G': {('B', 22), ('E', 23)},
 'H': {('G', 66)},
 'I': {('J', 70), ('K', 31)},
print(prims(graph, 'A'))
```

```
ALGORITHM Dijkstra (G, s)
                                //Dijkstra's algorithm for single-source shortest paths.
                                //Input: A weighted connected graph G = (V, E) with nonnegative
                                   weights and its vertex s.
                                //Output: The length d_v of a shortest path from s to v and its penultimate
                                  vertex p_v for every vertex v in V.
                                Initialize (Q)
                                                                   //initialize priority queue to empty.
                                for every vertex v in V do
                                     d_v \leftarrow \infty; p_v \leftarrow null
                                     Insert (Q, v, d_v) //initialize vertex priority in the priority queue.
                                d_s \leftarrow 0; Decrease (Q, s, d_s) //update priority of s with d_s.
                                V_T \leftarrow \emptyset
                                for i \leftarrow 0 to |V| - 1 do
                                     u^* \leftarrow \text{DeleteMin}(Q)
                                                                //delete the minimum priority element.
                                     V_T \leftarrow V_T \cup \{u^*\}
                                     for every vertex u in V - V_T that is adjacent to u * do
                                         if d_{u^*} + w(u^*, u) < d_u do
                                            d_u \leftarrow d_{u^*} + w(u^*, u); p_u \leftarrow u^*
                                            Decrease (Q, u, d_u)
# Time-Complexity O(E log V)
```

```
from queue import PriorityQueue
def dijkstra(graph, s):
    seen = set()
    cost = {s: 0}
    parent_path = {s: None}
    pq = PriorityQueue()
    pq.put((0, s))
    while not pq.empty():
        _, v = pq.get()
        seen.add(v)
        for w, distance in graph[v]:
            if w in seen: continue
            old_cost = cost.get(w, float('inf'))
            new_cost = cost[v] + distance
            if new_cost < old_cost:</pre>
                pq.put((new_cost, w))
                cost[w] = new cost
                parent_path[w] = v
    return parent_path
```

```
G = {
  'A': {('C', 31)},
  'B': {('C', 15), ('J', 58)},
  'C': {('C', 60), ('G', 77), ('H', 40)},
  'E': {('C', 17), ('E', 55), ('I', 3)},
  'G': {('B', 22), ('E', 23), ('G', 31)},
  'H': {('G', 66)},
  'I': {('J', 70), ('K', 31)},
  'J': {('H', 8), ('K', 28)},
  'K': {('I', 13)}
}

parent_path = dijkstra(G, 'A')
```