Mecanum Arm Manipulator 4-DOF

This board is for Mecanum car using arm robot 4-DOF project. The controller is teensy 3.5/3.6, using pin that showed below. The servoes for arm robot using Dynamixel servo. You can visit our webside to find more about our project.

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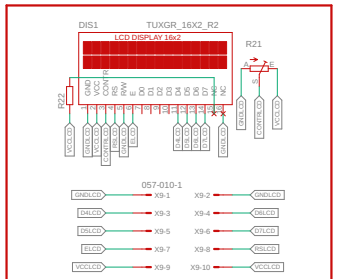
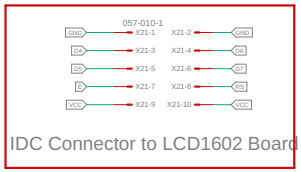
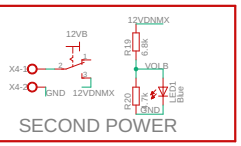
Design by Tirza Sarwono



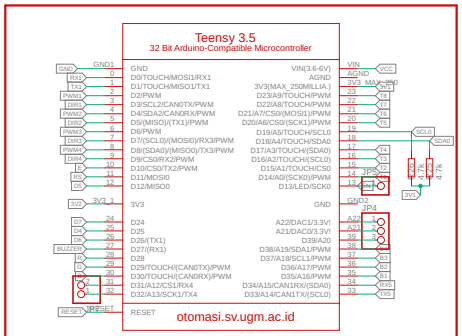
LCD 1602



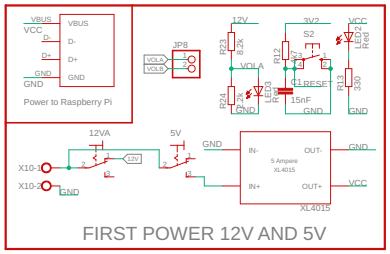
IDC Connector to LCD1602 Board



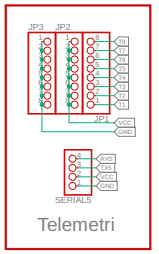
SECOND POWER



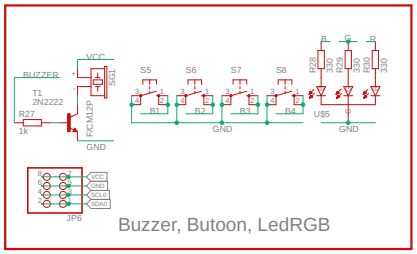
MAIN CONTROLLER TEENSY 3.5



FIRST POWER 12V AND 5V



Telemetri



Buzzer, Butoon, LedRGB

About Me

My name is Tirza Sarwono. I live in Klaten, Central Java, Indonesia. I'm student at Gadjah Mada University. In this year (2020), i made this project for graduate requirement from Gadjah Mada University. This project was made by help from my friends in Instrumen dan kendali laboratory.

You can found more about our others project in:

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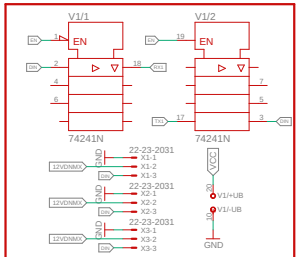
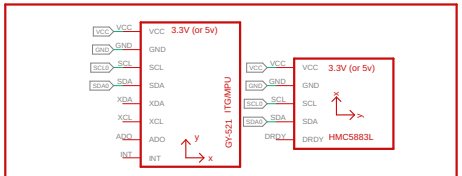
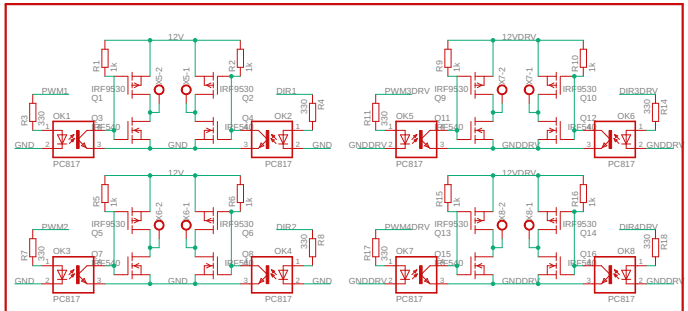


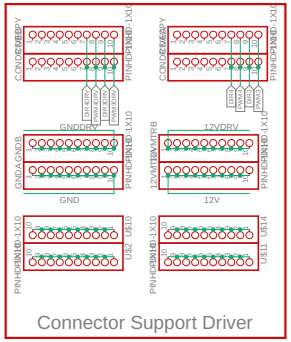
74241 DYNAMIXEL



IMU AND COMPASS



HBRIDGE DRIVER MOTOR DC



Connector Support Driver