

# Approximate nearest neighbor search using the Hierarchical Navigable Small World (HNSW) algorithm

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# Outline

## 1 Theoretical foundations

- Voronoi diagram
- Delaunay graph
- Greedy NN search using Delaunay graph

## 2 HNSW algorithm

- Navigable small world (NSW)
- Hierarchical navigable small world (HNSW)
- Nearest neighbor search using HNSW

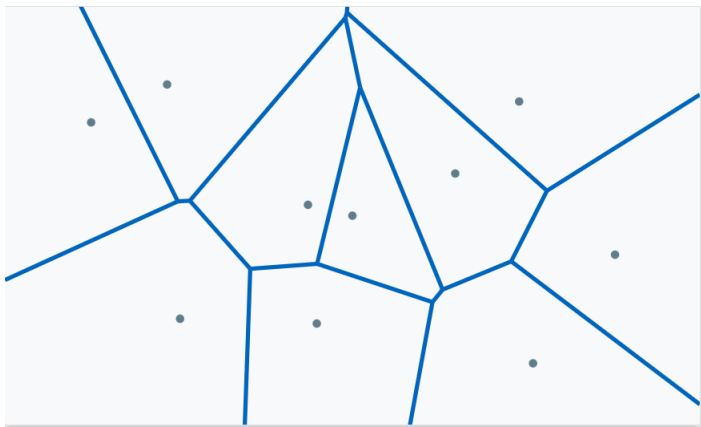
## 3 Performance

- Search accuracy
- Build time and index size

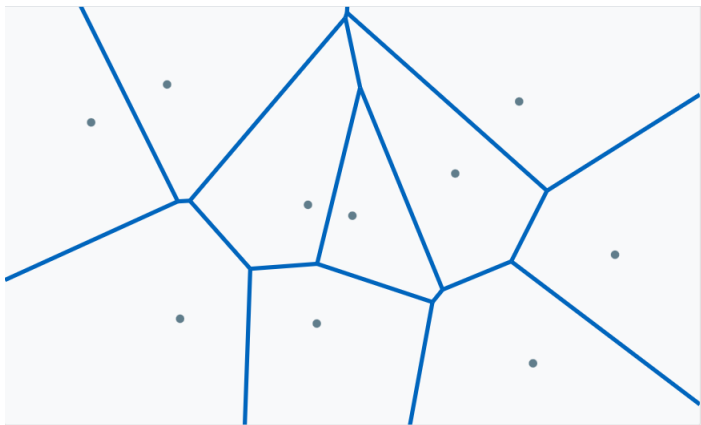
# Voronoi diagram for a set of points



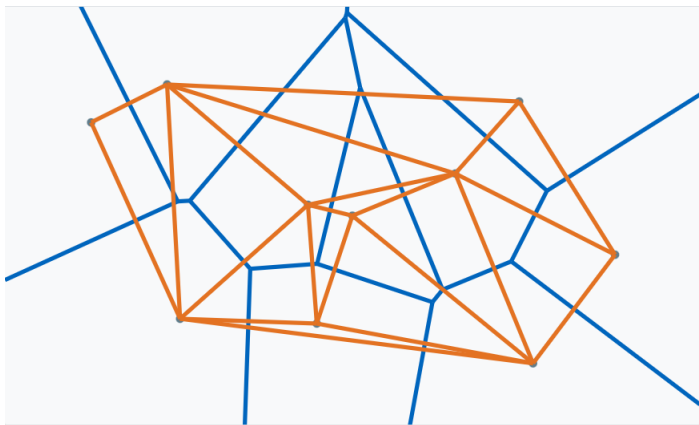
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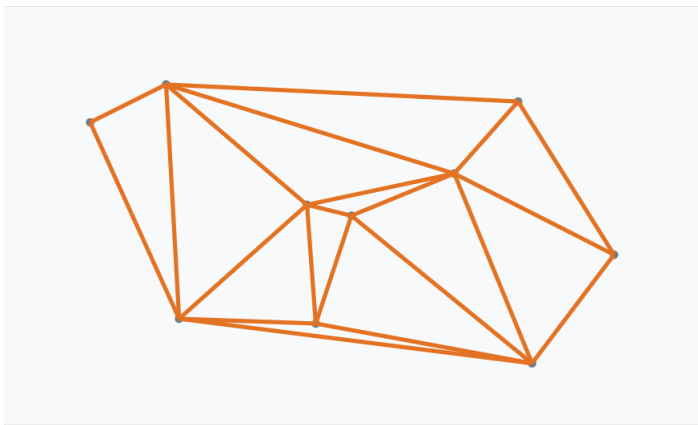
# Voronoi diagram to Delaunay graph



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# Delaunay graph



# Greedy NN search algorithm



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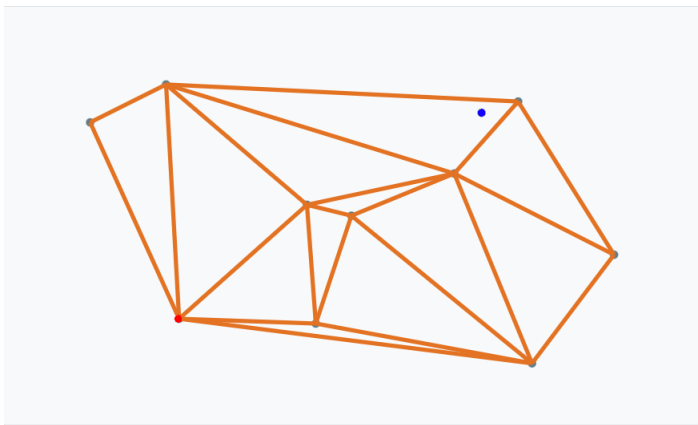
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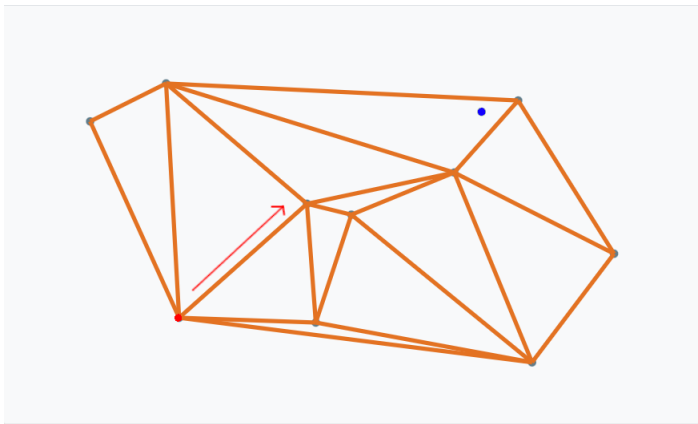
# Greedy NN search algorithm

- 1 Select any graph node as entry node
- 2 Calculate distance from query to current node and from query to all neighbors of current node
- 3 Select neighbor with smallest distance to query as next node to visit
- 4 Repeat 2 and 3 until no neighbor is closer to query than the current node

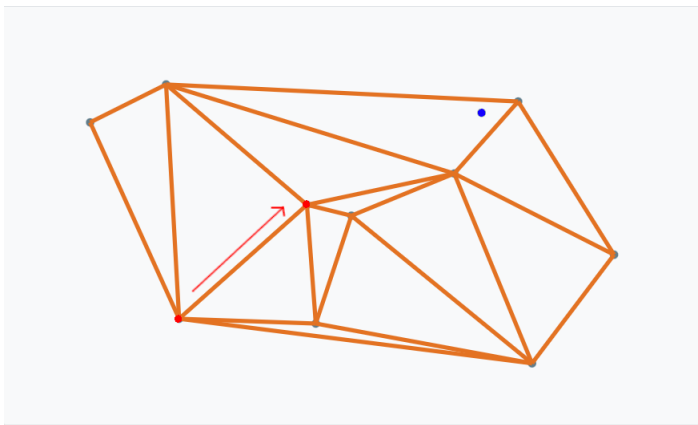
# Greedy NN search start - Query and entry node



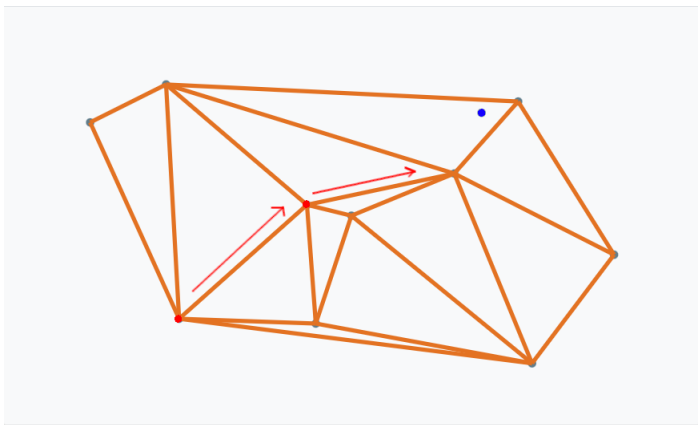
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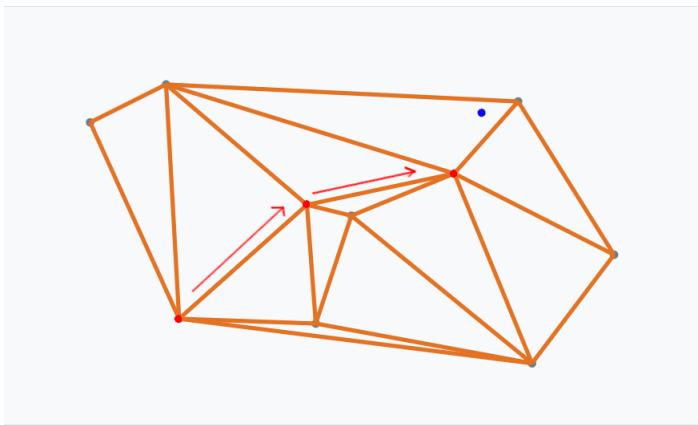


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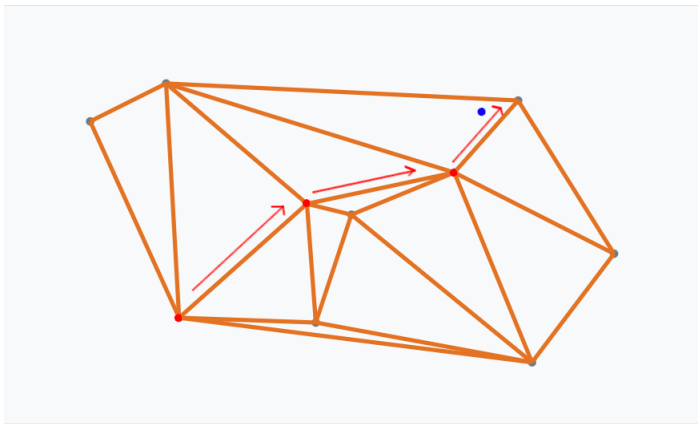




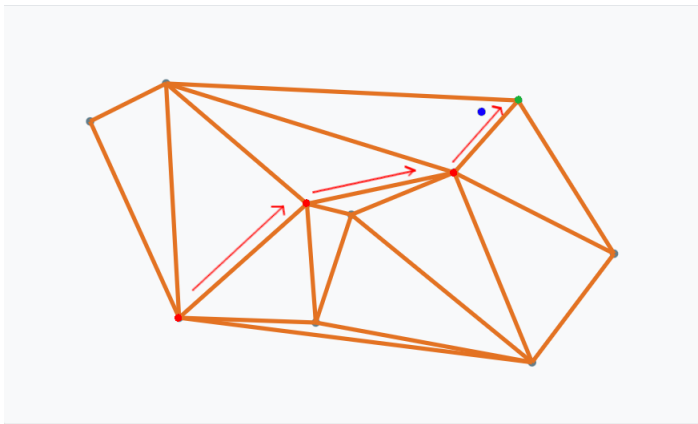
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# Greedy NN search done!



# Drawbacks

- Delaunay graph intractable to construct for large, high-dimensional data sets
- Greedy search might require a lot of steps if graph is large

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- Greedy search algorithm has logarithmic scalability

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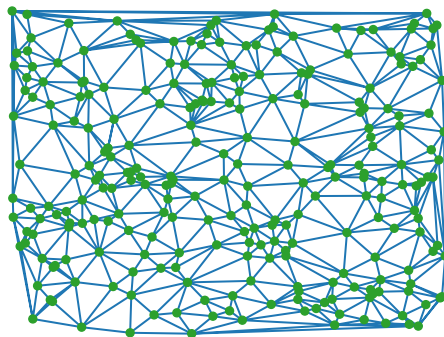
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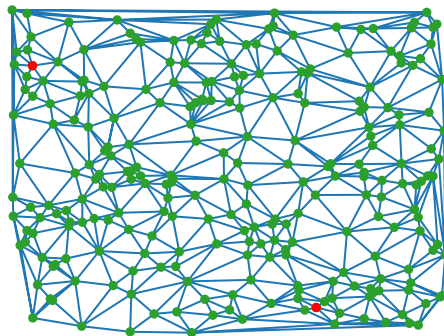
- Logarithmic distance allows us to get anywhere in the graph quickly
- Navigability ensures that the greedy algorithm finds the logarithmic path
- High clustering coefficient lets us zoom in on the actual correct node when we're in the right area

# Making Delaunay graph navigable



256 nodes

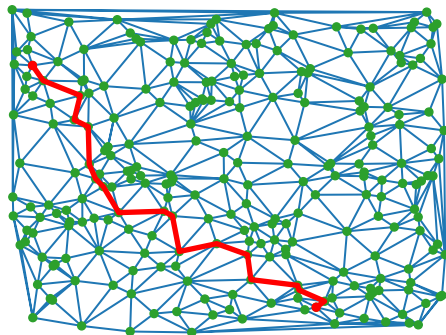
# Making Delaunay graph navigable



Start and end nodes in red

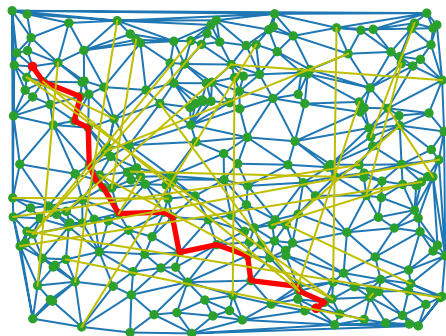


# Making Delaunay graph navigable



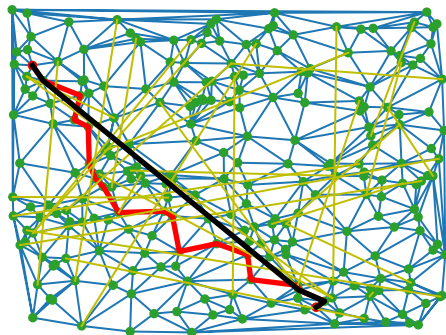
Length of path: 19

# Making Delaunay graph navigable



32 random edges added

# Making Delaunay graph navigable



Length of path: 5

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- Ok since we're doing approximate nearest neighbor search!

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- Approximation of Delaunay graph is sufficient

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- 4 Repeat 2 and 3 until all data points have been added

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- Adding enough nearest neighbor edges approximates Delaunay graph
- The edges added for the early nodes give long-range connections, enabling navigability

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- To improve results we can redo the search  $m$  times from different start nodes

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- 5 Repeat until step 2 returns a candidate that's further away than the  $k$ th result in the queue

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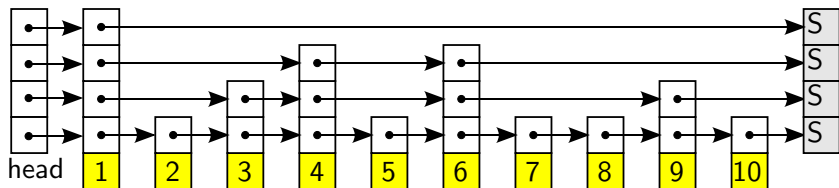
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- Algorithm scales polylogarithmically in general (logarithmic scaling in both steps and degrees of nodes)
- Performance degrades on high-dimensional data
- Insertion order must be random



# Inspiration: Skiplist



[https://en.wikipedia.org/wiki/Skip\\_list](https://en.wikipedia.org/wiki/Skip_list)

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- NSW enables finding the approximate nearest neighbors
- Skipping allows zooming in to the correct area quickly and reliably
- The zoom-in property is accomplished by a hierarchical construction, like in skiplists

# HNSW diagram

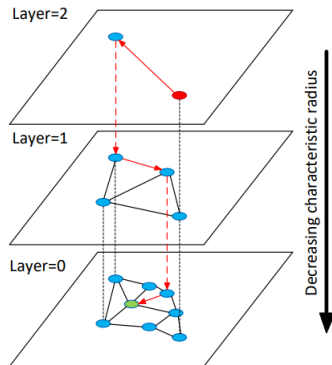


Fig. 1. Illustration of the Hierarchical NSW idea. The search starts from an element from the top layer (shown red). Red arrows show direction of the greedy algorithm from the entry point to the query (shown green).

*Efficient and robust approximate nearest neighbor search using Hierarchical Navigable Small World graphs (Malkov et al.)* <https://arxiv.org/abs/1603.09320>

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- 4 Run kNN algorithm on bottom layer (like when using NSW)

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  - After adding nearest neighbors to node, prune connections from neighbors if number exceeds  $M$



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- 3 *ef* - amount of neighbors to explore in the kNN search during inference (*exploreAdditionalHits* in Vespa)

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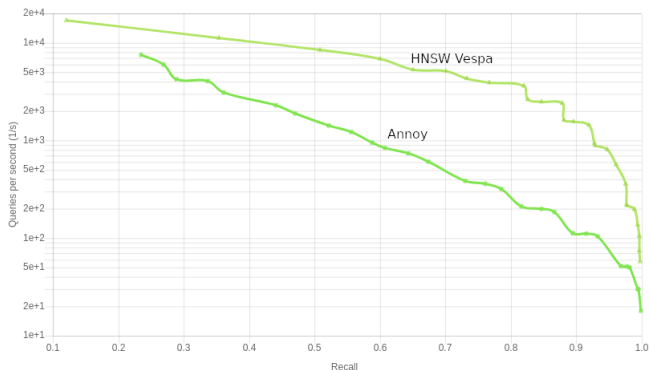
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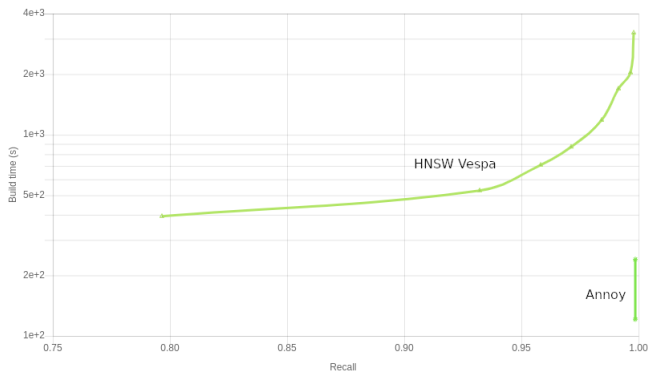
- Less risk to get stuck in local minima due to long range edges being used first
- Logarithmic scalability of search due to hierarchical structure
- Better performance on high-dimensional data
- Insertion order can be anything - randomization happens automatically during index construction

# Recall vs queries per second (up and to the right is better)



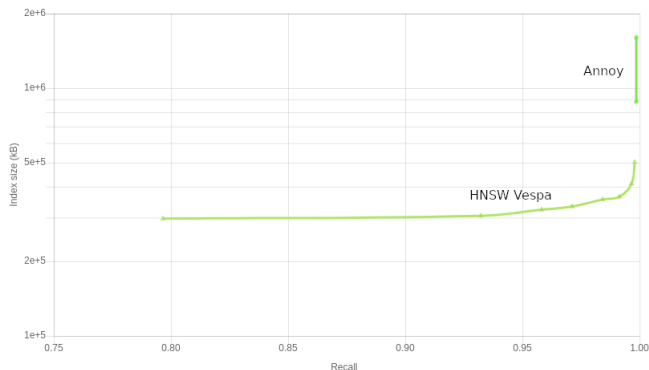
[https://ann-benchmarks.com/nytimes-256-angular\\_10-angular.html](https://ann-benchmarks.com/nytimes-256-angular_10-angular.html)

# Recall vs build time (down and to the right is better)



[https://ann-benchmarks.com/nytimes-256-angular\\_10-angular.html](https://ann-benchmarks.com/nytimes-256-angular_10-angular.html)

# Recall vs index size (down and to the right is better)



[https://ann-benchmarks.com/nytimes-256-angular\\_10-angular.html](https://ann-benchmarks.com/nytimes-256-angular_10-angular.html)

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- Performs well on high-dimensional data
- Supports adding new vectors without rebuilding graph from scratch



## References

- *Efficient and robust approximate nearest neighbor search using Hierarchical Navigable Small World graphs (Malkov et al.)*  
<https://arxiv.org/abs/1603.09320>
- *Approximate nearest neighbor algorithm based on navigable small world graphs (Malkov et al.)*  
<https://doi.org/10.1016/j.is.2013.10.006>
- *Voronoi diagrams—a survey of a fundamental geometric data structure (Aurenhammer)*  
<https://dl.acm.org/doi/10.1145/116873.116880>
- *Hierarchical Navigable Small Worlds (HNSW) (Pinecone blog)*  
<https://www.pinecone.io/learn/hnsw/>