

Multi-agent learning

Conditional Regret

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Conditional regret: example

Shapley's game:

$$G = \begin{array}{c|ccc} & R & Y & B \\ \hline R & (1,0) & (0,0) & (0,1) \\ Y & (0,1) & (1,0) & (0,0) \\ B & (0,0) & (0,1) & (1,0) \end{array}$$

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Rounds: 1 2 3 4 5 6 7 8 9 10

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Action row:	<i>R</i>	<i>R</i>	<i>B</i>	<i>B</i>	<i>B</i>	<i>Y</i>	<i>Y</i>	<i>R</i>	<i>Y</i>	<i>R</i>
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Better for row to play *R* in the three periods where he actually played *Y*?

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■ Actual payoff *Y*: 3×0

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Better for row to play *R* in the three periods where he actually played *Y*?

- Actual payoff *Y*: 3×0
- Hypothetical payoff *R*: 3×1 .
- Average regret: $(3 - 0)/10$.

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- Average regret: $(3 - 0)/10$.

The complete conditional regret matrix is:

$$\mathbf{R} = \begin{matrix} & \begin{matrix} R & Y & B \end{matrix} \\ \begin{matrix} R \\ Y \\ B \end{matrix} & \begin{pmatrix} 0.0 & 0.1 & 0.0 \\ 0.3 & 0.0 & 0.0 \\ -0.1 & 0.1 & 0.0 \end{pmatrix} \end{matrix}$$

Row: original actions;
column: alternative actions.

Conditional regret matrix

The conditional regret matrix at time t is

$$R^t(\omega) =_{Def} \begin{pmatrix} (u(1, y^t) - u(1, y^t))e_1^t & \dots & (u(k, y^t) - u(1, y^t))e_1^t \\ \vdots & \ddots & \vdots \\ (u(1, y^t) - u(k, y^t))e_k^t & \dots & (u(k, y^t) - u(k, y^t))e_k^t \end{pmatrix}$$

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The player's conditional regrets through time t are given by the average of the R^t 's:

$$\bar{R}^t =_{Def} \frac{1}{t} \sum_{s=1}^t R^s.$$

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- Both \bar{R}^t and \bar{R}^t have zeros on the diagonal.
- The average conditional regret vector at time t , \bar{r}^t , is just the sum of the columns of \bar{R}^t .

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- Let V be the vector-valued payoff matrix for the row player.
- Consider a set of, for row, **desirable payoffs** $C \subseteq \mathbb{R}^m$.
- If the row player has a strategy $\sigma : H \rightarrow \Delta(X)$ such that

$$\lim_{t \rightarrow \infty} d(\bar{v}^t, C) = 0 \quad \text{a.s.}$$

then C is said to be **approachable**.

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■ Suppose for some $q^N \in \Delta(Y)$ and some $\delta > 0$ we have $\mathbf{W}q^N \geq (\delta, \dots, \delta)$.

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■ By the strong law of large numbers for dependent r.v.'s

$$\lim_{t \rightarrow \infty} \bar{v}^t \cdot \alpha \geq \delta \text{ a.s.}$$

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■ Then immediately (by def. of expectation): $E[v \cdot \alpha] \geq \delta$.

■ By the strong law of large numbers for dependent r.v.'s

$$\lim_{t \rightarrow \infty} \bar{v}^t \cdot \alpha \geq \delta \text{ a.s.}$$

■ By definition of C we have $\lim_{t \rightarrow \infty} d(\bar{v}^t, C) \geq \delta$ a.s.

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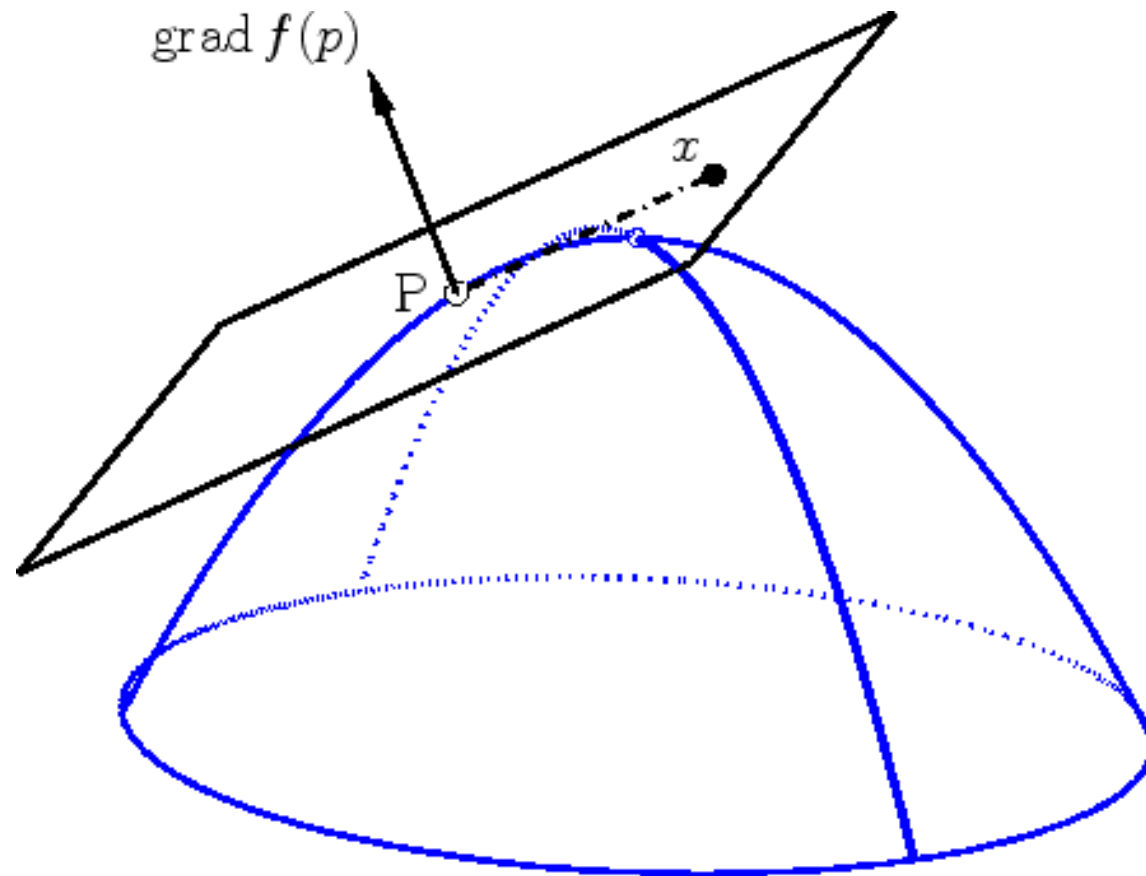
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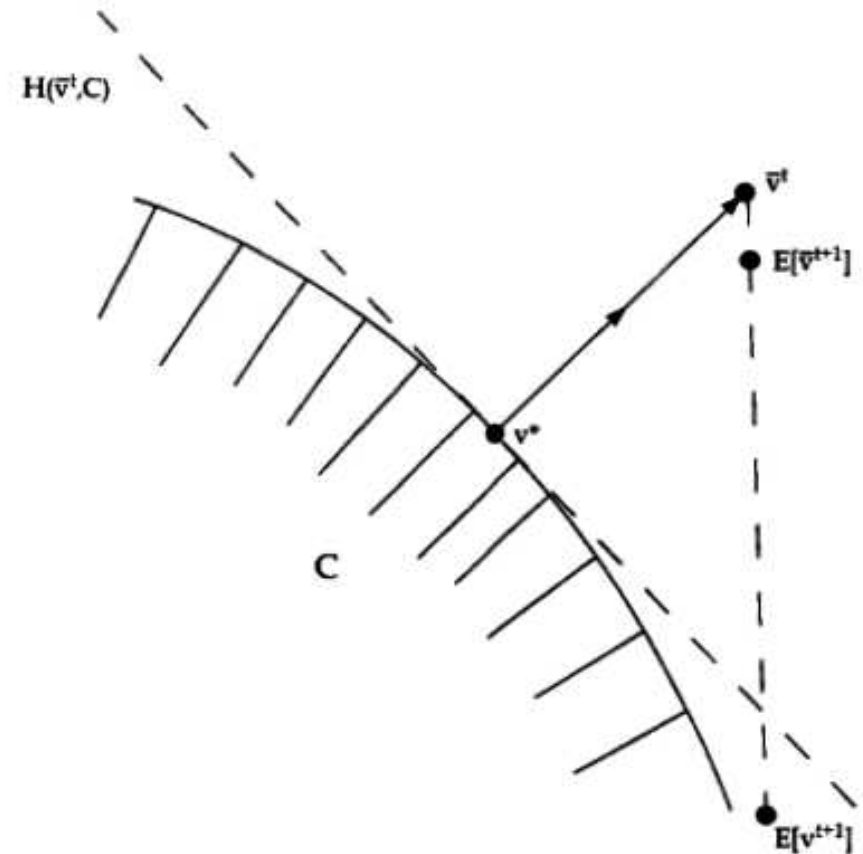
Tangent plane

Blackwell's theorem make use of the concept of **tangent plane**:



Blackwell's theorem

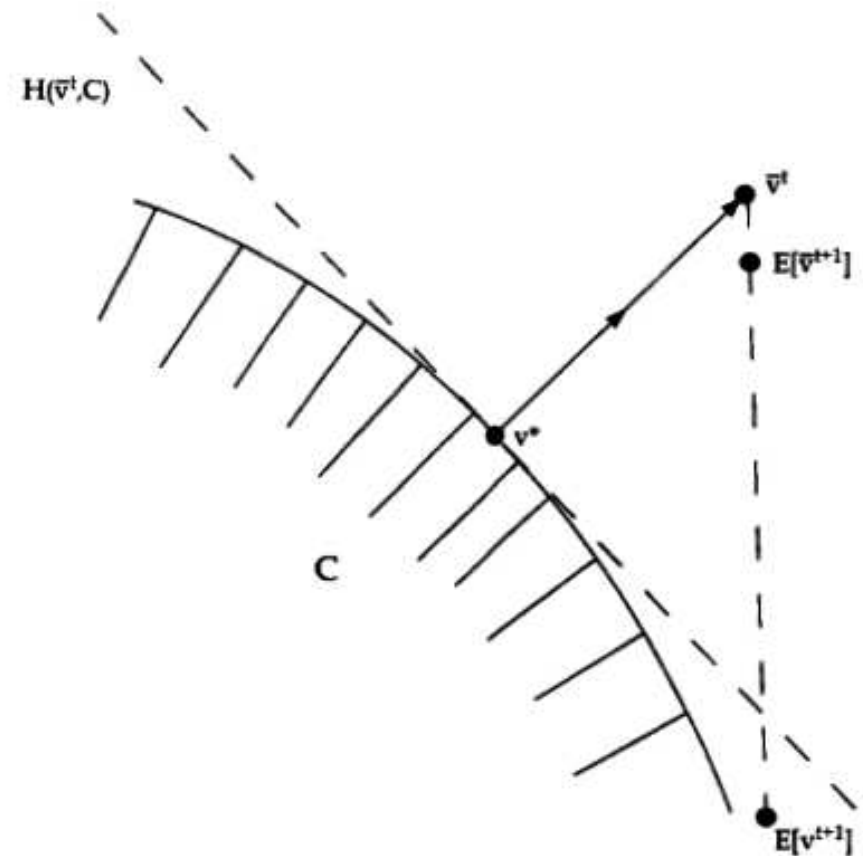
Theorem (Blackwell, 1956) Let G be a finite two-player game with payoffs in \mathbb{R}^m . A closed non-empty convex set C in \mathbb{R}^m is approachable by the row player if and only if every tangent half-space containing C is approachable.



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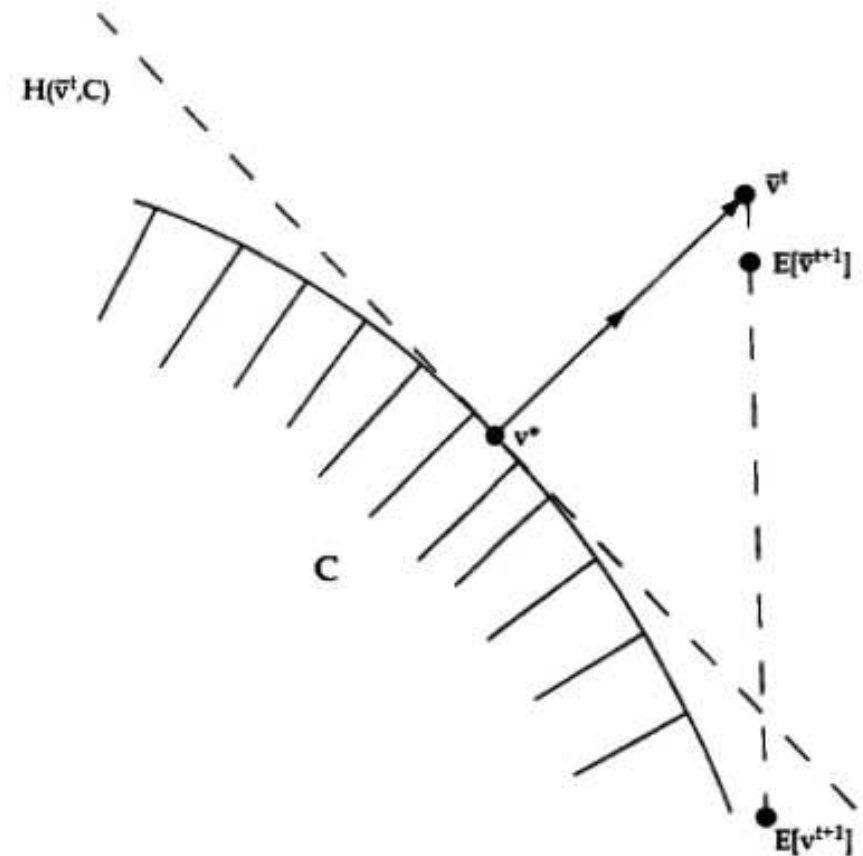
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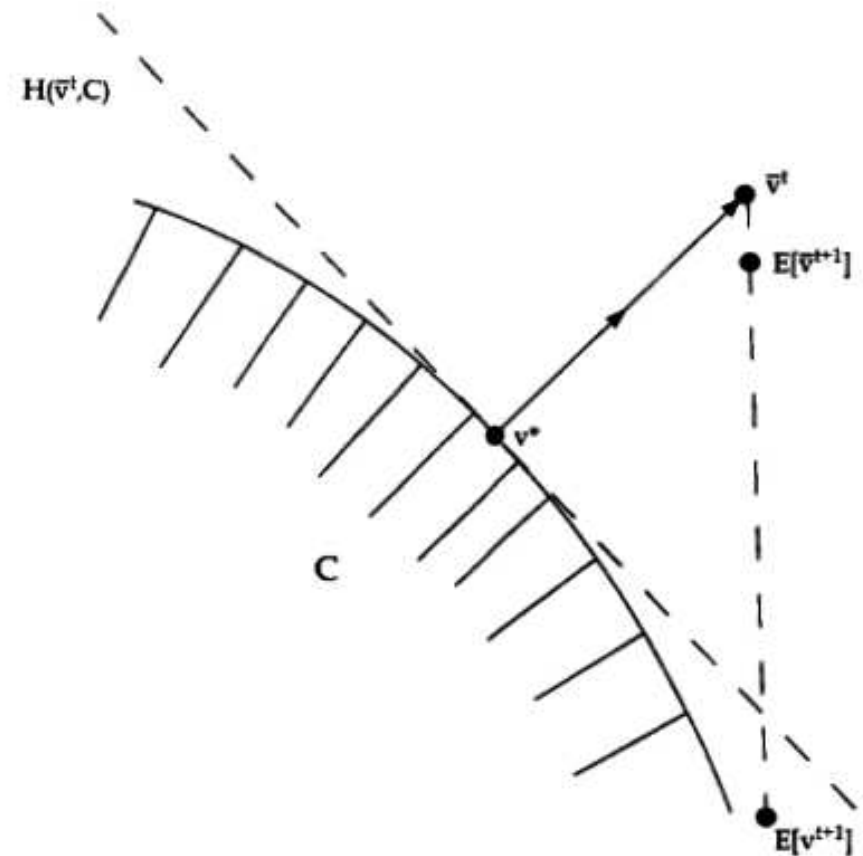
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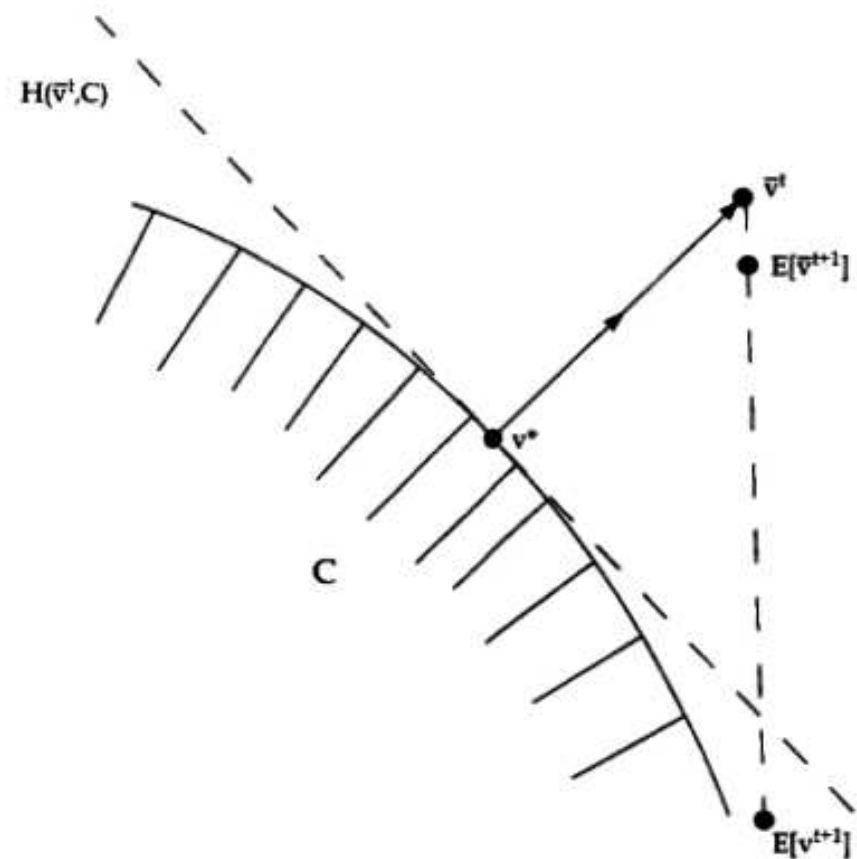
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Eliminating regret

(Result left hanging in Ch. 2)

Eliminating regret

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We now have a vector-valued game.

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- Suppose $\bar{r}^t \notin C$. Then the closest point in C is \bar{r}_-^t .
- Blackwell: randomise play such that $E[r^{t+1}] \perp (\bar{r}^t - \bar{r}_-^t)$, so $E[r^{t+1}] \perp \bar{r}_+^t$.

Eliminating regret

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So take $q^T \sim \bar{r}_+^t$, i.e., take q^T proportional to \bar{r}_+^t .

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- The problem boils down to ensure that, for every $1 \leq j \leq k$:

$$\sum_h q_h (\bar{r}_{hj})_+ - q_j \sum_h (\bar{r}_{jh})_+ = 0. \quad (2)$$

Eliminating conditional regret

- The expected incremental conditional regret matrix is $\mathbf{QA} = \mathbf{Q}(\mathbf{P} - \mathbf{P}^T)$.
- Blackwell's theorem tells us to choose \mathbf{Q} such that

$$(\mathbf{QA}) \cdot \bar{\mathbf{R}}_+ = 0.$$

Here, “ \cdot ” is the dot-product of two matrices in $\mathbb{R}^k \times \mathbb{R}^k$, not their matrix product.

- Since \mathbf{Q} and \mathbf{A} commute (check), we have

$$(\mathbf{QA}) \cdot \bar{\mathbf{R}}_+ = \mathbf{A} \cdot (\mathbf{Q}\bar{\mathbf{R}}_+) = (\mathbf{P} - \mathbf{P}^T) \cdot (\mathbf{Q}\bar{\mathbf{R}}_+) = \mathbf{P} \cdot (\mathbf{Q}\bar{\mathbf{R}}_+) - \mathbf{P}^T \cdot (\mathbf{Q}\bar{\mathbf{R}}_+).$$

- The problem boils down to ensure that, for every $1 \leq j \leq k$:

$$\sum_h q_h (\bar{r}_{hj})_+ - q_j \sum_h (\bar{r}_{jh})_+ = 0. \quad (2)$$

- Every q satisfying this equation is called a **left-invariant** for $\bar{\mathbf{R}}_+$.

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$$\begin{pmatrix} -\sum_j m_{1j} & m_{12} & \dots & m_{1k} \\ m_{21} & -\sum_j m_{2j} & \dots & m_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ m_{k1} & \dots & m_{2k} - \sum_j m_{kj} \end{pmatrix}$$

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- Let β be as least as large as the absolute value of the most negative of the diagonal elements in \mathbf{M} . Then

$$\mathbf{I} + \frac{1}{\beta}\mathbf{N}$$

is non-negative and row stochastic.

Hence, it has at least one fixed point q^* .

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- Any such q^* has the property that $q^*\mathbf{N} = 0$, so q^* is the desired left-invariant for \mathbf{M} .

Eliminating conditional regret

Theorem (Foster and Vohra, 1999). *Given a finite game G , if in each period a player plays a distribution q that satisfies*

$$\sum_h q_h (\bar{r}_{hj})_+ - q_j \sum_h (\bar{r}_{jh})_+ = 0,$$

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Corollary. When every player uses the Foster-Vohra algorithm to suppress conditional regret, the empirical joint frequency of play converges almost surely to the set of correlated equilibria.

Example

In an earlier example, the conditional regret matrix after 10 rounds was:¹

$$\mathbf{R} = \begin{array}{c} \begin{array}{ccc} & R & Y & B \\ R & 0.0 & 0.1 & 0.0 \\ Y & 0.3 & 0.0 & 0.0 \\ B & -0.1 & 0.1 & 0.0 \end{array} \end{array}$$

So,

$$\mathbf{N} = \begin{array}{c} \begin{array}{ccc} & R & Y & B \\ R & -0.1 & 0.1 & 0.0 \\ Y & 0.3 & -0.3 & 0.0 \\ B & -0.1 & 0.1 & 0.0 \end{array} \end{array}$$

We need to find a $q \geq 0$ such that $q\mathbf{N} = 0$, $|q| = 1$. If we set $\beta = 0.3$, then q is the fixed-point of

$$\mathbf{I} + \frac{1}{\beta}\mathbf{N} = \begin{array}{c} \begin{array}{ccc} & R & Y & B \\ R & 2/3 & 1/3 & 0 \\ Y & 1 & 0 & 0 \\ B & 0 & 1/3 & 2/3 \end{array} \end{array}$$

with $|q| = 1$.

By the theory of Markov chains such a fixed point exists. In this case, it is

$$q^* = (1/3, 1/3, 1/3).$$

¹There is a typo in SLaiL, third row.

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Theorem. If, in a finite game G , a player uses incremental conditional regret matching with a sufficiently small learning parameter, his conditional regrets become non-positive almost surely, independently of the behaviour of the participants.

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Proof. Based on the standard iterative procedure for find an invariant distribution of a finite Markov chain.

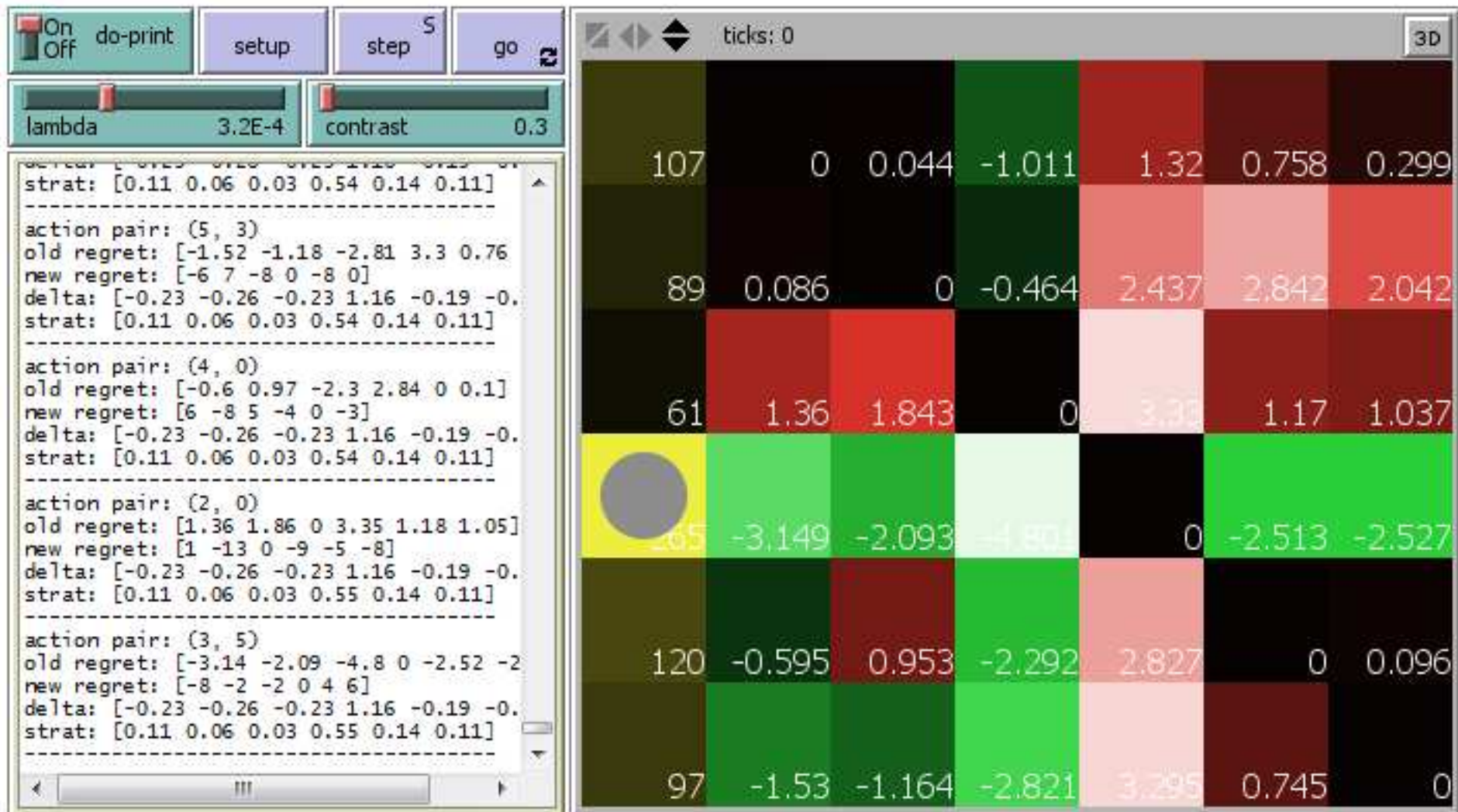
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Corollary. If, in a finite game G , **all players** use **incremental conditional regret matching** with a sufficiently small learning parameter, the empirical joint frequency of play converges almost surely to the set of **correlated equilibria**.

Demo



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- The effect is that change in behaviour over periods is discontinuous.
- **All** players need to use this method to eliminate conditional regret.