

Proposed solution to problem 1

- (a) (0.25 pts.) A graph with n vertices has $O(n^2)$ edges.
- (b) (0.25 pts.) A connected graph with n vertices has $\Omega(n)$ edges.
- (c) (0.25 pts.) A complete graph with n vertices has $\Omega(n^2)$ edges.
- (d) (0.25 pts.) A min-heap with n vertices has $\Theta(n)$ leaves.
- (e) (0.25 pts.) A binary search tree with n vertices has height $\Omega(\log n)$.
- (f) (0.25 pts.) A binary search tree with n vertices has height $O(n)$.
- (g) (0.25 pts.) An AVL tree with n vertices has height $\Omega(\log n)$.
- (h) (0.25 pts.) An AVL tree with n vertices has height $O(\log n)$.

Proposed solution to problem 2

- (a) Breadth-first search.
- (b) Dijkstra's algorithm.
- (c) Bellman-Ford's algorithm.
- (d) There cannot be any cycle with negative weight in the graph.
- (e) By induction over the number of arcs of the path.
 - **Base case:** If the path has not arc, the source vertex u is the same as the target vertex v . So in this case we have that $\omega_\pi(c) = \omega(c) = 0$. Since $\omega(c) - \pi(u) + \pi(v) = 0$, what we wanted to prove holds.
 - **Inductive case:** Assume that the path has k arcs, that is, is of the form (u_0, u_1, \dots, u_k) , where $u_0 = u$ and $u_k = v$. As u_1, \dots, u_k is a path from u_1 to u_k with $k - 1$ arcs, we can apply the induction hypothesis. So $\omega_\pi(u_1, \dots, u_k) = \omega(u_1, \dots, u_k) - \pi(u_1) + \pi(u_k)$. But

$$\begin{aligned}
 \omega_\pi(u_0, \dots, u_k) &= \omega_\pi(u_0, u_1) + \omega_\pi(u_1, \dots, u_k) \\
 &= \omega_\pi(u_0, u_1) + \omega(u_1, \dots, u_k) - \pi(u_1) + \pi(u_k) \\
 &= \omega(u_0, u_1) - \pi(u_0) + \pi(u_1) + \omega(u_1, \dots, u_k) - \pi(u_1) + \pi(u_k) \\
 &= \omega(u_0, u_1) - \pi(u_0) + \omega(u_1, \dots, u_k) + \pi(u_k) \\
 &= \omega(u_0, \dots, u_k) - \pi(u_0) + \pi(u_k)
 \end{aligned}$$

- (f) If π is a potential, then the reduced weights ω_π are non-negative. So we can apply Dijkstra's algorithm to compute the distances with weights ω_π from s to all vertices. Then we can compute the distances with weights ω using the following observation: if $u, v \in V$ and c is the minimum path with weights ω from u to v (which exists by hypothesis), then c is the minimum path with weights ω_π from u to v and $\omega(c) = \omega_\pi(c) + \pi(u) - \pi(v)$.

Proposed solution to problem 3

- (a) If M is an $n \times n$ matrix, function *matrix_mystery*(**const** *matrix*& M) computes $M^{\sum_{i=1}^n i}$, or equivalently, $M^{\frac{n(n+1)}{2}}$.
- (b) The product of two matrices $n \times n$, which is computed by function *aux*, takes $\Theta(n^3)$ time. Since $\Theta(n)$ iterations are performed, and in each of them two matrix products are computed with cost $\Theta(n^3)$, in total the cost is $\Theta(n^4)$.
- (c) A possible solution:

```

matrix exp(const matrix&  $M$ , int  $k$ ) {
    if ( $k == 1$ ) return  $M$ ;
    matrix  $P = \text{exp}(M, k/2)$ ;
    if ( $k \% 2 == 0$ ) return aux( $P, P$ );
    else return aux(aux( $P, P$ ),  $M$ );
}

matrix mystery(const matrix&  $M$ ) {
    int  $n = M.\text{size}()$ ;
    return exp( $M, n*(n+1)/2$ );
}

```

Fast exponentiation makes $\Theta(\log(n(n+1)/2)) = \Theta(\log(n))$ matrix products, each of which takes $\Theta(n^3)$ time. In total, the cost is $\Theta(n^3 \log n)$.

Proposed solution to problem 4

- (a) The witness is p .
- (b) The code of the verifier is between lines 4 and 16.
- (c) A possible solution:

```

bool ham2_rec(const vector<vector<int>>&  $G$ , int  $k$ , int  $u$ , vector<int>& next) {
    int  $n = G.\text{size}()$ ;
    if ( $k == n$ )
        return find( $G[u].\text{begin}()$ ,  $G[u].\text{end}()$ , 0)  $\neq G[u].\text{end}()$ ;

    for (int  $v : G[u]$ )
        if (next[ $v$ ] == -1) {
            next[ $u$ ] =  $v$ ;
            if (ham2_rec( $G, k+1, v, \text{next}$ )) return true;
            next[ $u$ ] = -1;
        }
    return false;
}

bool ham2(const vector<vector<int>>&  $G$ ) {

```

```

int n = G.size ();
vector<int> next(n, -1);
return ham2_rec(G, 1, 0, next);
}

```

(d) One can replace the call

```

return find (G[u].begin (), G[u].end (), 0)  $\neq$  G[u].end();

```

by

```

return not G[u].empty() and G[u][0] == 0;

```

(e) If G is not connected then it cannot be Hamiltonian. In this case the function only needs to return **false**.