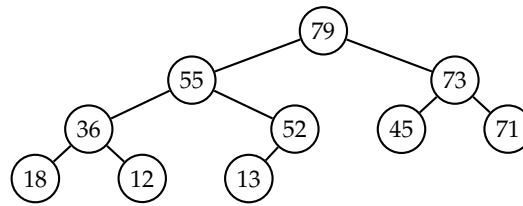


Proposed solution to problem 1

(a) The resulting max-heap is:



(b) To prove that $P \subseteq \text{co-NP}$ we only need to see that if L is a problem from class P , then its complement \bar{L} belongs to NP . But if L is from P then there is a deterministic polynomial algorithm A that decides L . Let us consider now the algorithm \bar{A} that does the same as A , but returns 1 when A returns 0, and returns 0 when A returns 1. Then \bar{A} decides \bar{L} , and since \bar{A} takes polynomial time, we have $\bar{L} \in P \subseteq \text{NP}$.

(c) The cost $C(n)$ of f in function of n follows the recurrence

$$C(n) = 3C(n/3) + \Theta(1)$$

as there are 3 recursive calls on subvectors of size $n/3$ and additionally operations of constant cost are performed. By the Master Theorem of Divisive Recurrences, the solution to the recurrence is $C(n) = \Theta(n)$.

(d) It is not true. For example, $n^{2n} = (n^n)^2$ grows asymptotically faster than n^n .

Proposed solution to problem 2

We must use a dictionary with integer keys implemented with a hash table, and a vector which is initially empty that will contain the intersection.

First of all we pass over A and add all its elements to the dictionary. We make n insertions to the dictionary, each of which takes time $O(1)$ on average. So the first pass costs $O(n)$ on average.

In the second place we pass over B and, for each of its elements, we check if it already belongs to the dictionary. If so, the element is added to the vector of the intersection with a *push_back*. Otherwise nothing is done. Hence we make m lookups to the dictionary, each of which takes time $O(1)$ on average. Since each *push_back* takes constant time, the cost of the second pass is $O(m)$ on average.

In total, the cost is $O(n + m)$ on average.

Proposed solution to problem 3

(a) The filled table is:

level :	A	B	C	D	E	F	G	H	depth :	4
	0	1	1	1	4	2	0	3		

(b) The filled table is:

	(1)	(2)	(3)	(4)
TRUE		X	X	
FALSE	X			X

(c) A possible solution:

```

vector<int> levels(const vector<vector<int>>& G) {
    int n = G.size ();
    vector<int> lvl(n, -1), pred(n, 0);

    for (int u = 0; u < n; ++u)
        for (int v : G[u])
            ++pred[v];

    queue<int> Q;
    for (int u = 0; u < n; ++u)
        if (pred[u] == 0) {
            Q.push(u);
            lvl[u] = 0;
        }

    while (not Q.empty()) {
        int u = Q.front (); Q.pop();
        for (int v : G[u]) {
            --pred[v];
            lvl[v] = max(lvl[v], lvl[u]+1);
            if (pred[v] == 0) Q.push(v);
        }
    }
    return lvl;
}

```

The construction of the vectors has cost $\Theta(n)$. The first loop has cost $\Theta(n + m)$. The second loop has cost $\Theta(n)$. The third loop has cost $\Theta(n + m)$. In total the cost is $\Theta(n + m)$.

Proposed solution to problem 4

```

void write(const vector<int>& p, int n) {
    for (int k = 0; k < n; ++k) cout << " " << p[k];
    cout << endl;
}

void generate(int k, int n, vector<int>& p, vector<bool>& used) {
    if (k == n) write(p, n);
    else {

```

```

        for (int i = 0; i < n; ++i)
            if (not used[i] and k ≠ i) {
                used[i] = true;
                p[k] = i;
                generate(k+1, n, p, used);
                used[i] = false;
            }
    }
};

void generate_all (int n) {
    vector<int> p(n);
    vector<bool> used(n, false);
    generate(0, n, p, used);
}

```