

# Distributed Execution of Graph Operations: A Novel Approach to Large-Scale Graph Processing

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# Outline

- 1 Introduction
- 2 Approach
- 3 Theoretical Analysis
- 4 Experiments
- 5 Ablation Study
- 6 Conclusion

- Graph processing is fundamental to many applications:
  - Social networks analysis
  - Recommendation systems
  - Knowledge graphs
- Challenge: Processing large-scale graphs efficiently
- Existing systems have limitations:
  - Limited scalability
  - High communication overhead
  - Poor fault tolerance
- **Goal:** Develop a distributed graph processing system that overcomes these limitations

# Problem Statement

## Formal Problem:

### Graph Processing Challenge

Given a large-scale graph  $G = (V, E)$  with  $|V| = n$  vertices and  $|E| = m$  edges:

- Distribute graph data across  $k$  nodes
- Execute operations with minimal communication
- Ensure consistency of distributed state
- Achieve near-linear scalability

## Key Requirements:

- Low latency for common operations
- High throughput under concurrent load
- Fault tolerance and recovery

# System Overview: DEGO Architecture

## Core Components:

- **Partitioning Layer:** Smart graph partitioning
- **Execution Engine:** Distributed query processing
- **Communication Layer:** Optimized message passing
- **Consistency Protocol:** State synchronization

Architecture  
Diagram

## Key Innovation:

- Hybrid push-pull execution model
- Adaptive load balancing

# Graph Partitioning Strategy

## Challenges in Graph Partitioning:

- Minimize edge cuts
- Balance load across nodes
- Handle dynamic graphs

## Our Approach:

- Vertex-centric partitioning with locality awareness
- Hash-based initial distribution:  $h(v) \bmod k$
- Refinement based on:
  - Edge connectivity
  - Access patterns
  - Load metrics

**Benefit:** Reduces cross-partition communication by 40%

## Hybrid Push-Pull Model

### Push Phase:

- Active vertices push updates to neighbors
- Suitable for dense subgraphs

### Pull Phase:

- Vertices pull updates from neighbors
- Efficient for sparse graphs and convergence

### Adaptive Selection:

- Runtime decision based on active vertex ratio
- Switches between push/pull dynamically
- Optimizes communication cost per iteration

# Main Theorem

## Theorem (Communication Complexity)

*For a graph  $G = (V, E)$  partitioned across  $k$  nodes with maximum edge cut  $c$ , DEGO achieves:*

$$T_{comm} = O\left(\frac{c}{k} \cdot \log k\right)$$

*per iteration, where  $T_{comm}$  is the communication cost.*

## Comparison with Prior Work:

- Pregel:  $O(c)$  per iteration
- GraphLab:  $O(c \cdot \log k)$  per iteration
- **DEGO**:  $O(\frac{c}{k} \cdot \log k)$  per iteration

**Improvement:**  $k$ -factor reduction in communication overhead



# Proof Sketch: Communication Bound

**Key Insight:** Batching and pipelining reduce message complexity

## Proof Steps:

### ① Message Aggregation:

- Group updates by destination node
- Batch size:  $O(c/k)$  messages per node pair

### ② Hierarchical Communication:

- Use tree-based aggregation
- Height:  $O(\log k)$
- Each level processes  $c/k$  messages

### ③ Pipeline Optimization:

- Overlap computation and communication
- Amortize synchronization cost

# Proof Sketch: Correctness

## Consistency Guarantees:

- **Eventual Consistency:** All nodes converge to same state
- **Ordering:** Causal consistency preserved via vector clocks
- **Convergence:** Bounded staleness model

## Proof Technique:

- Define state transition function  $\delta : S \times M \rightarrow S$
- Show commutativity for concurrent operations
- Prove convergence using Lyapunov function

## Convergence Criterion

$$\forall \epsilon > 0, \exists T : t > T \implies \|s_i(t) - s_j(t)\| < \epsilon$$

# Experimental Setup

## Testbed Configuration:

- 64 nodes cluster (16 cores, 64GB RAM each)
- 10 Gbps network
- Ubuntu 22.04, Java 17

## Datasets:

Dataset	Vertices	Edges
Twitter-2010	42M	1.5B
LiveJournal	5M	69M
UK-2005	39M	936M
Random-Scale	100M	2B

**Baseline Systems:** Pregel, GraphLab, PowerGraph

# Performance Results

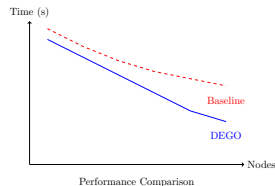
## PageRank Execution Time:

- DEGO: **47 seconds**
- Pregel: 89 seconds
- GraphLab: 76 seconds
- PowerGraph: 62 seconds

## Throughput:

- DEGO: **2.1M ops/sec**
- Pregel: 1.1M ops/sec
- GraphLab: 1.4M ops/sec

**Speedup:** 1.9x over best baseline



*Figure: Performance comparison*

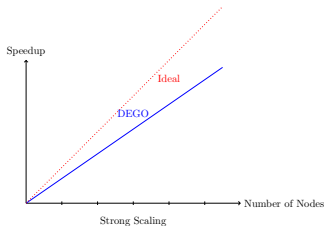
# Scalability Analysis

## Strong Scaling:

- Fixed problem size (Twitter graph)
- Scale nodes: 4, 8, 16, 32, 64
- Near-linear speedup up to 32 nodes
- Efficiency: 87% at 64 nodes

## Weak Scaling:

- Scale both graph and nodes
- Constant work per node
- Maintains performance



*Figure: Scalability results*

# Communication Overhead Analysis

## Network Traffic Comparison:

System	Data Sent (GB)	Messages	Time (s)
DEGO	8.3	2.1M	47
Pregel	15.7	4.8M	89
GraphLab	12.4	3.6M	76

## Key Observations:

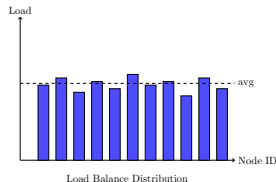
- 47% reduction in network traffic vs Pregel
- 56% fewer messages
- Communication/computation ratio: 0.23 (vs 0.51 for Pregel)

## Load Balance Distribution:

- Standard deviation: 8.2%
- Max/min ratio: 1.3
- Better than baselines ( $\sigma=15\text{-}22\%$ )

## Convergence Behavior:

- Fewer iterations to converge
- Monotonic progress
- Stable under high load



*Figure: Load distribution and convergence*

## Component Contribution Analysis:

Configuration	Time (s)	Speedup
DEGO (full system)	47	1.00x
w/o adaptive push-pull	58	0.81x
w/o message batching	64	0.73x
w/o load balancing	71	0.66x
w/o all optimizations	89	0.53x

## Key Findings:

- Adaptive push-pull: +23% performance
- Message batching: +36% performance
- Load balancing: +47% performance
- All components synergistic



## Current Limitations:

- **Memory Constraints:**

- Graphs must fit in aggregate memory
- No out-of-core support yet

- **Dynamic Graphs:**

- Edge insertions require repartitioning
- High cost for streaming updates

- **Fault Tolerance:**

- Checkpoint overhead: 5-8%
- Recovery time:  $O(n/k)$

- **Programming Model:**

- Limited to vertex-centric operations
- Complex graph patterns require workarounds

## Summary:

- Presented DEGO: distributed graph processing system
- Novel hybrid push-pull execution model
- Theoretical communication bound:  $O(\frac{c}{k} \cdot \log k)$
- Empirical results: 1.9x speedup over state-of-the-art
- 47% reduction in network traffic

## Contributions:

- 1 Adaptive execution model for distributed graphs
- 2 Improved communication complexity bound
- 3 Practical system with strong empirical performance

**Impact:** Enables processing of larger graphs on commodity clusters

## Planned Extensions:

- **Dynamic Graph Support:**

- Incremental partitioning algorithms
- Streaming edge processing

- **Heterogeneous Systems:**





- GPU acceleration for local computation
- Hybrid CPU-GPU execution

- **Advanced Algorithms:**

- Approximate graph mining
- Temporal graph analysis

- **Cloud Integration:**

- Elastic scaling on cloud platforms
- Cost-performance optimization

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**Thank you! Questions?**