

The background of the slide features a large, light gray watermark of the University of Maryland seal. The seal is circular, with the words "UNIVERSITY OF" at the top and "MARYLAND" at the bottom. In the center is a shield with a red and white checkered pattern, a yellow chevron, and a red bird (a cardinal) perched on a branch. The numbers "18" and "56" are also visible on the left and right sides of the seal respectively.

COMPASS

Cardinal Orientation Manipulation and Pattern-Aware Spatial Search

ACM SIGSPATIAL GEOSEARCH WORKSHOP

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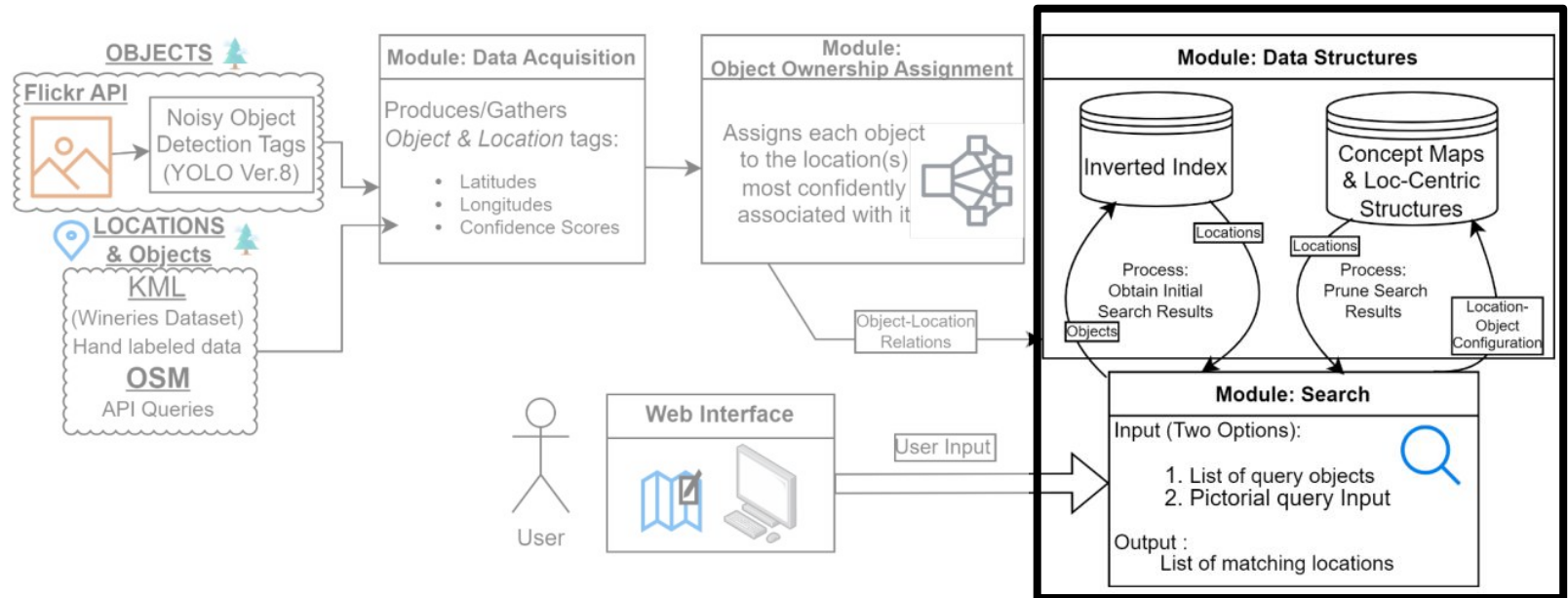
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Presentation Scope

1. Overview.
2. Background and current limitations.
3. Location-centric spatial pattern matching.
4. Object-centric spatial pattern matching.
5. Demo of COMPASS algorithms and data structures.
6. Conclusion and future directions.

GESTALT Architecture

Data Structures & Search



COMPASS provides scalable Spatial Pattern Matching (SPM)

Enables spatial search over objects and locations

- **Data structure:** Matrix-based encoding of relative object positions
- **Search:** Recursively prunes the matrix until a match is identified



Collect.



	0	1	2	3	4	5	6	7
NS:	D	B	B	C	D	B	C	A
WE:	B	C	D	C	B	D	B	A

	0	1	2	3	4	5	6	7
0	0	0	0	0	0	D	0	0
1	B	0	0	0	0	0	0	0
2	0	0	0	0	0	0	B	0
3	0	0	0	C	0	0	0	0
4	0	0	D	0	0	0	0	0
5	0	0	0	0	B	0	0	0
6	0	C	0	0	0	0	0	0
7	0	0	0	0	0	0	0	A

Encode.



Query								
		C						
	D	B						
			A					

	0	1	2	3	4	5	6	7
0	0	0	0	0	0	D	0	0
1	B	0	0	0	0	0	0	0
2	0	0	0	0	0	0	B	0
3	0	0	0	C	0	0	0	0
4	0	0	D	0	0	0	0	0
5	0	0	0	0	B	0	0	0
6	0	C	0	0	0	0	0	0
7	0	0	0	0	0	0	0	A

Search.

Most approaches to SPM are **at least cubic** in complexity

Keyword, **metric**, and **topological** constraints:

- Ignore critical spatial information

Directional constraints:

- Encode spatial patterns as *pairwise* constraints

Algorithm	Implementation			Relationship Constraints				Search Features			Complexity
	Encoding	Search	Objects	Keyword	Metric	Topological	Directional	Fuzzy	Negation	Card. Inv.	
SKECa+ [13]	N/A	SKQ	P	X	X				X	N/A	$O(rn^Q)$
PQL [8]	Set	SI	P, L, R	X	X	X	X	X	X		Unclear
McheckSsl [21, 22, 24]	Set	SI	P	X	X				X		$O(n'^2 + 2n')$
GESTALT _{SI-Basic} [18]	Set	SI	P	X						N/A	$O(Gn)$
GESTALT _{SI-Ranked} [18]	Set	SI	P	X						N/A	$O((G(n + n'Q)))$
GESTALT _{SI-Fuzzy} [18]	Set	SI	P	X				X		N/A	$O(QGn)$
PQIS [12]	Link	SGM	P	X	X		X		X		$O(m^m)$
Spacekey _{MPJ} [10, 11]	Link	SKQ & SGM	P	X	X			X	X		$O(m\zeta^2 + \xi)$
Spacekey _{SPJ} [10, 11]	Link	SKQ & SGM	P	X	X			X	X		$O(n^4 + mn^2 + \xi)$
ESPM [5]	Link	SKQ & SGM	P	X	X			X	X		$O(n^n)$
MSJ _{MSJ} [19]	Link	CSP	P, L, R		X	X	X	X			$O(n^Q)^*$
MSJ _{WR} [19]	Link	CSP	P, L, R		X	X	X	X			$O(n^m)^*$
MSJ _{JWR} [19]	Link	CSP	P, L, R		X	X	X	X			$O(n^m)^*$
STARVARS [16]	Segment	CSP	P				X			X	$O(m^n)$
SketchMapia [15, 20]	Link	SGM	P, L, R	X		X	X	X		X	Unclear
OSS [17]	Segment	Other	P, R		X	X	X			X	$O(n)^*$
SRQL [6, 7]	Segment	Other	R	X		X	X		X		Unclear
COMPASS _{LO} [ours]	Set	SI	P	X			X		X		$O(G(Q + n))$
COMPASS _{OO} [ours]	CM	RGS	P	X			X				$O(G(Q + n^2))$
COMPASS _{CI} [ours]	CM	RGS	P	X			X			X	$O(G(Q^2 + Qn^2))$

Table 2: Summary of related work.

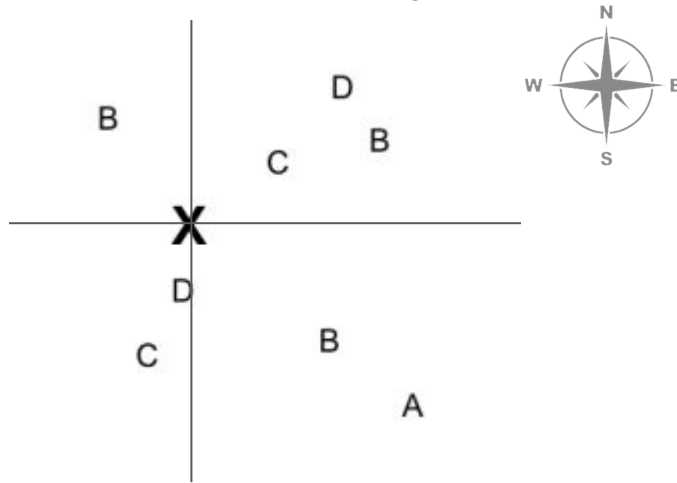
Where the authors do not provide worst-case complexity, we estimate (denoted with *). n is the number of spatial objects in the database, m is the number of relations, G is the number of object collections (locations) to search over, Q is the number of query objects, n' is the subset of objects matching a keyword query, ζ is a sampling threshold in $[0, 1]$ and ξ is the maximal number of partial matches to a query ζ



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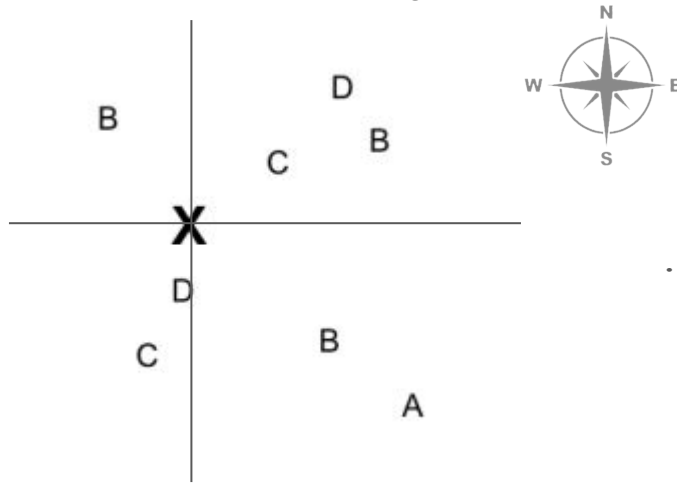
Location-Centric Spatial Pattern Matching

Given a known set of objects and how they each relate to a central location...



Location-Centric Spatial Pattern Matching

Given a known set of objects and how they each relate to a central location...



... and a sketch map or pictorial query...

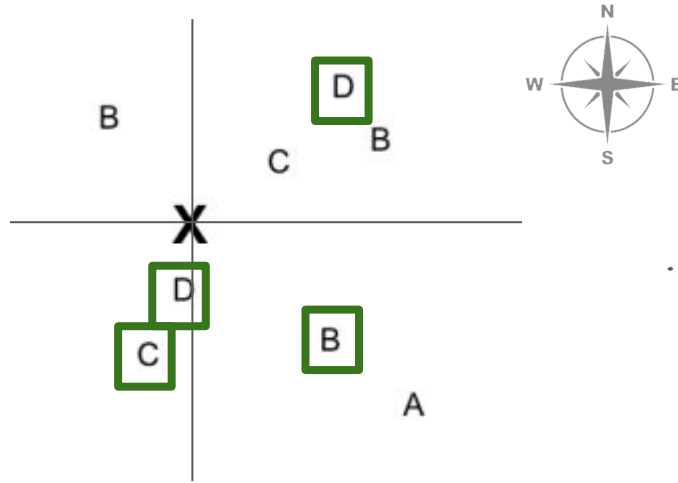
Query

E		D
-	X	-
C,D		B

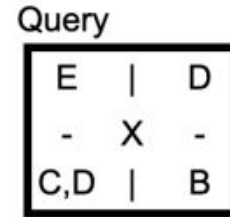


Location-Centric Spatial Pattern Matching

Given a known set of objects and how they each relate to a central location...



... and a sketch map or pictorial query...



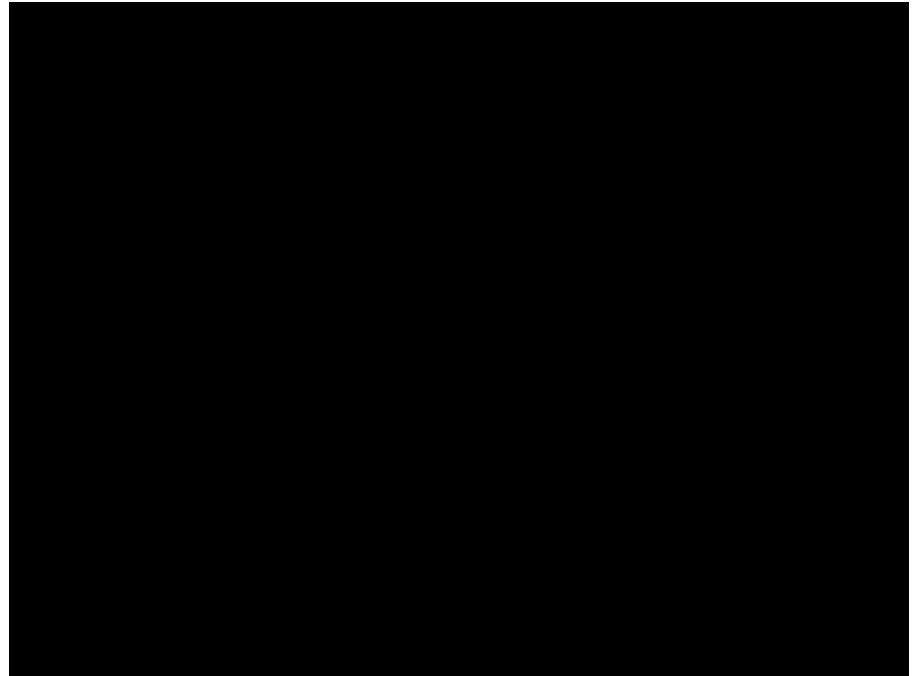
... determine which known locations are a match for the query.



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COMPASS: Cardinal Orientation Manipulation and Pattern-Aware Spatial Search

Searching for **objects** by their
directional relations to their
associated **location**

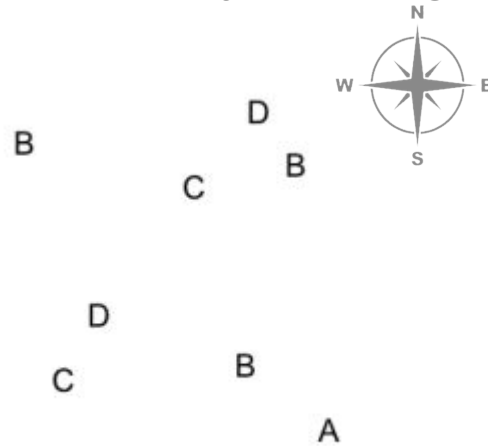




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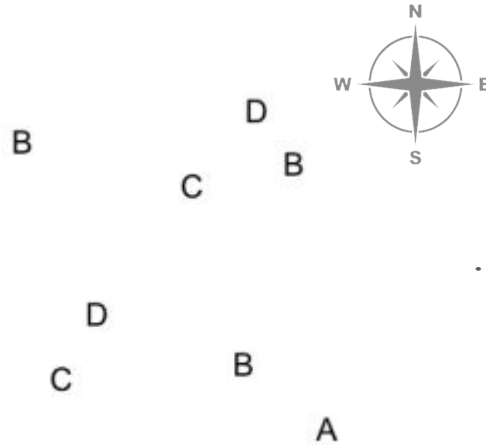
Object-Centric Spatial Pattern Matching

Given a known set of objects arranged in a spatial pattern...

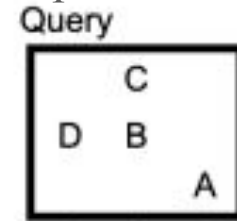


Object-Centric Spatial Pattern Matching

Given a known set of objects arranged in a spatial pattern...

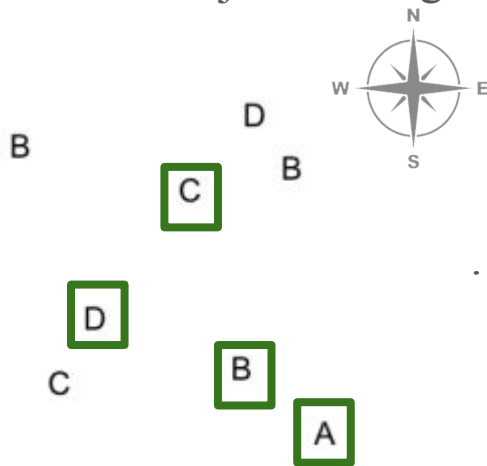


... and a sketch map or pictorial query...

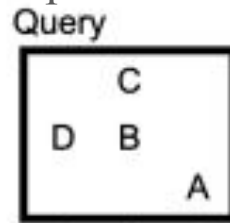


Object-Centric Spatial Pattern Matching

Given a known set of objects arranged in a spatial pattern...



... and a sketch map or pictorial query...



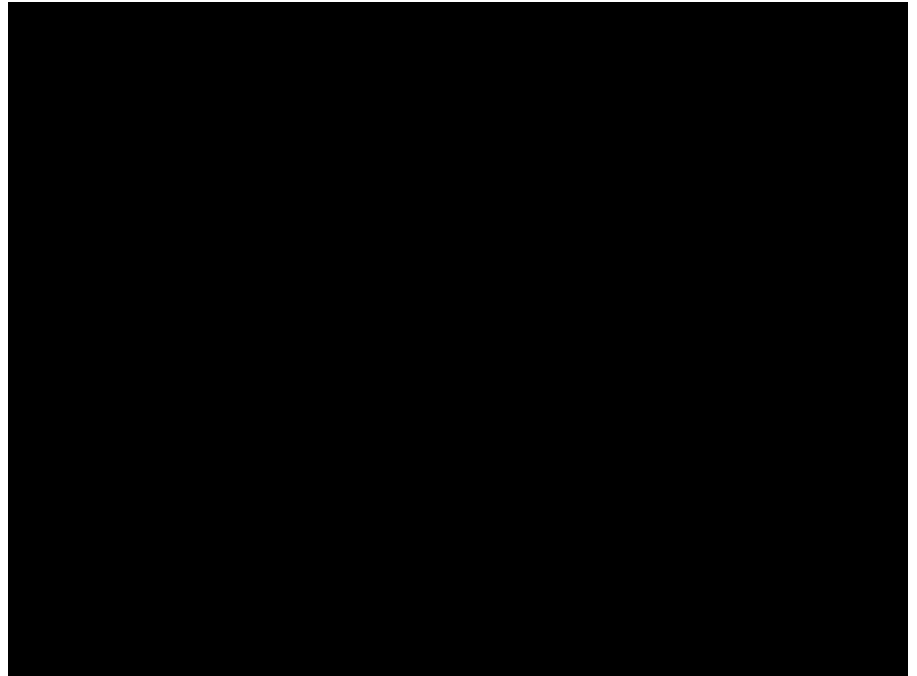
... determine if the query matches at least one set of known objects.



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COMPASS: Cardinal Orientation Manipulation and Pattern-Aware Spatial Search

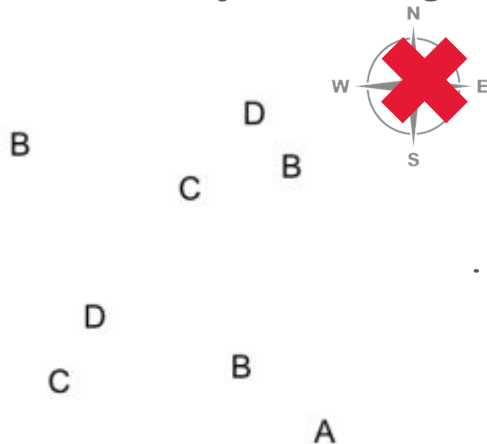
Searching for **objects**
recursively by their directional
relations to other **objects**



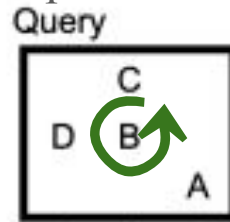


Cardinality-Invariant Object-Centric Spatial Pattern Matching

Given a known set of objects arranged in a spatial pattern...



... and a sketch map or pictorial query...



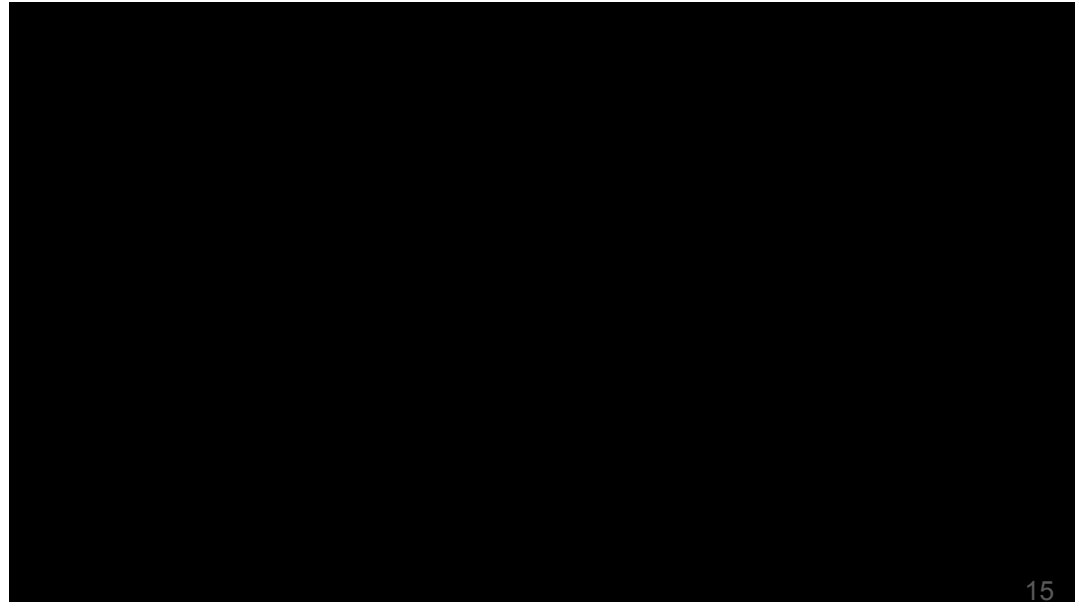
... determine if *any orientation* of the query matches at least one set of known objects.



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COMPASS: Cardinal Orientation Manipulation and Pattern-Aware Spatial Search

Searching for **objects** by their
directional relations to other
objects, *regardless of
cardinal orientation of the
query*





Summary

- We present COMPASS, a suite of data structures and scalable search algorithms that enable spatial pattern matching over sets of objects associated with a location

Future directions

- Extend COMPASS to find *all* instead of *any* match to the query pattern.
- Extend our theoretical analysis of COMPASS with an empirical comparison against related works.
- Investigate if the COMPASS matrix-based embedding can be extended to support line and region data.



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Questions

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