(1) Expected cost for a finite-horizon problem of length 8 originating from the different initial states

Initial-states	w/o-control	with-control
s0	2.21	2.17
s1	1.96	1.90
s2	2.09	2.03
s3	2.02	1.99
s4	2.17	2.14
s5	2.21	2.17
s6	2.17	2.14
s7	1.96	1.90

(2) Expected cost for a finite-horizon problem of length 16 originating from the different initial states

Initial-states	w/o-control	with-control
s0	2.04	2.01
s1	2.04	2.01
s2	2.04	2.01
s3	2.04	2.01
s4	2.04	2.01
s5	2.04	2.01
s6	2.04	2.01
s7	2.04	2.01

(3) Expected cost of finite-horizon control of different lengths originating from the initial state s5

Control-horizon	w/o-control	with-control
8	2.21	2.17
10	2.11	2.08
12	2.07	2.04
14	2.05	2.02
16	2.04	2.01

(4) Expected cost of finite-horizon control of different lengths originating from the initial state s6

Control-horizon w/o-control with-cont	roι
8 2.17 2.14	
10 2.10 2.07	
12 2.07 2.04	
2.05 2.03	
2.01 2.01	