

RESEARCH SCIENTIST · SOFTWARE ENGINEER

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Education

Ph.D. in Computer Science

Tübingen, Germany

University of Tübingen

11/2019-10/2023 (expected)

• Thesis: Differentiable Trust Region Projection Layers for Deep Reinforcement Learning

• Advisor: Gerhard Neumann

M.Sc. in Computer Science (with distinction), Minor in Psychology

Darmstadt, Germany

TECHNICAL UNIVERSITY OF DARMSTADT

10/2017-10/2019

• GPA: 1.0 (on a scale of 1-5, with 1 being the highest score)

· Honors & Awards: ECTS A Ranking; Germany Scholarship; Schaeffler Top Student Scholarship

• Thesis: Deep Demand Management

B.Sc. in Business Information Systems – Software Engineering

Mannheim, Germany

10/2014-09/2017

BADEN-WÜRTTEMBERG COOPERATIVE STATE UNIVERSITY

• GPA: 1.4 (on a scale of 1-5, with 1 being the highest score)

· Honors & Awards: ECTS A Ranking

Research Experience

Graduate Research Assistant

Tübingen, Germany

University of Tübingen & Bosch Center for Artificial Intelligence

11/2019-Present

- Developed novel trust region methods for deep reinforcement learning in PyTorch comparing to baselines, such as PPO, SAC, TD3, and MPO, on MuJoCo tasks.
- Integrated **movement primitives** into deep reinforcement learning to combine benefits of **episode-based** and **step-based** reinforcement learning, especially for scenarios with **sparse** and **non-Markovian** rewards.

Research Assistant Darmstadt, Germany

TECHNICAL UNIVERSITY OF DARMSTADT

10/2017-09/2019

- Jan Peters' lab: Implemented and evaluated reinforcement learning algorithms, such as **DQN**, **A3C**, and **PILCO**, in **PyTorch**, for **simulation** and **physical** robotic systems.
- Kristian Kersting's lab: Utilized **TensorFlow** to implement the **PixelNet** architecture for **semantic segmentation** of the city scenes dataset.
- Kristian Kersting's lab: Employed CRFs and HMMs to accurately classify POS tags and named entities in the Groningen Meaning Bank.
- Iryna Gurevych's lab: Developed a system to classify tweet authorship using random forests and deep approaches with GloVe embeddings.

Research Intern: Animal Biometrics

Darmstadt, Germany

FRAUNHOFER INSTITUTE FOR COMPUTER GRAPHICS RESEARCH

04/2018-09/2018

- Implemented ResNet and RetinaNet in TensorFlow for classifying individual animals and species in low-quality camera trap images.
- Reduced biologists' workload by eliminating the need to review approximately 90% of the images, enabling them to focus on relevant cases, aiding wildlife conservation efforts and ecological research.

Occupational Experience _

Data Scientist (Part-time)/Top Student Scholarship

Langen, Germany

SCHAEFFLER GROUP

10/2017-10/2019

- Recognized as exceptional dual student, selected for Schaeffler's Top Student Scholarship, pursuing a master's degree and working part-time.
- Conducted a comprehensive evaluation of **traditional**, **deep learning**, and **hybrid** approaches to enhance **demand forecasting**. Successfully **improved forecast quality by 30%** compared to the existing system.
- Played a key role in strategizing and optimizing the intricate data landscape to elevate analytics capabilities and unlock valuable insights.

Dual StudentHerzogenaurach, Germany

Schaeffler Group

10/2014-09/2017

- Designed and implemented a **user-friendly graphical editor**, streamlining configuration management for production machines. Part of a system that was recognized with the *German Design Award 2023 "Special Mention"*.
- · Led the development of a global document security concept, ensuring the protection and integrity of sensitive information.
- Provided instrumental support to **project management** in the successful rollout of an SAP system. Collaborated with **cross-functional teams**, ensuring smooth and timely **communication**, as well as efficient **issue resolution**. Contributed to system configuration, **user training**, and facilitated a seamless transition, maximizing the utilization of the SAP system.
- Engineered a data mapping tool with Java, optimizing the loading process of CAD models, saving approximately 10 minutes per model loaded.

SCHAEFFLER TRANSMISSION, LLC 05/2016-08/2016

- Assessed the reliability of the site's network infrastructure and the potential repercussions along the supply chain in the event of an outage.
- Identified critical dependencies and vulnerabilities, enabling proactive risk management and continuity planning to mitigate downtime risks.

Publications

- Fabian Otto*, Hongyi Zhou*, Onur Celik, Ge Li, Rudolf Lioutikov, and Gerhard Neumann. "MP3: Movement Primitive-Based (Re-) Planning Policy". Under submission. 2023.
- Philipp Becker, Sebastian Markgraf, Fabian Otto, and Gerhard Neumann. "Reinforcement Learning from Multiple Sensors via Joint [2] Representations". Under submission. 2023.
- Ge Li, Zeqi Jin, Michael Volpp, Fabian Otto, Rudolf Lioutikov, and Gerhard Neumann. "ProDMP: A Unified Perspective on Dynamic and Probabilistic Movement Primitives". In: IEEE Robotics and Automation Letters (RA-L)/International Conference on Intelligent Robots and Systems (IROS) 8.4 (2023), pp. 2325–2332.
- Fabian Otto, Onur Celik, Hongyi Zhou, Hanna Ziesche, Vien Anh Ngo, and Gerhard Neumann. "Deep Black-Box Reinforcement Learning with Movement Primitives". In: Conference on Robot Learning (CoRL). PMLR. 2022, pp. 1244–1265.
- Fabian Otto, Philipp Becker, Ngo Anh Vien, Hanna Ziesche, and Gerhard Neumann. "Differentiable Trust Region Layers for Deep Reinforcement Learning". In: International Conference on Learning Representations (ICLR). 2021.
- Fabian Otto. "Model-Free Deep Reinforcement Learning Algorithms and Applications". In: Reinforcement Learning Algorithms: Analysis and Applications. Ed. by Boris Belousov, Hany Abdulsamad, Pascal Klink, Simone Parisi, and Jan Peters. Springer Cham: Springer International Publishing, 2021, pp. 109–121. ISBN: 978-3-030-41188-6.

Teaching Experience _____

Student Supervision Tübingen, Germany

University of Tübingen & Karlsruhe Institute of Technology	
• "Air HocKIT" student team: NeurIPS 2023 Competition Track: Robot Air Hockey Challenge (Intern)	04/2023-today
• Leonhard Kraft: Deep Black-Box Reinforcement Learning with Movement Primitives on Infinite-Horizon Problems (B.Sc.)	05/2023-today
Moritz Behr: Deep Black-Box Reinforcement Learning with NeRFs (M.Sc.)	11/2022-today
• Dhimiter Pikuli: Learning Complex Robot Arm Manipulations with Deep Reinforcement Learning (M.Sc., Intern)	09/2022-03/2023
• Dominik Roth: Exploration Strategies in Step-Based Deep Reinforcement Learning (B.Sc., 3x Intern)	08/2022-11/2022
Denis Megerle: Stable Optimization of Gaussian Likelihoods (M.Sc.)	03/2022-09/2022
Ahmed Agha: Improved Trust Regions for Adversarial Imitation Learning (M.Sc.)	03/2021-09/2022
Ricardo Dominguez: Action Correlations for Deep Reinforcement Learning (2x Intern)	06/2021-02/2022

Community Service _____

Workshop Organization

- IROS 2023: Policy Learning in Geometric Spaces (Main Organizer)
- CoRL 2022: Geometry, Physics, and Human Knowledge as Inductive Bias in Robot Learning (Main Organizer)

Reviewing

- Conference on Neural Information Processing Systems (NeurIPS)
- International Conference on Machine Learning (ICML)
- Conference on Robot Learning (CoRL)
- IEEE International Conference on Robotics and Automation (ICRA)
- IEEE Robotics and Automation Letters (RA-L)
- · Springer Nature, Machine Learning

Open Source Contributions

• Farama Foundation: Contributions to Shimmy and Meta-World

Skills

Language German (native), English (fluent)

Machine Learning Gymnasium, MuJoCo, Numpy, Pandas, Pytorch, Scipy, Tensorflow

Software Engineering Docker, Git, Java, Jira, Jupyter, Kafka, LSF, Optuna, Slurm, Spark, SQL, Unitest

Other MTFX, Linux-Ubuntu, Microsoft Office