

view_frames Result
Recorded at time: 1677157897.750409

world

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

map

Broadcaster: default authority
Average rate: 17.222
Buffer length: 4.935
Most recent transform: 1677157898.679154
Oldest transform: 1677157893.743721

odom

Broadcaster: default authority
Average rate: 20.202
Buffer length: 4.95
Most recent transform: 1677157897.701513
Oldest transform: 1677157892.751535

base_footprint

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

base link

- os_sensor: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- chassis_connect_wheel_lf_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- chassis_connect_wheel_lr_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- chassis_connect_wheel_rf_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- chassis_connect_wheel_rr_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- chassis_middle_connect_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- chassis_middle_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- chassis_top_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- display_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- lf_s_wheel_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- lr_s_wheel_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- mapping_construction_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- rear_roof_symbol_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- rf_s_wheel_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- rr_s_wheel_link: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- scanner_x: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0
- scanner_y: Broadcaster: default authority, Average rate: 10000.0, Buffer length: 0.0, Most recent transform: 0.0, Oldest transform: 0.0

- os_imu: Broadcaster: default authority, Average rate: 100.199, Buffer length: 5.02, Most recent transform: 8459.618043, Oldest transform: 8454.598043
- os_lidar: Broadcaster: default authority, Average rate: 10.204, Buffer length: 4.9, Most recent transform: 8459.435902, Oldest transform: 8454.536057