## **Dirac Notation**

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# Overview

Vectors

- Matrix Algebra
- Oirac Notation

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#### Vectors

 A vector A can be described by specifying its components with respect to a set of axes

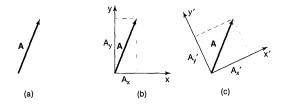


Figure 1: (a) vector, (b) x,y axis, (c) x',y' axis [Griffiths, 2005]

- $\bullet \ A: A_x = \hat{\imath} \cdot A, \ A_y = \hat{\jmath} \cdot A \quad \text{or} \quad A: A_x' = \hat{\imath}' \cdot A, \ A_y' = \hat{\jmath}' \cdot A$
- ullet Same vector A, different choice of basis
- The vector lives in a space independent of coordinates

#### The Wave Function

- ullet The state of a system is also represented by a vector, |S
  angle
- This vector lives in Hilbert space
- Represented with respect to different bases

$$\Psi(x,t) = \langle x|S(t)\rangle \tag{1}$$

ullet |xangle is the position eigenfunction with eigenvalues x

$$\Phi(p,t) = \langle p|S(t)\rangle \tag{2}$$

- ullet |p
  angle is the momentum eigenfunction with eigenvalues p
- ullet Same vector S expanded over different bases of eigenfunctions

#### The Wave Function

 S may also be expanded in the energy eigenfunction basis (assuming discrete spectrum for simplicity)

$$c_n(t) = \langle n|S(t)\rangle) \tag{3}$$

- ullet In this case, |n
  angle is the nth eigenfunction of  $\hat{H}$
- ullet In all cases, it is the same state S
- $\Psi$ ,  $\Phi$  and  $c_n$  contain the same exact information and are simply different ways of describing the same vector:

$$\Psi(x,t) = \int \Psi(y,t)\delta(x-y)dy = \int \Phi(p,t)\frac{1}{\sqrt{2\pi\hbar}}e^{\imath px/\hbar}dp \qquad (4)$$
$$= \sum c_n e^{-\imath E_n t/\hbar}\psi_n(x)$$

#### Linear Transformations

Operators transform one vector into another:

$$|\beta\rangle = \hat{Q}|\alpha\rangle \tag{5}$$

• A vector is represented by it's components with respect to a basis  $|e_n\rangle$  by:

$$|\alpha\rangle = \sum_{n} a_n |e_n\rangle$$
 with  $a_n = \langle e_n | \alpha \rangle$  (6)

• Operators are expressed by their matrix elements:

$$\langle e_m | \hat{Q} | e_n \rangle \equiv Q_{mn} \tag{7}$$

With this notation, 5 becomes:

$$\sum_{n} b_n |e_n\rangle = \sum_{n} a_n \hat{Q} |e_n\rangle \tag{8}$$

#### Linear Transformations

ullet 8 can be rewritten by using the inner product with  $|e_m
angle$ 

$$\sum_{n} b_{n} \langle e_{m} | e_{n} \rangle = \sum_{n} a_{n} \langle e_{m} | \hat{Q} | e_{n} \rangle \tag{9}$$

Which gives

$$b_m = \sum_n Q_{mn} a_n \tag{10}$$

- The elements of the matrix describe how the components transform
- We might ecounter systems with a finite number of linearly independent states
- Then, we have an N-dimensional vector space with operators in the form of  $(N \times N)$  matricies

## Dirac - bra and ket

- Dirac split the inner product bracket notation into two pieces: the bra,  $\langle \alpha |$  and ket,  $|\beta \rangle$
- The ket is a vector, but the bra is a linear function of vectors
- When the bra acts on the ket, it results in a complex number (the inner product)
- Similar to an operator, except an operator acting on a vector produces another vector, whereas the bra acting on a vector produces a number
- We can think of the bra as an instruction telling us to integrate:

$$\langle f| = \int f^*[\cdots] dx$$

ullet Where the  $[\cdots]$  represents the function encountered in the ket

#### Dirac - bra and ket

 A vector in a finite-dimensional vector space can be expressed in columns as

$$|\alpha\rangle = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} \tag{11}$$

• The bra corresponding to this vector is:

$$\langle \alpha | = (a_1^* a_2^* \cdots a_n^*) \tag{12}$$

The collection of all bras describes a vector space known as dual space

# **Projection Operator**

ullet If |lpha
angle is normalized, we can define the *projection operator* to be

$$\hat{P} \equiv |\alpha\rangle\langle\alpha| \tag{13}$$

• which picks out the portion of any vector along  $|\alpha\rangle$ :

$$\hat{P}|\beta\rangle = \langle \alpha|\beta|\alpha\rangle \tag{14}$$

ullet Lets consider a discrete orthonormal basis  $|e_n|\rangle$  such that

$$\langle e_m | e_n \rangle = \delta_{mn} \tag{15}$$

Then the identity operator is

$$\sum_{n} |e_n\rangle\langle e_n| = 1 \tag{16}$$

## Dirac Orthonormalized Continuous Basis

• If this operator acts on a vector  $|\alpha\rangle$  we obtain

$$\sum_{n} |e_n\rangle\langle e_n|\alpha\rangle = |\alpha\rangle \tag{17}$$

• The same can be said for a Dirac orthonormalized continuous basis  $|e_z\rangle$  :

$$\langle e_z | e_{z'} \rangle = \delta(z - z') \tag{18}$$

Then

$$\int |e_z\rangle\langle e_z|dz = 1 \tag{19}$$

## References



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