Lecture 11: Principal component and factor analyses

BTBI30081

統計應用方法Applied Methods in Statistics

2025/4/30

Aspects of multivariate analysis

- Data include simultaneous measurements on many variables- multivariate analysis
- Multivariate methods include the following:
 - Hypothesis construction and testing
 - 2. Investigation of the dependence among variables
 - 3. Data reduction or structure simplification (principal component and factor analysis)
 - 4. Sorting and grouping (clustering)
 - 5. Prediction (classification)

PIXNET Hackathon 開放資料



Datasets

1. 分類熱門照片 (含 EXIF)

下載連結:JSON format 🧖 | CSV format 🕢

資料格式:

ZIP 檔案內有 24 個 JSON 檔案,檔案名稱為 "相簿分類 ID",分類名稱請參考頁面上方「資料使用須知」。所有的資料一定有 EXIF 與位置資訊。

2. 去識別化後的照片 EXIF 資訊

下載連結:JSON format 🗖 | CSV format 🗖

資料格式:

ZIP 檔案內有 5 個 JSON 檔案,檔案名稱為 YYYY-W.json,每個檔案內含一週的資料,分類名稱請參考頁面上方「資料使用須知」。所有的資料一定有 EXIF 欄位。

3. 分類人氣部落格相關資料

下載連結: JSON format 2 | CSV format 2

資料格式:

ZIP 檔案內有 41 個 JSON 檔案,檔案名稱為 "部落格分類ID"。部落格分類名稱請參考頁面上方「資料使用須知」。

4. 去識別化後的部落格訪客資料

下載連結: JSON format 🗖 | CSV format 🗖

資料格式:

ZIP 檔案內有 1 個 JSON 檔案,檔案名稱為 YYYY-mm.json ,表示該月份的訪客資訊。部落格文章分類名稱請參考頁面上方「資料使用須知」。

Principal component analysis

Principal component analysis (PCA)

- A PCA is concerned with explaining the variancecovariance structure of a set of variables through a few "linear" combinations of these variables.
- Objectives of a PCA:
 - data reduction: the total variability of p variables can be accounted for by k principle components, where p>k.
 - interpretation: can reveal relationship that were not previously suspected.

PCA

- Principle components depend solely on the covariance matrix.
- Development of principle components dose NOT require a multivariate normal assumption.
- However, a multivariate normal assumption is useful for inference of the principle components.

Principal components (PCs)

• Observed data: $X = (X_1, X_2, \dots, X_p)$

$$Y_{1} = a_{11}X_{1} + a_{12}X_{2} + \dots + a_{1p}X_{p}$$

$$Y_{2} = a_{21}X_{1} + a_{22}X_{2} + \dots + a_{2p}X_{p}$$

$$\vdots$$

$$Y_{k} = a_{k1}X_{1} + a_{k2}X_{2} + \dots + a_{kp}X_{p}$$

$$k < p$$

PCs

- Find $a_{11}, a_{12}, \cdots, a_{1p}$ such that $Var(Y_1)$ has the maximum variance among all linear combination of $X \to Y_1$ is the 1st principal component
- Find $a_{21}, a_{22}, \cdots, a_{2p}$ such that $Var(Y_2)$ has the maximum variance among all linear combination of X with $Cov(Y_1, Y_2) = 0 \rightarrow Y_2$ is the 2nd principal component
- Find $a_{k1}, a_{k2}, \cdots, a_{kp}$ such that $Var(Y_k)$ has the maximum variance among all linear combination of X with $Cov(Y_i, Y_k) = 0 \ \forall i < k \rightarrow Y_k$ is the kth principal component

PCs (cont'd)

- $Var(Y_1) = the largest eigenvalue of the covariance matrix <math>Cov(X)$, and $(a_{11}, a_{12}, \cdots, a_{1p})$ is its corresponding eigenvector
- $Var(Y_2)$ = the 2nd largest eigenvalue of the covariance matrix Cov(X), and $(a_{21}, a_{22}, \dots, a_{2p})$ is its corresponding eigenvector
- $Var(Y_k)$ = the kth largest eigenvalue of the covariance matrix Cov(X), and $(a_{k1}, a_{k2}, \cdots, a_{kp})$ is its corresponding eigenvector

分類熱門照片

	А	В	С	D	Е	F	G	Н	I
1	類別	ISO	光圈	快門	焦距	相機型號	上傳時間	累計人氣	
2	1	50	2.4	0.042	3	1	13.88202186	3876	
3	1	80	2.4	0.042	3	1	13.88202189	1650	
4	1	75	2.8	0.042	3	1	12.55760815	1184	
5	1	640	2.4	0.067	4	1	13.52986414	1178	
6	1	71	2.8	0.042	3	1	12.55760838	957	
7	1	73	2.8	0.059	3	1	12.55760834	913	
8	1	72	2.8	0.059	3	1	12.55760825	825	
9	1	74	2.8	0.05	3	1	12.5576083	805	
10	1	72	2.8	0.033	3	1	12.55760819	778	
11	1	1000	3.5	0.02	18	2	13.02962592	708	
12	1	79	2.8	0.05	3	1	12.65794278	594	
13	1	86	2.8	0.067	3	1	12.65794276	568	
14	1	220	2.8	0.067	3	1	12.65794273	405	
15	1	80	2.8	0.033	3	1	12.65794275	388	
16	1	1016	2.8	0.1	3	1	12.79276768	385	
17	1	640	2.8	0	28	2	12.55523557	358	

(RMD_example 11.1)

Variable	Description
類別	1=女生個人,2=男生個人
ISO	照片的感光度,數值越高,對光越敏感
光圈	光圈值
快門	快門速度(秒)
焦距	毫米 (mm)
相機型號	0, 1, 2
上傳時間	UNIX 時間戳,與1970年1月1日 00:00:00的秒差×10 ⁻⁸
累計人氣	Hits

分類熱門照片PC loadings

- Y₁ = 0.97(ISO) 0.00015(光圏) + 0.000019(快門) + 0.000083(焦距) + 0.000001(相機型號) + 0.24(上傳時間) 0.0095(累積人氣)
- Y₂ = -0.24(ISO) 0.00040(光圈) 0.000015(快門) 0.00099(焦距) + 0.000035(相機型號) + 0.97(上傳時間) 0.0070(累積人氣)

PC loadings

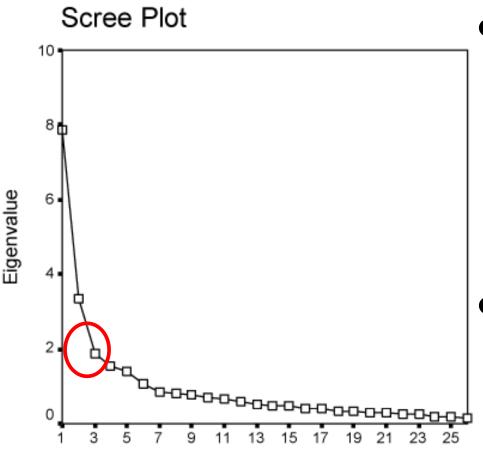
Loadings:

```
Comp.4
                                                      Comp.5
         Comp.1
                    Comp.2
                                Comp.3
          0.9711254 -0.2384491
                                 0.0075776
                                            0.0003176 - 0.0000632
ISO
光圏
         -0.0001543 -0.0003978
                                -0.0000032 -0.0276181 -0.9981672
          0.0000192 - 0.0000153
                                 0.0000031
                                            0.0006682 -0.0038335
          0.0000832 - 0.0009911
                                 0.0002883 - 0.9996118
                                                       0.0273896
          0.0000015
                     0.0000354
                                 0.0001029 - 0.0034608
                                                       0.0538259
          0.2383799
                     0.9711294
                                 0.0090343 -0.0009512 -0.0003986
         -0.0095131
                    -0.0069668
                                 0.9999304
                                            0.0002946 - 0.0000126
         Comp.6
                    Comp.7
ISO
          0.0000109
                     0.0000227
光圈
          0.0537373
                     0.0034113
快門
         -0.0073856 -0.9999652
焦距
         -0.0049467 -0.0007364
相機型號
          0.9985155 -0.0075836
         -0.0000176 -0.0000093
累計人氣 -0.0001011
                     0.0000040
```

The number of PCs

- The amount of total variance explained
 - If most (e.g., 80% to 90%) of the total population variance can be explained by the first k principle components (k < p), then these k principle components can replace the original p variables without much loss of information (total variance).
- The relative size of eigenvalues (variances)
 - Scree plot
- Subject-matter interpretation of the components

Scree plot



Component Number

- The point at which the remaining eigenvalues are relatively small and all about the same size (an elbow (bend) in the scree plot).
- In the above plot, an elbow occurs at about k=3 → choose TWO principle components.

分類熱門照片:# of PCS

```
Importance of components:
                          Comp.1
                                       Comp.2
                                                    Comp.3
                                                                  Comp. 4
                       461.89174
Standard deviation
Proportion of Variance
                         0.53003
Cumulative Proportion
Standard deviation
Proportion of Variance 6.792850e-
                                    2.07463e-07 2.543307e-09
Cumulative Proportion
                       9.999998e-01 1.00000e+00 1.000000e+00
 2 PCs with the
                                                                          _ D X
                                             🥷 R Graphics: Device 2 (ACTIVE)
 amount of total
                                                             Scree plot
 variance
 explained > 90%
                                            /ariances
                                               100000
                                               20000
 Scree plot with an
  elbow occurs at
 about k=3
                                                                  Comp.5
                                                                           Comp.7
                                                 Comp.1
                                                          Comp.3
```

PCA from standardized variables

- Variables should probably be standardized if they are measures on scales with widely differing ranges.
- Example:
 - X_1 : annual sales in the \$10,000 to \$350,000 range
 - X_2 : the ratio (net annual income/total assets) that falls in the 0.01 to 0.6 range
 - No standardization: the 1st principle component will have a heavy weighting of X_1
 - Standardization: X_2 will play a larger role

PCA from standardized variables

• Standardizing observed data: $Z_1 = \frac{X_1 - \mu_1}{\sigma_1}$, $Z_2 = \frac{X_2 - \mu_2}{\sigma_2}$, ...

$$W_{1} = b_{11}Z_{1} + b_{12}Z_{2} + \dots + b_{1p}Z_{p}$$

$$W_{2} = b_{21}Z_{1} + b_{22}Z_{2} + \dots + b_{2p}Z_{p}$$

$$\vdots$$

$$W_{k} = b_{k1}Z_{1} + b_{k2}Z_{2} + \dots + b_{kp}Z_{p}$$

PCA from standardized variables

- $Var(W_1) = the largest eigenvalue of the correlation matrix <math>Cor(X)$, and $(b_{11}, b_{12}, \cdots, b_{1p})$ is its corresponding eigenvector
- $Var(W_2)$ = the 2nd largest eigenvalue of the correlation matrix Cor(X), and $(b_{21}, b_{22}, \dots, b_{2p})$ is its corresponding eigenvector
- $Var(W_k) = the kth largest eigenvalue of the correlation matrix <math>Cor(X)$, and $(b_{k1}, b_{k2}, \dots, b_{kp})$ is its corresponding eigenvector

分類熱門照片 standardized PCs

```
Importance of components:
                                    Comp.2
                                            Comp.3
                                                        Comp.4
                          Comp.1
                       1.2154626 1.1551005 1.0297473 1.0079490 0.9408723
Standard deviation
Proportion of Variance 0.2110499 0.1906082 0.1514828 0.1451373 0.1264630
Cumulative Proportion 0.2110499 0.4016581 0.5531409 0.6982782 0.8247412
                           Comp.6
                                     Comp.7
Standard deviation
                       0.80580979 0.7599227
Proportion of Variance 0.09276134 0.0824975
Cumulative Proportion 0.91750250 1.0000000
Loadings:
        Comp.1
                  Comp.2
                             Comp.3
                                       Comp.4
                                                 Comp.5
        -0.0714726 0.6044901 0.4736265 -0.0812640 -0.1886824
ISO
光圈
        0.6778339 -0.0083201 -0.0088570 -0.0707311 -0.0199902
                                                                  5 PCs
快門
         0.0633094 0.7067502 0.0454794 0.1313349 0.1457447
佳缸
         0.4731235 - 0.1996835 0.4939576 - 0.2235479 - 0.4076155
相機型號 -0.0770545 -0.2603461 0.6730539 0.2121282
                                                  0.6414747
上傳時間 -0.5454875 -0.1516771 0.2716848 -0.1781902 -0.4716178
                                        0.9189236 - 0.3777491
         0.0639136 -0.0660834
                             0.0521810
                   Comp. /
ISO
        -0.5171128 -0.3091128
光圈
        0.3044372 -0.6650632
快門
         0.5993112 0.3110681
         0.0236462
                   0.5249793
焦距
                                        (RMD example 11.3)
相機型號 0.1026508 -0.0790929
        0.5186529 -0.2871392
      氣 -0.0253233 -0.0326948
```

Factor analysis

Factor analysis

- The purpose of factor analysis is to describe the covariance relationships among many variables in terms of a few underlying, but unobservable, random quantities call factors.
- Factor analysis is motivated by
 - variables can be grouped by their correlation
 - all variables within a particular group are highly correlated among themselves
 - variables have relatively small correlations with variables in a different group

Orthogonal factor model

- Observed data: $X = (X_1, X_2, \dots, X_p)$
- X_1, X_2, \dots, X_p are linearly dependent on a few unobservable random variables F_1, F_2, \dots, F_m (common factor)
- \bullet p > m

$$X_{1} - \mu_{1} = \ell_{11}F_{1} + \ell_{12}F_{2} + \dots + \ell_{1m}F_{m} + \varepsilon_{1}$$

$$X_{2} - \mu_{2} = \ell_{21}F_{1} + \ell_{22}F_{2} + \dots + \ell_{2m}F_{m} + \varepsilon_{2}$$

$$\vdots$$

$$X_{p} - \mu_{p} = \ell_{p1}F_{1} + \ell_{p2}F_{2} + \dots + \ell_{pm}F_{p} + \varepsilon_{p}$$
(in a matrix fom: $X - \mu = LF + \varepsilon$)
$$\mu_{i} = \text{mean of variable } i$$

$$\varepsilon_{i} = i\text{th error}$$

$$F_{j} = j\text{th common factor}$$

$$\ell_{ij} = \text{loading of the } i\text{th variable on the } j\text{th factor}$$

• Unobservable random vectors F_j 's and ε_i 's are mutually independent

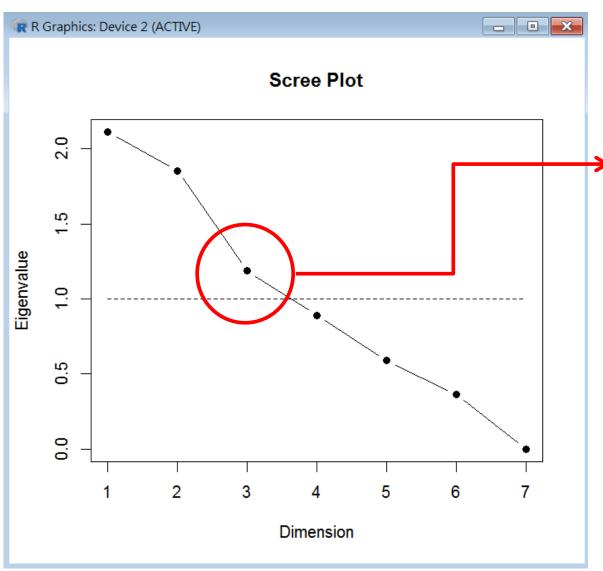
分類熱門照片:factor analysis

```
Uniquenesses:
              光圈
                        快門
                                 焦距
                                       相機型號
                                                上傳時間
                                                          累計人氣
     ISO
0.0912872 0.4054439 0.7589743 0.6987590 0.9552639
                                                0.7812365 0.9982685
Loadings:
        Factor1
                   Factor2
                             Factor3
                                                      Factor
         0.9531224 0.0108353
                              0.0123782
ISO
        -0.0684252 0.7676951 -0.0227622
                                                      loadings
         0.3126406 0.0768856 -0.3706365
         0.0137846 0.4001137 0.3754566
相機型號 -0.0113459 -0.0559101
                              0.2036606
         0.0454631 -0.3968105
                              0.2433759
        -0.0336443
                    0.0209563 -0.013113
                                   Factor3
SS loadings
              1.0143859
                        0.9164991
Proportion Var
              0.1449123
                        0.1309284
Cumulative Var 0.1449123
                        0.2758407
```

The number of factors

- Use criteria similar to those used in PCA
 - The amount of total variance explained until a suitable proportion
 - The relative size of eigenvalues (variances): scree plot of the covariance matrix
 - Set m equal to the number of eigenvalues of the correlation matrix greater than one
 - Subject-matter interpretation of the factors

分類熱門照片:# of factors



The number of eigenvalues of the correlation matrix greater than one = 3

Factor rotation

• Factor loadings L are determined only up to an orthogonal matrix T (TT' = T'T = I):

$$X - \mu = LF + \varepsilon = L(TT')F + \varepsilon = L^*F^* + \varepsilon$$

- $L^* = LT$ (rotated loadings)
 - $F^* = T'F$ (rotated factors)

Why factor rotation?

- Original loadings may not be readily interpretable, usual rotate them until a simpler structure is achieved.
- Ideally, we like to see a pattern of loadings such that each variable loads highly on a single factor and has small loadings on the remaining factors:

$$X_{1} - \mu_{1} = \underbrace{\ell_{11}}_{\text{large}} F_{1} + \underbrace{\ell_{12}}_{\text{small}} F_{2} + \dots + \underbrace{\ell_{1m}}_{\text{small}} F_{m} + \varepsilon_{1}$$

$$X_{2} - \mu_{2} = \underbrace{\ell_{21}}_{\text{small}} F_{1} + \underbrace{\ell_{22}}_{\text{large}} F_{2} + \dots + \underbrace{\ell_{2m}}_{\text{small}} F_{m} + \varepsilon_{1}$$

$$\vdots$$

$$X_{p} - \mu_{p} = \underbrace{\ell_{p1}}_{\text{p1}} F_{1} + \underbrace{\ell_{p2}}_{\text{p2}} F_{2} + \dots + \underbrace{\ell_{pm}}_{\text{large}} F_{p} + \varepsilon_{p}$$

$$\vdots$$

$$\text{small} \quad \text{small} \quad \text{large}$$

Methods of factor rotation

Varimax rotations

- Select the orthogonal transformation T that maximizes the spreading out of the squares of the loadings in each factor.
- We hope to find groups of large and negligible coefficients in any column of L^*

Oblique (non-orthogonal) rotations

- Many investigators in social sciences consider the rotated factors are not necessarily to be independent.
- Orthogonal rotations- a rigid rotation of the coordinate axes (factors) such that the rotated axes pass as closely the clusters of variables as possible.
- Oblique rotation- a nonrigid rotation such that the rotated axes (no longer perpendicular) pass through the clusters of variables.

分類熱門照片: rotated vs. unrotated loadings

```
Loadings:
        Factor1
                 Factor2 Factor3
        0.9325038 0.0598971 0.1885787
ISO
光圈
       -0.1482474 0.7303608 0.1978678
                                       Rotated
快門
    0.2281710 -0.0083560 0.4346206
焦距
     0.0437581 0.4850338 -0.2531325
                                       (varimax)
相機型號 0.0327628 -0.0007951 -0.2089456
上傳時間 0.1299696 -0.3160405 -0.3193487
累計人氣 -0.0374397
                            0.0106340
                  0.0151079
```

Loadings:

```
Factor1 Factor2 Factor3
ISO 0.9531224 0.0108353 0.0123782
光圏 -0.0684252 0.7676951 -0.0227622
快門 0.3126406 0.0768856 -0.3706365
焦距 0.0137846 0.4001137 0.3754566
相機型號 -0.0113459 -0.0559101 0.2036606
上傳時間 0.0454631 -0.3968105 0.2433759
累計人氣 -0.0336443 0.0209563 -0.0131131
```

(RMD_example 11.4)

Factor scores

- Estimated values of the common factors are called factor scores.
- Factor scores can be used for diagnostic purposes and inputs to a subsequent analysis.
- Factor scores are not estimates of unknown parameters. Factor scores are estimates of unobserved random factor vectors F_1, F_2, \dots, F_m .

分類熱門照片:factor scores

> factfit\$scores

```
Factor2
                                      Factor3
          Factor1
[1,] -0.744478512 -0.4390968203 -0.2421767848
[2,] -0.572821108 -0.5262584971 -0.4302286198
[3,] -0.843173384 0.2953278622 0.5238103500
[4,] 0.514612877 -0.2920302012
                                 0.0908727086
[5,] -0.839981043 0.2847687444
                                 0.5027908527
[6,] -0.847735204
                  0.2585411098 0.6602863806
[7,] -0.845381209
                   0.2545780777 0.6522816904
[8,] -0.832918679
                   0.2673538481 0.5658902695
[9,] -0.821629459
                   0.2905749951 0.4021470393
[10,] 1.266750889
                   1.9190923884 -0.7707859163
                                 0.4833648686
[11,] -0.795406138
                   0.2283314115
[12,] -0.793919006
                   0.2040492470
                                 0.6437493174
[13,] -0.514118004
                   0.2288582020 0.6643793857
[14,] -0.769122005
                   0.2446826331 0.3046530819
[15,] 1.096261264
                   0.3261509954 1.0949048259
[16,] 0.680574299
                   1.7287376488 -1.5034657744
[17,] -0.458116823
                   0.2322163316
                                 0.6653574986
[18,] 1.100411881
                   0.3207546911
                                 1.0836600315
[19,] 1.099298921
                   0.3235670407 1.0895351702
[20,1 -0.526639685
                   0.2218586079 0.6519107506
[21,] -0.066986803
                   0.2568968261 0.6733340165
[22,] 0.072574391 -0.3867257670 -0.0505240060
[23,] -0.003387440
                   0.2635979134
                                 0.6801051329
```

Every
observation
(picture) has
scores on all 3
factors!

Exploratory factor analysis (EFA)

- EFA is a technique within factor analysis whose goal is to identify the underlying relationships between measured variables (i.e., identifying common factors).
- It should be used when the researcher has no a priori hypothesis about factors or patterns of measured variables.

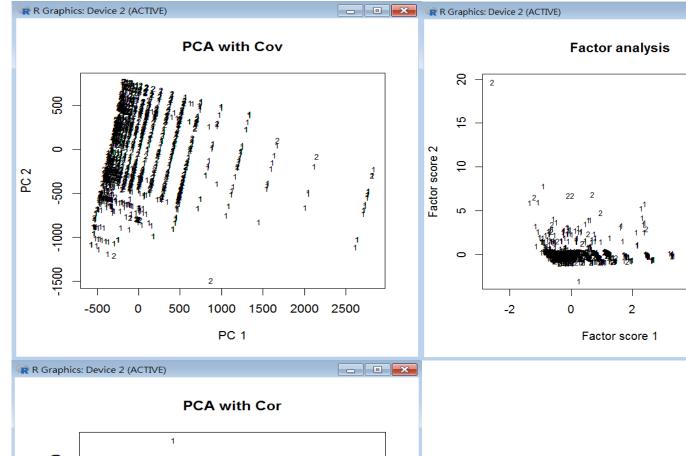
Confirmatory factor analysis (CFA)

 CFA is a special form of factor analysis, it is used to test whether measures of a construct are consistent with a researcher's understanding of the nature of that construct (or factor).

- In CFA, first develop a hypothesis about what factors he believes are underlying the measures he has used.
- 2. Impose constraints (e.g., zero loadings) on the model based on these a priori hypotheses. By imposing these constraints, the researcher is forcing the model to be consistent with his theory.
- 3. **Model fit measures** could then be obtained to assess how well the proposed model captured the covariance between all the measures in the model.
 - If the constraints the researcher has imposed on the model are inconsistent with the sample data, then the results of statistical tests of model fit will indicate a poor fit, and the model will be rejected.

Visualization of multivariate data

- Visualising and processing high-dimensional datasets, while still retaining as much of the variances in the data as possible.
- Can plot scores on the first two principal components or factors



分類熱門照片: visualization

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