

Near-Optimal Model Discrimination

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- General problem formulation
- Linear models
- Extensions

General problem

Model discrimination task

- Let $z \in \mathcal{Z}$ be a random observation distributed according to \mathbb{P}_0 or \mathbb{P}_1 .
- Let $\theta_0, \theta_1 \in \mathbb{R}^d$ be the **best-fit models** of z according to $\mathbb{P}_0, \mathbb{P}_1$, i.e.

$$\theta_k = \operatorname{argmin}_{\theta \in \mathbb{R}^d} \{ L_k(\theta) := \mathbb{E}_{z \sim \mathbb{P}_k} \ell(\theta, z) \},$$

with strictly convex loss $\ell(\cdot, z) : \mathbb{R}^d \rightarrow \mathbb{R}$, population risks $L_0(\cdot), L_1(\cdot)$.

- **Statistician** has access to $\theta^* \in \{\theta_0, \theta_1\}$ (but **not** to $\bar{\theta} \in \{\theta_0, \theta_1\} \setminus \theta^*$), knows $\ell(\cdot, z)$, and observes **two** i.i.d. samples:

$$Z^0 = (z_1^0, \dots, z_n^0) \sim \mathbb{P}_0^{\otimes n}, \quad Z^1 = (z_1^1, \dots, z_n^1) \sim \mathbb{P}_1^{\otimes n}.$$

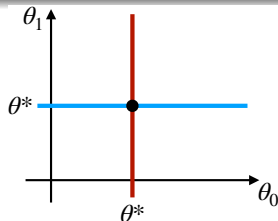
- **Task:** distinguish between the two hypotheses

$$\mathcal{H}_0 : \{\theta^* = \theta_0\}, \quad \mathcal{H}_1 : \{\theta^* = \theta_1\}.$$

Model discrimination task

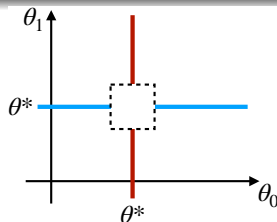
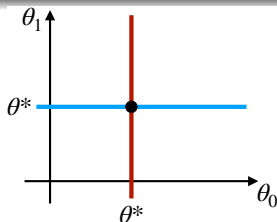
- **Classical setup:** both θ_0, θ_1 known; one sample $Z \sim \mathbb{P}_\theta^{\otimes n}$ observed.
Which $\theta \in \{\theta_0, \theta_1\}$ corresponds to the sample?
*Two **simple** hypotheses about θ .*
- **Our setup:** we observe both samples but only one model $\theta^* \in \{\theta_0, \theta_1\}$.
Which $Z \in \{Z^0, Z^1\}$ corresponds to θ^ ?*
*Two **composite** hypotheses about (θ_0, θ_1) .*
- **Statistician** has access to $\theta^* \in \{\theta_0, \theta_1\}$ (but **not** to $\bar{\theta} \in \{\theta_0, \theta_1\} \setminus \theta^*$), knows $\ell(\cdot, z)$, and observes **two** i.i.d. samples:
$$Z^0 = (z_1^0, \dots, z_n^0) \sim \mathbb{P}_0^{\otimes n}, \quad Z^1 = (z_1^1, \dots, z_n^1) \sim \mathbb{P}_1^{\otimes n}.$$
- **Task:** distinguish between the two hypotheses about $(\theta_0, \theta_1) \in \mathbb{R}^{2d}$:
$$\mathcal{H}_0 : (\theta_0, \theta_1) \in \{\theta^*\} \times \{\theta \neq \theta^*\} \quad \text{vs.} \quad \mathcal{H}_1 : (\theta_0, \theta_1) \in \{\theta \neq \theta^*\} \times \{\theta^*\}$$

Separation and sample complexity



$$\mathcal{H}_0 : (\theta_0, \theta_1) \in \{\theta^*\} \times \{\theta \neq \theta^*\} \quad \text{vs.} \quad \mathcal{H}_1 : (\theta_0, \theta_1) \in \{\theta \neq \theta^*\} \times \{\theta^*\}$$

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- **Separate** θ_0 and θ_1 to exclude the degenerate case $\theta_0 = \theta_1 = \theta^*$.

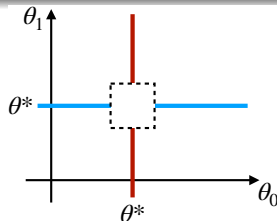
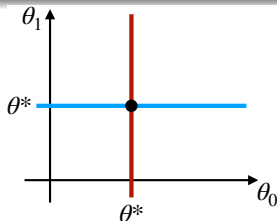
$$\mathcal{H}_0 : (\theta_0, \theta_1) \in \{\theta^*\} \times \bar{\Theta}_0 \quad \text{vs.} \quad \mathcal{H}_1 : (\theta_0, \theta_1) \in \bar{\Theta}_1 \times \{\theta^*\}$$

- “Prediction-wise” separation:

$$\Delta_0 := L_0(\theta_1) - L_0(\theta_0) > 0, \quad \Delta_1 := L_1(\theta_0) - L_1(\theta_1) > 0.$$

- Implicitly choose $\bar{\Theta}_0, \bar{\Theta}_1$ according to this separation assumption.

Separation and sample complexity



$$\mathcal{H}_0 : (\theta_0, \theta_1) \in \{\theta^*\} \times \{\theta \neq \theta^*\} \quad \text{vs.} \quad \mathcal{H}_1 : (\theta_0, \theta_1) \in \{\theta \neq \theta^*\} \times \{\theta^*\}$$

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- “Prediction-wise” separation:

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- Implicitly choose $\bar{\Theta}_0, \bar{\Theta}_1$ according to this separation assumption.

Characterize the **sample complexity** of distinguishing between \mathcal{H}_0 and \mathcal{H}_1 with fixed error probabilities of both types (say $2/3$) in terms of Δ_0, Δ_1, d .

Well-specified linear models

Well-specified linear model: $z = (x, y) \in \mathbb{R}^{d+1}$, $\ell(\theta, z) = \frac{1}{2}(x^\top \theta - y)^2$, and

$\mathbb{P}_k : x \sim \mathcal{N}(0, \Sigma_k)$, $y = x^\top \theta_k + \xi$ with $\xi \sim \mathcal{N}(0, 1)$ for $k \in \{0, 1\}$.

- Write $Z_k = (X_k; Y_k)$, where $X_k \in \mathbb{R}^{n \times d}$ and $Y_k \in \mathbb{R}^n$ for $k \in \{0, 1\}$.
- Covariances Σ_k and their estimates: $\hat{\Sigma}_k := \frac{1}{n} X_k^\top X_k$.
- Population and empirical ranks: $r_k = \text{rank}(\Sigma_k)$ and $\hat{r}_k = \text{rank}(\hat{\Sigma}_k)$.
- Separations and their empirical counterparts:

$$\Delta_k = \frac{1}{2} \|\theta_1 - \theta_0\|_{\Sigma_k}^2 = \frac{1}{2} \|\Sigma_k^{1/2}(\theta_1 - \theta_0)\|^2,$$
$$\hat{\Delta}_k = \frac{1}{2} \|\theta_1 - \theta_0\|_{\hat{\Sigma}_k}^2 = \frac{1}{2n} \|X_k(\theta_1 - \theta_0)\|^2.$$

Basic test based on the prediction error of θ^* under \mathcal{H}_0 and \mathcal{H}_1 :

$$\mathbb{1} \left\{ \|Y_0 - X_0\theta^*\|^2 - n \geq \|Y_1 - X_1\theta^*\|^2 - n \right\}.$$

Let $\xi_k = Y_k - X_k\theta_k \sim \mathcal{N}(0, I_n)$ be the noises. Under $\mathcal{H}_0 : \theta^* = \theta_0$, one has

$$\text{LHS} = \|\xi_0\|^2 - n,$$

$$\text{RHS} = \|\xi_1\|^2 - n - 2 \langle \xi_1, X_1(\theta_0 - \theta_1) \rangle + \|X_1(\theta_1 - \theta_0)\|^2.$$

- Thus, $\mathbb{E}[\text{LHS}] = 0$ and $\mathbb{E}[\text{RHS}|X_1] = \|X_1(\theta_1 - \theta_0)\|^2 = n\hat{\Delta}_1$, where

$$\hat{\Delta}_1 = \frac{1}{n} \|X_1(\theta_0 - \theta_1)\|^2 = \|\theta_0 - \theta_1\|_{\hat{\Sigma}_1}^2$$

is the empirical counterpart of $\Delta_1 = \|\theta_1 - \theta_0\|_{\Sigma_1}^2$.

- This motivates the basic test: type-I error \iff “fluctuations $\geq n\Delta_1$.”

$$\mathbb{1} \{ \|Y_0 - X_0 \theta^*\|^2 - n \geq \|Y_1 - X_1 \theta^*\|^2 - n \}.$$

More precisely, LHS $\sim \chi_n^2 - n$ and $\text{RHS} | X_1 \sim \chi_n^2 - n + 2\mathcal{N}(0, n\hat{\Delta}_1) + n\hat{\Delta}_1$.

- Basic tail inequalities for Gaussian and χ^2 laws:

$$\mathbb{P}[\mathcal{N}(0, 1) \geq u] \leq \exp(-u^2), \quad \mathbb{P}[|\chi_s^2 - s| \geq v] \lesssim \exp(-c \min\{v, v^2/s\}).$$

- Bound for the (conditional over X_0, X_1) type-I error:

$$\begin{aligned} \mathbb{P}_I &= \mathbb{P}[\text{fluctuations} \geq n\hat{\Delta}_1] \\ &\leq \mathbb{P}\left[\chi_n^2 - n \geq \frac{n\hat{\Delta}_1}{3}\right] + \mathbb{P}\left[n - \chi_n^2 \geq \frac{n\hat{\Delta}_1}{3}\right] + \mathbb{P}\left[\mathcal{N}(0, n\hat{\Delta}_1) \geq \frac{n\hat{\Delta}_1}{6}\right] \\ &\lesssim \exp\left(-\frac{cn^2\hat{\Delta}_1^2}{n}\right) + \exp(-cn\hat{\Delta}_1). \end{aligned}$$

- Thus, error prob. of both types at most $\exp(-cn \min\{\Delta, \Delta^2\})$, where

$$\Delta := \min\{\Delta_0, \Delta_1\}.$$

If $\Delta \lesssim 1$: term $\exp(-cn\Delta^2)$ dominates $\Rightarrow O(1/\Delta^2)$ sample complexity.

Idea: reduce χ^2 fluctuations by projecting the residuals on signal spaces.

Test for linear model

$$\hat{T} = \mathbb{1} \left\{ \|\Pi_{X_0}[Y_0 - X_0\theta^*]\|^2 - \hat{r}_0 \geq \|\Pi_{X_1}[Y_1 - X_1\theta^*]\|^2 - \hat{r}_1 \right\},$$

where $\Pi_X := X(X^\top X)^\dagger X^\top$ is the projector on signal space $\text{col}(X) \subseteq \mathbb{R}^n$.

- Recall that $\hat{r}_k := \text{rank}(\hat{\Sigma}_k)$ and $\hat{\Sigma} = \frac{1}{n}X^\top X$, hence indeed

$$\dim(\text{col}(X)) = \text{Tr}(\Pi_X) = \text{Tr}[(X^\top X)^\dagger X^\top X] = \text{rank}(X^\top X) = \text{rank}(\hat{\Sigma}).$$

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- For this test, under \mathcal{H}_0 , we have

$$\text{LHS}|X_0 \sim \chi_{\hat{r}_0}^2 - \hat{r}_0, \quad \text{RHS}|X_1 \sim \chi_{\hat{r}_1}^2 - \hat{r}_1 + 2\mathcal{N}(0, n\hat{\Delta}_1) + n\hat{\Delta}_1.$$

- Smaller χ^2 fluctuations since $\hat{r}_k \stackrel{\text{a.s.}}{\leq} \min\{r_k, n\} \leq n$. Type-I error prob.:

$$\begin{aligned} & \mathbb{P} \left[\chi_{\hat{r}_0}^2 - \hat{r}_0 \geq \frac{n\hat{\Delta}_1}{3} \right] + \mathbb{P} \left[\hat{r}_1 - \chi_{\hat{r}_1}^2 \geq \frac{n\hat{\Delta}_1}{3} \right] + \mathbb{P} \left[\mathcal{N}(0, n\hat{\Delta}_1) \geq \frac{n\hat{\Delta}_1}{6} \right] \\ & \lesssim \exp \left(-\frac{cn^2\hat{\Delta}_1^2}{\hat{r}_0} \right) + \exp \left(-\frac{cn^2\hat{\Delta}_1^2}{\hat{r}_1} \right) + \exp(-cn\hat{\Delta}_1). \end{aligned}$$

Theorem. Denoting $r_{\max} := \max\{r_0, r_1\}$, we have

$$\max\{P_I, P_{II}\} \lesssim \exp \left(-c \min \left\{ n\Delta, \frac{n^2\Delta^2}{\min\{n, r_{\max}\}} \right\} \right).$$

Error probability bound

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Sample complexity bound

Lemma Assume $\Delta \lesssim 1$. Then $\log(\max\{P_I, P_{II}\}) \lesssim -1$ is equivalent to

$$n \gtrsim \min\left\{\frac{1}{\Delta^2}, \frac{\sqrt{r_{\max}}}{\Delta}\right\}.$$

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Proof:

1. Prove: $n\Delta \gtrsim \min\left\{\frac{1}{\Delta}, \sqrt{r_{\max}}\right\} \iff n\Delta \min\left\{1, \frac{n\Delta}{\min\{n, r_{\max}\}}\right\} \gtrsim 1$ if $\Delta \lesssim 1$.
2. The second condition reads $n\Delta \gtrsim \max\left\{1, \min\left\{\frac{1}{\Delta}, \frac{r_{\max}}{n\Delta}\right\}\right\}$, or equivalently $n\Delta \gtrsim \min\left\{\frac{1}{\Delta}, \max\left\{1, \frac{r_{\max}}{n\Delta}\right\}\right\}$ by using $\Delta \lesssim 1$ and treating all possible cases.
3. It remains to verify that $n\Delta \gtrsim \sqrt{r_{\max}}$ if and only if $n\Delta \gtrsim \max\left\{1, \frac{r_{\max}}{n\Delta}\right\}$. \square

Basic test

$$\mathbb{1} \left\{ \|Y_0 - X_0 \theta^*\|^2 - n \geq \|Y_1 - X_1 \theta^*\|^2 - n \right\},$$

$$\text{Sample complexity: } n = O\left(\frac{1}{\Delta^2}\right).$$

Improved test

$$\mathbb{1} \left\{ \|\Pi_{X_0}[Y_0 - X_0 \theta^*]\|^2 - \hat{r}_0 \geq \|\Pi_{X_1}[Y_1 - X_1 \theta^*]\|^2 - \hat{r}_1 \right\}.$$

$$\text{Sample complexity: } n = O\left(\min\left\{\frac{1}{\Delta^2}, \frac{\sqrt{r_{\max}}}{\Delta}\right\}\right).$$

Note: $\hat{r}_k \stackrel{\text{a.s.}}{=} \min\{r_k, n\}$ and Π_{X_k} projects on $\text{col}(X_k) \subset \mathbb{R}^n$ of dimension \hat{r}_k . Thus, the tests coincide when $n \leq \min\{r_0, r_1\}$. In fact, a **phase transition**:

- **Well-separated:** $\Delta \gtrsim \frac{1}{\sqrt{r_{\max}}}$. Sample complexity $n = O(1/\Delta^2) \lesssim r_{\max}$.
- **Ill-separated:** $\Delta \ll \frac{1}{\sqrt{r_{\max}}}$. Sample complexity $\gg r_{\max} \Rightarrow$ projections.

Interpretation via least-squares

Recall the normal equations for the least-squares estimates $\hat{\theta}_0, \hat{\theta}_1$ of θ_0, θ_1 :

$$\hat{\Sigma}_0 \hat{\theta}_0 = \frac{1}{n} X_0^\top Y_0, \quad \hat{\Sigma}_1 \hat{\theta}_1 = \frac{1}{n} X_1^\top Y_1.$$

This allows to rewrite the squared norms of the projected residuals:

$$\begin{aligned} \|\Pi_X[Y - X\theta^*]\|^2 &= (Y - X\theta^*)^\top \Pi_X (Y - X\theta^*) \\ &= (X^\top Y - X^\top X\theta^*)^\top (X^\top X)^\dagger (X^\top Y - X^\top X\theta^*) \\ &= n^2 (\hat{\Sigma}(\hat{\theta} - \theta^*))^\top (X^\top X)^\dagger \hat{\Sigma}(\hat{\theta} - \theta^*) \\ &= n(\hat{\theta} - \theta^*)^\top \hat{\Sigma} \hat{\Sigma}^\dagger \hat{\Sigma}(\hat{\theta} - \theta^*) = n(\hat{\theta} - \theta^*)^\top \hat{\Sigma}(\hat{\theta} - \theta^*) \\ &= n \|\hat{\theta} - \theta^*\|_{\hat{\Sigma}}^2. \end{aligned}$$

Thus, our test amounts to $\mathbb{1}\{\|\theta^* - \hat{\theta}_0\|_{\hat{\Sigma}_0}^2 - \frac{\hat{r}_0}{n} \geq \|\theta^* - \hat{\theta}_1\|_{\hat{\Sigma}_1}^2 - \frac{\hat{r}_1}{n}\}$.

- We compare the empirical prediction distances from $\hat{\theta}^*$ to $\hat{\theta}_0$ and $\hat{\theta}_1$ *after debiasing them under the matching hypothesis*.
- **NB:** we don't require $\hat{\theta}_0, \hat{\theta}_1$ to be unique (i.e. $n \geq r_{\max}$).

Sample complexity for improved test: $O\left(\min\left\{\frac{1}{\Delta^2}, \frac{\sqrt{r_{\max}}}{\Delta}\right\}\right) \ll \frac{r_{\max}}{\Delta}$.

- Sample complexity of **estimating** $\bar{\theta} = \theta_0 + \theta_1 - \theta^*$ up to Δ prediction error (i.e., better than by θ^*) is at least $\frac{r_{\min}}{\Delta}$.
- Thus, when $r_0 \approx r_1$, **recovery is way harder than discrimination!**

Non-disclosure property

*We can **discriminate** between \mathcal{H}_0 and \mathcal{H}_1 with sample size that does not allow to **recover** the complementary model $\bar{\theta}$ (with better quality than θ^*).*

- In fact, our tests access θ^* through “scalar” statistic $\|\Pi_X[Y - X\theta^*]\|^2$ that carries only $O(1)$ Fisher information about θ^* .
- Hence, we also guarantee **non-disclosure of θ^*** (up to accuracy Δ).

Lower bound: key ideas

We need to prove two bounds:

$$\inf_{\hat{T}} \sup_{\|\theta_1 - \theta_0\|_{r'}^2 \geq \Delta} P_I(\hat{T}) + P_{II}(\hat{T}) \gtrsim \max \left\{ \exp(-cn\Delta), \exp\left(-c \frac{n^2 \Delta^2}{\min\{n, r\}}\right) \right\}.$$

First bound: easier problem with **known** $\bar{\theta}$ and **simple hypotheses**:

$$\tilde{\mathcal{H}}_0 : (\theta_0, \theta_1) = (\theta^*, \bar{\theta}), \quad \text{vs.} \quad \tilde{\mathcal{H}}_1 : (\theta_0, \theta_1) = (\bar{\theta}, \theta^*).$$

Likelihood-ratio (LR) test

$$\begin{aligned} T_{\text{LR}} &= \mathbb{1}\{\|Y_0 - X_0\theta^*\|^2 + \|Y_1 - X_1\bar{\theta}\|^2 \geq \|Y_0 - X_0\bar{\theta}\|^2 + \|Y_1 - X_1\theta^*\|^2\} \\ &\text{is optimal (w.r.t. sum of errors) by the Neyman-Pearson lemma, and for it} \\ \mathbb{P}_{\tilde{\mathcal{H}}_0}[T_{\text{LR}} = 1 | X_0, X_1] \\ &= \mathbb{P}[\|Y_0 - X_0\theta_0\|^2 + \|Y_1 - X_1\theta_1\|^2 \geq \|Y_0 - X_0\theta_1\|^2 + \|Y_1 - X_1\theta_0\|^2 | X_0, X_1] \\ &= \mathbb{P}[2\langle \xi_0, X_0(\theta_0 - \theta_1) \rangle + 2\langle \xi_1, X_1(\theta_0 - \theta_1) \rangle \geq \|X_0(\theta_0 - \theta_1)\|^2 + \|X_1(\theta_0 - \theta_1)\|^2] \\ &\geq \mathbb{P}[2\mathcal{N}(0, n\hat{\Delta}_0) + 2\mathcal{N}(0, n\hat{\Delta}_1) \geq n\hat{\Delta}_0 + n\hat{\Delta}_1] \\ &\geq \mathbb{P}[\mathcal{N}(0, n\hat{\Delta}_0) \geq n\hat{\Delta}_0/2] \cdot \mathbb{P}[\mathcal{N}(0, n\hat{\Delta}_1) \geq n\hat{\Delta}_1/2] \gtrsim \exp(-cn \max\{\hat{\Delta}_0, \hat{\Delta}_1\}). \end{aligned}$$

Then $\max\{\hat{\Delta}_0, \hat{\Delta}_1\} \lesssim \Delta$ with fixed probability by Markov's inequality.

We need to prove two bounds:

$$\inf_{\hat{T}} \sup_{\|\theta_1 - \theta_0\|_{I_r}^2 \geq \Delta} P_I(\hat{T}) + P_{II}(\hat{T}) \gtrsim \max \left\{ \exp(-cn\Delta), \exp\left(-c \frac{n^2 \Delta^2}{\min\{n, r\}}\right) \right\}.$$

Second bound captures dependence on the rank. Bayesian approach:

- Put a Gaussian prior π on $\bar{\theta}$ such that $\pi\{\|\bar{\theta} - \theta^*\|_{I_r}^2 \leq \Delta\}$ is very small.
- This allows to lower-bound the maximal risk by the Bayes risk.
- The Bayes risk can be lower-bounded by the Neyman-Pearson lemma—through surprisingly tedious calculations. \square

In our paper:

- General result for parametric models in asymptotic regime $n \rightarrow \infty$ with fixed r_0, r_1 and $n\Delta \rightarrow \lambda$.
- Technical result for generalized linear models (GLMs) allowing for heavy tails and misspecification.
- **Same general picture:**

$$\max\{P_I, P_{II}\} \asymp \exp\left(-c \min\left\{n\Delta, \frac{n^2\Delta^2}{\max\{\rho_0, \rho_1\}}\right\}\right)$$

where ρ_0, ρ_1 are “effective model ranks”.

Open questions:

- Closing the gap for linear models
- General nonasymptotic result
- Mixtures
- New insights on two-sample testing?

Thank you!

And check our paper:

arxiv.org/abs/2012.02901

General asymptotics

General setup: Newton decrement test

Linear model: $\mathbb{1} \{ \|\boldsymbol{\Pi}_{X_0}[Y_0 - X_0\theta^*]\|^2 - \hat{r}_0 \geq \|\boldsymbol{\Pi}_{X_1}[Y_1 - X_1\theta^*]\|^2 - \hat{r}_1 \}.$

General setup:

- Empirical risk $\hat{L}_k(\theta) = \frac{1}{n} \sum_{i=1}^n \ell(\theta, z_i^{(k)})$ has gradient $\nabla \hat{L}_k(\theta)$ and Hessian $\hat{\mathbf{H}}_k(\theta)$:

$$\hat{\mathbf{H}}_k(\theta) := \nabla^2 \hat{L}_k(\theta), \quad \mathbf{H}_k(\theta) := \nabla^2 L_k(\theta).$$

- Let $\mathbf{G}_k(\theta) := \text{Cov}_{\mathbb{P}_k}[\nabla \ell_z(\theta)]$. **For well-specified models:**

$$\mathbf{G}_k(\theta_k) = \mathbf{H}_k(\theta_k).$$

- Standardized Fisher matrix: $\mathbf{J}_k(\theta) := \mathbf{H}_k(\theta)^{-\dagger/2} \mathbf{G}_k(\theta) \mathbf{H}_k(\theta)^{-\dagger/2}.$
- Effective rank $\rho_k := \text{Tr}[\mathbf{J}_k(\theta_k)]$. **For well-specified models:** $\rho_k = r_k.$

In linear regression $\nabla \hat{L}(\theta) = \frac{1}{n} X^\top (Y - X\theta)$ and $\hat{\mathbf{H}}(\theta) \equiv \frac{1}{n} X^\top X$, hence

$$\|\boldsymbol{\Pi}_X[Y - X\theta^*]\|^2 = \|(X^\top X)^{\dagger/2} X^\top (Y - X\theta^*)\|^2 = n \|\hat{\mathbf{H}}(\theta^*)^{\dagger/2} \nabla \hat{L}(\theta^*)\|^2.$$

General setup: Newton decrement test (cont'd)

$$\mathbb{1} \{ \|\mathbf{\Pi}_{X_0}[Y_0 - X_0\theta^*]\|^2 - \hat{r}_0 \geq \|\mathbf{\Pi}_{X_1}[Y_1 - X_1\theta^*]\|^2 - \hat{r}_1 \}.$$

- Replace $\|\mathbf{\Pi}_{X_k}[Y_k - X_k\theta^*]\|^2$ with $n\|\hat{\mathbf{H}}_k(\theta_k)^{\dagger/2}\nabla\hat{L}_k(\theta^*)\|^2$.
- When $n \rightarrow \infty$,

$$\mathbb{E}_k[n\|\hat{\mathbf{H}}_k(\theta_k)^{\dagger/2}\nabla\hat{L}_k(\theta_k)\|^2] \rightarrow \rho_k = \text{Tr}[\mathbf{J}_k(\theta_k)].$$

- Cannot use ρ_k 's as one of them uses $\bar{\theta}$ which is unknown. Instead use

$$\text{Tr}[\mathbf{J}_k(\theta^*)] = n_k \mathbb{E}_k [\|\mathbf{H}_k(\theta^*)^{\dagger/2}(\nabla\hat{L}_k(\theta^*) - \nabla L_k(\theta^*))\|^2],$$

or, more precisely, its asymptotically (as $n \rightarrow \infty$) unbiased estimate:

$$\hat{\mathbf{T}}_k = \frac{1}{2}n_k\|\mathbf{H}_k(\theta^*)^{\dagger/2}(\nabla\hat{L}_k(\theta^*) - \hat{\nabla}L'_k(\theta^*))\|^2.$$

$$\hat{\mathbf{T}} = \mathbb{1} \{ n_0\|\hat{\mathbf{H}}_0(\theta^*)^{\dagger/2}\nabla\hat{L}_0(\theta^*)\|^2 - \hat{\mathbf{T}}_0 \geq n_1\|\hat{\mathbf{H}}_1(\theta^*)^{\dagger/2}\nabla\hat{L}_1(\theta^*)\|^2 - \hat{\mathbf{T}}_1 \}.$$

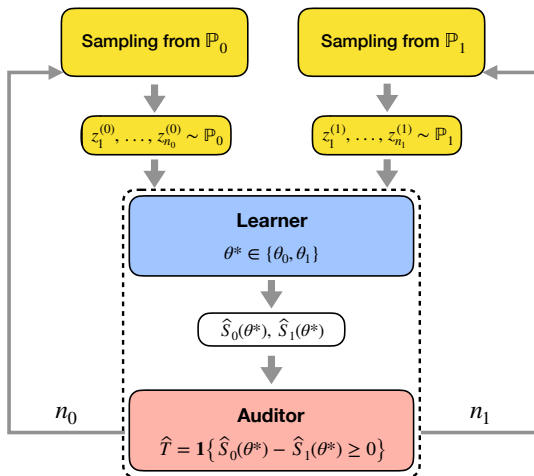
Theorem. Denoting $\rho_{\max} := \max\{\rho_0, \rho_1\}$, we have that

$$\lim_{n \rightarrow \infty} [\max\{P_I, P_{II}\}] \lesssim \exp \left(-c \min \left\{ n\Delta, \frac{n^2\Delta^2}{\rho_{\max}} \right\} \right).$$

Applications

Applications: generic testing protocol

Key observation: θ^* does not have to be known to run the test, and it cannot be inferred from Z_0, Z_1 when they are small.



- We want to protect θ^* and $\bar{\theta} = \theta_0 + \theta_1 - \theta^*$ from inference via Z_0, Z_1 .

Application #1: testing for data deletion

Testing for data deletion

- Company FAANG¹ trained a prediction model θ^* on a large dataset \mathbb{P}^* pertaining to many users.
- Some users ask their data to be removed—and θ^* retrained accordingly.
- FAANG should comply—and would like to demonstrate the compliance.
- Model θ^* is proprietary, hence FAANG would like to avoid disclosing it.

Given a subsample $Z^* \sim \mathbb{P}^*$ of FAANG's dataset and the pool Q of deletion queries, we can check that FAANG indeed retrained the model excluding Q .

- Let $\mathbb{P}_0, \mathbb{P}_1$ correspond to hypotheses $\mathcal{H}_0 : \mathbb{P}^* = \mathbb{P}_0$ (“clean data”) and

$$\mathcal{H}_1 : \mathbb{P}^* = \mathbb{P}_1 := (1 - \delta)\mathbb{P}_0 + \delta Q,$$

where \mathbb{P}_0 is “clean” data, and $\delta \in (0, 1)$ is the share of deletion queries.

- FAANG (“Learner”) gives to the tester (“Auditor”) access to $Z_0 \sim \mathbb{P}_0$.
- Having Z_0 , Q , and δ , Auditor can generate $Z_1 = (1 - \delta)Z_0 + \delta Q \sim \mathbb{P}_1$.

Application #2: testing fair representation of subpopulations

- Let \mathbb{P}_{dem} and \mathbb{P}_{rep} be two populations: Democrats and Republicans.
- We want them to be equally represented in the dataset \mathbb{P}^* .

- Define the hypotheses:

$$\mathcal{H}_0 : \mathbb{P}^* = \mathbb{P}_0 := \frac{1}{2}\mathbb{P}_{\text{dem}} + \frac{1}{2}\mathbb{P}_{\text{rep}},$$

$$\mathcal{H}_1 : \mathbb{P}^* = \mathbb{P}_1 := (\frac{1}{2} + \delta)\mathbb{P}_{\text{dem}} + (\frac{1}{2} - \delta)\mathbb{P}_{\text{rep}} \text{ for some } \delta \in (-\frac{1}{2}, \frac{1}{2}).$$

- Knowing δ , we can easily implement the sampling oracles for \mathbb{P}_0 and \mathbb{P}_1 can be implemented using those for \mathbb{P}_{dem} and \mathbb{P}_{rep} .