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# Free-Shape Optimization of VHF Air-Core Inductors using a Constraint-Aware Genetic Algorithm

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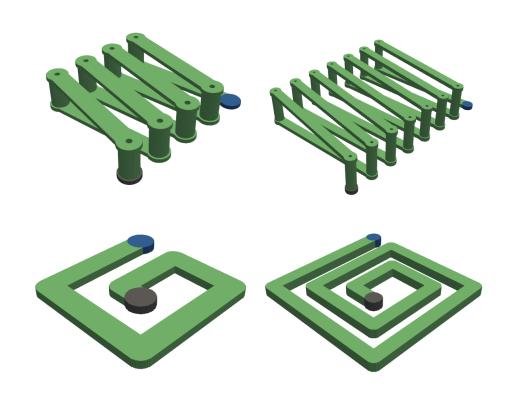






### **Optimization of Magnetics**

- Magnetics are often a bottleneck
- Optimizing the materials?
  - Copper, silver, aluminum, gold, etc.
  - Magnetic material improvements are slow
- Optimizing the geometry?
- Optimal air-core inductor geometries?
  - Spiral, solenoid, staple
  - o Toroid, cylinder



### **Free-Shape Optimization**

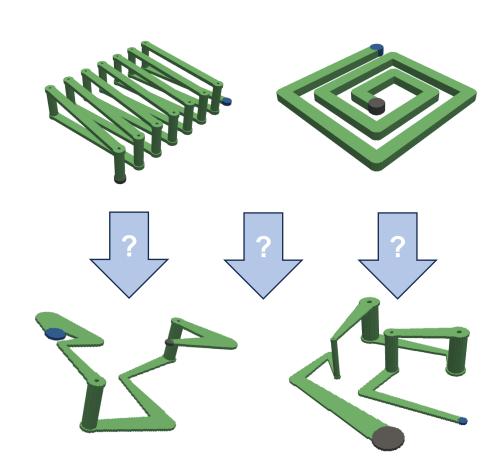
#### Topological optimization

- Definition of constraints
- Definition of an objective
- Automated shape optimization

#### Common for structural mechanics

#### Applicability to magnetics

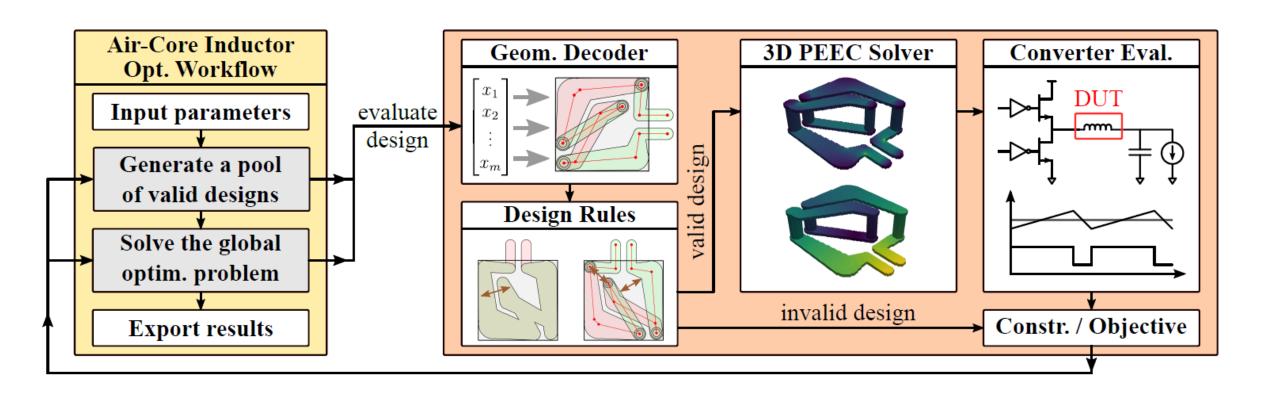
- Large computational cost
- Complex topologies and constraints
- Discrete variables (e.g. layers)
- Non-differentiable / discontinuous objective





# **Optimization Workflow**

### **Air-Core Inductor Optimization Workflow**



### **Geometry and Constraints**

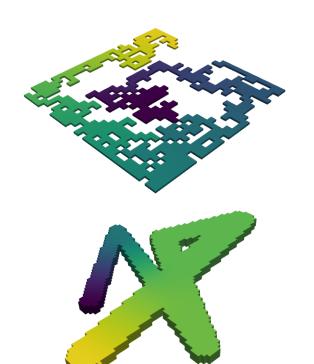
#### Considered geometries

- Multilayer planar process
- Variable trace width
- Variable via size

#### Design rules

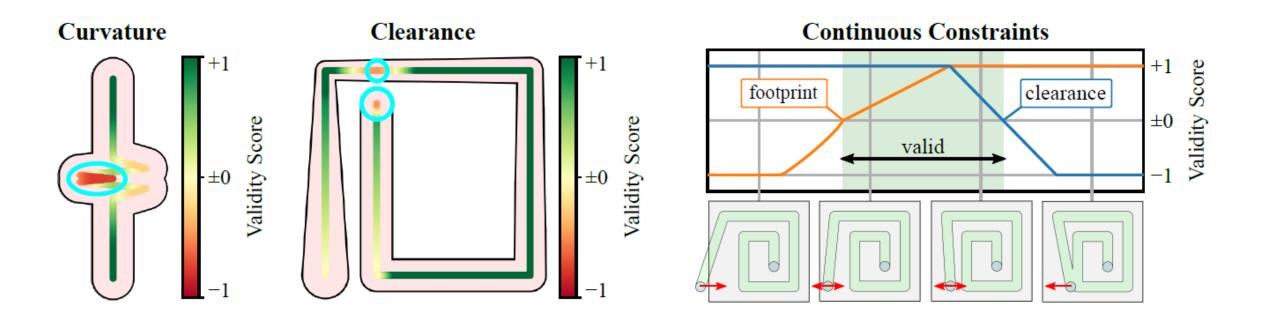
- Clearance, width, footprint, angle, curvature, etc.
- Complex computational geometry
- Optimal designs are often located at the limit
- Optimizers are very good at finding loopholes

#### **Invalid Geometries**



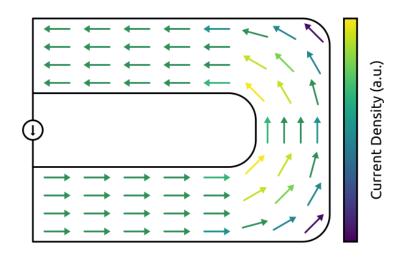
#### **Soft Constraints**

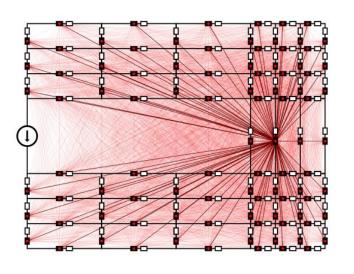
- How "close" is a design to become valid/invalid?
- Helpful for the optimizer (as constraints and/or penalty)

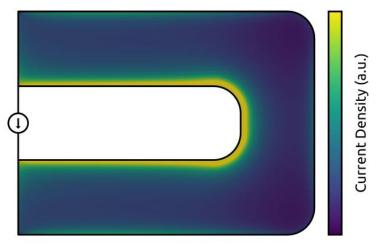


#### 3D PEEC Solver

- PEEC (Partial Element Equivalent Circuit) method [1970s]
  - o Integral equations method using large equivalent circuit
  - Fast for air-core structures (only the conductors are meshed)
- Generates large dense matrices



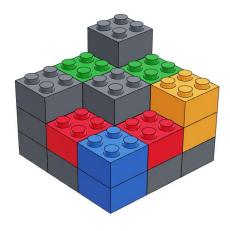




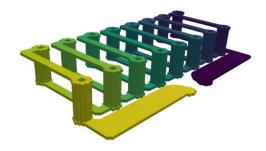
#### 3D PEEC Solver

- FFT acceleration [2018, 2022]
  - Using voxels to represent the geometries
  - Embedding the matrices in circulant tensors
- Advantages
  - Memory storage: from O(n²) to O(n)
  - Matrix multiplication: from O(n²) to O(n In(n))
- **PyPEEC** (custom implementation)
  - 3D magnetic solver (DC and AC)
  - Can handle arbitrary geometries
- Can solve 6.5 designs per seconds

#### **Voxel Structure**

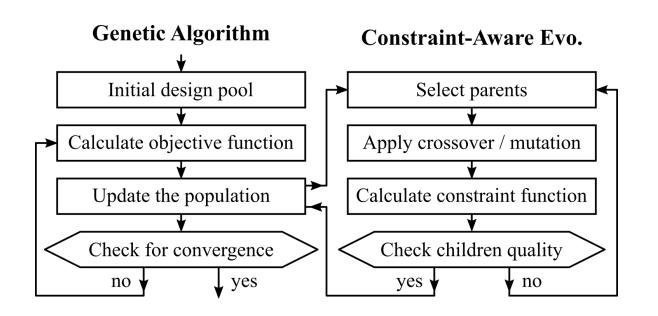


**PyPEEC Inductor** 



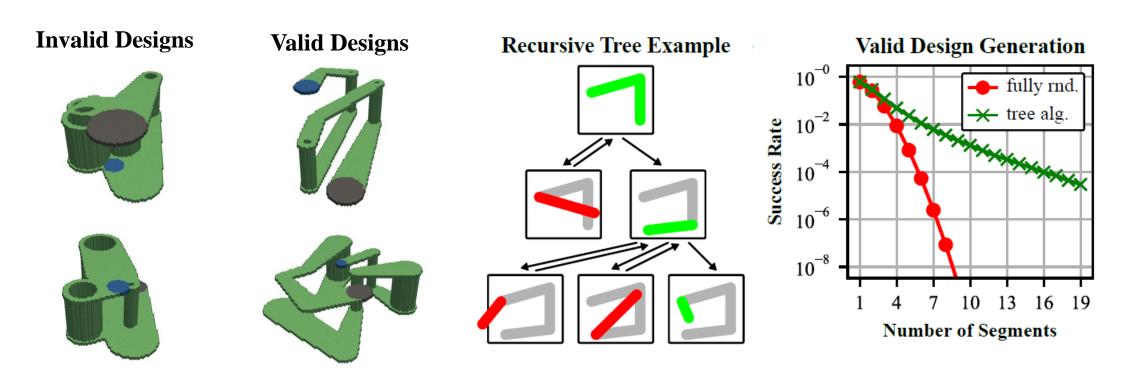
### **Global Optimization**

- Gradient-free algorithms: differential evolution, particle swarm,
   Parzen estimator, CMA-ES, NglohTuned, and genetic algorithm
- The design rules are extremely restrictive
- Constraint-aware genetic algorithm
- Enforce the design rules during the optimization



### Design Rule Awareness

- Generation of random designs for the initial population
  - o Probability to obtain a valid design: below one in a billion
  - Fully random generation is not feasible
- A recursive tree algorithm has been developed

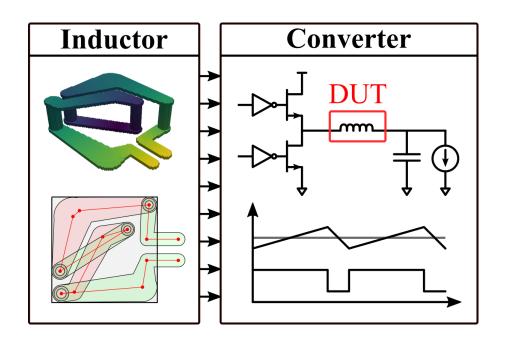




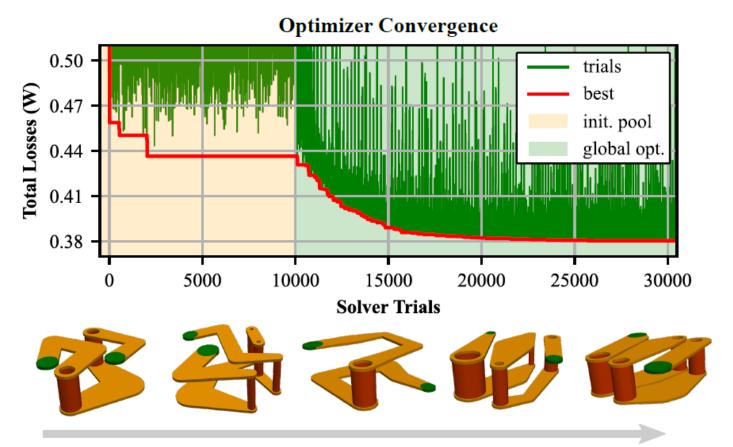
# **Optimization Results**

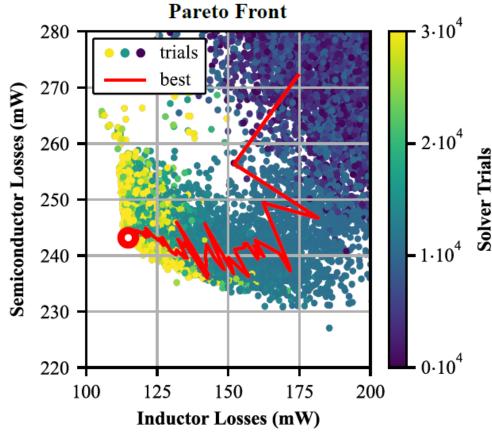
### **Problem Specifications**

- Inductor of a DC-DC Buck IVR
  - 3.3 V to 0.8 V at 1.6 W
  - 40.68 MHz operating frequency
  - o 180 nm SOI switches
- Design rules
  - Limited footprint: 1 mm²
  - Two-layer planar inductor
- Minimize converter losses



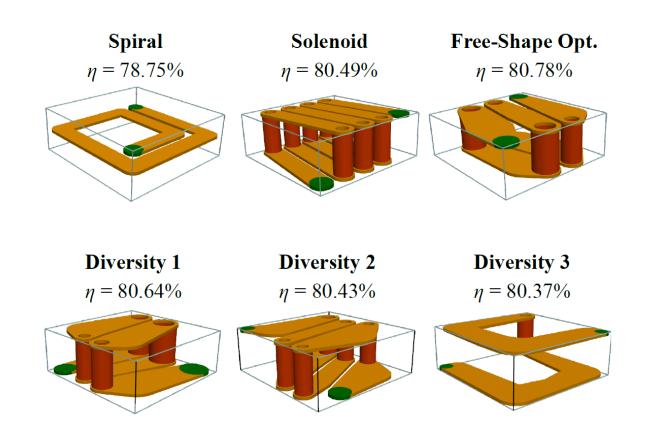
### **Optimizer Convergence**



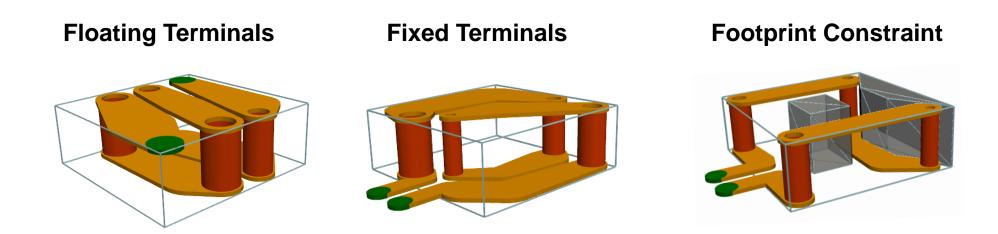


### **Design Space Diversity**

- Classical design
  - Spiral with 1.5 turns
  - o **Solenoid** with 4 turns
- Free-shape design
  - Solenoid with 3 turns
  - Only 0.3% more efficient
- Is shape opt. useless?
  - Design space diversity
  - Additional constraints



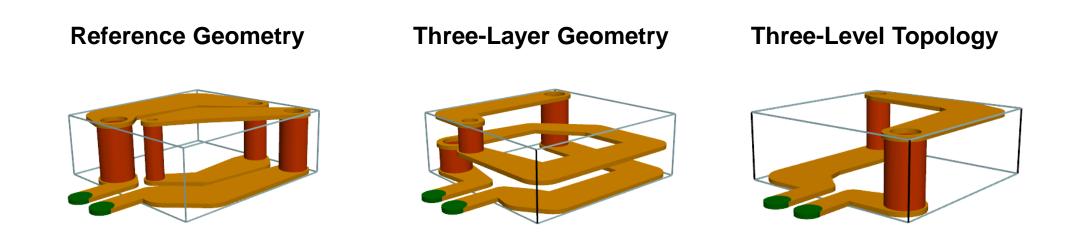
#### **Additional Constraints**



Shape	Solenoid shaped		Solenoid shaped		Loop shaped
Total Efficiency	80.8%	- 1.8%	79.0%	- 1.2%	77.8%
Inductor Efficiency	93.3%		90.8%		89.7%

- Shape optimization can handle complex constraints
- Terminals have a non-negligible impact

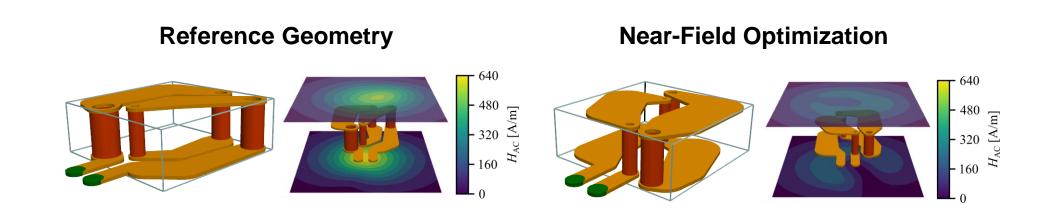
### **Extension of the Design Space**



Shape	Solenoid shaped		Loop shaped		Loop shaped
Total Efficiency	<b>79</b> . <b>0</b> %	+ 1.0%	80.0%	+ 3.8%	83.8%
Resistance Value	16.9 mΩ		21.8 mΩ		11.1 mΩ
Inductance Value	2.17 nH		3.42 nH		1.31 nH

Different boundary conditions lead to different shapes

### **Near-Field Optimization**



Shape	Solenoid shaped		Non-conventional shape			
Total Efficiency	79.0%	- 0.9%	<b>78</b> . <b>1</b> %			
DC Mag. Near Field	771 A/m	. 2 Ev	288 A/m			
AC Mag. Near Field	616 A/m	÷ 2.5x	249 A/m			

- Magnetic near-field: eddy-current losses and/or EMI issues
- Massive field reduction with marginal impact on the efficiency



## Conclusion

#### **Conclusion and Outlooks**

#### Free-shape optimization

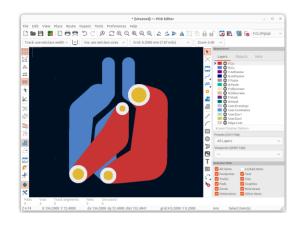
- Strict design rule enforcement
- Fast 3D FFT-accelerated PEEC
- Constraint-aware genetic algorithm

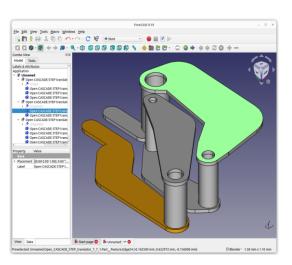
#### Air-core inductors for IVRs

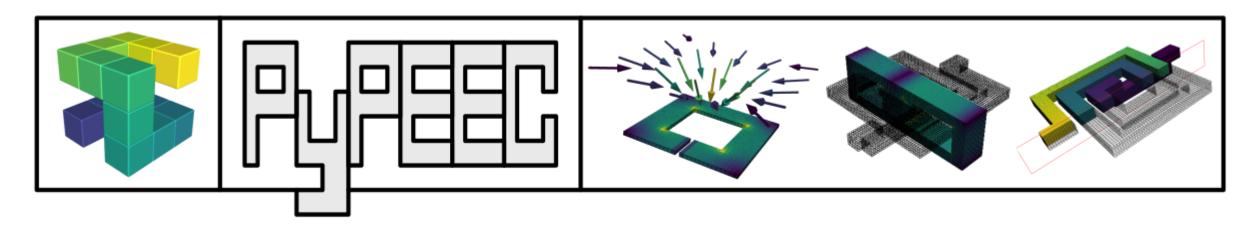
- Classical shapes good for standard problems
- Shape optimization can handle complex constraints

#### Outlooks

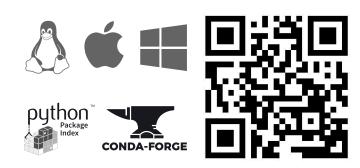
- Scaling to more complex problems
- Gradient-based methods (e.g., auto-diff)
- Neural networks (e.g., surrogate)



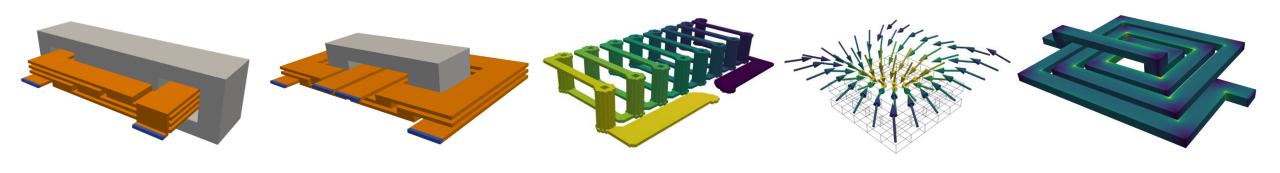




- 3D FFT-accelerated PEEC solver
- DC and AC magnetic problems
- Fully open source Python code



pypeec.otvam.ch



# Shape Opt. Source Code



github.com/otvam/pyfreecoil





zenodo.org/records/14247697





# Thank you! Questions?







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