

# Hypothesis testing 4

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## Outline:

- Recap (p-value, tests we learned)
- Type-1 and type-2 errors.
- Simple vs simple HT. Likelihood-ratio test. **Neyman-Pearson lemma**
- **Concept of power.**
- Most powerful tests. Unbiasedness.

## Definition

Statistical hypotheses:

- $H$  : data  $X_1, \dots, X_n$  distributed according to  $P \in \mathcal{C}_0$
- $K$  : data  $X_1, \dots, X_n$  distributed according to  $P \in \mathcal{C}_1$

where  $\mathcal{C}_0, \mathcal{C}_1$  are **COLLECTIONS OF DISTRIBUTIONS**.

Remarks:

- Find statistic  $T(X_1, \dots, X_n)$  with known dist. under  $H$
- Test:  $T > t_\alpha$  **REJECT**
- $t_\alpha$  is chosen depending on required **size**:

$$\max_{P \in \mathcal{C}_0} P[T > t_\alpha] \leq \alpha.$$

- Alternatively, report **p-value**: If  $T(x_1, \dots, x_n) = t_{obs}$

$$p = \max_{P \in \mathcal{C}_0} P[T > t_{obs}]$$

(aka “**probability of same or more extreme data under null**”)

## We learned:

- One-sample tests:
  - ① for mean of population:  $\mathbb{E}[X] = \mu_0$  vs  $\mathbb{E}[X] \neq \mu_0$
  - ② for other parameters:  $\theta \in \Theta_0$  vs  $\theta \notin \Theta_0$
  - ③ generalized likelihood-ratio test:  $X \sim \text{Uniform}$  vs  $X \sim \text{not Uniform}$
  - ④ testing normality:  $X \sim \mathcal{N}(0, 1)$  vs  $X \not\sim \mathcal{N}(0, 1)$
- Two-sample tests:
  - ① Equality of means:  $\mathbb{E}[X] = \mathbb{E}[Y]$  vs.  $\mathbb{E}[X] \neq \mathbb{E}[Y]$
  - ② Equality of distributions:  $P_X = P_Y$  vs.  $P_X \neq P_Y$
  - ③ Testing independence:  $X \perp\!\!\!\perp Y$  vs  $X \not\perp\!\!\!\perp Y$

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- **TODAY:** Only one more test (LRT).  
Of interest to: Bayesianists, theorists.

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# Curious asymmetry

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- **Best test:** whatever the data, always **ACCEPT** null
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- But if we are so worried about type-1 error only, why reject at all?
- **Best test:** whatever the data, always **ACCEPT** null
- What is bad about this test? **It has no power**
- ... i.e. cannot detect alternative even if billions of samples are given.



## Another mystery: Why we had $K$ ?



### Definition

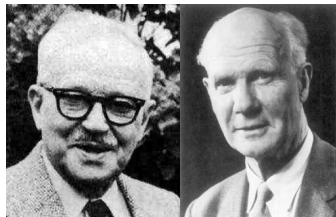
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- We only talked about behavior under  $H$ . Why do we even have  $K$ ?
- Fisher: We don't need to.
- Neyman-Pearson: need to control **power of test** to reject  $K$   
(i.e. need to know what aspects of  $H$  are tested)
- Concept of **power** complicated in general

## Easy (but important) special case

### Simple vs simple HT

- null  $H : X_i \stackrel{iid}{\sim} P_X$
- alt.  $K : X_i \stackrel{iid}{\sim} Q_X$
- ...  $P_X$  and  $Q_X$  are known fixed distributions over some  $\mathcal{X}$

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- When  $|\mathcal{C}_0| = 1$  we say **null hypothesis is simple**
  - When  $|\mathcal{C}_1| = 1$  we say **alt. hypothesis is simple**
  - ... so here we have **simple vs. simple** HT

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- Any test is an algorithm

*if  $(X_1, \dots, X_n) \in E$  then **REJECT** null.*

So each **set**  $E \subset \mathcal{X}^n$  determines a **different test**

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So each set  $E \subset \mathcal{X}^n$  determines a different test

- How good is a given  $E$ ? Need to compute 2x2 table:

	$H$ true	$K$ true
Test rejects	$\alpha$	$\beta$
Test accepts	$1 - \alpha$	$1 - \beta$

- Type-1 error =  $\alpha$ . Type-2 error =  $1 - \beta$ .

# Example

- Suppose  $\mathcal{X} = \{1, \dots, 6\}$ .
- Under null we have a fair die:  $X \stackrel{iid}{\sim} P_X = [\frac{1}{6}, \frac{1}{6}, \frac{1}{6}, \frac{1}{6}, \frac{1}{6}, \frac{1}{6}]$
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$n = 1$		
	$H$ true	$K$ true
Test rejects	0.5	0.67
Test accepts	0.5	0.33

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Test rejects	0.42	0.67
Test accepts	0.58	0.33

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$n = 10$

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Test rejects	0.32	0.71
Test accepts	0.68	0.29

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Test accepts	0.85	0.13

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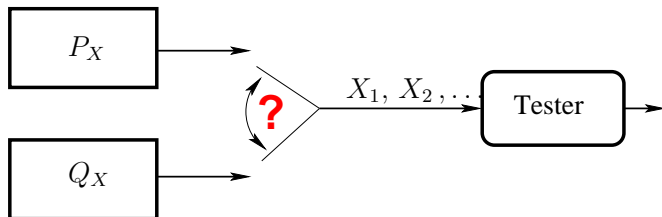
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- **Next:** How do we find better (and less ad hoc) tests?

## Easy case: Two simple hypotheses

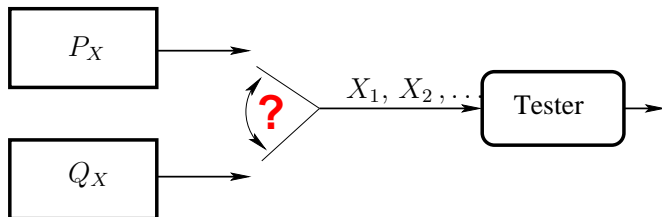


- Return to general case. Test = rejection set  $E \subset \mathcal{X}^n$
- For each test:

$$\text{size} = \alpha \triangleq \mathbb{P}[\text{REJECT}]$$

$$\text{power} = \beta \triangleq \mathbb{Q}[\text{REJECT}]$$

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- if tests never rejects:  $\alpha = 0, \beta = 0$  (i.e.  $E = \emptyset$ )
- randomized test: reject w.p.  $\alpha$  w/o looking at the data:  $\beta = \alpha$
- Best tradeoff?

Solve binary HT  $\iff$  maximize  $\beta$  subject to  $\alpha$

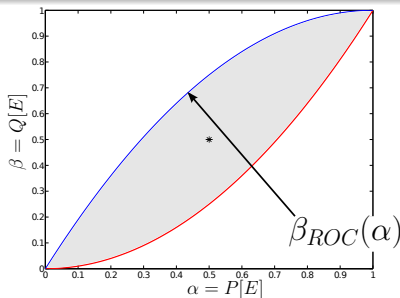
# Neyman-Pearson's ROC curve

## Definition

Let  $P$  and  $Q$  be distributions of  $(X_1, \dots, X_n)$  under null and alt. Then ROC-curve is

$$\beta_{ROC}(\alpha) \triangleq \max_{E: P[E] \leq \alpha} Q[E].$$

iterate over  
all “sets”  $E$   
 $\Rightarrow$   
plot pairs  $(P[E], Q[E])$



- **Meaning:**  $\beta_{ROC}(\alpha)$  = power of best size- $\alpha$  test.
- $\alpha$  = false-positive rate,  $\beta$  = true-positive rate
- Later: in logistic regression and binary classification.

# How to compute $\beta(\alpha)$ ?

## Theorem (Neyman-Pearson)

*Fix any  $0 \leq \gamma \leq +\infty$ . Consider the test*

$$E = \left\{ X : \frac{P(X)}{Q(X)} \leq \gamma \right\}$$

*It achieves  $\alpha = P[E]$  and  $\beta = Q[E]$  that belong to the boundary curve  $\beta_{ROC}(\alpha)$ . As  $\gamma$  varies these tests trace all of  $\beta_{ROC}(\alpha)$ .*

- Thus, likelihood-ratio tests are **OPTIMAL**. For iid data:

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## Optimal test for simple HT

$$T = - \sum_{i=1}^n \log \frac{P(X_i)}{Q(X_i)}$$

If  $T \geq t$  **REJECT**

- Selecting threshold: use simulations or normal approximation ( $\mathbb{E}[T] = nD(P||Q)$ ,  $\text{Var}[T] = \dots$ )

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- Stein's lemma:  $\beta(\alpha) = e^{-nD(P\|Q)+o(n)}$

# Example: Detection in communication systems

## Binary detection in Gaussian noise

- Null  $H$ :  $X_i \sim \mathcal{N}(0, 1)$  (white noise)
  - Alt  $K$ :  $X_i \sim \mathcal{N}(a_i, 1)$  (signal + noise)
  - Goal: decide between the two
- 
- Write-down LLR:

$$T = - \sum_i \log \frac{P(X_i)}{Q(X_i)} = C + \sum_{i=1}^n a_i x_i = C + \mathbf{a} \cdot \mathbf{x}$$

where  $C$  is some constant, indep. of  $\mathbf{x}$ . So take  $C = 0$ .



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- Under null:  $T \sim \mathcal{N}(0, \|\mathbf{a}\|^2)$ .

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- Under null:  $T \sim \mathcal{N}(0, \|\mathbf{a}\|^2)$ . Under alt.:  $T \sim \mathcal{N}(\|\mathbf{a}\|^2, \|\mathbf{a}\|^2)$
- Thus, optimal decoder is:

$$\frac{\mathbf{a} \cdot \mathbf{x}}{\|\mathbf{a}\|} > z_\alpha \quad \Rightarrow \quad \text{DETECT ALARM}$$

- Its ROC curve – see PSET.

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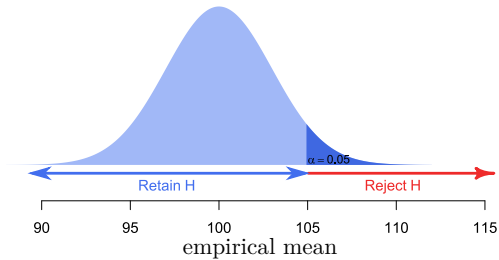
where  $C$  is some constant, indep. of  $\mathbf{x}$ . So take  $C = 0$ .

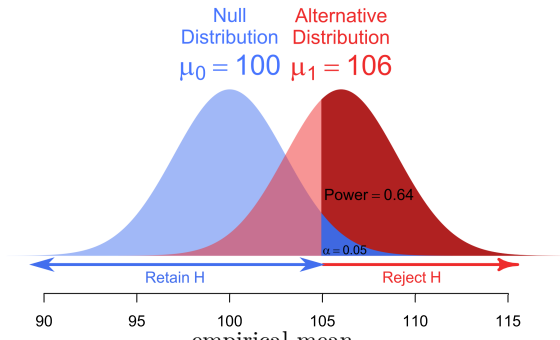
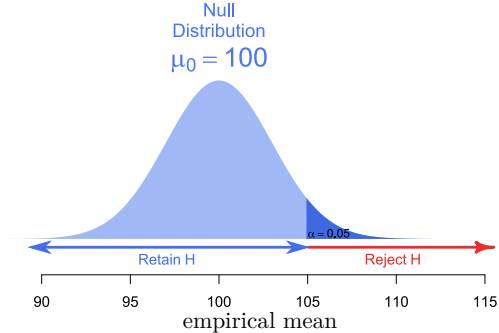
- Under null:  $T \sim \mathcal{N}(0, \|\mathbf{a}\|^2)$ . Under alt.:  $T \sim \mathcal{N}(\|\mathbf{a}\|^2, \|\mathbf{a}\|^2)$
- Thus, optimal decoder is:

$$\frac{\mathbf{a} \cdot \mathbf{x}}{\|\mathbf{a}\|} > z_\alpha \quad \Rightarrow \quad \text{DETECT ALARM}$$

- Its ROC curve – see PSET.
- Pictorially, distribution of  $T$  is...

Null  
Distribution  
 $\mu_0 = 100$





# General definition of power

## Definition

Statistical hypotheses:

- $H$  : data  $X_1, \dots, X_n$  distributed according to  $P \in \mathcal{C}_0$
- $K$  : data  $X_1, \dots, X_n$  distributed according to  $P \in \mathcal{C}_1$
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- Let's illustrate on example of parametric tests

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- Have a good parametric model  $X \stackrel{iid}{\sim} P_\theta$  (e.g.  $X \sim \text{Ber}(\theta)$ )

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$$W = \frac{\hat{\theta} - \theta_0}{\widehat{se}}$$

$\hat{\theta}$  = parameter estimator (eg. MLE),  
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- **Once threshold is fixed** can compute **power  $\beta(\theta)$**  as a function of  $\theta$

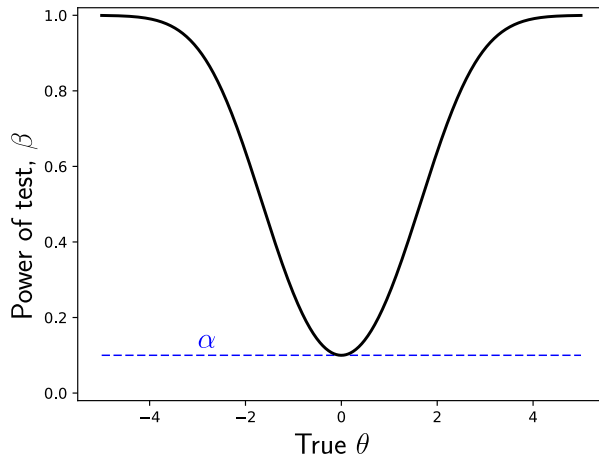
# Illustration of power behavior

**Open:** `figs/zEffectSize.gif` in browser

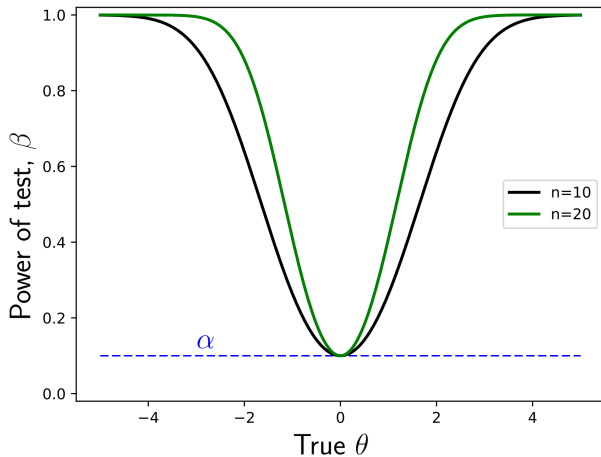
Orig. URL:

<http://my.ilstu.edu/~wjschne/138/Psychology138Lab14.html>

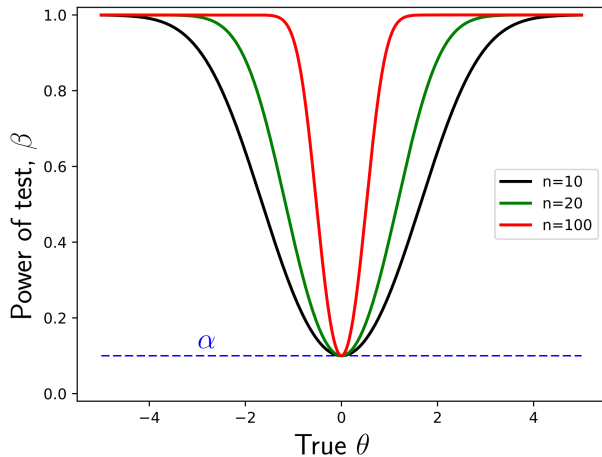
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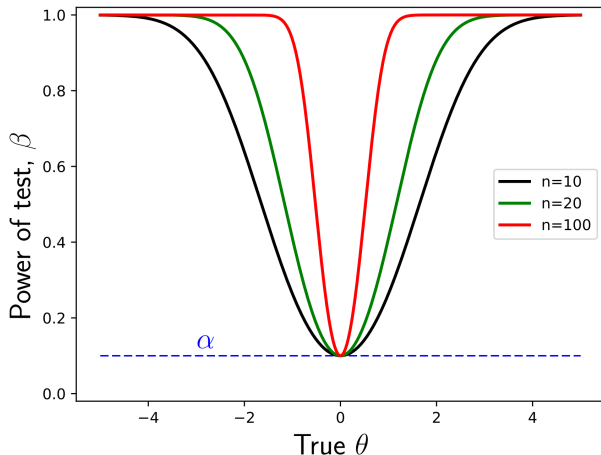


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# Power as a function of $\theta$ ... and number of samples



- Tests need to be properly **powered**
- expert (doctor/engineer/etc) needs to specify resolution of  $\theta$
- statistician determines # of samples required to resolve 0 from  $\neq 0$ .

## Example of under-powered test

*H: Rain in Seattle is iid w.p. 1/2 everyday*

- $\mu_0 = 1/2$ ,  $\sigma_0^2 = 1/4$ . Test of size  $\alpha = 0.05$  will be:

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Test: **sometimes reject sometimes accept**

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- $n = 1000$ , got  $Z$ -scores:

$$Z = -5.76, -2.72, -3.29, -3.92, -4.42$$

Test: **reject null (always)**

(FYI: over 1948-2017  $\hat{P}[\text{rain}] = 42.6\%$

**$\leftarrow \text{TRUE } \theta$** )

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# Comparing tests

- We now want to see how tests compare.
- The general idea:
  - ▶ Consider two tests (e.g.  $z$ -test vs  $G$ -test)
  - ▶ Choose thresholds in both so that size= $\alpha$
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- Hard task in general. So let us consider very toy (parametric) models.



# Gaussian location model

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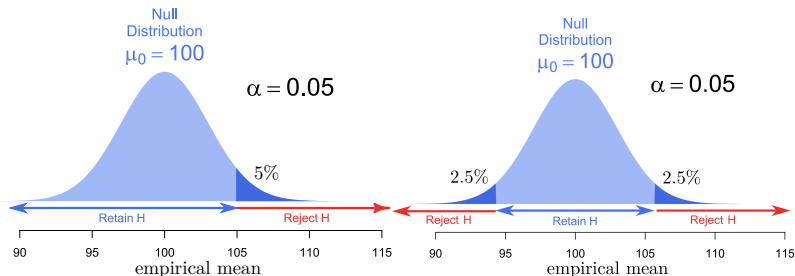
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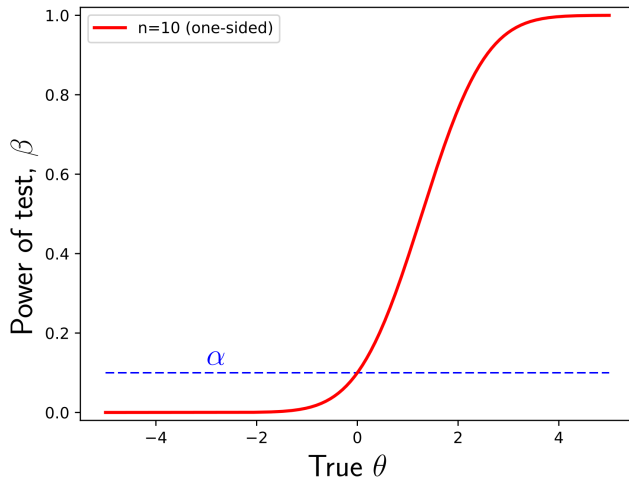
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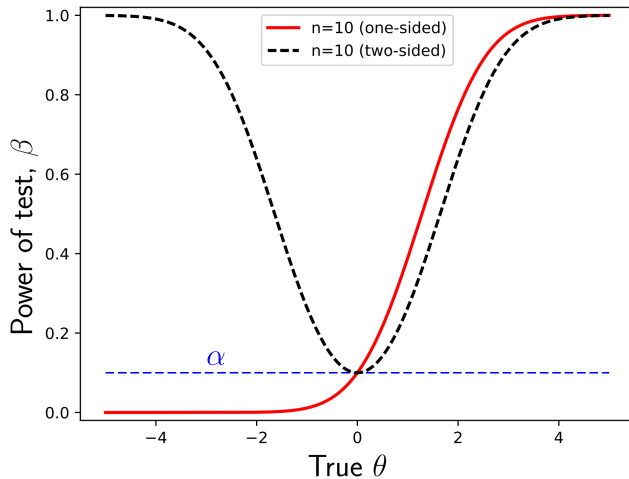


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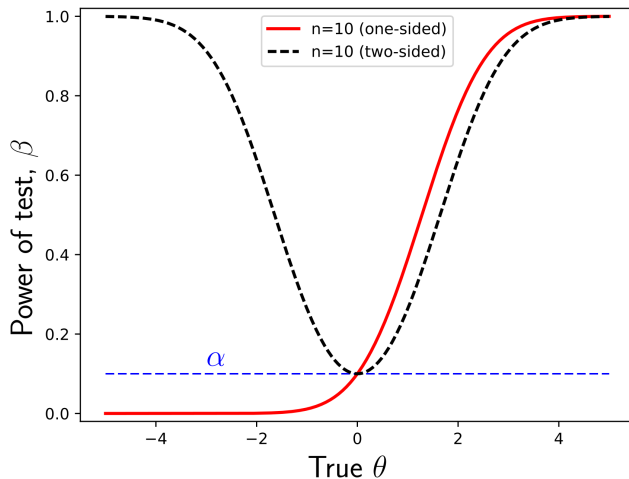




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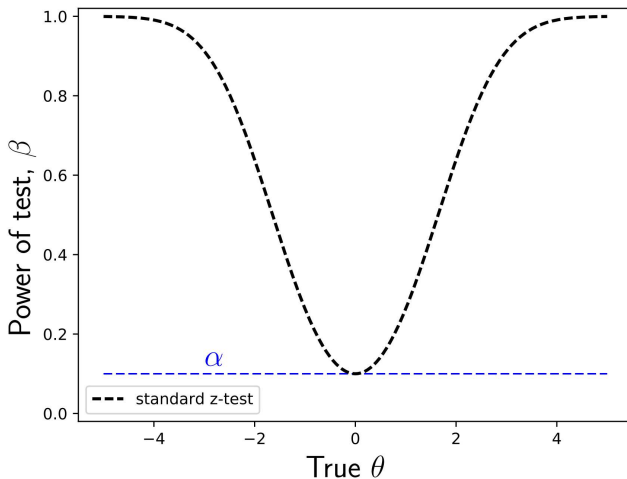
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- **Punchline:** Since  $\theta \geq 0$  by assumption, one-sided test is strictly better.

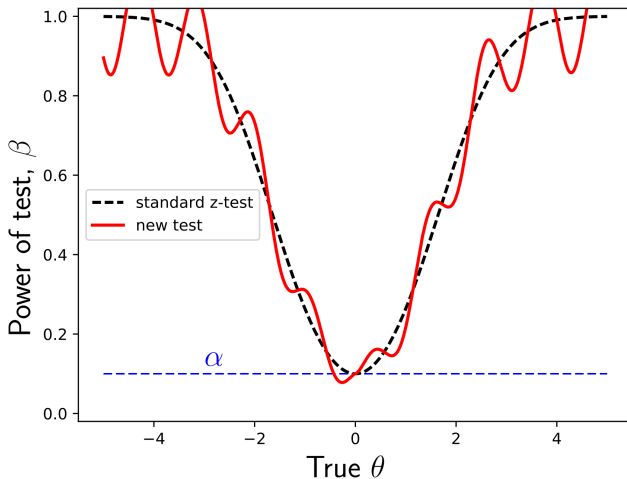
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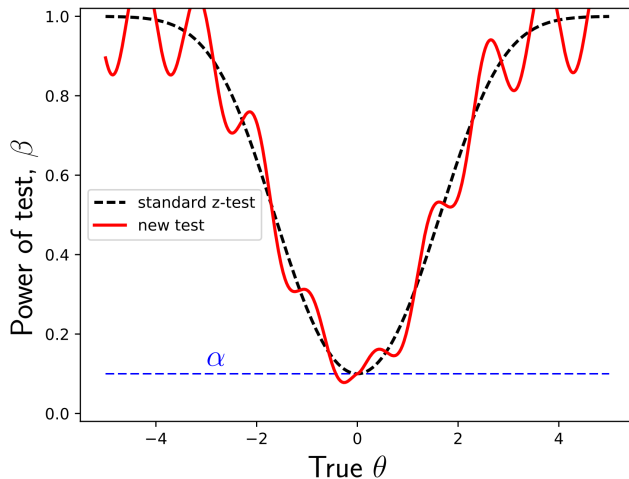
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- MIT student proposes a new test. Is it better than standard?
- Is test size  $\alpha$ ? Yes. Is it better than the standard? Hmm...

# The (doomed) quest for optimality

- Consider two size- $\alpha$  tests  $T$  and  $T'$  with powers  $\beta_T(\theta)$  and  $\beta_{T'}(\theta)$ .
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- **Sadly**: Most of the time it does not exist.
- ... That is why HT is an art and many hundreds of tests exist.
- However, in special cases they do exist:
  - ▶ One-sided GLM: UMP exists
  - ▶ Two-sided GLM: no UMP, but  $\exists$  UMP-unbiased (**UMPU**)
  - ▶ A list of UMPU

## Bayesian resolution of “optimal test” problem

- Recall: Bayesianist has a prior for everything
- So he says: **Under null  $H$ , data is generated as:**
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- **Pros:** always have some test. **Cons:** hard to find good priors

**Next topic:** Examples of optimal tests for frequentists.

# One-sided GLM test

- Setting:

- ▶  $X \stackrel{iid}{\sim} \mathcal{N}(\theta, 1)$

- ▶ known-variance, Gaussian location model

$$H : \theta = 0 \quad \text{vs.} \quad K : \theta > 0 \quad (\text{one-sided})$$

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- Neyman-Pearson's lemma: log-likelihood is optimal:

$$\begin{aligned} \tilde{T}_a(x_1, \dots, x_n) &= - \sum_{i=1}^n \log \frac{P_{X|\theta=0}(x_i)}{P_{X|\theta=a}(x_i)} \\ &= (na)\bar{x}_n - na^2 \end{aligned}$$

# One-sided GLM test

- Setting:

- $X \stackrel{iid}{\sim} \mathcal{N}(\theta, 1)$

- known-variance, Gaussian location model

$$H : \theta = 0 \quad \text{vs.} \quad K : \theta > 0 \quad (\text{one-sided})$$

- Test is size- $\alpha$  iff  $\beta(0) \leq \alpha$

- Side problem: What is the best test for  $\theta = 0$  vs.  $\theta = a$ ?

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- Select threshold:  $P[(na)\bar{X}_n - na^2 > t | \theta = 0] = \alpha$

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$$\sqrt{n}\bar{X}_n \geq \Phi^{-1}(1 - \alpha) \quad \Rightarrow \quad \text{REJECT}$$

where  $\Phi^{-1}(q) = q$ -th quantile of  $\mathcal{N}(0, 1)$ .

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**MAGIC:** Rule does not depend on  $a$

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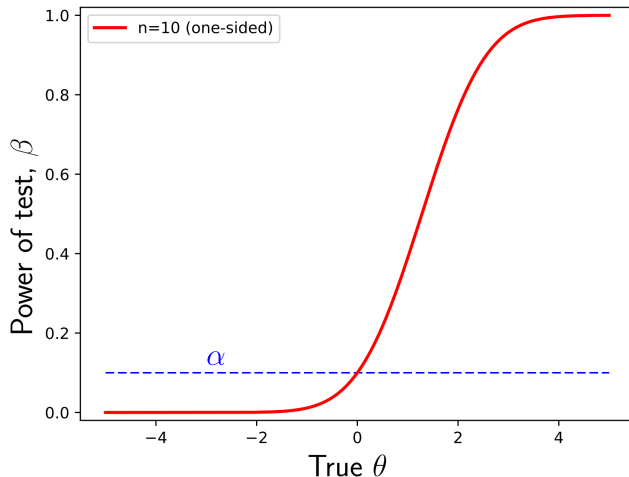
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# One-sided GLM test is UMP

$$H : \theta = 0 \quad \text{vs.} \quad K : \theta > 0$$



**Punchline:** one-sided  $z$ -test is unique most-powerful test.



# Two-sided GLM test

- Setting:

- ▶  $X \stackrel{iid}{\sim} \mathcal{N}(\theta, 1)$
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$$H : \theta = 0 \quad \text{vs.} \quad K : \theta \neq 0 \quad (\text{one-sided})$$

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- So there is no one rule to dominate them. No magic.
- What should we do?

## Definition (Unbiased tests)

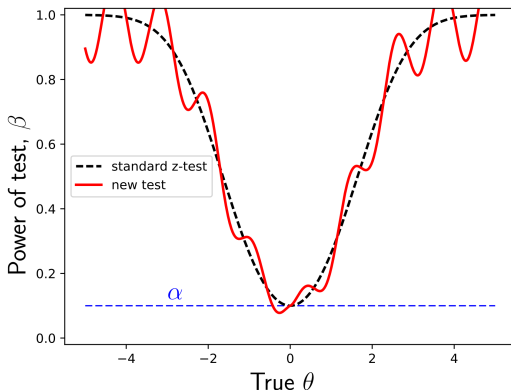
A **size- $\alpha$**  test  $T$  is unbiased if  $\beta(\theta) \geq \alpha \quad \forall \theta \in K$

- **Important:** unbiasedness of  $T$  depends on **both  $H$  and  $K$**
- Aka “test does not treat some  $\theta \in K$  more favorably than  $\theta \in H$ ”

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- Aka “test does not treat some  $\theta \in K$  more favorably than  $\theta \in H$ ”
- Examples: **black** – unbiased, **red** – biased.



# Best unbiased tests (UMPU)

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- ▶ **known-variance, Gaussian location model (GLM)**

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- We have seen, no most powerful test exist
- But there exists most powerful test among all unbiased.

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- We have seen, no most powerful test exist
- But there exists most powerful test among all unbiased.
- No surprise: it is our friend  **$z$ -test**
- ... it is **unique** such test! (aka **UMPU**).

# Best unbiased tests (UMPU)

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Other examples of **UMPUs**:

- One-sample tests:  $(X \stackrel{iid}{\sim} \mathcal{N}(\mu_X, \sigma_X^2))$ 
  - ▶ unknown-variance, one-sided:  $\mu_X = 0$  vs  $\mu_X > 0$
  - ▶ unknown-variance, two-sided:  $\mu_X = 0$  vs  $\mu_X \neq 0$UMPU:  **$t$ -test** (with threshold from Student- $t$ )
- Two-sample tests:  $(X, Y \stackrel{iid}{\sim} \mathcal{N})$ 
  - ▶ unknown variance,  $\sigma_X = \sigma_Y$  two-sided:  $\mu_X = \mu_Y$  vs  $\mu_X \neq \mu_Y$
  - ▶ unknown variance,  $\sigma_X = \sigma_Y$  one-sided:  $\mu_X = \mu_Y$  vs  $\mu_X > \mu_Y$UMPU: **two-sample  $t$ -test (pooled variance)**
- ▶ unknown-variance,  $\sigma_X \neq \sigma_Y$ .  
UMPU: **???** (Behrens-Fisher problem)