

EMMA OUYANG

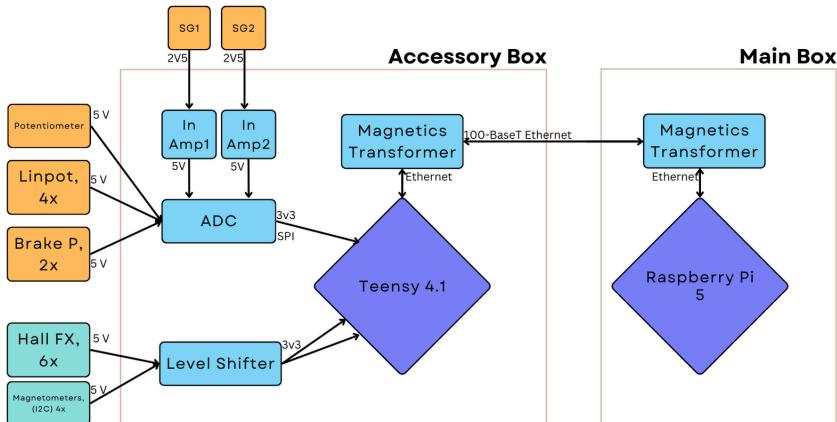
ELECTRICAL ENGINEERING AT JOHNS HOPKINS UNIVERSITY

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DATA ACQUISITION PCB FOR A/D SENSORS - BLUE JAY RACING

(Revision 1)

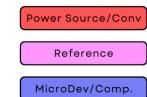
Signal Architecture



Purpose

- Design a circuit that reads the strain, speed, pressure, suspension, and distance traveled for an off-road vehicle
- Performed a **needs analysis** to initiate the design process

Key:



Revision 1:

- All sensors in black were implemented for the first revision

1 Accessory (DAQ) PCB on car for all sensors

Front	
Digital	Analog
FL axle Hall (9 mA max)	FL Linpot
FR axle Hall (9 mA max)	FR Linpot
Prop Shaft. Hall (20 kHz)	F Brake Pressure
FL Magnetometer (I2C, ~1 kHz)	FL Tie Rod SG (120 Ω, Q Bridge)
FR Magnetometer	FR Tie Rod SG
	Steering Potent.

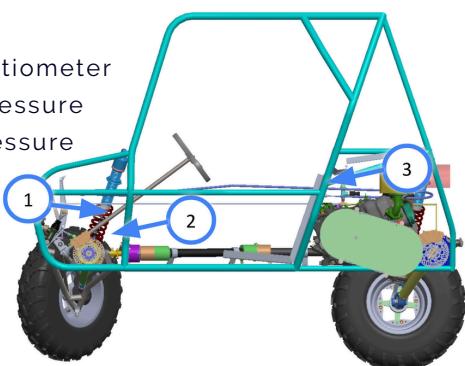
Rear	
Digital	Analog
CVT Primary Hall (Tach) (9 mA max)	RL Linpot
Brake Rotor Hall (WS) (9 mA max)	RR Linpot
Rear Axle Hall (position)	R Brake Pressure
RL Magnetometer (I2C)	
RR Magnetometer	

21XT Vehicle

Sensor Placement

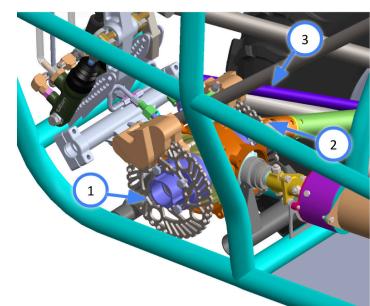
General Sensors

- 1) Steering Potentiometer
- 2) Front Brake Pressure
- 3) Rear Brake Pressure



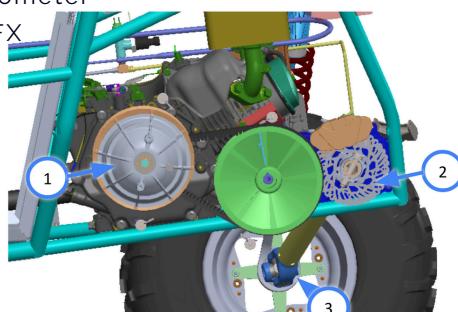
Front Sensors

- 1) FL Axe Hall Effect
- 2) FR Axe Hall Effect
- 3) Tie Rod Strain Gauges (x2)



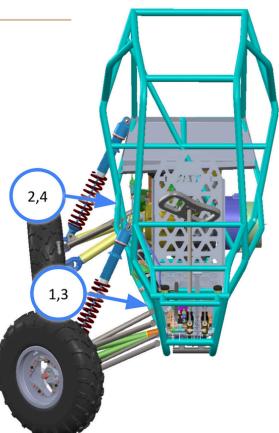
Rear Hall Effect Sensors

- 1) CVT Primary Tachometer
- 2) Brake Rotor Hall FX
- 3) Rear Axle Hall FX



Suspension Sensors

- 1) FL Magnetometer (x2 for FR)
- 2) RL Magnetometer (x2 for RR)
- 3) FL Linear Potentiometer (x2 for FR)
- 4) RL Linear Potentiometer (x2 for FR)



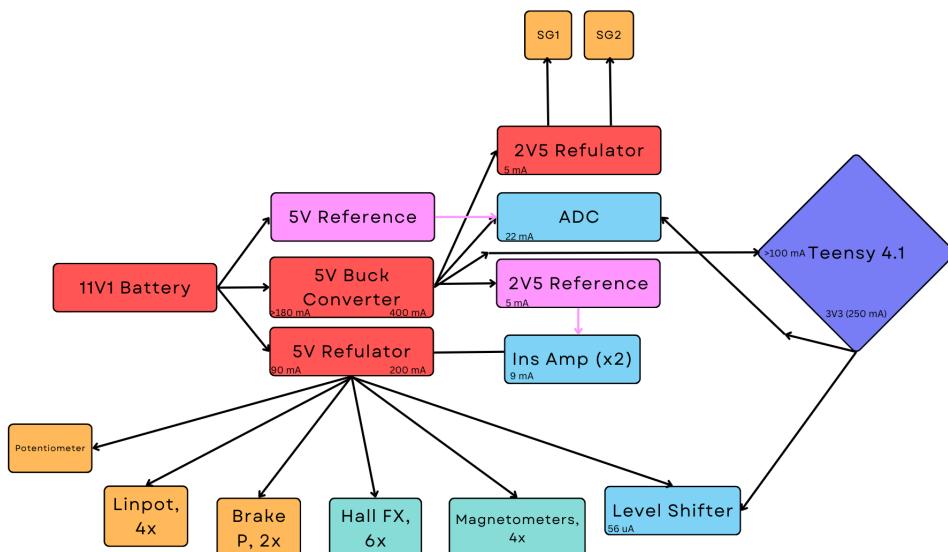
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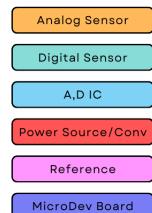
Power Architecture



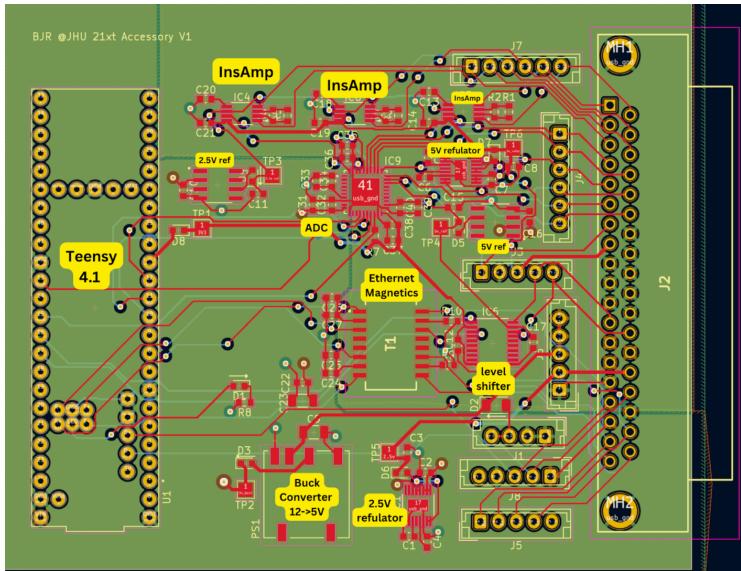
Requirements

- Design a system that is able to support 5V analog and digital sensors, and 2.5V differential analog sensors
- Verify the power sourcing and sinking capabilities of all ICs

Key:



Schematic & PCB Design



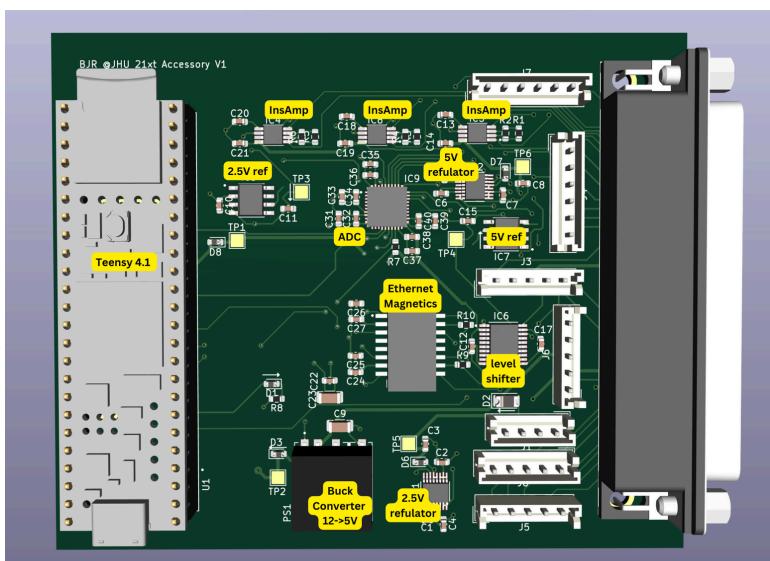
96.5 mm x 79 mm

Design Process

- Used KiCAD to design schematic and PCB
- Implemented Teensy 4.1 Dev. Board for its strong CPU performance & RAM
- Selected DC37 Connector along with testing connectors

Testing Procedure

- Tested for power and ADC signal connectivity
- Confirm buck converter, reference, and regulator stability w/ oscilloscope
- Verified strain gauge linearity, calibrated sensors
- Analyzed Teensy 4.1 Program Output



Results

- Power ICs and ADC operated within expectations
- Ethernet successfully transmitted at 100 Mbps
- Increased sensor capacity by 260% from 20XT
- Teensy 4.1 fully functional
- Reduced PCB size by 15% between Revision 1 & 2
- Implemented a DAC for a variable reference to InAmps