FIR Filter Design: Windows Method

Dr John O' Toole

Irish Centre for Fetal and Neonatal Translational Research (INFANT)

Department of Paediatrics and Child Health,

University College Cork.

jotoole@ucc.ie
Tel: 021-4205599

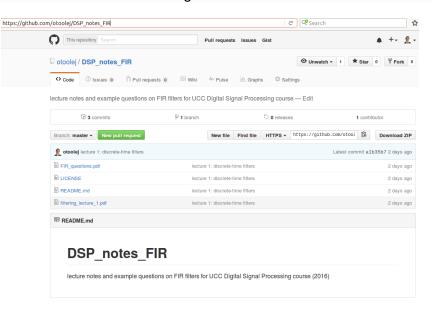
February 15, 2016

lecture notes and example questions

https://github.com/otoolej/DSP_notes_FIR



click on 'Download ZIP' on right-hand side



Learning Objectives

procedure to design non-ideal (FIR) filters using the window method

- review: FIR and IIR filters, importance of phase, ideal filters
- ideal filter not possible ⇒ use non-ideal filter.
- · Window method:
 - 1. define ideal in the frequency domain
 - 2. find impulse response function in time domain $(H_d(\omega) \Rightarrow h_d[n])$
 - 3. shift impulse response function in time
 - 4. truncate impulse response (infinite ⇒ finite) using a window
- · effect of window shape and window length on filter

Review: discrete-time filters

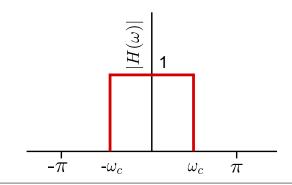
- convolution and modulation: $x[n]*h[n] \leftrightarrow X(\omega)H(\omega)$
- frequency response: magnitude and phase
 - magnitude scales frequency components (e.g. low-pass filter)
 - phase provides information on time-delay
 - linear phase: constant time-delay
 - non-linear phase: different time-delays for different frequencies
- comparing FIR and IIR:
 - stability, phase response, design complexity, sensitivity to numerical precision
- ideal filter: non-causal, unstable, and not realisable
 - ⇒ need non-ideal filter

Ideal Low-Pass Filter

Frequency Response

$$H(\omega) = \begin{cases} 1 & |\omega| \le \omega_c \\ 0 & \omega_c < |\omega| \le \pi \end{cases}$$

Magnitude response:



Phase response:

$$\angle H(\omega) = 0$$

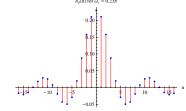
Impulse Response (time-domain)

Inverse DTFT

$$h[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} H(\omega) e^{j\omega n} d\omega$$

$$= \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} e^{j\omega n} d\omega$$

$$= \begin{cases} \frac{\omega_c}{\pi} & n = 0\\ \frac{\omega_c}{\pi} \frac{\sin \omega_c n}{\omega_c n} & n \neq 0 \end{cases}$$
• ideal filt



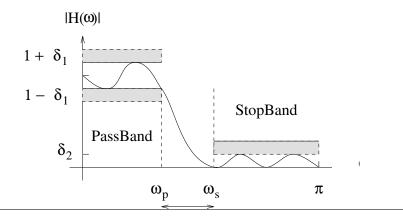
Problems:

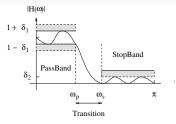
- ideal filter is non-causal
- not realisable for stored data $(n=-\infty)$
- unstable

Non-Ideal Filters

Compromise:

- let $|H(\omega)| \approx 0$ in stopband
- let $|H(\omega)| \approx 1$ in passband
- smooth transition from passband to stopband





• ω_n defines bandwidth with passband ripple (in dB):

$$A_p = 20 \log_{10}(1 + \delta_1)$$

• ω_s start of the stopband with Stopband attenuation:

$$A_s = -20\log_{10}\delta_2$$

• Width of the transition band $\omega_s - \omega_p$.

FIR Filters

• Force to be causal and finite:

$$h[n] = 0,$$
 for $n < 0$ and $n \ge M$

• impulse response is then FIR:

$$y[n] = \sum_{k=0}^{M-1} h[k]x[n-k]$$

The output at n is the weighted linear combination input samples $x[n], x[n-1], \dots x[n-M+1]$

FIR Frequency Response

$$\begin{split} H(\omega) &= \mathsf{DTFT}\{h[n]\} \\ &= \sum_{k=0}^{M-1} h[n] \mathrm{e}^{-j\omega k} \end{split}$$

- The FIR Digital filter design problem:
 - determine h[n]
 - to satisfy limits set for δ_1,δ_2 and $\omega_s-\omega_p$
- Accuracy depends on h[n] and on M.

Windows Method: shift and truncate

- 1. Start with ideal frequency response: $H_d(\omega)$
- 2. calculate impulse response $h_d[n]$ from inverse DTFT:

$$h_d[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} H_d(\omega) e^{j\omega n} d\omega$$

- 3. But is not casual $(h_d[n] \neq 0 \text{ for } n < 0)$ and has infinite duration. Solution:
 - 3.1 shift $h_d[n]$ by (M-1)/2 (M is odd)
 - 3.2 truncate $h_d[n]$ to finite duration M

- order is important: shift first then truncate, i.e. truncate $h_d[n-(M-1)/2]$ and not $h_d[n]$
- finite impulse response:

$$h[n] = 0$$
 for $n < 0$ and $n \ge M$

• h[n] now equal to $h_d[n-(M-1)/2]w[n]$, where w[n] is rectangular window defined as

$$w[n] = \begin{cases} 1 & 0 \le n \le M - 1 \\ 0 & \text{otherwise} \end{cases}$$

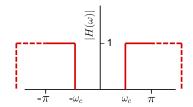
- notation:
 - $h_d[n]$: infinite ideal impulse response
 - h[n]: finite non-ideal impulse response

Relation of h[n] to Ideal Impulse Response $h_d[n]$

Let
$$M_h = \frac{M-1}{2}$$
 (M odd):

$$\begin{split} h[n] &= h_d \left[n - M_h \right] w[n] \\ &= \begin{cases} h_d \left[n - M_h \right] & 0 \leq n \leq M - 1 \\ 0 & n < 0 \quad \text{and} \quad n \geq M \end{cases} \end{split}$$

High-Pass FIR Filter



Question: Derive the impulse response for high-pass FIR filter with cut-off ω_c using the window method with a rectangular window of length M (assume M is odd) Ideal Impulse

Response (with cutoff ω_c):

$$h_d[n] = \begin{cases} 1 - \frac{\omega_c}{\pi} & n = 0\\ -\frac{\sin(\omega_c n)}{\pi n} & n \neq 0 \end{cases}$$

shift and truncate

- shift: $h_d[n] \rightarrow h_d[n-M_h]$
- truncate: multiple by rectangular window w[n]

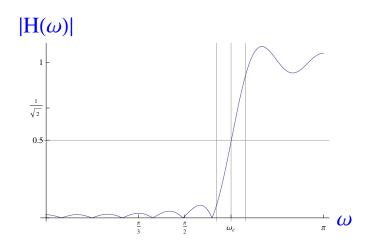
$$\begin{split} h[n] &= h_d \left[n - M_h \right] w[n] \\ &= \begin{cases} \frac{-\sin[\omega_c(n-M_h)]}{\pi(n-M_h)} & 0 \leq n \leq M-1 \text{ and } n \neq M_h \\ 1 - \frac{\omega_c}{\pi} & n = M_h \\ 0 & n < 0 \text{ and } n > M-1 \end{cases} \end{split}$$

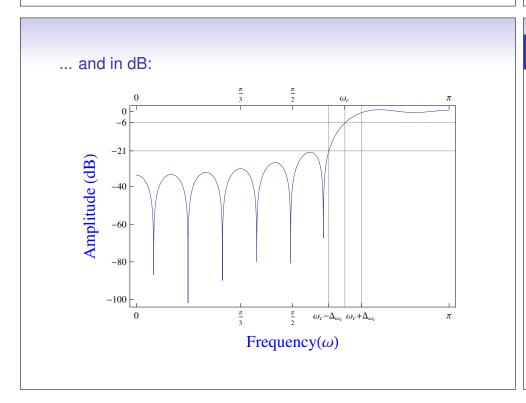
Example impulse response (FIR high-pass filter):

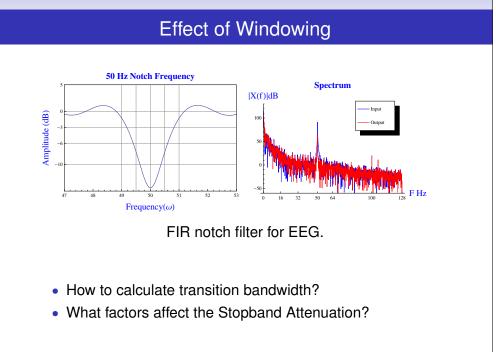
$$\omega_c = rac{2\pi}{3}$$
 and $M=17$

... and frequency response (magnitude):

$$\omega_c = \frac{2\pi}{3}$$







• multiplication in the time-domain (i.e. window ideal impulse response):

$$h[n] = h_d[n]w[n]$$

• equivalent to convolution in frequency domain:

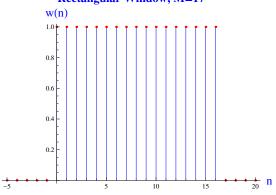
$$H(\omega) = H_d(\omega) * W(\omega)$$
$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} H_d(\nu) W(\omega - \nu) d\nu$$

- main lobe of window ⇒ (discontinuity in) transition bandwidth
- side lobe of window ⇒ (level of) passband ripple and stopband attenuation

Rectangular Window

$$w[n] = \begin{cases} 1 & 0 \le n \le M - 1 \\ 0 & n < 0, n > M - 1 \end{cases}$$

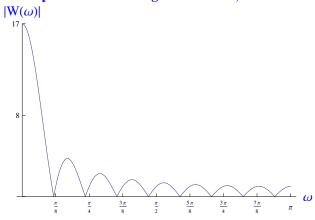




spectrum:

$$W(\omega) = \mathsf{DTFT}\{w[n]\} = \mathrm{e}^{-j\omega(M-1)/2} \frac{\sin(\omega M/2)}{\sin(\omega/2)}$$

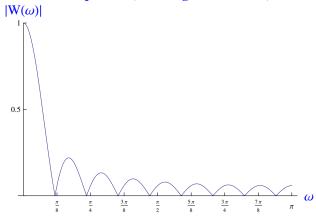
Spectrum of Rectangular Window, M=17



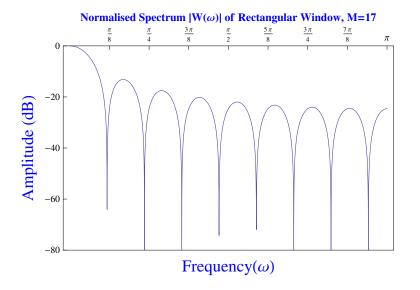
normalise spectrum

$$W(\omega) \leftarrow \frac{W(\omega)}{|W(0)|}$$

Normalised Spectrum, Rectangular Window, M=17

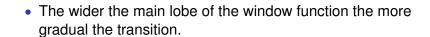


... in dB:

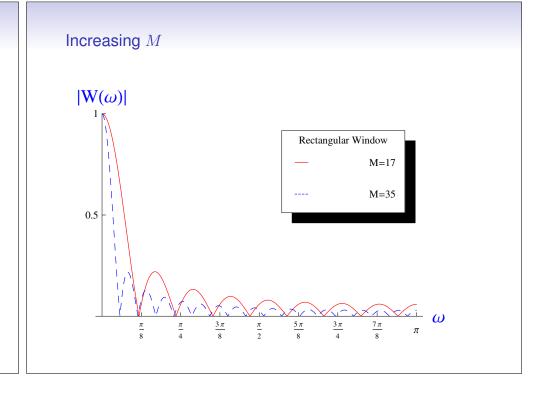


Width of Main Lobe

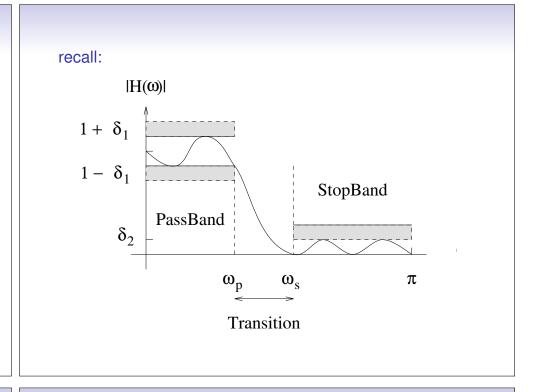
- The main lobe width is defined as the distance from $\omega=0$ to the first zero of $W(\omega)$
- The width of the main lobe is $2\pi/M$
 - hence as M increases the main lobe becomes narrower.
- The main lobe of $W(\omega)$ affects the transition region from the passband to the stopband.
 - Recall: our desired frequency response $H_d(\omega)$ has a discontinuity or infinitely sharp transition from stop to pass band.



- Therefore by increasing the window length M we reduce the main lobe width and thus get a reduced transition region.
- ullet But increasing M also increases computational load of the filter.

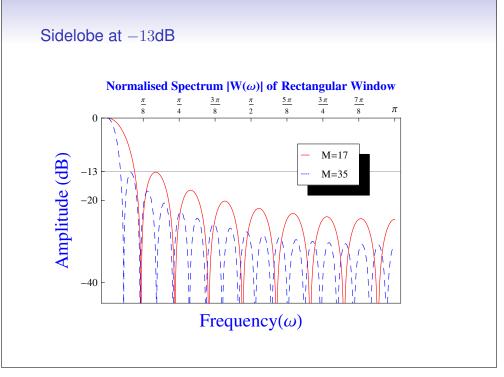


Increasing M (in dB) Normalised Spectrum |W(ω)| of Rectangular Window $\frac{\pi}{8} \quad \frac{\pi}{4} \quad \frac{3\pi}{8} \quad \frac{\pi}{2} \quad \frac{5\pi}{8} \quad \frac{3\pi}{4} \quad \frac{7\pi}{8} \quad \pi$ $-20 \quad -40 \quad -40$



Side Lobe

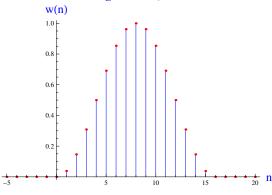
- The sidelobes of $W(\omega)$ cause a different distortion.
- The effect is most evident in the frequency ranges in which $H_d(\omega)$ is constant:
 - i.e. passband and stopband.
- For passband, these sidelobe effects appear both as overshoots and undershoots to the desired response.
- For stopband they appear as a nonzero response.
- \bullet For rectangular window sidelobes remain unaffected by increase M



Hanning Window

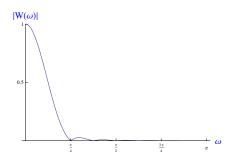
$$w[n] = \begin{cases} 0.5 - 0.5 \cos\left(\frac{2\pi n}{M-1}\right) & 0 \le n \le M-1 \\ 0 & n < 0, n > M-1 \end{cases}$$

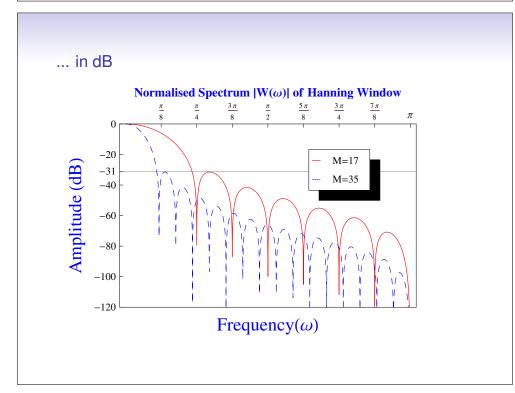
Hanning Window, M=17

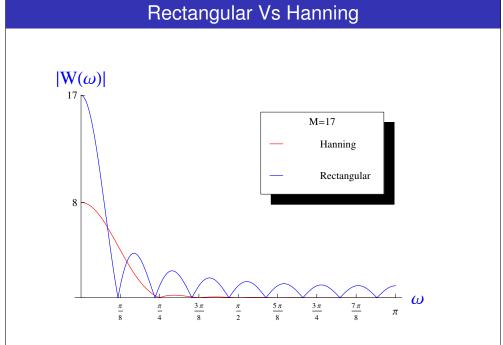


normalised spectrum for M=17:

$$W(\omega) = e^{-j8\omega} \left[w(8) + 2 \sum_{n=0}^{7} w[n] \cos \omega (8 - n) \right]$$
$$= e^{-j8\omega} \left[1 + 2 \sum_{n=0}^{7} \left(0.5 - 0.5 \cos \left(\frac{\pi n}{8} \right) \right) \cos \left(\omega (8 - n) \right) \right]$$



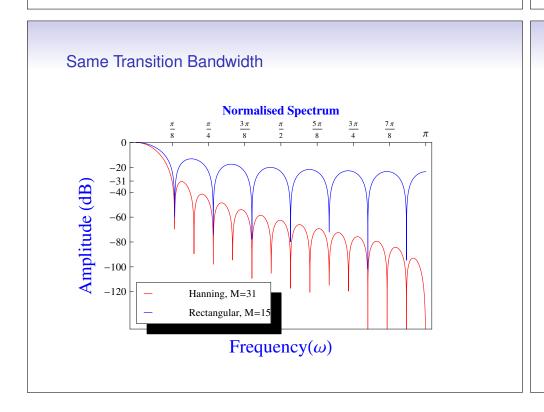


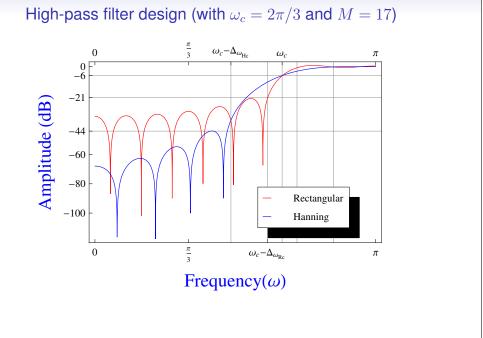


Comparing windows in dB: $\frac{\text{Normalised Spectrum of Hanning and Rectangular Windows}}{\frac{\pi}{8} \frac{\pi}{4} \frac{3\pi}{8} \frac{\pi}{2} \frac{5\pi}{8} \frac{3\pi}{4} \frac{7\pi}{8} \pi}$

Rectangular vs Hanning:

- Approximate width of the main lobe in the magnitude spectrum of the Hanning window is $4\pi/(M-1)$.
 - Width of the main lobe of the rectangular window spectrum is $2\pi/M$.
- Hanning window results in a wider transition region.
 - But the height of the sidelobes in the Hanning window spectrum is less than that for the rectangular window.
- ⇒ Hanning window has less overshoots and undershoots in the passband and less leakages in the stopband.





Windows

- Several window functions have been proposed which lead to filters with varying transition band widths and stopband attenuation for a fixed filter length.
- Can relate the transition band width $(\triangle f)$ to the filter length. For example the Rectangular Window $\triangle f = 0.9/M$.
- Can determine approximately the minimum stopband attenuation that can be achieved with a particular window.
 For example with the Hanning Window it is 44 dB.
- Can determine approximately the passband ripple. For example with the Hamming Window it is 0.0194 dB.

Windows II

$\begin{array}{c} \textbf{Window} \\ w[n] \end{array}$	Sidelobe	$\triangle f$	Stopband Attenuation	Passband Ripple
Rectangular	$-13~\mathrm{dB}$	$\frac{0.9}{M}$	$21~\mathrm{dB}$	0.7416~dB
$w[n] = \left\{ \begin{array}{cc} 1 & 0 \leq n \leq M-1 \\ 0 & \text{otherwise} \end{array} \right.$				
Hanning	$-31~\mathrm{dB}$	$\frac{3.1}{M}$	44 dB	0.0546 dB
$w[n] = \left\{ \begin{array}{cc} 0.5 - 0.5 \cos\left(\frac{2\pi n}{M-1}\right) & 0 \leq n \leq M-1 \\ 0 & \text{otherwise} \end{array} \right.$				
Hamming	$-41~\mathrm{dB}$	$\frac{3.3}{M}$	$53~\mathrm{dB}$	0.0194~dB
$w[n] = \left\{ \begin{array}{cc} 0.54 - 0.46\cos\left(\frac{2\pi n}{M-1}\right) & 0 \leq n \leq M-1 \\ 0 & \text{otherwise} \end{array} \right.$				
Blackman	$-57~\mathrm{dB}$	$\frac{5.5}{M}$	$75~\mathrm{dB}$	0.0017~dB
$w[n] = \left\{ \begin{array}{c} 0.42 - 0.5\cos\left(\frac{2\pi n}{M-1}\right) + 0.08\cos\left(\frac{4\pi n}{M-1}\right) & 0 \leq n \leq M-1 \\ 0 & \text{otherwise} \end{array} \right.$				

Passband Ripple and Stopband Attenuation

recall that:

- passband ripple (in dBs): $A_p = 20 \log_{10}(1 + \delta_1)$
- stopband attenuation (in dBs): $A_s = -20 \log_{10} \delta_2$

Rectangular

Blackman

$$20 \log(1 + \delta_p) = 0.7416 \, \mathrm{dB}$$
 $20 \log(1 + \delta_p) = 0.0017 \, \mathrm{dB}$
 $\delta_p = 0.08913$ $\delta_p = 0.0002$
 $-20 \log(\delta_s) = 21 \, \mathrm{dB}$ $-20 \log(\delta_s) = 75 \, \mathrm{dB}$
 $\delta_s = 0.089125$ $\delta_s = 0.0001778$

Summary

- 1. Specify the "ideal" or desired frequency response $H_d(\omega)$
- 2. Obtain the impulse response $h_d[n]$ by evaluating the inverse Fourier transform
- 3. Select a window function with the appropriate passband or stopband properties
- 4. Determine number (M) of coefficients necessary to get appropriate transition band width.
- 5. "shift and truncate": $h[n] = h_d \left[n \frac{M-1}{2} \right] w[n]$

Summary (cont.)

Also, the window is important:

- main lobe of window ⇒ transition bandwidth
 - \bullet increase in M (window length) results in a decrease in the transition band
- side lobe of window \Rightarrow passband ripple and stopband attenuation
 - different window types have different levels of passband ripple