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<pre>#!/bin/python3.6 #Ostop Voynarovskiy #CGML HW1 #Sept 12 2018 import numpy as np import tensorflow as tf import matplotlib.pyplot as plt import matplotlib.mlab as mlab from tqdm import tqdm NUM_PHIS = 7 BATCH_SIZE = 32 NUM_BATCHES = 400 class Data(object): def __init__(self): num_samp = 50 sigma = .1 np.random.seed(31415) # We're going to learn these paramters #creates your training data self.index = np.arange(num_samp) self.x = np.random.uniform(size=(num_samp, 1)) # random uniform distribution self.eps = sigma*np.random.normal(size=(num_samp,1)) self.y = np.sin(self.x*2*np.pi) + self.eps # sin wave plus noise def get_batch(self): choices = np.random.choice(self.index, size=BATCH_SIZE) return self.x[choices].flatten(), self.y[choices].flatten() def f(x): #these are the initializations of the things we will learn w = tf.get_variable('w', [NUM_PHIS, 1], tf.float32,tf.random_normal_initializer()) b = tf.get_variable('b', [], tf.float32, tf.zeros_initializer()) mu = tf.get_variable('mu', [NUM_PHIS, 1], tf.float32, tf.random_uniform_initializer()) sig = tf.get_variable('sig', [NUM_PHIS, 1], tf.float32,tf.random_normal_initializer()) phi = tf.exp(-tf.pow((x-mu)/sig, 2)) return tf.squeeze(tf.matmul(tf.transpose(w), phi) + b) x = tf.placeholder(tf.float32, [BATCH_SIZE]) y = tf.placeholder(tf.float32, [BATCH_SIZE]) y_hat = f(x) loss = tf.reduce_mean(tf.pow(y-y_hat, 2)/2) #loss funtion optim = tf.train.GradientDescentOptimizer(learning_rate=0.1).minimize(loss) #this does gradient descent init = tf.global_variables_initializer() sess = tf.Session() sess.run(init) data = Data() for _ in tqdm(range(0, NUM_BATCHES)): x_np, y_np = data.get_batch() loss_np, _ = sess.run([loss, optim], feed_dict={x: x_np, y: y_np}) prms = {} print ("Parameter estimates:")</pre>		

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<pre>for var in tf.get_collection(tf.GraphKeys.TRAINABLE_VARIABLES): name = var.name.rstrip(":0") value = np.array(sess.run(var)).flatten() prms[name] = value print(name, np.array_str(value, precision=3)) def rbf(x, mu, sig): return np.exp(-np.power((x-mu)/sig,2)) def genManifold(prms, x): return np.sum([w * rbf(x, mu, sig) for mu, sig, w in zip(prms['mu'], prms['sig'], prms['w'])], 0)+prms['b'] #figure 1 fig1= plt.figure(1) #plot sin wave NumPoints = 1000 x_v = np.linspace(0, 1, NumPoints) y_v = np.sin(2*np.pi*x_v) plt.plot(x_v, y_v) #plot our noisy training data points x_p = data.x y_p = data.y plt.plot(x_p, y_p, 'o') #plot our sum of gaussians curve AKA manifold yplot = genManifold(prms, x_v) plt.plot(x_v, yplot, 'r--') plt.title("Best Fit") plt.xlabel('x') plt.ylabel('y') fig2 = plt.figure(2) #loop to plot all phis for i in range(NUM_PHIS): sd= 3 x_b = np.linspace(prms['mu'][i] - sd*prms['sig'][i], prms['mu'][i] + sd*prms['sig'][i], NumPoints) # plot 3 standard devs from the mean plt.plot(x_b, rbf(x_b, prms['mu'][i], prms['sig'][i])) plt.title("Bases") plt.xlabel('x') plt.ylabel('y') plt.xlim(-0.1,1) plt.ylim(-.1,1.2) fig1.savefig('fig1.pdf', bbox_inches= 'tight') fig2.savefig('fig2.pdf', bbox_inches= 'tight') plt.show()</pre>		