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VDM-10 Language Manual

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Chapter 1

Introduction

The Vienna Development Method (VDM) [Bjørner&78a, Jones90, Fitzgerald&08a] was originally developed at the IBM laboratories in Vienna in the 1970's and as such it is one of the longest established formal method. This document is a common language manual for the three dialects for VDM-SL, VDM++ and VDM-RT in the VDM-10 commonly agreed language revision. These dialects are supported by both VDMTools [Fitzgerald&08b] (in the appropriate version) as well as in the Overture open source tool [Larsen&10a] built on top of the Eclipse platform. Whenever a construct is common to the three different dialects the term "VDM languages" will be used. Whenever a construct is specific to a subset of the VDM languages the specific dialect term mentioned above will be mentioned explictly.

1.1 The VDM Specification Language (VDM-SL)

The syntax and semantics of the VDM-SL language is essentially the standard ISO/VDM-SL [ISOVDM96] with a modular extension¹. Notice that all syntactically correct VDM-SL specifications are also correct in VDM-SL. Even though we have tried to present the language in a clear and understandable way the document is not a complete VDM-SL reference manual. For a more thorough presentation of the language we refer to the existing literature². Wherever the VDM-SL notation differs from the VDM-SL standard notation the semantics will of course be carefully explained.

1.2 The VDM++ Language

VDM++ is a formal specification language intended to specify object oriented systems with parallel and real-time behaviour, typically in technical environments [Fitzgerald&05]. The language is based on VDM-SL [ISOVDM96], and has been extended with class and object concepts, which are

¹A few other extensions are also included.

²A more tutorial like presentation is given in [Fitzgerald&98] whereas proofs in VDM-SL are treated best in [Jones90] and [Bicarregui&94].



also present in languages like Smalltalk-80 and Java. This combination facilitates the development of object oriented formal specifications.

1.3 The VDM Real Time Language (VDM-RT)

The VDM-RT language (formerly called VICE as an acronym for "VDM++ In Constrained Environments") is used to appropriately model and analyse Real-Time embedded and distributed systems [Mukherjee&00, Verhoef&06, Verhoef&07, Verhoef08, Larsen&09]. Thus VDM-RT is a pure extension of the VDM++ language.

1.4 Purpose of The Document

This document is the language reference manual for all the VDM-10 dialects. The syntax of VDM language constructs is defined using grammar rules. The meaning of each language construct is explained in an informal manner and some small examples are given. The description is supposed to be suited for 'looking up' information rather than for 'sequential reading'; it is a manual rather than a tutorial. The reader is expected be familiar with the concepts of object oriented programming/design.

We will use the ASCII (also called the interchange) concrete syntax but we will display all reserved words in a special keyword font. Note that general Unicode identifiers are allowed so it is for example possible to write Japanese characters directly.

1.5 Structure of the Document

Chapter 2 presents the BNF notation used for the description of syntactic constructs. The VDM notations are described in Chapter 3 to Chapter 16. The complete syntax of the language is described in Appendix A, the lexical specification in Appendix B and the operator precedence in Appendix C. Appendix D presents a list of the differences between symbols in the mathematical syntax and the ASCII concrete syntax.

Chapter 2

Concrete Syntax Notation

Wherever the syntax for parts of the language is presented in the document it will be described in a BNF dialect. The BNF notation used employs the following special symbols:

,	the concatenate symbol
=	the define symbol
	the definition separator symbol (alternatives)
[]	enclose optional syntactic items
{ }	enclose syntactic items which may occur zero or more times
٠,	single quotes are used to enclose terminal symbols
meta identifier	non-terminal symbols are written in lower-case letters (pos-
	sibly including spaces)
;	terminator symbol to denote the end of a rule
()	used for grouping, e.g. "a, (b c)" is equivalent to "a, b a,
	c".
_	denotes subtraction from a set of terminal symbols (e.g.
	"character – (""')" denotes all characters excepting the dou-
	ble quote character.)



Chapter 3

Data Type Definitions

As in traditional programming languages it is possible to define data types in the VDM languages and give them appropriate names. Such an equation might look like:

```
types
Amount = nat
```

Here we have defined a data type with the name "Amount" and stated that the values which belong to this type are natural numbers (**nat** is one of the basic types described below). One general point about the type system of the VDM languages which is worth mentioning at this point is that equality and inequality can be used between any value. In programming languages it is often required that the operands have the same type. Because of a construct called a union type (described below) this is not the case for the VDM languages.

In this chapter we will present the syntax of data type definitions. In addition, we will show how values belonging to a type can be constructed and manipulated (by means of built-in operators). We will present the basic data types first and then we will proceed with the compound types.

3.1 Basic Data Types

In the following a number of basic types will be presented. Each of them will contain:

- Name of the construct.
- Symbol for the construct.
- Special values belonging to the data type.
- Built-in operators for values belonging to the type.
- Semantics of the built-in operators.



• Examples illustrating how the built-in operators can be used.¹

For each of the built-in operators the name, the symbol used and the type of the operator will be given together with a description of its semantics (except that the semantics of Equality and Inequality is not described, since it follows the usual semantics). In the semantics description identifiers refer to those used in the corresponding definition of operator type, e.g. a, b, x, y etc.

The basic types are the types defined by the language with distinct values that cannot be analysed into simpler values. There are five fundamental basic types: booleans, numeric types, characters, tokens and quote types. The basic types will be explained one by one in the following.

3.1.1 The Boolean Type

In general the VDM languages allow one to specify systems in which computations may fail to terminate or to deliver a result. To deal with such potential undefinedness, the VDM languages employs a three valued logic: values may be true, false or bottom (undefined). The semantics of the VDM interpreters differs from the ISO/VDM-SL standard in that it does not have an LPF (Logic of Partial Functions) three valued logic where the order of the operands is unimportant (see [Jones90]). The **and** operator, the **or** operator and the imply operator, though, have a conditional semantics meaning that if the first operand is sufficient to determine the final result, the second operand will not be evaluated. In a sense the semantics of the logic in the VDM interpreter can still be considered to be three-valued as for ISO/VDM-SL. However, bottom values may either result in infinite computation or a run-time error in the VDM interpreter.

Name: Boolean

Symbol: bool

Values: true, false

Operators: Assume that a and b in the following denote arbitrary boolean expressions:

Operator	Name	Type
not b	ot b Negation bool → bool	
a and b	Conjunction	$ exttt{bool} * exttt{bool} o exttt{bool}$
a or b	Disjunction	$ exttt{bool} * exttt{bool} o exttt{bool}$
a => b	Implication	$ exttt{bool} * exttt{bool} o exttt{bool}$
a <=> b	Biimplication	$egin{aligned} extsf{bool} & * extsf{bool} & o extsf{bool} \end{aligned}$
a = b	Equality	$egin{aligned} extsf{bool} & * extsf{bool} & o extsf{bool} \end{aligned}$
a <> b	Inequality	oxdots bool st bool $ ightarrow$ bool

Semantics of Operators: Semantically <=> and = are equivalent when we deal with boolean values. There is a conditional semantics for **and**, **or** and =>.

¹In these examples the Meta symbol '≡' will be used to indicate what the given example is equivalent to.



We denote undefined terms (e.g. applying a map with a key outside its domain) by \perp . The truth tables for the boolean operators are then²:

Negation not b

b		true	false	上
not	b	false	true	

Conjunction a and b

$a \setminus b$	true	false	\perp
true	true	false	\perp
false	falco	falco	falco
	Tarse	Tarse	Tarse

Disjunction a or b

$a \setminus b$	true	false	\perp
true	true	true	true
false	true	false	\perp
			\perp

Implication a => b

$a \setminus b$	true	false	\perp
true	true	false	
false	true	true	true
			上

Biimplication a <=> b

$a \setminus b$	true	false	
true	true	false	\perp
false	false	true	_
	工		_

Examples: Let a = true and b = false then:

```
not a
                                        ≡ false
a and b
                                        \equiv false
                                        \equiv false
b and \perp
a or b
                                        ≡ true
a or \perp
                                        ≡ true
a \Rightarrow b
                                        \equiv false
b \Rightarrow b
                                        ≡ true
b \Rightarrow \bot
                                        ≡ true
a \ll b
                                        ≡ false
a = b
                                        \equiv false
a <> b
                                        ≡ true
\perp or not \perp
                                        \equiv \bot
(b and \perp) or (\perp and false) \equiv \perp
```

²Notice that in standard VDM-SL all these truth tables (except =>) would be symmetric.



3.1.2 The Numeric Types

There are five basic numeric types: positive naturals, naturals, integers, rationals and reals. Except for three, all the numerical operators can have mixed operands of the three types. The exceptions are integer division, modulo and the remainder operation.

The five numeric types denote a subset hierarchy where **real** is the most general type followed by **rat**³, **int**, **nat** and **nat1**. Note that no "casting" like it is done in many programming languages is needed in the VDM languages.

Type	Values
nat1	1, 2, 3,
nat	0, 1, 2,
int	, -2, -1, 0, 1,
real	, -12.78356,, 0,, 3,, 1726.34,

This means that any number of type **int** is also automatically of type **real** but not necessarily of type **nat**. Another way to illustrate this is to say that the positive natural numbers are a subset of the natural numbers which again are a subset of the integers which again are a subset of the rational numbers which finally are a subset of the real numbers. The following table shows some numbers and their associated type:

Number	Type				
3	real,	rat,	int,	nat,	nat1
3.0	real,	rat,	int,	nat,	nat1
0	real,	rat,	int,	nat	
-1	real,	rat,	int		
3.1415	real,	rat			

Note that all numbers are necessarily of type **real** (and **rat**).

Names: real, rational, integer, natural and positive natural numbers.

Symbols: real, rat, int, nat, nat1

Operators: Assume in the following that x and y denote numeric expressions. No assumptions are made regarding their type.

³From the VDM interpreter's point of view there is no difference between **real** and **rat** because only rational numbers can be represented in a computer.



Operator	Name	Type
-x	Unary minus	$ exttt{real} o exttt{real}$
abs x	Absolute value	$ exttt{real} o exttt{real}$
floor x	Floor	$\mathtt{real} o \mathtt{int}$
x + y	Sum	$ exttt{real} * exttt{real} ightarrow exttt{real}$
х - у	Difference	$ exttt{real} * exttt{real} ightarrow exttt{real}$
х * у	Product	$ exttt{real} * exttt{real} ightarrow exttt{real}$
х / у	Division	$ exttt{real} * exttt{real} ightarrow exttt{real}$
x div y	Integer division	$\mathtt{int} * \mathtt{int} o \mathtt{int}$
x rem y	Remainder	$\mathtt{int} * \mathtt{int} o \mathtt{int}$
x mod y	Modulus	$\mathtt{int} * \mathtt{int} o \mathtt{int}$
x**y	Power	$ exttt{real} * exttt{real} ightarrow exttt{real}$
х < у	Less than	$ exttt{real} * exttt{real} o exttt{bool}$
x > y	Greater than	$ exttt{real} * exttt{real} o exttt{bool}$
х <= у	Less or equal	$ exttt{real} * exttt{real} o exttt{bool}$
x >= y	Greater or equal	$ exttt{real} * exttt{real} o exttt{bool}$
x = y	Equal	$ exttt{real} * exttt{real} o exttt{bool}$
х <> у	Not equal	$\mathtt{real} * \mathtt{real} o \mathtt{bool}$

The types stated for operands are the most general types allowed. This means for instance that unary minus works for operands of all five types (nat1, nat, int, rat and real).

Semantics of Operators: The operators Unary minus, Sum, Difference, Product, Division, Less than, Greater than, Less or equal, Greater or equal, Equal and Not equal have the usual semantics of such operators.

Operator Name	Semantics Description	
Floor	yields the greatest integer which is equal to or smaller	
	than x.	
Absolute value	yields the absolute value of x, i.e. x itself if $x >= 0$	
	and $-x$ if $x < 0$.	
Power	yields x raised to the y'th power.	

There is often confusion on how integer division, remainder and modulus work on negative numbers. In fact, there are two valid answers to -14 div 3: either (the intuitive) -4 as in the VDM interpreters, or -5 as in e.g. Standard ML [Paulson91]. It is therefore appropriate to explain these operations in some detail.

Integer division is defined using **floor** and real number division:

```
x/y < 0: x \text{ div } y = -\text{floor}(\text{abs}(-x/y))
x/y >= 0: x \text{ div } y = \text{floor}(\text{abs}(x/y))
```



Note that the order of **floor** and **abs** on the right-hand side makes a difference, the above example would yield -5 if we changed the order. This is because **floor** always yields a smaller (or equal) integer, e.g. **floor** (14/3) is 4 while **floor** (-14/3) is -5.

Remainder x **rem** y and modulus x **mod** y are the same if the signs of x and y are the same, otherwise they differ and **rem** takes the sign of x and **mod** takes the sign of y. The formulas for remainder and modulus are:

```
x \text{ rem } y = x - y * (x \text{ div } y)
x \text{ mod } y = x - y * \text{ floor}(x/y)
```

Hence, -14 **rem** 3 equals -2 and -14 **mod** 3 equals 1. One can view these results by walking the real axis, starting at -14 and making jumps of 3. The remainder will be the last negative number one visits, because the first argument corresponding to x is negative, while the modulus will be the first positive number one visit, because the second argument corresponding to y is positive.

Examples: Let a = 7, b = 3.5, c = 3.1415, d = -3, e = 2 then:

```
-7
– a
                           7
abs a
                        \equiv
abs d
                        \equiv 3
floor a <= a</pre>
                        ≡ true
a + d
                        \equiv 4
a * b
                        \equiv 24.5
a / b
                        \equiv 2
                        \equiv 3
a div e
                        \equiv -2
a div d
a mod e
                        \equiv 1
                        \equiv -2
a mod d
                        = -1
-a mod d
                        \equiv 1
a rem e
                        \equiv 1
a rem d
-a rem d
                        = -1
3**2 + 4**2 = 5**2
                        ≡ true
b < c
                        \equiv false
b > c
                        ≡ true
a \le d
                        \equiv false
b \ge e
                        ≡ true
                        \equiv false
a = e
a = 7.0
                        ≡ true
c <> d
                        ≡ true
                        \equiv false
abs c < 0
```



(a **div** e)
$$\star$$
 e \equiv 6

3.1.3 The Character Type

The character type contains all the single character elements of the VDM character set (see Table B.1 on page 196).

Name: Char

Symbol: char

Values: 'a', 'b', ..., '1', '2', ...'+', '-' ...

Operators: Assume that c1 and c2 in the following denote arbitrary characters:

Operator	Name	Type
c1 = c2	Equal	$\mathtt{char} * \mathtt{char} o \mathtt{bool}$
c1 <> c2	Not equal	$\mathtt{char} * \mathtt{char} o \mathtt{bool}$

Examples:

3.1.4 The Quote Type

The quote type corresponds to enumerated types in a programming language like Pascal. However, instead of writing the different quote literals between curly brackets in VDM it is done by letting a quote type consist of a single quote literal and then let them be a part of a union type.

Name: Quote

Symbol: e.g. <QuoteLit>

Values: <RED>, <CAR>, <QuoteLit>, ...

Operators: Assume that q and r in the following denote arbitrary quote values belonging to an enumerated type T:

Operator	Name	Type
q = r	Equal	$T * T \rightarrow \mathtt{bool}$
q <> r	Not equal	$T*T o exttt{bool}$



Examples: Let T be the type defined as:

3.1.5 The Token Type

The token type consists of a countably infinite set of distinct values, called tokens. The only operations that can be carried out on tokens are equality and inequality. In VDM, tokens cannot be individually represented whereas they can be written with a **mk_token** around an arbitrary expression. This is a way of enabling testing of specifications which contain token types. However, in order to resemble the ISO/VDM-SL standard these token values cannot be decomposed by means of any pattern matching and they cannot be used for anything other than equality and inequality comparisons.

Name: Token

Symbol: token

```
Values: mk_token(5), mk_token({9, 3}), mk_token([true, {}]),...
```

Operators: Assume that s and t in the following denote arbitrary token values:

Operator	Name	Type
s = t	Equal	$\verb"token" * \verb"token" \to \verb"bool"$
s <> t	Not equal	$\verb"token" * \verb"token" \to \verb"bool"$

```
Examples: Let for example s = mk\_token(6) and let t = mk\_token(1) in:

s = t \equiv false
```

```
s \Leftrightarrow t \equiv true

s = mk\_token(6) \equiv true
```

3.2 Compound Types

In the following compound types will be presented. Each of them will contain:

- The syntax for the compound type definition.
- An equation illustrating how to use the construct.
- Examples of how to construct values belonging to the type. In most cases there will also be given a forward reference to the section where the syntax of the basic constructor expressions is given.



- Built-in operators for values belonging to the type⁴.
- Semantics of the built-in operators.
- Examples illustrating how the built-in operators can be used.

For each of the built-in operators the name, the symbol used and the type of the operator will be given together with a description of its semantics (except that the semantics of Equality and Inequality is not described, since it follows the usual semantics). In the semantics description identifiers refer to those used in the corresponding definition of operator type, e.g. m, m1, s, s1 etc.

3.2.1 Set Types

A set is an unordered collection of values, all of the same type⁵, which is treated as a whole. All sets in VDM languages are finite, i.e. they contain only a finite number of elements. The elements of a set type can be arbitrarily complex, they could for example be sets themselves.

In the following this convention will be used: A is an arbitrary type, S is a set type, s, s1, s2 are set values, ss is a set of set values, e, e1, e2 and en are elements from the sets, bd1, bd2, ..., bdm are bindings of identifiers to sets or types, and P is a logical predicate.

Constructors:

Set enumeration: $\{e1, e2, \ldots, en\}$ constructs a set of the enumerated elements. The empty set is denoted by $\{\}$.

Set comprehension: {e | bd1, bd2, ..., bdm & P} constructs a set by evaluating the expression e on all the bindings for which the predicate P evaluates to true. A binding is either a set binding or a type binding⁶. A set bind bdn has the form pat1, ..., patp in set s, where pati is a pattern (normally simply an identifier), and s is a set constructed by an expression. A type binding is similar, in the sense that in set is replaced by a colon and s is replaced with a type expression.

⁴These operators are used in either unary or binary expressions which are given with all the operators in section 6.3.

⁵Note however that it is always possible to find a common type for two values by the use of a union type (see section 3.2.6.)

⁶Notice that type bindings cannot be executed by the VDM interpreters because in general they are not executable (see section 8 for further information about this).



The syntax and semantics for all set expressions are given in section 6.7.

Operators:

Operator	Name	Туре
e in set s1	Membership	$A * \mathtt{set}$ of $A o \mathtt{bool}$
e not in set s1	Not membership	$A * \mathtt{set}$ of $A o \mathtt{bool}$
s1 union s2	Union	set of $A * set$ of $A \rightarrow set$ of A
s1 inter s2	Intersection	set of $A * set$ of $A \rightarrow set$ of A
s1 \ s2	Difference	set of $A * set$ of $A \rightarrow set$ of A
s1 subset s2	Subset	set of $A * set$ of $A o bool$
s1 psubset s2	Proper subset	set of $A * set$ of $A \rightarrow bool$
s1 = s2	Equality	set of $A * set$ of $A o bool$
s1 <> s2	Inequality	set of $A * set$ of $A \rightarrow bool$
card s1	Cardinality	set of $\mathrm{A} o \mathtt{nat}$
dunion ss	Distributed union	set of set of $A \rightarrow$ set of A
dinter ss	Distributed intersection	set of set of $A o$ set of A
power s1	Finite power set	set of $A \rightarrow \text{set}$ of set of A

Note that the types A, set of A and set of set of A are only meant to illustrate the structure of the type. For instance it is possible to make a union between two arbitrary sets s1 and s2 and the type of the resultant set is the union type of the two set types. Examples of this will be given in section 3.2.6.

Semantics of Operators:

Operator Name	Semantics Description	
Membership	tests if e is a member of the set s1	
Not membership	tests if e is not a member of the set s1	
Union	yields the union of the sets s1 and s2, i.e. the set	
	containing all the elements of both s1 and s2.	
Intersection	yields the intersection of sets s1 and s2, i.e. the set	
	containing the elements that are in both s1 and s2.	
Difference	yields the set containing all the elements from s1 that	
	are not in s2. s2 need not be a subset of s1.	
Subset	tests if s1 is a subset of s2, i.e. whether all elements	
	from s1 are also in s2. Notice that any set is a subset	
	of itself.	
Proper subset	tests if s1 is a proper subset of s2, i.e. it is a subset	
	and s2\s1 is non-empty.	
Cardinality	yields the number of elements in s1.	
Distributed union	the resulting set is the union of all the elements (these	
	are sets themselves) of ss, i.e. it contains all the ele-	
	ments of all the elements/sets of ss.	



Operator Name	Semantics Description	
Distributes intersec-	the resulting set is the intersection of all the elements	
tion	(these are sets themselves) of, i.e. it contains the ele-	
	ments that are in all the elements/sets of ss. ss must	
	be non-empty.	
Finite power set	yields the power set of s1, i.e. the set of all subsets of	
	s1.	

Examples: Let $s1 = \{ \langle France \rangle, \langle Denmark \rangle, \langle SouthAfrica \rangle, \langle SaudiArabia \rangle \}, s2 = \{2, 4, 6, 8, 11\}$ and $s3 = \{ \}$ then:

```
<England> in set s1
                                                 \equiv false
10 not in set s2
                                                 ≡ true
                                                 \equiv {2, 4, 6, 8, 11}
s2 union s3
s1 inter s3
(s2 \setminus \{2,4,8,10\}) union \{2,4,8,10\} = s2 \equiv
                                                    false
s1 subset s3
                                                 ≡ false
s3 subset s1
                                                 ≡ true
s2 psubset s2
                                                 ≡ false
s2 \iff s2 \text{ union } \{2, 4\}
                                                 \equiv false
card s2 union \{2, 4\}
dunion \{s2, \{2,4\}, \{4,5,6\}, \{0,12\}\}
                                               \equiv \{0, 2, 4, 5, 6, 8, 11, 12\}
dinter {s2, {2,4}, {4,5,6}}
dunion power \{2,4\}
                                                 \equiv \{2, 4\}
dinter power \{2,4\}
```

3.2.2 Sequence Types

A sequence value is an ordered collection of elements of some type indexed by 1, 2, ..., n; where n is the length of the sequence. A sequence type is the type of finite sequences of elements of a type, either including the empty sequence (seq0 type) or excluding it (seq1 type). The elements of a sequence type can be arbitrarily complex; they could e.g. be sequences themselves.

In the following this convention will be used: A is an arbitrary type, L is a sequence type, S is a set type, 1, 11, 12 are sequence values, 11 is a sequence of sequence values. e1, e2 and en are elements in these sequences, 1 will be a natural number, P is a predicate and e is an arbitrary expression.

```
Syntax: type = seq type | ...; seq type = seq0 type | seq1 type;
```



```
seq0 type = 'seq of', type;
seq1 type = 'seq1 of', type;
Equation: L = seq of A or L = seq1 of A
```

Constructors:

Sequence enumeration: [e1, e2,..., en] constructs a sequence of the enumerated elements. The empty sequence will be written as []. A text literal is a shorthand for enumerating a sequence of characters (e.g. "ifad" = ['i','f','a','d']).

Sequence comprehension: [e | id in set S & P] constructs a sequence by evaluating the expression e on all the bindings for which the predicate P evaluates to **true**. The expression e will use the identifier id. S is a set of numbers and id will be matched to the numbers in the normal order (the smallest number first).

The syntax and semantics of all sequence expressions are given in section 6.8.

Operators:

Operator	Name	Туре
hd 1	Head	seq1 of $A \rightarrow A$
tl 1	Tail	$ exttt{seq1}$ of $A o exttt{seq}$ of A
len 1	Length	$\texttt{seq of } A \to \texttt{nat}$
elems 1	Elements	$ extsf{seq}$ of $A o$ set of A
inds 1	Indexes	$\texttt{seq of } A \to \texttt{set of nat1}$
reverse 1	Reverse	$\texttt{seq of } A \to \texttt{seq of } A$
11 ^ 12	Concatenation	$(\mathtt{seq}\ \mathtt{of}\ A)*(\mathtt{seq}\ \mathtt{of}\ A) o \mathtt{seq}\ \mathtt{of}\ A$
conc 11	Distributed concatenation	$\textbf{seq of seq of} \ A \rightarrow \textbf{seq of} \ A$
l ++ m	Sequence modification	$egin{array}{cccccccccccccccccccccccccccccccccccc$
l(i)	Sequence application	$\texttt{seq of } A * \texttt{nat1} \rightarrow A$
11 = 12	Equality	$(\texttt{seq of }A) * (\texttt{seq of }A) \rightarrow \texttt{bool}$
11 <> 12	Inequality	$(\texttt{seq of }A) * (\texttt{seq of }A) \rightarrow \texttt{bool}$

The type A is an arbitrary type and the operands for the concatenation and distributed concatenation operators do not have to be of the same (A) type. The type of the resultant sequence will be the union type of the types of the operands. Examples will be given in section 3.2.6.

Semantics of Operators:

Operator Name	Semantics Description
Head	yields the first element of 1. 1 must be a non-empty
	sequence.



Operator Name	Semantics Description	
Tail	yields the subsequence of 1 where the first element is	
	removed. 1 must be a non-empty sequence.	
Length	yields the length of 1.	
Elements	yields the set containing all the elements of 1.	
Indexes	yields the set of indexes of 1, i.e. the set	
	$\{1, \ldots, \text{len } 1\}.$	
Reverse	yields a new sequence where the order of the elements	
	have been reversed.	
Concatenation	yields the concatenation of 11 and 12, i.e. the se-	
	quence consisting of the elements of 11 followed by	
	those of 12, in order.	
Distributed concate-	yields the sequence where the elements (these are se-	
nation	quences themselves) of 11 are concatenated: the first	
	and the second, and then the third, etc.	
Sequence modifica-	the elements of 1 whose indexes are in the domain of	
tion	m are modified to the range value that the index maps	
	into. dom m must be a subset of inds 1	
Sequence applica-	yields the element of index from 1. i must be in the	
tion	indexes of 1.	

```
Examples: Let 11 = [3, 1, 4, 1, 5, 9, 2], 12 = [2, 7, 1, 8],
     13 = [<England>, <Rumania>, <Colombia>, <Tunisia>] then:
len 11
                                                     \equiv 7
                                                     ≡ 3
hd (11<sup>1</sup>2)
 tl (11<sup>1</sup>2)
                                                     \equiv [1,4,1,5,9,2,2,7,1,8]
 13(len 13)
                                                     ≡ <Tunisia>
 "England" (2)
                                                     = 'n'
 reverse 11
                                                     \equiv [2,9,5,1,4,1,3]
 conc [11,12] = 11^12
                                                     ≡ true
 conc [11,11,12] = 11^12
                                                     \equiv false
 elems 13
                                                     \equiv \{ \langle England \rangle, \}
                                                          <Rumania>,
                                                          <Colombia>, <Tunisia>}
 (elems 11) inter (elems 12)
                                                     \equiv \{1, 2\}
 inds 11
                                                     \equiv \{1,2,3,4,5,6,7\}
 (inds 11) inter (inds 12)
                                                     \equiv \{1, 2, 3, 4\}
 13 ++ \{2 \mid -\rangle < Germany >, \{4 \mid -\rangle < Nigeria >\} \equiv \{\{5\} \in A\}
                                                          <Germany>,
                                                          <Colombia>,
                                                          <Nigeria>]
```



3.2.3 Map Types

A map type from a type A to a type B is a type that associates with each element of A (or a subset of A) an element of B. A map value can be thought of as an unordered collection of pairs. The first element in each pair is called a key, because it can be used as a key to get the second element (called the information part) in that pair. All key elements in a map must therefore be unique. The set of all key elements is called the domain of the map, while the set of all information values is called the range of the map. All maps in VDM languages are finite. The domain and range elements of a map type can be arbitrarily complex, they could e.g. be maps themselves.

A special kind of map is the injective map. An injective map is one for which no element of the range is associated with more than one element of the domain. For an injective map it is possible to invert the map.

In the following this convention will be used: m, m1 and m2 are maps from an arbitrary type A to another arbitrary type B, ms is a set of map values, a, a1, a2 and an are elements from A while b, b1, b2 and bn are elements from B and P is a logic predicate. e1 and e2 are arbitrary expressions and s is an arbitrary set.

Constructors:

Map enumeration: {a1 $\mid ->$ b1, a2 $\mid ->$ b2, ..., an $\mid ->$ bn} constructs a mapping of the enumerated maplets. The empty map will be written as { $\mid ->$ }.

Map comprehension: {ed |-> er | bd1, ..., bdn & P} constructs a mapping by evaluating the expressions ed and er on all the possible bindings for which the predicate P evaluates to true. bd1, ..., bdn are bindings of free identifiers from the expressions ed and er to sets or types.

The syntax and semantics of all map expressions are given in section 6.9.

Operators:



Operator	Name	Туре
dom m	Domain	$(\mathtt{map}\ A\ \mathtt{to}\ B) o \mathtt{set}\ \mathtt{of}\ A$
rng m	Range	$(\mathtt{map}\ A\ \mathtt{to}\ B) o \mathtt{set}\ \mathtt{of}\ B$
m1 munion m2	Merge	$(\texttt{map}\ A\ \texttt{to}\ B) * (\texttt{map}\ A\ \texttt{to}\ B) \to \texttt{map}\ A\ \texttt{to}\ B$
m1 ++ m2	Override	$(\texttt{map}\ A\ \texttt{to}\ B) * (\texttt{map}\ A\ \texttt{to}\ B) \to \texttt{map}\ A\ \texttt{to}\ B$
merge ms	Distributed merge	set of $(\text{map }A \text{ to }B) \rightarrow \text{map }A \text{ to }B$
s <: m	Domain restrict to	$(\textbf{set of }A) * (\textbf{map }A \textbf{ to }B) \rightarrow \textbf{map }A \textbf{ to }B$
s <-: m	Domain restrict by	$(\textbf{set of }A) * (\textbf{map }A \textbf{ to }B) \rightarrow \textbf{map }A \textbf{ to }B$
m :> s	Range restrict to	$(\mathtt{map}\ A\ \mathtt{to}\ B)*(\mathtt{set}\ \mathtt{of}\ B) o \mathtt{map}\ A\ \mathtt{to}\ B$
m :-> s	Range restrict by	$(\mathtt{map}\ A\ \mathtt{to}\ B)*(\mathtt{set}\ \mathtt{of}\ B) o \mathtt{map}\ A\ \mathtt{to}\ B$
m(d)	Map apply	$(\mathtt{map}\ A\ \mathtt{to}\ B)*A o B$
m1 comp m2	Map composition	$(\texttt{map} \ B \ \texttt{to} \ C) * (\texttt{map} \ A \ \texttt{to} \ B) \rightarrow \texttt{map} \ A \ \texttt{to} \ C$
m ** n	Map iteration	$(\mathtt{map}\ A\ \mathtt{to}\ A) * \mathtt{nat} o \mathtt{map}\ A\ \mathtt{to}\ A$
m1 = m2	Equality	$(\texttt{map}\ A\ \texttt{to}\ B) * (\texttt{map}\ A\ \texttt{to}\ B) \to \texttt{bool}$
m1 <> m2	Inequality	$(\texttt{map}\ A\ \texttt{to}\ B) * (\texttt{map}\ A\ \texttt{to}\ B) \to \texttt{bool}$
inverse m	Map inverse	inmap A to $B \to \text{inmap } B$ to A

Semantics of Operators: Two maps m1 and m2 are compatible if any common element of domm1 and domm2 is mapped to the same value by both maps.

Operator Name	Semantics Description	
Domain	yields the domain (the set of keys) of m.	
Range	yields the range (the set of information values) of m.	
Merge	yields a map combined by m1 and m2 such that the	
	resulting map maps the elements of dom m1 as does	
	m1, and the elements of domm2 as does m2. The two	
	maps must be compatible.	
Override	overrides and merges m1 with m2, i.e. it is like a	
	merge except that m1 and m2 need not be compati-	
	ble; any common elements are mapped as by m2 (so	
	m2 overrides m1).	
Distributed merge	yields the map that is constructed by merging all the	
	maps in ms. The maps in ms must be compatible.	
Domain restricted to	creates the map consisting of the elements in m whose	
	key is in s. s need not be a subset of dom m.	
Domain restricted	creates the map consisting of the elements in m whose	
by	key is not in s. s need not be a subset of dom m.	
Range restricted to	creates the map consisting of the elements in m whose	
	information value is in s. s need not be a subset of	
	rngm.	



Operator Name	Semantics Description		
Range restricted by	creates the map consisting of the elements in m whose		
	information value is not in s. s need not be a subset		
	of rng m.		
Map apply	yields the information value whose key is d. d must		
	be in the domain of m.		
Map composition	yields the the map that is created by composing m2		
	elements with m1 elements. The resulting map is a		
	map with the same domain as m2. The information		
	value corresponding to a key is the one found by first		
	applying m2 to the key and then applying m1 to the		
	result. rng m2 must be a subset of dom m1.		
Map iteration	yields the map where m is composed with itself n		
	times. n=0 yields the identity map where each ele-		
	ment of dom m is map into itself; $n=1$ yields m itself.		
	For $n>1$, the range of m must be a subset of dom m.		
Map inverse	yields the inverse map of m. m must be a 1-to-1 map-		
	ping.		

Examples: Let

```
m1 = { <France > |-> 9, <Denmark > |-> 4,}
         <SouthAfrica> |-> 2, <SaudiArabia> |-> 1},
  m2 = \{ 1 \mid -> 2, 2 \mid -> 3, 3 \mid -> 4, 4 \mid -> 1 \},
  Europe = { <France>, <England>, <Denmark>, <Spain> }
 then:
                                          \equiv {<France>, <Denmark>,
{f dom}\ {\it m1}
                                               <SouthAfrica>,
                                               <SaudiArabia>}
                                          \equiv \{1, 2, 4, 9\}
rng m1
m1 munion {<England> |-> 3}
                                          \equiv {<France> |-> 9,
                                               <Denmark> |-> 4,
                                               \langle England \rangle \mid - \rangle 3,
                                               <SaudiArabia> |-> 1,
                                               <SouthAfrica> |-> 2}
```



```
m1 ++ {<France> |-> 8,}
                                                      \equiv {<France> |-> 8,
           \langle England \rangle \mid - \rangle \langle 4 \rangle
                                                            \langle Denmark \rangle \mid - \rangle 4,
                                                            <SouthAfrica> |-> 2,
                                                            <SaudiArabia> |-> 1,
                                                            \langle England \rangle \mid - \rangle \langle 4 \rangle
merge{ <France> |-> 9,
                                                      \equiv {<France> |-> 9,
                                                            <England> |-> 3,
           <Spain> |-> 4}
          {< France > |-> 9,}
                                                            <Spain> |-> 4,
                                                            <UnitedStates> |-> 1}
           \langle England \rangle \mid - \rangle 3,
           <UnitedStates> |-> 1}}
                                                      \equiv {<France> |-> 9,
Europe <: m1
                                                            \langle Denmark \rangle | - \rangle 4
                                                      \equiv {<SouthAfrica> |-> 2,
Europe <-: m1
                                                            <SaudiArabia> |-> 1}
m1 :> \{2, \ldots, 10\}
                                                      \equiv {<France> |-> 9,
                                                            <Denmark> |-> 4,
                                                            <SouthAfrica> |-> 2}
m1 : -> \{2, ..., 10\}
                                                      \equiv \{ \langle SaudiArabia \rangle | - \rangle 1 \}
m1 comp ({"France" |-\rangle <France>}) \equiv {"France" |-\rangle 9}
m2 ** 3
                                                      \equiv \begin{cases} 1 \mid -> 4, 2 \mid -> 1, \\ 3 \mid -> 2, 4 \mid -> 3 \end{cases}
                                                      \equiv {2 |-> 1, 3 |-> 2,
inverse m2
                                                            4 |-> 3, 1 |-> 4 }
                                                      \equiv \begin{cases} 1 \mid -> 1, 2 \mid -> 2, \\ 3 \mid -> 3, 4 \mid -> 4 \end{cases}
m2 comp (inverse m2)
```

3.2.4 Product Types

The values of a product type are called tuples. A tuple is a fixed length list where the i'th element of the tuple must belong to the i'th element of the product type.

Syntax: type = product type
$$| \dots ;$$



```
product type = type, '*', type, { '*', type } ;
```

A product type consists of at least two subtypes.

```
Equation: T = A1 * A2 * ... * An
```

Constructors: The tuple constructor: **mk**₋(a1, a2, ..., an)

The syntax and semantics for the tuple constructor are given in section 6.10.

Operators:

Operator	Name	Туре
t.#n	Select	$T * \mathtt{nat} o Ti$
t1 = t2	Equality	$T * T o \mathtt{bool}$
t1 <> t2	Inequality	$T * T \rightarrow \mathtt{bool}$

The only operators working on tuples are component select, equality and inequality. Tuple components may be accessed using the select operator or by matching against a tuple pattern. Details of the semantics of the tuple select operator and an example of its use are given in section 6.12.

```
Examples: Let a = mk_{-}(1, 4, 8), b = mk_{-}(2, 4, 8) then:

a = b \equiv false

a <> b \equiv true

a = mk_{-}(2, 4) \equiv false
```

3.2.5 Composite Types

Composite types correspond to record types in programming languages. Thus, elements of this type are somewhat similar to the tuples described in the section about product types above. The difference between the record type and the product type is that the different components of a record can be directly selected by means of corresponding selector functions. In addition records are tagged with an identifier which must be used when manipulating the record. The only way to tag a type is by defining it as a record. It is therefore common usage to define records with only one field in order to give it a tag. This is another difference to tuples as a tuple must have at least two entries whereas records can be empty.

In VDM languages, **is** is a reserved prefix for names and it is used in an *is expression*. This is a built-in operator which is used to determine which record type a record value belongs to. It is often used to discriminate between the subtypes of a union type and will therefore be explained further in section 3.2.6. In addition to record types the **is** operator can also determine if a value is of one of the basic types.

In the following this convention will be used: A is a record type, A1, ..., Am are arbitrary types, r, r1, and r2 are record values, i1, ..., im are selectors from the r record value, e1, ..., em are arbitrary expressions.



where identifier denotes both the type name and the tag name.

Equation:

```
A :: selfirst : A1 selsec : A2
```

or

```
A :: selfirst : A1 selsec :- A2
```

or

```
A :: A1 A2
```

In the second notation, an *equality abstraction* field is used for the second field selsec. The minus indicates that such a field is ignored when comparing records using the equality operator. In the last notation the fields of A can only be accessed by pattern matching (like it is done for tuples) as the fields have not been named.

In the last notation the fields of A can only be accessed by pattern matching (as is done for tuples) since the fields have not been named.

The shorthand notation: used in the two previous examples where the tag name equals the type name, is the notation most used. The more general **compose** notation is typically used if a composite type has to be specified directly as a component of a more complex type:

```
T = map S to compose A of A1 A2 end
```



It should be noted however that composite types can only be used in type definitions, and not e.g. in signatures to functions or operations.

Typically composite types are used as alternatives in a union type definition (see section 3.2.6) such as:

```
MasterA = A | B | ...
```

where A and B are defined as composite types themselves. In this situation the \mathbf{is}_{-} predicate can be used to distingush the alternatives.

Constructors: The record constructor: **mk**_A(a, b) where a belongs to the type A1 and b belongs to the type A2.

The syntax and semantics for all record expressions are given in section 6.11.

Operators:

Operator	Name	Type
r.i	Field select	$A * Id \rightarrow Ai$
r1 = r2	1 "	$oxed{A*A ightarrow exttt{bool}}$
r1 <> r2	Inequality	$ig ext{ A} * ext{A} o extbool$
is _A(r1)	Is	Id * MasterA \rightarrow bool

Semantics of Operators:

Operator Name	Semantics Description	
Field select	yields the value of the field with fieldname i in the	
	record value r. r must have a field with name i.	

Examples: Let Score be defined as

and let

```
sc1 = mk_Score (<France>, 3, 0, 0, 9),
sc2 = mk_Score (<Denmark>, 1, 1, 1, 4),
sc3 = mk_Score (<SouthAfrica>, 0, 2, 1, 2) and
sc4 = mk_Score (<SaudiArabia>, 0, 1, 2, 1).
```



Then

The equality abstraction field, written using ':-' instead of ':', may be useful, for example, when working with lower level models of an abstract syntax of a programming language. For example, one may wish to add a position information field to a type of identifiers without affecting the true identity of identifiers:

```
Id :: name : seq of char
pos :- nat
```

The effect of this will be that the pos field is ignored in equality comparisons, e.g. the following would evaluate to true:

```
mk_Id("x",7) = mk_Id("x",9)
```

In particular this can be useful when looking up in an environment which is typically modelled as a map of the following form:

```
Env = map Id to Val
```

Such a map will contain at most one index for a specific identifier, and a map lookup will be independent of the pos field.

Moreover, the equality abstraction field will affect set expressions. For example,

```
\{ mk_Id("x",7), mk_Id("y",8), mk_Id("x",9) \}
```

will be equal to

```
{mk_Id("x",?),mk_Id("y",8)}
```

where the question mark stands for 7 or 9.



Finally, note that for equality abstraction fields valid patterns are limited to don't care and identifier patterns. Since equality abstraction fields are ignored when comparing two values, it does not make sense to use more complicated patterns.

3.2.6 Union and Optional Types

The union type corresponds to a set-theoretic union, i.e. the type defined by means of a union type will contain all the elements from each of the components of the union type. It is possible to use types that are not disjoint in the union type, even though such usage would be bad practice. However, the union type is normally used when something belongs to one type from a set of possible types. The types which constitute the union type are often composite types. This makes it possible, using the <code>is</code> operator, to decide which of these types a given value of the union type belongs to.

The optional type [T] is a kind of shorthand for a union type $T \mid nil$, where nil is used to denote the absence of a value. However, it is not possible to use the set $\{nil\}$ as a type so the only types nil will belong to will be optional types.

```
Syntax: type = union type
| optional type
| ...;

union type = type, '|', type, { '|', type } ;

optional type = '[', type, ']';
```

Equation: B = A1 | A2 | ... | An

Constructors: None.

Operators:

Operator	Name	Туре
t1 = t2	Equality	$A * A \rightarrow \texttt{bool}$
t1 <> t2	Inequality	$ig ext{ A} * ext{A} o extbf{bool}$

Examples: In this example Expr is a union type whereas Const, Var, Infix and Cond are composite types defined using the shorthand:: notation.



```
cons : Expr
altn : Expr
```

Using union types we can extend the use of previously defined operators. For instance, interpreting = as a test over **bool** | **nat** we have

```
1 = false \equiv false
```

Similarly we can take use union types for taking unions of sets and concatenating sequences:

```
\{1,2\} union \{false,true\} \equiv \{1,2, false,true\}
['a','b']^{(c>, d>)} \equiv ['a','b', <c>, <d>\}
```

In the set union, we take the union over sets of type $nat \mid bool$; for the sequence concatenation we are manipulating sequences of type $char \mid <c> \mid <d>$.

3.2.7 The Object Reference Type (VDM++ and VDM-RT

The object reference type has been added as part of the standard VDM-SL types. Therefore there is no direct way of restricting the use of object reference types (and thus of objects) in a way that conforms to pure object oriented principles; no additional structuring mechanisms than classes are foreseen. From these principles it follows that the use of an object reference type in combination with a type constructor (record, map, set, etc.) should be treated with caution.

A value of the object reference type can be regarded as a *reference* to an object. If, for example, an instance variable (see section 10.1) is defined to be of this type, this makes the class in which that instance variable is defined, a 'client' of the class in the object reference type; a *clientship relation* is established between the two classes.

An object reference type is denoted by a class name. The class name in the object reference type must be the name of a class defined in the specification.

The only operators defined for values of this type is the test for equality ('=') and inequality ('<>'). Equality is based on references rather than values. That is, if o1 and o2 are two distinct objects which happen to have the same contents, o1 = o2 will yield false.

Constructors Object references are constructed using the new expression (see section 6.13).

Operators

Opera	ator	Name	Туре
t1 =	= t2	Equality	$A * A \rightarrow \texttt{bool}$
t1 <	<> t2	Inequality	$ig ext{ A} * ext{A} o extbf{bool}$



Examples An example of the use of object references is in the definition of the class of binary trees:

Here we define the type of nodes, which consist of a node value, and references to left and right tree objects. Details of access specifiers may be found in section 13.3.3.

3.2.8 Function Types

In the VDM languages function types can also be used in type definitions. A function type from a type \mathbb{A} (actually a list of types as a tuple type) to a type \mathbb{B} is a type that associates with each element of \mathbb{A} an element of \mathbb{B} . A function value can be thought of as a function in a programming language which has no side-effects (i.e. it does not use any global variables).

Such usage can be considered advanced in the sense that functions are used as values (thus this section may be skipped during the first reading). Function values may be created by lambda expressions (see below), or by function definitions, which are described in section 5. Function values can be of higher order in the sense that they can take functions as arguments or return functions as results. In this way functions can be Curried such that a new function is returned when the first set of parameters are supplied (see the examples below).

```
Syntax: type = partial function type
| ...;

function type = partial function type
| total function type;

partial function type = discretionary type, '->', type;
```



Equation:
$$F = A +> B^7 \text{ or } F = A -> B$$

Constructors: In addition to the traditional function definitions the only way to construct functions is by the lambda expression: lambda pat1: T1, ..., patn: Tn & body where the patj are patterns, the Tj are type expressions, and body is the body expression which may use the pattern identifiers from all the patterns.

The syntax and semantics for the lambda expression are given in section 6.16.

Operators:

Operator	Name	Туре
f(a1,,an)	Function apply	$A1 * \cdots * An \rightarrow B$
f1 comp f2	Function composition	$(B \to C) * (A \to B) \to (A \to C)$
f ** n	Function iteration	$(A ightarrow A) * \mathtt{nat} ightarrow (A ightarrow A)$
t1 = t2	Equality	$A*A o exttt{bool}$
t1 <> t2	Inequality	$\mathrm{A} * \mathrm{A} o \mathtt{bool}$

Note that equality and inequality between type values should be used with great care. In the VDM languages this corresponds to the mathematical equality (and inequality) which is not computable for infinite values like general functions. Thus, in the VDM interpreters the equality is on the abstract syntax of the function value (see incl and incl below).

Semantics of Operators:

Operator Name	Semantics Description	
Function apply	yields the result of applying the function f to the val-	
	ues of a_j . See the definition of apply expressions in	
	Section 6.12.	
Function composi-	it yields the function equivalent to applying first £2	
tion	and then applying f1 to the result. f1, but not f2	
	may be Curried.	
Function iteration	yields the funciton equivalent to applying f n times.	
	n=0 yields the identity function which just returns the	
	value of its parameter; n=1 yields the function itself.	
	For n>1, the result of f must be contained in its pa-	
	rameter type.	

⁷Note that the total function arrow can only be used in signatures of totally defined functions and thus not in a type definition.



Examples: Let the following function values be defined:

```
f1 = lambda x : nat & lambda y : nat & x + y
f2 = lambda x : nat & x + 2
inc1 = lambda x : nat & x + 1
inc2 = lambda y : nat & y + 1
```

then the following holds:

Notice that the equality test does not yield the expected result with respect to the semantics of the VDM languages. Thus, one should be **very** careful with the usage of equality for infinite values like functions.

3.3 Invariants

If the data types specified by means of equations as described above contain values which should not be allowed, then it is possible to restrict the values in a type by means of an invariant. The result is that the type is restricted to a subset of its original values. Thus, by means of a predicate the acceptable values of the defined type are limited to those where this expression is true.

The general scheme for using invariants looks like this:

```
Id = Type
inv pat == expr
```

where pat is a pattern matching the values belonging to the type Id, and expr is a truth-valued expression, involving some or all of the identifiers from the pattern pat.

If an invariant is defined, a new (total) function is implicitly created with the signature:

```
inv_Id : Type +> bool
```

This function can be used within other invariant, function or operation definitions.

For instance, recall the record type Score defined on page 24. We can ensure that the number of points awarded is consistent with the number of games won and drawn using an invariant:

```
Score :: team : Team won : nat
```



```
drawn : nat
    lost : nat
    points : nat

inv sc == sc.points = 3 * sc.won + sc.drawn;
```

The invariant function implicitly created for this type is:

```
inv_Score : Score +> bool
inv_Score (sc) ==
   sc.points = 3 * sc.won + sc.drawn;
```



Chapter 4

Algorithm Definitions

In the VDM languages algorithms can be defined by both functions and operations. However, they do not directly correspond to functions in traditional programming languages. What separates functions from operations in the VDM languages is the use of local and global variables. Operations can manipulate both the global variables and any local variables. Both local and global variables will be described later. Functions are pure in the sense that they cannot access global variables and they are not allowed to define local variables. Thus, functions are purely applicative while operations are imperative.

Functions and operations can be defined both explicitly (by means of an explicit algorithm definition) or implicitly (by means of a pre-condition and/or a post condition). An explicit algorithm definition for a function is called an expression while for an operation it is called a statement. A pre-condition is a truth-valued expression which specifies what must hold before the function/operation is evaluated. A pre-condition can only refer to parameter values and global variables (if it is an operation). A post-condition is also a truth valued expression which specifies what must hold after the function/operation is evaluated. A post-condition can refer to the result identifier, the parameter values, the current values of global variables and the old values of global variables. The old values of global variables are the values of the variables as they were before the operation was evaluated. Only operations can refer to the old values of global variables in a post-condition as functions are not allowed access to the global variables in any way.

However, in order to be able to execute both functions and operations by the VDM interpreters they must be defined explicitly¹. In the VDM languages it is also possible for explicit function and operation definitions to specify an additional pre- and a post-condition. In the post-condition of explicit function and operation definitions the result value must be referred to by the reserved word **RESULT**.

¹Implicitly specified functions and operations cannot in general be executed because their post-condition does not need to directly relate the output to the input. Often it is done by specifying the properties the output must satisfy.



Chapter 5

Function Definitions

In the VDM languages we can define first order and higher order functions. A higher order function is either a Curried function (a function that returns a function as result), or a function that takes functions as arguments. Furthermore, both first order and higher order functions can be polymorphic. In VDM++ and VDM-RT functions are automatically available in a static form (i.e. without having an instance of the defining class). Thus there is no need to use the **static** keyword that can be used for operations in VDM++ and VDM-RT. In general, the syntax for the definition of a function is:

```
function definitions = 'functions', [ access function definition ],
                       { '; '}, access function definition function definition, [ '; '];
access function definition = [ access ], function definition ;
access = 'public'
           'private'
          'protected';
function definition = explicit function definition
                   implicit function definition
                      extended explicit function definition;
explicit function definition = identifier,
                              [ type variable list ], ':', function type,
                              identifier, parameters list, '==',
                              function body,
                              ['pre', expression],
                              ['post', expression],
                              ['measure', name];
implicit function definition = identifier, [ type variable list ],
                              parameter types, identifier type pair list,
                              ['pre', expression],
                               'post', expression;
```



```
extended explicit function definition = identifier, [ type variable list ],
                                        parameter types,
                                        identifier type pair list,
                                        '==', function body,
                                        ['pre', expression],
                                        ['post', expression];
type variable list = '[', type variable identifier,
                     { ', ', type variable identifier }, ']';
identifier type pair list = identifier, ':', type,
                          { ', ', identifier, ':', type } ;
parameter types = '(', [ pattern type pair list ], ')';
pattern type pair list = pattern list, ':', type,
                        { ', ', pattern list, ':', type } ;
function type = partial function type
              total function type;
partial function type = discretionary type, '->', type;
total function type = discretionary type, '+>', type;
discretionary type = type | '(',')';
parameters = '(', [ pattern list ], ')';
pattern list = pattern, { ', ', pattern } ;
function body = expression
                  'is not yet specified'
                  'is subclass responsibility';
```

Here is not yet specified may be used as the function body during development of a model; whereas the is subclass responsibility indicates that implementation of this body must be undertaken by any subclasses so that can only be used in VDM++ and VDM-RT.

A simple example of an explicit function definition is the function map_inter which takes two compatible maps over natural numbers and returns those maplets common to both

```
map_inter: (map nat to nat) * (map nat to nat) -> map nat to nat
map_inter (m1, m2) ==
  (dom m1 inter dom m2) <: m1
pre forall d in set dom m1 inter dom m2 & m1(d) = m2(d)</pre>
```



Note that we could also use the optional post condition to allow assertions about the result of the function:

```
map_inter: (map nat to nat) * (map nat to nat) -> map nat to nat
map_inter (m1, m2) ==
   (dom m1 inter dom m2) <: m1
pre forall d in set dom m1 inter dom m2 & m1(d) = m2(d)
post dom RESULT = dom m1 inter dom m2</pre>
```

The same function can also be defined implicitly:

```
map_inter2 (m1,m2: map nat to nat) m: map nat to nat
pre forall d in set dom m1 inter dom m2 & m1(d) = m2(d)
post dom m = dom m1 inter dom m2 and
    forall d in set dom m & m(d) = m1(d);
```

A simple example of an extended explicit function definition (non-standard) is the function map_disj which takes a pair of compatible maps over natural numbers and returns the map consisting of those maplets unique to one or other of the given maps:

(Note here that an attempt to interpret the post-condition could potentially result in a run-time error since m1 (d) and m2 (d) need not both be defined simultaneously.)

The functions map_inter and map_disj can be evaluated by the VDM interpreters, but the implicit function map_inter2 cannot be evaluated. However, in all three cases the pre- and post-conditions can be used in other functions; for instance from the definition of map_inter2 we get functions pre_map_inter2 and post_map_inter2 with the following signatures:



These kinds of functions are automatically created by the VDM interpreters and they can be used in other definitions (this technique is called quoting). In general, for a function f with signature

```
f : T1 * ... * Tn -> Tr
```

defining a pre-condition for the function causes creation of a function pre_f with signature

```
pre_f : T1 * ... * Tn +> bool
```

and defining a post-condition for the function causes creation of a function post_f with signature

```
post_f : T1 * ... * Tn * Tr +> bool
```

Functions can also be defined using recursion (i.e. by calling themselves). When this is done one is recommended to add a 'measure' function that can be used in the proof obligations generated from the model such that termination proofs can be carried out. The measure function shall take the same type of parameters as the recursive function itself and it yield a natural number. A simple example here could be the traditional factorial function defined as:

```
functions

fac: nat +> nat
fac(n) ==
  if n = 0
  then 1
  else n * fac(n - 1)
measure id
```

where id would be defined as:

Here the proof obligation will become:

```
forall n:nat &
  (not (n = 0) =>
   id(n) > id((n - 1)))
```



This proof obligation will ensure that the recursive function will terminate and thus sooner or later reach the base case.

5.1 Polymorphic Functions

Functions can also be polymorphic in VDM. This means that we can create generic functions that can be used on values of several different types. For this purpose type parameters (or type variables which are written like normal identifiers prefixed with a @ sign) are used. Consider the polymorphic function to create an empty bag:¹

```
empty_bag[@elem] : () +> (map @elem to nat1)
empty_bag() ==
{ |-> }
```

Before we can use the above function, we have to instantiate the function empty_bag with a type, for example integers (see also section 6.12):

```
emptyInt = empty_bag[int]
```

Now we can use the function emptyInt to create a new bag to store integers. More examples of polymorphic functions are:

If pre- and or post-conditions are defined for polymorphic functions, the corresponding predicate functions are also polymorphic. For instance if num_bag was defined as

```
num_bag[@elem] : @elem * (map @elem to nat1) +> nat
```

¹The examples for polymorphic functions are taken from [Dawes91]. Bags are modelled as maps from the elements to their multiplicity in the bag. The multiplicity is at least 1, i.e. a non-element is not part of the map, rather than being mapped to 0.



```
num_bag(e, m) ==
    m(e)
    pre e in set dom m
```

then the pre-condition function would be

```
pre_num_bag[@elem] :@elem * (map @elem to nat1) +> bool
```

In case functions are defined polymorphic a **measure** should also be used.

5.2 Higher Order Functions

Functions are allowed to receive other functions as arguments. A simple example of this is the function nat_filter which takes a sequence of natural numbers, and a predicate, and returns the subsequence that satisfies this predicate:

```
nat_filter : (nat -> bool) * seq of nat -> seq of nat
nat_filter (p,ns) ==
  [ns(i) | i in set inds ns & p(ns(i))];
```

Then nat_filter (lambda x:nat & x mod 2 = 0, [1,2,3,4,5]) $\equiv [2,4]$. In fact, this algorithm is not specific to natural numbers, so we may define a polymorphic version of this function:

```
filter[@elem]: (@elem -> bool) * seq of @elem -> seq of @elem
filter (p,l) ==
  [l(i) | i in set inds l & p(l(i))];
```

so filter[real] (lambda x:real & floor x = x, [2.3, 0.7, -2.1, 3]) $\equiv [3]$. Functions may also return functions as results. An example of this is the function fmap:

```
fmap[@elem]: (@elem -> @elem) -> seq of @elem -> seq of @elem
fmap (f)(1) ==
   if 1 = []
   then []
   else [f(hd 1)] ^ (fmap[@elem] (f)(tl 1));
```

```
So fmap[nat] (lambda x:nat & x * x) ([1,2,3,4,5]) \equiv [ 1,4,9,16,25 ].
```

Chapter 6

Expressions

In this chapter we will describe the different kinds of expressions one by one. Each of them will be described by means of:

- A syntax description in BNF.
- An informal semantics description.
- An example illustrating its usage.

6.1 Let Expressions

where the "function definition" component is described in section 5.

Semantics: A simple *let expression* has the form:

```
let p1 = e1, ..., pn = en in e
```



where p1, ..., pn are patterns, e1, ..., en are expressions which match the corresponding pattern pi, and e is an expression, of any type, involving the pattern identifiers of p1, ..., pn. It denotes the value of the expression e in the context in which the patterns p1, ..., pn are matched against the corresponding expressions e1, ..., en.

More advanced let expressions can also be made by using local function definitions. The semantics of doing so is simply that the scope of such locally defined functions is restricted to the body of the let expression.

In standard VDM-SL the collection of definitions may be mutually recursive. However, in the VDM languages this is not supported by the VDM interpreters. Furthermore, the definitions must be ordered such that all constructs are defined before they are used.

A *let-be-such-that expression* has the form:

```
let mb be st e1 in e2
```

where mb is a multi-binding of one or more patterns (mostly just one pattern) to a set value (or a type), e1 is a boolean expression, and e2 is an expression, of any type, involving the pattern identifiers of the patterns from mb. The **be** st e1 part is optional. The expression denotes the value of the expression e2 in the context in which all the patterns from mb has been matched against either an element in the set from mb or against a value from the type in mb¹. If the st e1 expression is present, only such bindings where e1 evaluates to true in the matching context are used.

Examples: Let expressions are useful for improving readability especially by contracting complicated expressions used more than once. For instance, we can improve the function map_disj from page 37:

They are also convenient for decomposing complex structures into their components. For instance, using the previously defined record type Score (see page 24) we can test whether one score is greater than another:

```
let mk_Score(-,w1,-,-,p1) = sc1,
```

¹Remember that only the set bindings can be executed by means of the VDM interpreters.



```
mk\_Score(-,w2,-,-,p2) = sc2
in (p1 > p2) or (p1 = p2 and w1 > w2)
```

In this particular example we extract the second and fifth components of the two scores. Note that don't care patterns (see page 75) are used to indicate that the remaining components are irrelevant for the processing done in the body of this expression.

Let-be-such-that expressions are useful for abstracting away the non-essential choice of an element from a set, in particular in formulating recursive definitions over sets. An example of this is a version of the sequence filter function (see page 40) over sets:

We could alternatively have defined this function using a set comprehension (described in section 6.7):

The last example shows how the optional "be such that" part (**be st**) can be used. This part is especially useful when it is known that an element with some property exists but an explicit expression for such an element is not known or difficult to write. For instance we can exploit this expression to write a selection sort algorithm:

```
remove : nat * seq of nat -> seq of nat
remove (x,1) ==
  let i in set inds l be st l(i) = x
  in
  l(1,...,i-1) ^ l(i+1,...,len l)
pre x in set elems l;

selection_sort : seq of nat -> seq of nat
```



Here the first function removes a given element from the given list; the second function repeatedly removes the least element in the unsorted portion of the list, and places it at the head of the sorted portion of the list.

6.2 The Define Expression

This expression can only be used inside operations which will be described in section 11. In order to deal with global variables inside the expression part an extra expression construct is available inside operations.

Semantics: A *define expression* has the form:

```
def pb1 = e1;
    ...
    pbn = en
    in
    e
```

The *define expression* corresponds to a let expression except that the right hand side expressions may depend on the value of the local and/or global variable and that it may not be mutually recursive. It denotes the value of the expression e in the context in which the patterns (or binds) pb1, ..., pbn are matched against the corresponding expressions e1, ..., en².

²If binds are used, it simply means that the values which can match the pattern are further constrained by the type or set expression as explained in Chapter 7.



Examples: The *define expression* is used in a pragmatic way, in order to make the reader aware of the fact that the value of the expression depends upon the global variable.

This can be illustrated by a small example:

```
def user = lib(copy)
in
  if user = <OUT>
  then true
  else false
```

where copy is defined in the context, lib is global variable (thus lib (copy) can be considered as looking up the contents of a part of the variable).

The operation GroupRunnerUp_expl in section 12.1 also gives an example of a define expression.

6.3 Unary and Binary Expressions

```
Syntax:
          expression = ...
                       unary expression
                     binary expression
          unary expression = prefix expression
                            map inverse;
          prefix expression = unary operator, expression;
          unary operator = '+' | '-' | 'abs' | 'floor' | 'not' | 'reverse'
                          'card' | 'power' | 'dunion' | 'dinter'
                          'hd' | 'tl' | 'len' | 'elems' | 'inds' | 'conc'
                          'dom' | 'rng' | 'merge';
          map inverse = 'inverse', expression;
          binary expression = expression, binary operator, expression;
          binary operator = '+' | '-' | '*' | '/'
                        | 'rem' | 'div' | 'mod' | '**'
                          'union' | 'inter' | '\' | 'subset'
                           'psubset' | 'in set' | 'not in set'
```



```
'++' | 'munion' | '<:' | '<-:' | ':>' | ':->'
| 'and' | 'or'
| '=>' | '<=>' | '=' | '<>'
| '<' | '<=' | '>' | '>='
| 'comp';
```

Semantics: Unary and binary expressions are a combination of operands and operators denoting a value of a specific type. The signature of all these operators is already given in Chapter 3, so no further explanation will be provided here. The map inverse unary operator is treated separately because it is written with postfix notation in the mathematical syntax.

Examples: Examples using these operators were given in Chapter 3, so none will be provided here.

6.4 Conditional Expressions

Semantics: *If expressions* and *cases expressions* allow the choice of one from a number of expressions on the basis of the value of a particular expression.

The *if expression* has the form:



```
if e1
then e2
else e3
```

where e1 is a boolean expression, while e2 and e3 are expressions of any type. The if expression denotes the value of e2 evaluated in the given context if e1 evaluates to true in the given context. Otherwise the if expression denotes the value of e3 evaluated in the given context. The use of an **elseif** expression is simply a shorthand for a nested if then else expression in the **else** part of the expression.

The cases expression has the form

where e is an expression of any type, all pij's are patterns which are matched one by one against the expression e. The ei's are expressions of any type, and the keyword **others** and the corresponding expression emplus1 are optional. The cases expression denotes the value of the ei expression evaluated in the context in which one of the pij patterns has been matched against e. The chosen ei is the first entry where it has been possible to match the expression e against one of the patterns. If none of the patterns match e an **others** clause must be present, and then the cases expression denotes the value of emplus1 evaluated in the given context.

Examples: The if expression in the VDM languages corresponds to what is used in most programming languages, while the cases expression in the VDM languages is more general than most programming languages. This is shown by the fact that real pattern matching is taking place, but also because the patterns do not have to be constants as in most programming languages.

An example of the use of conditional expressions is provided by the specification of the mergesort algorithm:

```
lmerge : seq of nat * seq of nat -> seq of nat
lmerge (s1,s2) ==
  if s1 = []
  then s2
  elseif s2 = []
  then s1
```



The pattern matching provided by cases expressions is useful for manipulating members of type unions. For instance, using the type definition Expr from page 27 we have:

```
print_Expr : Expr -> seq1 of char
print_Expr (e) ==
  cases e:
    mk_Const(-) -> "Const of" ^ (print_Const(e)),
    mk Var(id,-) -> "Var of" ^ id,
    mk_Infix(mk_(e1,op,e2)) -> "Infix of" ^ print_Expr(e1)^","
                                     ^ print_Op(op) ^ ","
                                     ^ print_Expr(e2),
    mk_Cond(t,c,a) -> "Cond of" ^ print_Expr(t) ^ ","
                                ^ print_Expr(c) ^ ","
                                ^ print_Expr(a)
 end;
print_Const : Const -> seq1 of char
print_Const(mk_Const(c)) ==
  if is_nat(c)
 then "nat"
  else -- must be bool
       "bool";
```

The function print_Op would be defined similarly.

6.5 Quantified Expressions

```
Syntax: expression = \dots
```



```
| quantified expression | ...; | quantified expression = all expression | exists expression | exists unique expression ; | all expression = 'forall', bind list, '&', expression ; | exists expression = 'exists', bind list, '&', expression ; | bind list = multiple bind, { ', ', multiple bind } ; | exists unique expression = 'exists1', bind, '&', expression ; |
```

Semantics: There are three forms of quantified expressions: *universal* (written as **forall**), *existential* (written as **exists**), and *unique existential* (written as **exists1**). Each yields a boolean value **true** or **false**, as explained in the following.

The *universal quantification* has the form:

```
forall mbd1, mbd2, ..., mbdn & e
```

where each mbdi is a multiple bind pi in set s (or if it is a type bind pi : type), and e is a boolean expression involving the pattern identifiers of the mbdi's. It has the value true if e is true when evaluated in the context of every choice of bindings from mbd1, mbd2, ..., mbdn and false otherwise.

The *existential quantification* has the form:

```
exists mbd1, mbd2, ..., mbdn & e
```

where the mbdi's and the e are as for a universal quantification. It has the value **true** if e is **true** when evaluated in the context of at least one choice of bindings from mbd1, mbd2, ..., mbdn, and **false** otherwise.

The *unique existential quantification* has the form:

```
exists1 bd & e
```

where bd is either a set bind or a type bind and e is a boolean expression involving the pattern identifiers of bd. It has the value **true** if e is **true** when evaluated in the context of exactly one choice of bindings, and **false** otherwise.



All quantified expressions have the lowest possible precedence. This means that the longest possible constituent expression is taken. The expression is continued to the right as far as it is syntactically possible.

Examples: An example of an existential quantification is given in the function shown below, QualificationOk. This function, taken from the specification of a nuclear tracking system in [Fitzgerald&98], checks whether a set of experts has a required qualification.

The function min gives us an example of a universal quantification:

```
min(s: set of nat) x: nat
pre s <> {}
post x in set s and
    forall y in set s \ {x} & y < x</pre>
```

We can use unique existential quantification to state the functional property satisfied by all maps m:

```
forall d in set dom m &
  exists1 r in set rng m & m(d) = r
```

6.6 The Iota Expression

```
Syntax: expression = ... | iota expression
```



```
iota expression = 'iota', bind, '&', expression ;
```

Semantics: An *iota expression* has the form:

```
iota bd & e
```

where bd is either a set bind or a type bind, and e is a boolean expression involving the pattern identifiers of bd. The **iota** operator can only be used if a unique value exists which matches the bind and makes the body expression e yield **true** (i.e. **exists1** bd & e must be **true**). The semantics of the iota expression is such that it returns the unique value which satisfies the body expression (e).

Examples: Using the values sc1, ..., sc4 defined by

```
sc1 = mk_Score (<France>, 3, 0, 0, 9);
sc2 = mk_Score (<Denmark>, 1, 1, 1, 4);
sc3 = mk_Score (<SouthAfrica>, 0, 2, 1, 2);
sc4 = mk_Score (<SaudiArabia>, 0, 1, 2, 1);
```

we have

```
iota x in set \{sc1, sc2, sc3, sc4\} & x.team = <France> \equiv sc1 iota x in set \{sc1, sc2, sc3, sc4\} & x.points > 3 \equiv \bot iota x : Score & x.points < x.won \equiv \bot
```

Notice that the last example cannot be executed and that the last two expressions are undefined - in the former case because there is more than value satisfying the expression, and in the latter because no value satisfies the expression.

6.7 Set Expressions



Semantics: A *Set enumeration* has the form:

```
{e1, e2, e3, ..., en}
```

where e1 up to en are general expressions. It constructs a set of the values of the enumerated expressions. The empty set must be written as $\{\}$.

The set comprehension expression has the form:

```
{e | mbd1, mbd2, ..., mbdn & P}
```

It constructs a set by evaluating the expression e on all the bindings for which the predicate P evaluates to **true**. A multiple binding can contain both set bindings and type bindings. Thus mbdn will look like pat1 in **set** s1, pat2: tp1, ...in **set** s2, where pati is a pattern (normally simply an identifier), and s1 and s2 are sets constructed by expressions (whereas tp1 is used to illustrate that type binds can also be used). Notice however that type binds can only be executed by the VDM interpreters in case the types can be statically declared as finite.

The set range expression is a special case of a set comprehension. It has the form

```
{e1, ..., e2}
```

where e1 and e2 are numeric expressions. The set range expression denotes the set of integers from e1 to e2 inclusive. If e2 is smaller than e1 the set range expression denotes the empty set.

Examples: Using the values Europe={<France>, <England>, <Denmark>, <Spain>} and GroupC = {sc1, sc2, sc3, sc4} (where sc1, ..., sc4 are as defined in the preceding example) we have



```
{<France>, <Spain>} subset Europe
                                            ≡ true
{<Brazil>, <Chile>, <England>}
                                            ≡ false
     subset Europe
{<France>, <Spain>, "France"}
                                            ≡ false
     subset Europe
{sc.team | sc in set GroupC
                                            \equiv {<France>,
     \& sc.points > 2
                                                 <Denmark>}
{sc.team | sc in set GroupC
                                            \equiv {<SouthAfrica>,
     & sc.lost > sc.won }
                                                 <SaudiArabia>}
{2.718,...,3.141}
                                            \equiv \{3\}
{3.141,...,2.718}
\{1, \ldots, 5\}
                                            \equiv \{1, 2, 3, 4, 5\}
\{ x \mid x : nat \& x < 10 \ and x \ mod 2 = 0 \} \equiv \{0, 2, 4, 6, 8 \}
```

6.8 Sequence Expressions

Semantics: A *sequence enumeration* has the form:

```
[e1, e2, ..., en]
```

where e1 through en are general expressions. It constructs a sequence of the enumerated elements. The empty sequence must be written as [].

A sequence comprehension has the form:

```
[e | pat in set S & P]
```

where the expression e will use the identifiers from the pattern pat (normally this pattern will simply be an identifier, but the only real requirement is that exactly one pattern identifier



must be present in the pattern). S is a set of values (normally natural numbers). The bindings of the pattern identifier must be to some kind of numeric values which then are used to indicate the ordering of the elements in the resulting sequence. It constructs a sequence by evaluating the expression e on all the bindings for which the predicate P evaluates to **true**.

A *subsequence* of a sequence 1 is a sequence formed from consecutive elements of 1; from index n1 up to and including index n2. It has the form:

```
l(n1, ..., n2)
```

where n1 and n2 are positive integer expressions. If the lower bound n1 is smaller than 1 (the first index in a non-empty sequence) the subsequence expression will start from the first element of the sequence. If the upper bound n2 is larger than the length of the sequence (the largest index which can be used for a non-empty sequence) the subsequence expression will end at the last element of the sequence.

Examples: Given that GroupA is equal to the sequence

```
[ mk_Score(<Brazil>,2,0,1,6),
    mk_Score(<Norway>,1,2,0,5),
    mk_Score(<Morocco>,1,1,1,4),
    mk_Score(<Scotland>,0,1,2,1) ]
```

then:

```
[GroupA(i).team
                             \equiv [<Brazil>,
| i in set inds GroupA
                                 <Norway>,
& GroupA(i).won <> 0]
                                 <Morocco>1
                             \equiv [mk_Score (<Scotland>, 0, 1, 2, 1)]
[GroupA(i)
| i in set inds GroupA
& GroupA(i).won = 0]
GroupA(1,...,2)
                                [mk_Score (<Brazil>, 2, 0, 1, 6),
                                 mk_Score (<Norway>, 1, 2, 0, 5)]
[GroupA(i)
                             \equiv
                                []
| i in set inds GroupA
& GroupA(i).points = 9
```

6.9 Map Expressions

```
Syntax: expression = ... | map enumeration | map comprehension | ...;
```



Semantics: A *map enumeration* has the form:

```
{d1 |-> r1, d2 |-> r2, ..., dn |-> rn}
```

where all the domain expressions di and range expressions ri are general expressions. The empty map must be written as $\{ \mid -> \}$.

A map comprehension has the form:

```
{ed |-> er | mbd1, ..., mbdn & P}
```

where constructs mbd1, ..., mbdn are multiple bindings of variables from the expressions ed and er to sets (or types). The *map comprehension* constructs a mapping by evaluating the expressions ed and er on all the possible bindings for which the predicate P evaluates to **true**.

Examples: Given that GroupG is equal to the map

```
{ <Romania> |-> mk_(2,1,0), <England> |-> mk_(2,0,1), <Colombia> |-> mk_(1,0,2), <Tunisia> |-> mk_(0,1,2) }
```

then:



6.10 Tuple Constructor Expressions

```
Syntax: expression = ...

| tuple constructor
| ...;

tuple constructor = 'mk_', '(', expression, ', ', expression list, ')';
```

Semantics: The *tuple constructor expression* has the form:

```
mk_(e1, e2, ..., en)
```

where ei is a general expression. It can only be used by the equality and inequality operators.

Examples: Using the map GroupG defined in the preceding example, we have:

```
mk_{-}(2,1,0) in set rng GroupG \equiv true mk_{-}("Romania",2,1,0) not in set rng GroupG \equiv true mk_{-}(<Romania>,2,1,0) <> mk_{-}("Romania",2,1,0) \equiv true
```

6.11 Record Expressions

Semantics: The *record constructor* has the form:

```
mk_T(e1, e2, ..., en)
```

where the type of the expressions (e1, e2, ..., en) matches the type of the corresponding entrances in the composite type T.

The record modification has the form:



```
mu (e, id1 |-> e1, id2 |-> e2, ..., idn |-> en)
```

where the evaluation of the expression e returns the record value to be modified. All the identifiers idi must be distinct named entrances in the record type of e.

Examples: If sc is the value mk_Score (<France>, 3, 0, 0, 9) then

Further examples are demonstrated in the function win. This function takes two teams and a set of scores. From the set of scores it locates the scores corresponding to the given teams (wsc and lsc for the winning and losing team respectively), then updates these using the **mu** operator. The set of teams is then updated with the new scores replacing the original ones.

6.12 Apply Expressions

```
Syntax: expression = ...
| apply
| field select
| tuple select
| function type instantiation
| ...;
```



```
apply = expression, '(', [ expression list ], ')';
field select = expression, '.', identifier;
tuple select = expression, '.#', numeral;
function type instantiation = name, '[', type, { ', ', type }, ']';
```

Semantics: The *field select expression* can be used for records and it has already been explained in section 3.2.5 so no further explanation will be given here.

The *apply* is used for looking up in a map, indexing in a sequence, and finally for calling a function. In section 3.2.3 it has already been shown what it means to look up in a map. Similarly in section 3.2.2 it is illustrated how indexing in a sequence is performed.

In the VDM languages an operation can also be called here. This is not allowed in standard VDM-SL and because this kind of operation call can modify the state such usage should be done with care in complex expressions. Note however that such operation calls are not allowed to throw exceptions.

With such operation calls the order of evaluation can become important. Therefore the type checker will allow the user to enable or disable operation calls inside expressions.

The tuple select expression is used to extract a particular component from a tuple. The meaning of the expression is if e evaluates to some tuple $\mathbf{mk}_{-}(v1, \ldots, vN)$ and M is an integer in the range $\{1, \ldots, N\}$ then e. #M yields vM. If M lies outside $\{1, \ldots, N\}$ the expression is undefined.

The *function type instantiation* is used for instantiating polymorphic functions with the proper types. It has the form:

```
pf [ t1, ..., tn ]
```

where pf is the name of a polymorphic function, and t1, ..., tn are types. The resulting function uses the types t1, ..., tn instead of the variable type names given in the function definition.

Examples: Recall that GroupA is a sequence (see page 54), GroupG is a map (see page 55) and selection_sort is a function (see page 44):

```
GroupA(1) \equiv mk_Score(<Brazil>,2,0,1,6)

GroupG(<Romania>) \equiv mk_(2,1,0)

GroupG(<Romania>).#2 \equiv 1

selection_sort([3,2,9,1,3]) \equiv [1,2,3,3,9]
```

As an example of the use of polymorphic functions and function type instantiation, we use the example functions from section 5:



```
let emptyInt = empty_bag[int]
in
    plus_bag[int](-1, emptyInt())

=
{ -1 |-> 1 }
```

6.13 The New Expression (VDM++ and VDM-RT)

```
Syntax: expression = ... | new expression ;

new expression = 'new', name, '(', [ expression list ], ')';
```

Semantics: The *new expression* has the form:

```
new classname(e1, e2, ..., en)
```

An object can be created (also called *instantiated*) from its class description using a *new* expression. The effect of a *new* expression is that a 'new', unique object as described in class classname is created. The value of the *new* expression is a reference to the new object.

If the *new expression* is invoked with no parameters, an object is created in which all instance variables take their "default" values (i.e. the values defined by their initialisation conditions). With parameters, the *new expression* represents a *constructor* (see Section 11.1) and creates customised instances (i.e. where the instance variables may take values which are different from their default values).

Examples: Suppose we have a class called Queue and that default instances of Queue are empty. Suppose also that this class contains a constructor (which will also be called Queue) which takes a single parameter which is a list of values representing an arbitrary starting queue. Then we can create default instances of Queue in which the actual queue is empty using the expression

```
new Queue()
```

and an instance of Queue in which the actual queue is, say, e1, e2, e3 using the expression



```
new Queue([e1, e2, e3])
```

Using the class Tree defined on page 28 we create new Tree instances to construct nodes:

```
mk_node(new Tree(), x, new Tree())
```

6.14 The Self Expression (VDM++ and VDM-RT)

Semantics: The *self expression* has the form:

```
self
```

The self expression returns a reference to the object currently being executed. It can be used to simplify the name space in chains of inheritance.

Examples: Using the class Tree defined on page 28 we can specify a subclass called BST which stores data using the binary search tree approach. We can then specify an operation which performs a binary search tree insertion:

```
Insert : int ==> ()
Insert (x) ==
  (dcl curr_node : Tree := self;

while not curr_node.isEmpty() do
    if curr_node.rootval() < x
    then curr_node := curr_node.rightBranch()
    else curr_node := curr_node.leftBranch();
    curr_node.addRoot(x);
)</pre>
```

This operation uses a self expression to find the root at which to being traversal prior to insertion. Further examples are given in section 12.9.



6.15 The Threadid Expression (VDM++ and VDM-RT)

Semantics: The *threadid expression* has the form:

```
threadid
```

The threadid expression returns a natural number which uniquely identifies the thread in which the expression is executed. Note that periodic threads gets a new threadid at the start of each new period.

Examples: Using **threadid**'s it is possible to provide a VDM++ base class that implements a Java-style wait-notify in VDM++ using permission predicates. Any object that should be available for the wait-notify mechanism must derive from this base class.

```
class WaitNotify
 instance variables
    waitset : set of nat := {};
 operations
   protected wait: () ==> ()
    wait() ==
      let p = threadid
      in (
        AddToWaitSet( p );
        Awake();
       );
   AddToWaitSet : nat ==> ()
   AddToWaitSet(p) ==
      waitset := waitset union { p };
    Awake: () ==> ()
   Awake() ==
      skip;
   protected notify: () ==> ()
```



```
notify() ==
   if waitset <> {}
   then let arbitrary_process in set waitset
       in waitset := waitset \ {arbitrary_process};

protected notifyAll: () ==> ()
   notifyAll() ==
      waitset := {};

sync
   mutex(notifyAll, AddToWaitSet, notify);
   per Awake => threadid not in set waitset;

end WaitNotify
```

In this example the **threadid** expression is used in two places:

- In the Wait operation for threads to register interest in this object.
- In the permission predicate for Awake. An interested thread should call Awake following registration using Wait. It will then be blocked until its threadid is removed from the waitset following another thread's call to notify.

6.16 The Lambda Expression

```
Syntax: expression = ...

| lambda expression | ...;

lambda expression = 'lambda', type bind list, '&', expression;

type bind list = type bind, { ', ', type bind } ;

type bind = pattern, ':', type;
```

Semantics: A *lambda expression* is of the form:

```
lambda pat1 : T1, ..., patn : Tn & e
```

where the pati are patterns, the Ti are type expressions, and e is the body expression. The scope of the pattern identifiers in the patterns pati is the body expression. A lambda expression cannot be polymorphic, but apart from that, it corresponds semantically to an



explicit function definition as explained in chapter 5. A function defined by a lambda expression can be Curried by using a new lambda expression in the body of it in a nested way. When lambda expressions are bound to an identifier they can also define a recursive function.

Examples: An increment function can be defined by means of a lambda expression like:

```
Inc = lambda n : nat & n + 1
```

and an addition function can be Curried by:

```
Add = lambda a : nat & lambda b : nat & a + b
```

which will return a new lambda expression if it is applied to only one argument:

```
Add(5) \equiv lambda b : nat & 5 + b
```

Lambda expression can be useful when used in conjunction with higher-order functions. For instance using the function set_filter defined on page 43:

```
set_filter[nat] (lambda n:nat & n mod 2 = 0) (\{1, ..., 10\})
\equiv \{2, 4, 6, 8, 10\}
```

6.17 Narrow Expressions

Semantics: The *narrow expression* convert the given expression value into given type. Down-casting in class inheritance, and narrowing Union type are permit. However, conversions between unrelated types become type errors.

Examples: In following examples, there is no difference in the results of running the Test() and Test'(), But, there is a type error (DEF) in Test().

```
class S
end S
```



```
class C1 is subclass of S
instance variables
public a : nat := 1;
end C1
class C2 is subclass of S
instance variables
public b : nat := 2;
end C2
class A
operations
public
Test: () ==> seq of nat
Test() ==
let list : seq of S = [ new C1(), new C2() ]
 in
   return [ let e = list(i)
            in cases true:
                (isofclass(C1, e)) -> e.a,
                (isofclass(C2, e)) -> e.b
               end | i in set inds list ];
public
Test': () ==> seq of nat
Test'() ==
let list : seq of S = [ new C1(), new C2() ]
   return [ let e = list(i)
            in cases true:
                (isofclass(C1, e)) -> narrow_(e, C1).a,
                (isofclass(C2, e)) -> narrow_(e, C2).b
               end | i in set inds list ];
end A
```



```
class A
types
public C1 :: a : nat;
public C2 :: b : nat;
public S = C1 | C2;
operations
public
Test: () ==> nat
Test() ==
 let s : S = mk_C1(1)
   let c : C1 = s
   in
     return c.a;
public
Test': () ==> nat
Test'() ==
 let s : S = mk_C1(1)
   let c : C1 = narrow_(s, C1)
   in
     return c.a;
end A
```

6.18 Is Expressions



```
| 'rat' | 'real' | 'char' | 'token' );
type judgement = 'is_', '(', expression, ', ', type, ')';
```

Semantics: The *is expression* can be used with values that are either basic or record values (tagged values belonging to some composite type). The is expression yields true if the given value belongs to the basic type indicated or if the value has the indicated tag. Otherwise it yields false.

A type judgement is a more general form which can be used for expressions whose types cannot be statically determined. The expression $\mathbf{is}_{-}(e,t)$ is equal to true if and only if e is of type t.

Examples: Using the record type Score defined on page 24 we have:

An example of a type judgement:

```
Domain : map nat to nat | seq of (nat*nat) -> set of nat
Domain(m) ==
   if is_(m, map nat to nat)
    then dom m
   else {d | mk_(d,-) in set elems m}
```

In addition there are examples on page 27.

6.19 Base Class Membership (VDM++ and VDM-RT)

Semantic: The function isofbaseclass when applied to an object reference expression and a class name name yields the boolean value true if and only if name is a root superclass in the inheritance chain of the object referenced to by expression, and false otherwise.



Examples: Suppose that BinarySearchTree is a subclass of Tree, Tree is not a subclass of any other class and Queue is not related by inheritance to either Tree or BinarySearchTree. Let t be an instance of Tree, b is an instance of BinarySearchTree and q is an instance of Queue. Then:

```
isofbaseclass(Tree, t) \equiv true isofbaseclass(BinarySearchTree, b) \equiv false isofbaseclass(Queue, q) \equiv true isofbaseclass(Tree, b) \equiv true isofbaseclass(Tree, q) \equiv false
```

6.20 Class Membership

Semantics: The function **isofclass** when applied to an object reference expression and a class name name yields the boolean value **true** if and only if expression refers to an object of class name or to an object of any of the subclasses of name, and **false** otherwise.

Examples: Assuming the classes Tree, BinarySearchTree, Queue, and identifiers t, b, q as in the previous example, we have:

```
isofclass(Tree,t) \equiv true isofclass(Tree,b) \equiv true isofclass(Tree,q) \equiv false isofclass(Queue,q) \equiv true isofclass(BinarySearchTree,t) \equiv false isofclass(BinarySearchTree,b) \equiv true
```

6.21 Same Base Class Membership (VDM++ and VDM-RT)



Semantics: The function samebaseclass when applied to object references expression1 and expression2 yields the boolean value true if and only if the objects denoted by expression1 and expression2 are instances of classes that can be derived from the same root superclass, and false otherwise.

Examples: Assuming the classes Tree, BinarySearchTree, Queue, and identifiers t, b, q as in the previous example, suppose that AVLTree is another subclass of Tree, BalancedBST is a subclass of BinarySearchTree, a is an instance of AVLTree and bb is an instance of BalancedBST:

```
samebaseclass(a,b) \equiv true
samebaseclass(a,bb) \equiv true
samebaseclass(b,bb) \equiv true
samebaseclass(t,bb) \equiv false
samebaseclass(q,a) \equiv false
```

6.22 Same Class Membership (VDM++ and VDM-RT)

Semantics: The function **sameclass** when applied to object references expression1 and expression2 yields the boolean value **true** if and only if the objects denoted by expression1 and expression2 are instances of the same class, and **false** otherwise.

Examples: Assuming the classes Tree, BinarySearchTree, Queue, and identifiers t, b, q from section 6.19, and assuming b' is another instance of BinarySearchTree we have:

```
sameclass(b,t) \equiv false

sameclass(b,b') \equiv true

sameclass(q,t) \equiv false
```

6.23 History Expressions (VDM++ and VDM-RT)

```
Syntax: expression = ... | act expression | fin expression | active expression | req expression | waiting expression | ...;
```



Semantics: History expressions can only be used in permission predicates (see section 14.1). History expressions may contain one or more of the following expressions:

- #act (operation name). The number of times that operation name operation has been activated.
- **#fin** (*operation name*). The number of times that the *operation name* operation has been completed.
- **#active** (*operation name*). The number of *operation name* operations that are currently active.

Thus: #active(operation name) = #act(operation name) - #fin(operation name).

- #req (operation name). The number of requests that has been issued for the operation name operation.
- **#waiting** (*operation name*). The number of outstanding requests for the *operation name* operation.

Thus: #waiting (operation name) = #req (operation name) - #act (operation name).

For all of these operators, the name list version $\#history\ op(op1,...,opN)$ is simply shorthand for $\#history\ op(op1) + \cdots + \#history\ op(opN)$.

Examples: Suppose at a point in the execution of a particular thread, three operations, A, B and C may be executed. A sequence of requests, activations and completions occur during this thread. This is shown graphically in figure 6.1.

Here we use the notation rA to indicate a request for an execution of operation A, aA indicates an activation of A, fA indicates completion of an execution of operation A, and likewise for operations B and C. The respective history expressions have the following values after the interval [S,T]:





Figure 6.1: *History Expressions*

```
\#act(A) = 1
                \#act(B) = 1
                                \#act(C) = 1
                                                 \#act(A,B,C) = 3
                                                 \#fin(A,B,C) = 2
\#fin(A) = 1
                \#fin(B) = 1
                                \#fin(C) = 0
\#active(A) = 0
                \#active(B) = 0
                                \#active(C) = 1
                                                 \#active(A,B,C) = 1
                \#req(B) = 1
\#req(A) = 2
                                \#req(C) = 3
                                                 \#req(A,B,C) = 6
\#waiting(A) = 1 \#waiting(B) = 0 \#waiting(C) = 2 \#waiting(A,B,C) = 3
```

6.24 The Time Expression (VDM-RT)

Syntax: time expression = 'time';

Semantics: This is simply an easy way to refer to the current time on a given CPU. The time is provided as a natural number.

Examples: If for example one would like to log when a certain operation takes place one can create an operation such as logEnvToSys below.

```
public logEnvToSys: nat ==> ()
logEnvToSys (pev) == e2s := e2s munion {pev |-> time};
```

6.25 Literals and Names



Semantics: *Names* and *old names* are used to access definitions of functions, operations, values and state components. A *name* has the form:

```
id1'id2
```

where id1 and id2 are simple identifiers. If a name consists of only one identifier, the identifier is defined within scope, i.e. it is defined either locally as a pattern identifier or variable, or globally within the current module as a function, operation, value or global variable. Otherwise, the identifier id1 indicates the module/class name where the construct is defined (see also section 13.1 and section 13.3.1 and appendix B.)

An *old name* is used to access the old value of global variables in the post condition of an operation definition (see chapter 11) and in the post condition of specification statements (see section 12.15). It has the form:

```
id~
```

where id is a state component.

Symbolic literals are constant values of some basic type.

Examples: *Names* and *symbolic literals* are used throughout all examples in this document (see appendix B.2).

For an example of the use of *old names*, consider the VDM-SL state defined as:

```
state sigma of
  numbers : seq of nat
  index : nat
inv mk_sigma(numbers, index) ==
  index not in set elems numbers
init s == s = mk_sigma([], 1)
end
```

For an example of the use of *old names*, consider the VDM++/VDM-RT instance variables defined as:

```
instance variables
  numbers: seq of nat := [];
  index : nat := 1;
inv index not in set elems numbers;
```



We can define an operation that increases the variable index in an implicit manner:

```
IncIndex()
ext wr index : nat
post index = index~ + 1
```

The operation IncIndex manipulates the variable index, indicated with the **ext wr** clause. In the post condition, the new value of index is equal to the old value of index plus 1. (See more about operations in chapter 11).

For a simple example of module/class names, suppose that a function called build_rel is defined (and exported) in a module/class called CGRel as follows:

In another module/class we can access this function by in VDM-SL first importing the module CGRel then by using the following call

```
CGRel'build_rel({mk_(<A>, <B>)})
```

Note that in VDM++ and VDM-RT build_rel function can additionally have an access modifier allowing access to it outside the defining class.

6.26 The Undefined Expression

Semantics: The *undefined expression* is used to state explicitly that the result of an expression is undefined. This could for instance be used if it has not been decided what the result



of evaluating the else-branch of an if-then-else expression should be. When an *undefined expression* is evaluated the VDM interpreters will terminate the execution and report that an undefined expression was evaluated.

Pragmatically use of undefined expressions differs from pre-conditions: use of a pre-condition means it is the caller's responsibility to ensure that the pre-condition is satisfied when the function is called; if an undefined expression is used it is the called function's responsibility to deal with error handling.

Examples: We can check that the type invariant holds before building Score values:

```
build_score : Team * nat * nat * nat * nat -> Score
build_score (t,w,d,l,p) ==
   if 3 * w + d = p
   then mk_Score(t,w,d,l,p)
   else undefined
```

6.27 The Precondition Expression

Semantics: Assuming e is of function type the expression $pre_{-}(e, e1, ..., en)$ is true if and only if the pre-condition of e is true for arguments e1, ..., em where m is the arity of the pre-condition of e. If e is not a function or m > n then the result is **true**. If e has no pre-condition then the expression equals true.

Examples: Consider the functions f and q defined below

Then the expression



```
pre_(let h in set {f,g,lambda mk_(x,y): nat * nat & x div y}
in h, 1,0,-1)
```

is equal to

- false if h is bound to f since this equates to pre_f(1,0);
- true if h is bound to g since this equates to **pre**_g (1);
- true if h is bound to lambda $mk_-(x,y)$: nat * nat & x div y since there is no pre-condition defined for this function.

Note that however h is bound, the last argument (-1) is never used.

Chapter 7

Patterns

```
Syntax:
           pattern bind = pattern | bind ;
           pattern = pattern identifier
                      match value
                      set enum pattern
                      set union pattern
                      seq enum pattern
                      seq conc pattern
                      map enumeration pattern
                      map muinon pattern
                      tuple pattern
                      record pattern;
           pattern identifier = identifier | '-';
           match value = symbolic literal
                       (', expression, ')';
           set enum pattern = '{', [ pattern list], '}';
           set union pattern = pattern, 'union', pattern;
           seq enum pattern = '[', [ pattern list], ']';
           seq conc pattern = pattern, '^', pattern ;
           map enumeration pattern = '{', [ maplet pattern list], '}';
           maplet pattern list = maplet pattern, { ', ', maplet pattern } ;
           maplet pattern = pattern, '|->', pattern ;
```



```
map muinon pattern = pattern, 'munion', pattern ;
tuple pattern = 'mk_(', pattern, ', ', pattern list, ') ';
record pattern = 'mk_', name, '(', [ pattern list], ') ';
pattern list = pattern, { ', ', pattern } ;
```

Semantics: A pattern is always used in a context where it is matched to a value of a particular type. Matching consists of checking that the pattern can be matched to the value, and binding any pattern identifiers in the pattern to the corresponding values, i.e. making the identifiers denote those values throughout their scope. In some cases where a pattern can be used, a bind can be used as well (see next chapter). If a bind is used it simply means that additional information (a type or a set expression) is used to constrain the possible values which can match the given pattern.

Matching is defined as follows

- 1. A *pattern identifier* fits any type and can be matched to any value. If it is an identifier, that identifier is bound to the value; if it is the don't-care symbol '-', no binding occurs.
- 2. A *match value* can only be matched against the value of itself; no binding occurs. If a match value is not a literal like e.g. 7 or <RED> it must be an expression enclosed in parentheses in order to discriminate it to a pattern identifier.
- 3. A *set enumeration pattern* fits only set values. The patterns are matched to distinct elements of a set; all elements must be matched.
- 4. A *set union pattern* fits only set values. The two patterns are matched to a partition of two subsets of a set. In the VDM interpreters the two subsets will always be chosen such that they are non-empty and disjoint.
- 5. A *sequence enumeration pattern* fits only sequence values. Each pattern is matched against its corresponding element in the sequence value; the length of the sequence value and the number of patterns must be equal.
- 6. A *sequence concatenation pattern* fits only sequence values. The two patterns are matched against two subsequences which together can be concatenated to form the original sequence value. In the VDM interpreters the two subsequences will always be chosen so that they are non-empty.
- 7. A map enumeration pattern fits only map values.
- 8. A *maplet pattern list* are matched to distinct elements of a map; all elements must be matched.
- 9. A *map munion pattern* fits only map values. The two patterns are matched to a partition of two sub maps of a map. In the VDM interpreters the two sub maps will always be chosen such that they are non-empty and disjoint.



- 10. A *tuple pattern* fits only tuples with the same number of elements. Each of the patterns are matched against the corresponding element in the tuple value.
- 11. A *record pattern* fits only record values with the same tag. Each of the patterns are matched against the field of the record value. All the fields of the record must be matched.

Examples: The simplest kind of pattern is the pattern identifier. An example of this is given in the following let expression:

```
let top = GroupA(1)
in top.sc
```

Here the identifier top is bound to the head of the sequence GroupA and the identifier may then be used in the body of the let expression.

In the following examples we use match values:

Match values can only match against their own values, so here if the team at the head of GroupA is <Brazil> then the first clause is matched; if the team at the head of GroupA is <France> then the second clause is matched. Otherwise the **others** clause is matched. Note here that the use of brackets around a forces a to be considered as a match value.

Set enumerations match patterns to elements of a set. For instance in

```
let {sc1, sc2, sc3, sc4} = elems GroupA
in
    sc1.points + sc2.points + sc3.points + sc4.points;
```

the identifiers sc1, sc2, sc3 and sc4 are bound to the four elements of GroupA. Note that the choice of binding is loose – for instance sc1 may be bound to [any] element of **elems** GroupA. In this case if **elems** GroupA does not contain precisely four elements, then the expression is not well-formed.

A set union pattern can be used to decompose a set for recursive function calls. An example of this is the function set2seq which converts a set into a sequence (with arbitrary order):



In the third cases alternative we see the use of a set union pattern. This binds s1 and s2 to arbitrary subsets of s such that they partition s. The VDM interpreters always ensures a disjoint partition.

Sequence enumeration patterns can be used to extract specific elements from a sequence. An example of this is the function promoted which extracts the first two elements of a sequence of scores and returns the corresponding pair of teams:

```
promoted : seq of Score -> Team * Team
promoted([sc1,sc2]^-) == mk_(sc1.team,sc2.team);
```

Here sc1 is bound to the head of the argument sequence, and sc2 is bound to the second element of the sequence. If promoted is called with a sequence with fewer than two elements then a runtime error occurs. Note that as we are not interested in the remaining elements of the list we use a don't care pattern for the remainder.

The preceding example also demonstrated the use of sequence concatenation patterns. Another example of this is the function quicksort which implements a standard quicksort algorithm:

Here, in the second cases clause a sequence concatenation pattern is used to decompose 1 into an arbitrary pivot element and two subsequences. The pivot is used to partition the list



into those values less than the pivot and those values greater, and these two partitions are recursively sorted.

Tuple patterns can be used to bind tuple components to identifiers. For instance since the function promoted defined above returns a pair, the following value definition binds the winning team of GroupA to the identifier Awinner:

```
values

mk_(Awinner,-) = promoted(GroupA);
```

Record patterns are useful when several fields of a record are used in the same expression. For instance the following expression constructs a map from team names to points score:

```
{ t |-> w * 3 + 1 | mk_Score(t,w,1,-,-) in set elems GroupA}
```

The function print_Expr on page 48 also gives several examples of record patterns.



Chapter 8

Bindings

Semantics: A *bind* matches a pattern to a value. In a *set bind* the value is chosen from the set defined by the set expression of the bind. In a *type bind* the value is chosen from the type defined by the type expression. *Multiple bind* is the same as *bind* except that several patterns are bound to the same set or type. Notice that type binds **can** only be executed by the VDM interpreters in case the type can be deduced to be finite statically. This would require the VDM interpreters to search through infinite domains like the natural numbers.

Examples: Bindings are mainly used in quantified expressions and comprehensions which can be seen from these examples:

```
forall i, j in set inds list & i < j => list(i) <= list(j)
{ y | y in set S & y > 2 }
{ y | y: nat & y > 3 }
```



```
occurs : seq1 of char * seq1 of char -> bool
occurs (substr,str) ==
  exists i,j in set inds str & substr = str(i,...,j);
```

Chapter 9

Value (Constant) Definitions

The VDM languages supports the definition of constant values. A value definition corresponds to a constant definition in traditional programming languages.

Semantics: The value definition has the form:

```
values
  access pat1 = e1;
  ...
  access patn = en
```

where the access part only can be used in VDM++ and VDM-RT.

The global values (defined in a value definition) can be referenced at all levels in a VDM specification. However, in order to be able to execute a specification these values must be defined before they are used in the sequence of value definitions. This "declaration before use" principle is only used by the VDM interpreters for value definitions. Thus for instance functions can be used before they are declared. In standard VDM-SL there are not any restrictions on the order of the definitions at all. It is possible to provide a type restriction as well, and this can be useful in order to obtain more exact type information.

Details of the VDM++ and VDM-RT access specifiers can be found in section 13.3.3.

Examples: The example below, taken from [Fitzgerald&98] assigns token values to identifiers p1 and eid2, an Expert record value to e3 and an Alarm record value to a1.



As this example shows, a value can depend on other values which are defined previous to itself. The access modifiers **private**, **protected** and **public** can only be used in VDM++ and VDM-RT. A top-level VDM-SL specification can consist of specifications from a number of files or modules (see section 13.1). It is good practice not to let a value depend on values defined in other modules as the ordering is important.

Chapter 10

Declaration of Modifiable State Components

Syntactically the definition of state components that can be modified using VDM operations differ in VDM-SL compared with VDM++ and VDM-RT. Since VDM-SL is module based the state definition is similar to a monolitic record like construct. On the other hand VDM++ and VDM-RT are object-oriented and thus state components needs to be more flexible in order to enable inheritence of such definitions and thus they are defined in terms of instance variables. In the two sections in this chapter the two different ways of defining states is presented.

10.1 Instance Variables (VDM++ and VDM-RT)

Both an object instantiated from a class description and the class itself can have an internal state, also called the *instance variables* of the object or class. In the case of objects, we also refer to this state as the global state of the object.



Semantics: The section describing the internal state is preceded by the keyword **instance variables**. A list of instance variable definitions and/or invariant definitions follows. Each instance variable definition consists of an instance variable name with its corresponding type indication and may also include an initial value and access and **static** specifiers. Details of the access and **static** specifiers can be found in section 13.3.3.

It is possible to restrict the values of the instance variables by means of invariant definitions. Each invariant definition, involving one or more instance variables, may be defined over the values of the instance variables of objects of a class. All instance variables in the class including those inherited from superclasses are visible in the invariant expression. Each invariant definition must be a boolean expression that limits the values of the instance variables to those where the expression is true. All invariant expressions must be true during the entire lifetime of each object of the class.

The overall invariant expression of a class is all the invariant definitions of the class and its superclasses combined by logical **and** in the order that they are defined in 1) the superclasses and 2) the class itself.

Example: The following examples show instance variable definitions. The first class specifies one instance variable:

```
class GroupPhase
types
GroupName = <A> | <B> | <C> | <D> | <E> | <F> | <G> | <H>;
Team = \dots -- as on page 24
Score::team : Team
       won
           : nat
       drawn : nat
       lost : nat
       points : nat;
instance variables
gps : map GroupName to set of Score;
inv forall qp in set rng qps &
      (card gp = 4 and
       forall sc in set gp & sc.won + sc.lost + sc.drawn <= 3)
end GroupPhase
```



10.2 The State Definition (VDM-SL)

If global variables are desired in a VDM-SL specification, it is possible to make a state definition. The components of the state definition can be considered the collection of global variables which can be referenced inside operations. A state in a module is initialised before any of the operation definitions (using that state) in a module can be used by the VDM interpreters.

Semantics: The state definition has the form:

```
state ident of
   id1 : type1
   ...
   idn : typen
   inv pat1 == invpred
   init pat2 == initpred
   end
```

A state identifier idn is declared of a specific type typen. The invariant invpred is a boolean expression denoting a property which must hold for the state ident at all times. initpred denotes a condition which must hold initially. It should be noticed that in order to use the VDM interpreters, it is necessary to have an initialisation predicate (if any of the operations using the state are to be executed). In addition the body of this initialisation predicate must be a binary equality expression with the name (which also must be used as the pattern) of the entire state on the left-hand side of the equality and the right-hand side must evaluate to a record value of the correct type. This enables the VDM interpreters to evaluate the initpred condition. A simple example of an initialisation predicate is shown below:

```
state St of
    x: nat
    y: nat
    l: seq1 of nat
    init s == s = mk_St(0,0,[1])
    end
```



In the specification of both the invariant and the initial value the state must be manipulated as a whole, and this is done by referring to it as a record tagged with the state name (see the example). When a field in the state is manipulated in some operation, the field must however be referenced to directly by the field name without pre-fixing it with the state name.

Examples: In the following example we create one state variable:

```
types
GroupName = \langle A \rangle | \langle B \rangle | \langle C \rangle | \langle D \rangle | \langle E \rangle | \langle F \rangle | \langle G \rangle | \langle H \rangle
state GroupPhase of
  gps : map GroupName to set of Score
inv mk_GroupPhase(gps) ==
  forall qp in set rng qps &
     (card gp = 4 and
     forall sc in set gp & sc.won + sc.lost + sc.drawn <= 3)</pre>
init qp ==
  gp = mk_GroupPhase({<A> |-> init_sc({<Brazil>, <Norway>,
                                                 <Morocco>, <Scotland>}),
                            ...})
end
functions
init_sc : set of Team -> set of Score
init\_sc (ts) ==
  { mk_Score (t,0,0,0,0) | t in set ts }
```

In the invariant we state that each group has four teams, and no team plays more than three games. Initially no team has played any games.

Chapter 11

Operation Definitions

Operations have already been mentioned in chapter 4. The general form is described here and for VDM++ and VDM-RT special operations called *constructors* which are used for constructing instances of a class are described in section 11.1. Note that the **async** keyword can only be used in the VDM-RT dialect.

```
Syntax:
           operation definitions = 'operations', [ access operation definition ],
                                   { '; ', access operation definition } ;
     ,[';']
           access operation definition = (['async'][ access], ['static'])
                                         (['async']['static'],[ access]),
                                         operation definition;
           operation definition = explicit operation definition
                                  implicit operation definition
                                  extended explicit operation definition;
           explicit operation definition = identifier, ':', operation type,
                                          identifier, parameters,
                                          '==',
                                          operation body,
                                          ['pre', expression],
                                          ['post', expression];
           implicit operation definition = identifier, parameter types,
                                          [ identifier type pair list ],
                                          implicit operation body;
           implicit operation body = [ externals ],
                                      ['pre', expression],
```



```
'post', expression,
                           [ exceptions ];
extended explicit operation definition = identifier,
                                         parameter types,
                                         [ identifier type pair list ],
                                         '==', operation body,
                                         [ externals ],
                                         ['pre', expression],
                                         ['post', expression],
                                         [ exceptions ];
operation type = discretionary type, '==>', discretionary type;
discretionary type = type | '()';
parameters = '(', [ pattern list ], ')';
pattern list = pattern, { ', ', pattern } ;
operation body = statement
                 'is not yet specified'
'is subclass responsibility';
externals = 'ext', var information, { var information } ;
var information = mode, name list, [':', type];
mode = 'rd' | 'wr' ;
name list = identifier, { ', ', identifier } ;
exceptions = 'errs', error list;
error list = error, { error };
error = identifier, ':', expression, '->', expression;
```

Semantics: Operations in VDM are per default synchronous but if the keyword "async" is used in VDM-RT in front of an operation definition it means that that operation will be treated as an asynchronous operation. This means that the operation cannot have a return type and the thread calling an asynchronous operation will continue its own execution after having requested the invocation of the asynchronous operation. Note that constructors cannot be declared asynchronous. In both VDM++ and VDM-RT the details of the access and **static**



specifiers can be found in section 13.3.3. Note that a static operation may not call non-static operations, and self expressions cannot be used in the definition of a static operation.

The following example of an explicit operation updates the VDM-SL state GroupPhase and the VDM++ instance variables of class GroupPhase when one team beats another.

An explicit operation consists of a statement (or several composed using a block statement), as described in chapter 12. The statement may access any state/instance variables it wishes, reading and writing to them as it sees fit.

An implicit operation is specified using an optional pre-condition, and a mandatory post-condition. For example we could specify the Win operation implicitly:



The externals field lists the state/instance variables that the operation will manipulate. The state/instance variables listed after the reserved word **rd** can only be read whereas the operation can both read and write the variables listed after **wr**.

In VDM-SL these pre- and post-conditions the VDM interpreters also creates new functions as with the pre- and post-conditions of operation definitions. However, if a specification contains a global state, the state is also part of the newly created functions. Thus, functions with the following signatures are created for operations with pre- and/or post-conditions¹:

```
pre_Op : InType * State +> bool

post_Op : InType * OutType * State * State +> bool
```

with the following exceptions:

- If the operation does not take any arguments, the InType part of the signature is left out in both the pre_Op and post_Op signatures.
- If the operation does not return a value, the OutType part is left out in the **post**_Op signature.
- If the specification does not define a state, the State part(s) of both signatures are left out.

In the **post**_Op signature, the first State part is for the old state, whereas the second State part is for the state after the operation call.

For instance, consider the following specifications:

```
module A

definitions

state St of
   n : nat
end

operations

Op1 (a : nat) b :nat
```

¹However, you should remember that these pre and post condition predicates for an operation are simply boolean functions and the state components are thus not changed by calling such a predicate.



```
pre a > 0
post b = 2 * a;

Op2 () b : nat
post b = 2;

Op3 ()
post true
end A
```

```
module B

definitions

operations

Op1 (a : nat) b : nat
pre a > 0
post b = 2 * a;

Op2 () b : nat
post b = 2;

Op3 ()
post true
end B
```

For **module A** we could then quote the pre and post conditions defined in this specification as illustrated below



Quote expression	Explanation
pre _Op1(1, mk _St(2))	a bound to 1 in state St with n bound
	to 2
post_Op1(1,2,mk_St(1), mk_St(2))	a bound to 1, b bound to 2, state before
	with n bound to 1, state after with n
	bound to 2
$post_Op2(2,mk_St(1),mk_St(2))$	b bound to 2, state before with n bound
	to 1, state after with n bound to 2
$post_Op3(mk_St(1), mk_St(2))$	state before with n bound to 1, state af-
	ter with n bound to 2

For **module B** we can quote the pre and post conditions defined in this specification as illustrated below

Quote expression	Explanation
pre _Op1(1)	a bound to 1
post_Op1(1,2)	a bound to 1, b bound to 2
post_Op2(2)	b bound to 2
post_Op3()	No binding at all

The exceptions clause can be used to describe how an operation should deal with error situations. The rationale for having the exception clause is to give the user the ability to separate the exceptional cases from the normal cases. The specification using exceptions does not give any commitment as to how exceptions are to be signalled, but it gives the means to show under which circumstances an error situation can occur and what the consequences are for the result of calling the operation.

The exception clause has the form:

```
errs COND1: c1 -> r1
...
CONDn: cn -> rn
```

The condition names COND1, ..., CONDn are identifiers which describe the kind of error which can be raised². The condition expressions c1, ..., cn can be considered as preconditions for the different kinds of errors. Thus, in these expressions the identifiers from the arguments list and the variables from the externals list can be used (they have the same scope as the pre-condition). The result expressions r1, ..., rn can correspondingly be considered as post-conditions for the different kinds of errors. In these expressions the result identifier and old values of global variables (which can be written to) can also be used. Thus, the scope corresponds to the scope of the post-condition.

²Notice that these names are purely of mnemonic value, i.e. semantically they are not important.



An operation definition making use of an **errs** clause essentially gets an effective precondition which is a disjunction of the original pre-condition and all the condition expressions c1, ..., cn. The effective post-condition in these cases becomes a disjunction of the conjuncts (orig_pre and orig_post) and the c1 and r1, ..., cn and rn.

Superficially there appears to be some redundancy between exceptions and pre-conditions here. However there is a conceptual distinction between them which dictates which should be used and when. The pre-condition specifies what callers to the operation must ensure for correct behaviour; the exception clauses indicate that the operation being specified takes responsibility for error handling when an exception condition is satisfied. Hence normally exception clauses and pre-conditions do not overlap.

The next VDM-SL example of an operation uses the following state definition:

```
state qsys of
q: Queue
end
```

The next VDM++/VDM-RT example of an operation uses the following instance variable definition:

```
instance variables
q : Queue
```

This example shows how exceptions with an implicit definition can be used:

```
DEQUEUE() e: [Elem]
ext wr q : Queue
post q~ = [e] ^ q
errs QUEUE_EMPTY: q = [] -> q = q~ and e = nil
```

This is a dequeue operation which uses a global variable q of type Queue to get an element e of type Elem out of the queue. The exceptional case here is that the queue in which the exception clause specifies how the operation should behave is empty.

Note that the VDM interpreters for VDM-SL models creates a function here:

```
post_DEQUEUE: [Elem] * qsys * qsys +> bool
```



11.1 Constructors (VDM++ and VDM-RT)

Constructors are operations which have the same name as the class in which they are defined and which create new instances of that class. Their return type must therefore be the same class name, and if a return value is specified this should be **self** though this can optionally be omitted.

Multiple constructors can be defined in a single class using operation overloading as described in section 13.3.1.

Chapter 12

Statements

In this chapter the different kind of statements will be described one by one. Each of them will be described by means of:

- A syntax description in BNF.
- An informal semantics description.
- An example illustrating its usage.

12.1 Let Statements

where the "function definition" component is described in chapter 5.

Semantics: The *let statement* and the *let-be-such-that statement* are similar to the corresponding *let* and *let-be-such-that expressions* except that the *in* part is a statement instead of an expression. Thus it can be explained as follows:

A simple *let statement* has the form:



```
let p1 = e1, ..., pn = en in s
```

where p1, ..., pn are patterns, e1, ..., en are expressions which match the corresponding patterns pi, and s is a statement, of any type, involving the pattern identifiers of p1, ..., pn. It denotes the evaluation of the statement s in the context in which the patterns p1, ..., pn are matched against the corresponding expressions e1, ..., en.

More advanced let statements can also be made by using local function definitions. The semantics of doing that is simply that the scope of such locally defined functions is restricted to the body of the let statement.

A let-be-such-that statement has the form

```
let mb be st e in s
```

where mb is a multi-binding of one or more patterns (mostly just one pattern) to a set value (or a type), e is a boolean expression, and s is a statement, involving the pattern identifiers of the patterns from mb. The **be** st e part is optional. The expression denotes the evaluation of the statement s in the context where all the patterns from mb has been matched against an element in the set (or type) from mb¹. If the **be** st expression e is present, only such bindings where e evaluates to true in the matching context are used.

Examples: An example of a **let** be st statement is provided in the operation GroupWinner from the class GroupPhase which returns the winning team in a given group:

```
GroupWinner : GroupName ==> Team
GroupWinner (gp) ==

let sc in set gps(gp) be st
    forall sc' in set} gps(gp) \ {sc} &
        (sc.points > sc'.points) or
        (sc.points = sc'.points and sc.won > sc'.won)
in
    return sc.team
```

The companion operation GroupRunnerUp gives an example of a simple let statement as well:

```
GroupRunnerUp_expl : GroupName ==> Team
GroupRunnerUp_expl (gp) ==
```

¹Remember that only the set bindings can be executed by means of the VDM interpreters.



Note the use of the **def** statement (section 12.2) here; this is used rather than a **let** statement since the right-hand side is an operation call, and therefore is not an expression.

12.2 The Define Statement

Semantics: A *define statement* has the form:

```
def pb1 = e1;
    ...
    pbn = en
    in
    s
```

The *define statement* corresponds to a *define expression* except that it is also allowed to use operation calls on the right-hand sides. Thus, operations that change the state can also be used here, and if there are more than one definition they are evaluated in the order in which they are presented. It denotes the evaluation of the statement s in the context in which the patterns (or binds) pb1, ..., pbn are matched against the values returned by the corresponding expressions or operation calls e1, ..., en^2 .

²If binds are used it simply means that the values which can match the pattern are further constrained by the type or set expression as it is explained in section 7.



Examples: Given the following sequences:

```
secondRoundWinners = [<A>, <B>, <C>, <D>, <E>, <F>, <G>, <H>];
secondRoundRunnersUp = [<B>, <A>, <D>, <C>, <F>, <E>, <H>, <G>]
```

The operation SecondRound, in VDM++ from class GroupPhase returns the sequence of pairs representing the second round games gives an example of a **def** statement:

12.3 The Block Statement

Semantics: The *block statement* corresponds to block statements from traditional high-level imperative programming languages. It enables the use of locally defined variables (by means of the declare statement) which can be modified inside the body of the block statement. It simply denotes the ordered execution of what the individual statements prescribe. The first statement in the sequence that returns a value causes the evaluation of the sequence statement to terminate. This value is returned as the value of the block statement. If none of the statements in the block returns a value, the evaluation of the block statement is terminated



when the last statement in the block has been evaluated. When the block statement is left the values of the local variables are discharged. Thus, the scope of these variables is simply inside the block statement.

Examples: In the context of a VDM-SL state definition

```
state St of
   x: nat
   y: nat
   l: seq1 of nat
   end
```

or in the context of a VDM++ instance variables

```
instance variables
    x: nat;
    y: nat;
    l: seq1 of nat;
```

the operation Swap uses a block statement to swap the values of variables x and y:

```
Swap : () ==> ()
Swap () ==
  (dcl temp: nat := x;
    x := y;
    y := temp
)
```

12.4 The Assignment Statement



Semantics: The *assignment statement* corresponds to a generalisation of assignment statements from traditional high level programming languages. It is used to change the value of the global or local state. Thus, the assignment statement has side-effects on the state. However, in order to be able to simply change a part of the state, the left-hand side of the assignment can be a state designator. A state designator is either simply the name of a variable, a reference to a field of a variable, a map reference of a variable, or a sequence reference of a variable. In this way it is possible to change the value of a small component of the state. For example, if a state component is a map, it is possible to change a single entry in the map.

An assignment statement has the form:

```
sd := ec
```

where sd is a state designator, and ec is either an expression or a call of an operation. The assignment statement denotes the change to the given state component described at the right-hand side (expression or operation call). If the right-hand side is a state changing operation then that operation is executed (with the corresponding side effect) before the assignment is made.

Multiple assignment is also possible. This has the form:

All of the expressions or operation calls on the right hand sides are executed or evaluated, and then the results are bound to the corresponding state designators. The right-hand sides are executed atomically with respect to invariant evaluation. However in the case of a multi-threaded concurrent VDM++ or VDM-RT model, execution is not necessarily atomic with respect to task switching.



Examples: The operation in the previous example (Swap) illustrated normal assignment. The operation Win_sd, a refinement of Win on page 91 illustrates the use of state designators to assign to a specific map key:

The operation SelectionSort is a state based version of the function selection_sort on page 44. It demonstrates the use of state designators to modify the contents of a specific sequence index, using the VDM-SL state St or the VDM++ instance variables defined on page 101.

```
functions
min_index : seq1 of nat -> nat
min_index(1) ==
   if len 1 = 1
   then 1
   else let mi = min_index(tl 1)
        in if l(mi+1) < hd 1
            then mi+1
        else 1

operations

SelectionSort : nat ==> ()
SelectionSort (i) ==
   if i < len 1
   then (dcl temp: nat;</pre>
```



```
dcl mi : nat := min_index(l(i,...,len l)) + i - 1;
  temp := l(mi);
  l(mi) := l(i);
  l(i) := temp;
  SelectionSort(i+1)
);
```

The following VDM++ example illustrates multiple assignment.

```
class C
instance variables
size : nat;
1 : seq of nat;
inv size = len 1

operations
add1 : nat ==> ()
add1 (x) ==
   (1 := [x] ^ 1;
    size := size + 1);

add2 : nat ==> ()
add2 (x) ==
   atomic (1 := [x] ^ 1;
        size := size + 1)
end C
```

Here, in add1 the invariant on the class's instance variables is broken, whereas in add2 using the multiple assignment, the invariant is preserved.

12.5 Conditional Statements



Semantics: The semantics of the *if statement* corresponds to the *if expression* described in section 6.4 except for the alternatives which are statements (and that the **else** part is optional)³.

The semantics for the *cases statement* corresponds to the *cases expression* described in section 6.4 except for the alternatives which are statements.

Examples: Assuming functions clear_winner and winner_by_more_wins and operation RandomElement with the following signatures:

```
clear_winner : set of Score -> bool
winner_by_more_wins : set of Score -> bool
RandomElement : set of Team ==> Team
```

then the operation GroupWinner_if demonstrates the use of a nested if statement (the iota expression is presented on page 50):

```
GroupWinner_if : GroupName ==> Team
GroupWinner_if (gp) ==

if clear_winner(gps(gp))

-- return unique score in gps(gp) which has more points

-- than any other score

then return ((iota sc in set gps(gp) &

forall sc' in set gps(gp) \ {sc} &

sc.points > sc'.points).team)

elseif winner_by_more_wins(gps(gp))

-- return unique score in gps(gp) with maximal points

-- & has won more than other scores with maximal points

then return ((iota sc in set gps(gp) &

forall sc' in set gps(gp) \ {sc} &
```

³If the **else** part is omitted semantically it is like using **else skip**.



Alternatively, we could use a cases statement with match value patterns for this operation:

```
GroupWinner_cases : GroupName ==> Team
GroupWinner_cases (gp) ==
 cases true:
    (clear_winner(gps(gp))) ->
         return ((iota sc in set gps(gp) &
                   forall sc' in set gps(gp) \ {sc} &
                    sc.points > sc'.points).team),
    (winner_by_more_wins(gps(gp))) ->
         return ((iota sc in set gps(gp) &
                   forall sc' in set gps(gp) \ {sc} &
                      (sc.points > sc'.points) or
                      (sc.points = sc'.points and
                        sc.won > sc'.won)).team),
    others -> RandomElement ( {sc.team | sc in set gps(gp) &
                                 forall sc' in set gps(gp) &
                                  sc'.points <= sc.points} )</pre>
  end
```

12.6 For-Loop Statements



Semantics: There are three kinds of *for-loop statements*. The for-loop using an index is known from most high-level programming languages. In addition, there are two for-loops for traversing sets and sequences. These are especially useful if access to all elements from a set (or sequence) is needed one by one.

An *index for-loop statement* has the form:

```
for id = e1 to e2 by e3 do
s
```

where id is an identifier, e1 and e2 are integer expressions indicating the lower and upper bounds for the loop, e3 is an integer expression indicating the step size, and s is a statement where the identifier id can be used. It denotes the evaluation of the statement s as a sequence statement where the current context is extended with a binding of id. Thus, the first time s is evaluated id is bound to the value returned from the evaluation of the lower bound e1 and so forth until the upper bound is reached i.e. until s > e2. Note that e1, e2 and e3 are evaluated before entering the loop.

A set for-loop statement has the form:

```
for all e in set S do S
```

where S is a set expression. The statement s is evaluated in the current environment extended with a binding of e to subsequent values from the set S.

A sequence for-loop statement has the form:

```
for e in 1 do
```

where 1 is a sequence expression. The statement s is evaluated in the current environment extended with a binding of e to subsequent values from the sequence 1.

Examples: The operation Remove demonstrates the use of a *sequence-for* loop to remove all occurences of a given number from a sequence of numbers:



```
Remove : (seq of nat) * nat ==> seq of nat
Remove (k,z) ==
(dcl nk : seq of nat := [];
for elem in k do
   if elem <> z
   then nk := nk^[elem];
return nk
);
```

A *set-for* loop can be exploited to return the set of winners of all groups:

```
GroupWinners: () ==> set of Team
GroupWinners () ==
(dcl winners : set of Team := {};
for all gp in set dom gps do
   (dcl winner: Team := GroupWinner(gp);
   winners := winners union {winner}
   );
return winners
);
```

An example of a *index-for* loop is the classic bubblesort algorithm:



12.7 The While-Loop Statement

Semantics: The semantics for the *while statement* corresponds to the while statement from traditional programming languages. The form of a *while loop* is:

```
while e do
s
```

where e is a boolean expression and s a statement. As long as the expression e evaluates to **true** the body statement s is evaluated.

Examples: The *while loop* can be illustrated by the following example which uses Newton's method to approximate the square root of a real number r within relative error e.

12.8 The Nondeterministic Statement

Semantics: The *nondeterministic statement* has the form:



```
| | (stmt1, stmt2, ..., stmtn)
```

and it represents the execution of the component statements stmti in an arbitrary (non-deterministic) order. However, it should be noted that the component statements are not executed simultaneously. Notice that the VDM interpreters will use an underdetermined⁴ semantics even though this construct is called a non-deterministic statement.

Examples: Using the VDM-SL state definition

```
state St of
   x:nat
   y:nat
   l:seq1 of nat
   end
```

or the VDM++ instance variables

```
instance variables
x:nat;
y:nat;
l:seq1 of nat;
```

we can use the non-deterministic statement to effect a bubble sort:

Here BubbleMin "bubbles" the minimum value in the subsequence l(x, ..., y) to the head of the subsequence and BubbleMax "bubbles" the maximum value in the subsequence l(x, ..., y) to the last index in the subsequence. BubbleMin works by first iterating through the subsequence to find the index of the minimum value. The contents of this index are then swapped with the contents of the head of the list, l(x).

```
BubbleMin : () ==> ()
BubbleMin () ==
```

⁴Even though the user of the VDM interpreters does not know the order in which these statements are executed they are always executed in the same order unless the seed option is used.



BubbleMax operates in a similar fashion. It iterates through the subsequence to find the index of the maximum value, then swaps the contents of this index with the contents of the last element of the subsequence.

```
BubbleMax : () ==> ()
BubbleMax () ==
  (dcl z:nat := x;
    dcl m:nat := 1(z);
    -- find max val in 1(x..y)
for i = x to y do
    if 1(i) > m
    then ( m := 1(i);
        z := i);
    -- move max val to index y
    (dcl temp:nat;
    temp := 1(y);
    1(y) := 1(z);
    1(z) := temp;
    y := y-1));
```

12.9 The Call Statement

```
Syntax: statement = ... | call statement | ...;
```



For VDM-SL call statements are defined as:

Semantics: In VDM-SL the *call statement* has the form:

```
opname(param1, param2, ..., paramn)
```

In VDM++ and VDM-RT the *call statement* can additionally have the form:

```
object.opname(param1, param2, ..., paramn)
```

The *call statement* calls an operation, opname, (in a VDM++ and VDM-RT context it can also be on a specific object, object), and returns the result of evaluating the operation. Because operations can manipulate global variables a *call statement* does not necessarily have to return a value as function call do.

In VDM++ and VDM-RT if an *object designator* is specified it must yield an object reference to an object of a class in which the operation opname is defined, and then the operation must be specified as public. If no *object designator* is specified the operation will be called in the current object. If the operation is defined in a superclass, it must have been defined as public or protected.

Examples: In VDM-SL the operation ResetStack given below does not have any parameter and does not return a value whereas the operation PopStack returns the top element of the stack.



```
ResetStack();
...
top := PopStack();
```

where PopStack could be defined as:

```
PopStack: () ==> Elem
PopStack() ==
  def res = hd stack in
   (stack := t1 stack;
   return res)
pre stack <> []
post stack~ = [RESULT] ^ stack
```

where stack is a global variable.

In VDM++ and VDM-RT this Stack example can be made like:

```
class Stack
instance variables
    stack: seq of Elem := [];

operations

public Reset: () ==> ()
Reset() ==
    stack := [];

public Pop: () ==> Elem
Pop() ==
    def res = hd stack in
    (stack := t1 stack;
    return res)
pre stack <> []
post stack = [RESULT] ^ stack
end Stack
```

In the example the operation Reset does not have any parameters and does not return a



value whereas the operation Pop returns the top element of the stack. The stack could be used as follows:

```
( dcl stack := new Stack();
    stack.Reset();
    ....
    top := stack.Pop();
)
```

Inside class Stack the operations can be called as shown below:

```
Reset();
....
top := Pop();
```

Or using the **self** reference:

```
self.Reset();
top := self.Pop();
```

12.10 The Return Statement

Semantics: The *return statement* returns the value of an expression inside an operation. The value is evaluated in the given context. If an operation does not return a value, the expression must be omitted. A *return statement* has the form:

```
return e
```

or

```
return
```



where expression e is the return value of the operation.

Examples: In the following example OpCall is an operation call whereas FunCall is a function call. As the *if statement* only accepts statements in the two branches FunCall is "converted" to a statement by using the *return statement*.

```
if test
then OpCall()
else return FunCall()
```

For instance in VDM++, we can extend the stack class from the previous section with an operation which examines the top of the stack:

```
public Top : () ==> Elem
Top() ==
  return (hd stack)
pre stack <> [];
```

12.11 Exception Handling Statements

Semantics: The exception handling statements are used to control exception errors in a specification. This means that we have to be able to signal an exception within a specification. This can be done with the *exit statement*, and has the form:



```
exit e
```

or

```
exit
```

where e is an expression which is optional. The expression e can be used to signal what kind of exception is raised.

The *always statement* has the form:

```
always s1 in s2
```

where \$1 and \$2 are statements. First statement \$2 is evaluated, and regardless of any exceptions raised, statement \$1 is also evaluated. The result value of the complete *always statement* is determined by the evaluation of statement \$1: if this raises an exception, this value is returned, otherwise the result of the evaluation of statement \$2 is returned.

The *trap statement* only evaluates the handler statement, s1, when certain conditions are fulfilled. It has the form:

```
trap pat with s1 in s2
```

where pat is a pattern or bind used to select certain exceptions, s1 and s2 are statements. First, we evaluate statement s2, and if no exception is raised, the result value of the complete *trap statement* is the result of the evaluation of s2. If an exception is raised, the value of s2 is matched against the pattern pat. If there is no matching, the exception is returned as result of the complete *trap statement*, otherwise, statement s1 is evaluated and the result of this evaluation is also the result of the complete *trap statement*.

The recursive trap statement has the form:

```
tixe {
   pat1 |-> s1,
   ...
   patn |-> sn
} in s
```

where pat1, ..., patn are patterns or binds, s, s1, ..., sn are statements. First, statement s is evaluated, and if no exception is raised, the result is returned as the



result of the complete *recursive trap statement*. Otherwise, the value is matched in order against each of the patterns pati. When a match cannot be found, the exception is returned as the result of the *recursive trap statement*. If a match is found, the corresponding statement si is evaluated. If this does not raise an exception, the result value of the evaluation of si is returned as the result of the *recursive trap statement*. Otherwise, the matching starts again, now with the new exception value (the result of the evaluation of si).

Examples: In many programs, we need to allocate memory for a single operation. After the operation is completed, the memory is not needed anymore. This can be done with the *always statement*:

```
( dcl mem : Memory;
   always Free(mem) in
   ( mem := Allocate();
      Command(mem, ...)
   )
)
```

In the above example, we cannot act upon a possible exception raised within the body statement of the *always statement*. By using the *trap statement* we can catch these exceptions:

```
trap pat with ErrorAction(pat) in
( dcl mem : Memory;
  always Free(mem) in
  ( mem := Allocate();
    Command(mem, ...)
)
```

Now all exceptions raised within the *always statement* are captured by the *trap statement*. If we want to distinguish between several exception values, we can use either nested *trap statements* or the *recursive trap statement*:



In operation DoCommand we use the *always statement* in the allocation of memory, and all exceptions raised are captured by the *recursive trap statement* in operation Example. An exception with value <NOMEM> results in a return value of -1 and no exception raised. If the value of the exception is <BUSY> we try to perform the operation DoCommand again. If this raises an exception, this is also handled by the *recursive trap statement*. All other exceptions result in the return of the value -2.

12.12 The Error Statement

Semantics: The *error statement* corresponds to the undefined expression. It is used to state explicitly that the result of a statement is undefined and because of this an error has occurred. When an *error statement* is evaluated the VDM interpreters will terminate the execution of the specification and report that an *error statement* was evaluated.

Pragmatically use of error statements differs from pre-conditions as was the case with undefined expressions: use of a pre-condition means it is the caller's responsibility to ensure that the pre-condition is satisfied when the operation is called; if an error statement is used it is the called operation's responsibility to deal with error handling.

Examples: The operation SquareRoot on page 109 does not exclude the possibility that the number to be square rooted might be negative. If we do not wish this to be a pre-condition we can remedy this in the operation SquareRootErr:

```
SquareRootErr : real * real ==> real
SquareRootErr (r,e) ==
if r < 0</pre>
```



12.13 The Identity Statement

Semantics: The *identity statement* is used to signal that no evaluation takes place.

Examples: In the operation Remove in section 12.6 the behaviour of the operation within the **for** loop if elem=z is not explicitly stated. Remove 2 below does this.

```
Remove2 : (seq of nat) * nat ==> seq of nat
Remove2 (k,z) ==
  (dcl nk : seq of nat := [];
  for elem in k do
    if elem <> z
     then nk := nk^[elem]
    else skip;
  return nk
);
```

Here, we explicitly included the **else**-branch to illustrate the *identity statement*, however, in most cases the **else**-branch will not be included and the *identity statement* is implicitly assumed.

12.14 Start and Start List Statements (VDM++ and VDM-RT)

```
Syntax: statement = \dots
```



```
| start statement
| start list statement ;
start statement = 'start', '(', expression, ')';
start list statement = 'startlist', '(', expression, ')';
```

Semantics: The *start* and *start list* statements have the form:

```
start(aRef)
startlist(aRef_s)
```

If a class description includes a thread (see chapter 15), each object created from this class will have the ability to operate as a stand-alone virtual machine, or in other terms: the object has its own processing capability. In this situation, a *new expression* creates the 'process' leaving it in a waiting state. For such objects VDM++ and VDM-RT has a mechanism to change the waiting state into an active state⁵ in terms of a predefined operation, which can be invoked through a *start statement*.

The explicit separation of object creation and start provides the possibility to complete the initialisation of a (concurrent) system *before* the objects start exhibiting their described behaviour, in this way avoiding problems that may arise when objects are referred to that are not yet created and/or connected.

A syntactic variant of the start statement is available to start up a number of active objects in arbitrary order: the *start list statement*. The parameter aRef_s to **startlist** must be a set of object references to objects instantiated from classes containing a thread.

Examples: Consider the specification of an operating system. A component of this would be the daemons and other processes started up during the boot sequence. From this perspective, the following definitions are relevant:

```
types

runLevel = nat;

Process = Kerneld | Ftpd | Syslogd | Lpd | Httpd

instance variables
 pInit : map runLevel to set of Process
```

⁵When an object is in an active state, its behaviour can be described using a thread (see chapter 15).



where Kerneld is an object reference type specified elsewhere, and similarly for the other processes listed.

We can then model the boot sequence as an operation:

```
bootSequence : runLevel ==> ()
bootSequence(rl) ==
  for all p in set pInit(rl) do
    start(p);
```

Alternatively we could use the **startlist** statement here:

```
bootSequenceList : runLevel ==> ()
bootSequenceList(rl) ==
    startlist(pInit(rl))
```

12.15 The Specification Statement

Semantics: The specification statement can be used to describe a desired effect a statement in terms of a pre- and a post-condition. Thus, it captures the abstraction of a statement, permitting it to have an abstract (implicit) specification without being forced to an operation definition. The specification statement is equivalent with the body of an implicitly defined operation (see chapter 11). Thus specification statements can not be executed.

Examples: We can use a specification statement to specify a bubble maximum part of a bubble sort:



```
permutation(l^{\sim}(x,\ldots,y^{\sim}), l(x,\ldots,y^{\sim})) and forall i in set \{x,\ldots,y\} & l(i) < l(y^{\sim})]
```

(permutation is an auxiliary function taking two sequences which returns true iff one sequence is a permutation of the other.)

12.16 The Duration Statement (VDM-RT)

Semantics: The duration statement is a runtime directive to the VDM interpreters telling it that when incrementing the internal clock for the enclosed statement, the value (a natural number) given in the duration statement should be used instead of the increment which would normally be computed for that statement. Thus the duration statement provides a mechanism to override the VDM interpreter's default execution time computation.

Example: First a simple example:

```
while n < 10 do
   duration(10) n := n + 1;</pre>
```

In this example, assuming that this loop is not executed in the context of an enclosing duration statement, on each iteration of the loop the VDM interpreters will increment its internal clock by 10 time units (nanoseconds), rather than computing the amount of time required to execute the statement n := n + 1.

If duration statements are nested, the outermost one takes precedence and the remainder are ignored. For instance

```
duration(30)
( n := 1;
  while n < 10 do
    duration(10) n := n + 1;
)</pre>
```

The outer duration statement takes precedence, so assuming this is not executed in the context of an enclosing duration statement, the VDM interpreters would increment its internal clock by 30 time units when executing this statement.



Note that nesting can occur due to operation calls. Consider the following example:

```
op1 : nat ==> nat
op1(m) ==
   duration (20) return m + 1;

op2 : () ==> nat
op2() ==
( dcl n : nat := 3;
   duration(10) n := op1(1);
   return n)
```

When executing op2, if the call to op1 is executed, the duration statement in op1 will be overridden by the duration statement in the environment of the call. Thus in op2 following execution of the statement n := op1(1); the internal clock is incremented by 10 time units only.

12.17 The Cycles Statement (VDM-RT)

Semantics: The cycles statement is a runtime directive to the VDM interpreters telling it that when incrementing the internal clock for the enclosed statement, the value (a natural number) given in the cycles statement should be used as an indication of how many clock cycles that the enclosed statement should be incremented by instead of the increment which would normally be computed for that statement. Thus the cycles statement provides a mechanism to override the VDM interpreter's default execution time computation similar to the duration statement but in a way that is relative to the speed of the CPU that the computation is carried out on.

Example: First a simple example:

```
while n < 10 do
  cycles(1000) n := n + 1;</pre>
```

In this example, assuming that this loop is not executed in the context of an enclosing cycles statement, on each iteration of the loop the VDM interpreters will increment its internal clock by the time it will take to process 1000 instructions on the given CPU (relative to its



capacity), rather than computing the amount of time required to execute the statement n := n + 1.

If cycles statements are nested, the outermost one takes precedence and the remainder are ignored. For instance

```
cycles(3000)(
    n := 1;
    while n < 10 do
        cycles(1000) n := n + 1;
)</pre>
```

The outer cycles statement takes precedence, so assuming this is not executed in the context of an enclosing cycles statement, the interpreter would increment its internal clock by the time it takes to process 3000 instructions on the given CPU when executing this statement.

Note that nesting can occur due to operation calls. Consider the following example:

```
op1 : nat ==> nat
op1(m) ==
    cycles (2000) return m + 1;

op2 : () ==> nat
op2() ==
    (dcl n : nat := 3;
    cycles(1000) n := op1(1);
    return n)
```

When executing op2, if the call to op1 is executed, the cycles statement in op1 will be overridden by the cycles statement in the environment of the call. Thus in op2 following execution of the statement n := op1(1); the internal clock is incremented by the time it takes to process 1000 instructions on the given CPU only.

Chapter 13

Top-level Specification in VDM

The top-level specification structure differs significantly between the VDM-SL appraoch and the VDM++ and VDM-RT approach. In VDM-SL the ISO standard prescribes a flat-language but here a modular extension is also enabled using imports and exprts primitives. In VDM++ and VDM-RT structuring is done using object-oriented classes that can inherit constructs between them controlled by access modifiers. These two different approaches are explained in the two sections in this chapter.

13.1 Top-level Specification in VDM-SL

In the previous chapters all the VDM-SL constructs such as types, expressions, statements, functions and operations have been described. A number of these constructs can constitute a top-level VDM-SL specification. A top-level specification can be created in two ways:

- 1. The specification is split into a number of modules which are specified separately, but can depend on each other.
- 2. The specification is specified in a flat manner, i.e. no modules are used (note that in VDM-10 it is possible to have access to standard modules also from a flat VDM-SL specification).

Thus, a complete specification, or document, has the following syntax.

```
Syntax: document = any module, { any module } | definition block, { definition block } ; any module = module ;
```

13.1.1 A Flat Specification

As said, a flat specification does not use modules. This means that all constructs can be used throughout the specification. In the flat case, a document has a syntax of:



Thus, a flat specification is made up of several *definition* blocks. However, only one state definition is allowed. The following is an example of a flat top-level specification:

```
values
  st1 = mk_St([3,2,-9,11,5,3])
state St of
 1:seq1 of nat
end
functions
 min_index : seq1 of nat -> nat
 min_index(1) ==
    if len 1 = 1
    then 1
    else let mi = min_index(tl 1)
           if 1(mi+1) < hd 1
           then mi+1
           else 1
operations
  SelectionSort : nat ==> ()
  SelectionSort (i) ==
    if i < len 1
    then (dcl temp: nat;
          dcl mi : nat := min_index(l(i,...,len l)) + i - 1;
          temp := l(mi);
          l(mi) := l(i);
```



```
l(i) := temp;
SelectionSort(i+1)
)
```

13.1.2 A Structured Specification

As an extension to the standard VDM-SL language, it is possible to structure an VDM-SL specification using modules. In this section, the use of modules to create the top-level specification will be described. With the structuring facilities offered by VDM-SL it is possible to:

- Export constructs from a module.
- Import constructs from a module.
- Rename constructs upon import.
- Define a state in a module.

The Layout of a Module

Before the actual facilities are described, the general layout of a module is described. A module consists of three parts: a *module declaration*, an *interface section*, and a *definitions section*. It is possible to leave out the definitions part in the early development of a module specification.

In the module declaration, the module is named. The name must be a unique module name within the complete specification. The second part, the interface section, defines the relation of a module with other modules and consists of two sections. These sections are:

- An *imports section*. In the imports section, all the constructs that are going to be used from other modules are described. If constructs are going to be renamed it has to be done in the imports section.
- An *exports section*. Here all the constructs that are going to be used in other modules are defined. If no exports section is present the module cannot be used from any other modules.

The third part of a module declaration, the definitions section, contains all the definitions of the module. Thus, in general, the syntax of a module is:

To illustrate the use of modules, the example flat top-level specification are rewritten with some minor modifications. Some unimportant parts of the flat specification are left out for clarity.



The Exports Section

```
Syntax:
           interface = [ import definition list ],
                       export definition;
           export definition = 'exports', export module signature ;
           export module signature = 'all'
                                   export signature,
                                      { export signature };
           export signature = export types signature
                              values signature
                              export functions signature
                              operations signature;
           export types signature = 'types', type export,
                                    { '; ', type export }, [ '; '];
           type export = ['struct'], name;
           values signature = 'values', value signature,
                              { '; ', value signature }, [ '; '];
           value signature = name list, ':', type;
           export functions signature = 'functions' function export,
                                        { '; ', function export } ;
           function export = name list, [ type variable list ], ':',
                              function type;
           functions signature = 'functions' function signature,
                                 { '; ', function signature }, [ '; '];
           function signature = name list, ':', function type;
           operations signature = 'operations' operation signature,
                                  { '; ', operation signature }, [ '; '];
           operation signature = name list, ':', operation type;
```



Semantics: The exports section must be used to make constructs visible to other modules. Some or all of the defined constructs from a module can be exported. In the latter case, the keyword **all** is used. However, imported constructs are not exported from the module. If only part of the constructs are exported, the visible constructs with the appropriate signatures are stated.

Normally, if a construct is visible to another module, that construct can be considered to be defined inside the module. However, with types and operations there are some exceptions:

Types: If a type T is defined in module A and this type is also going to be used in module B, the type from module A has to be exported. This can be done in two ways:

- 1. The name of the type is exported.
- 2. The structure of the type is exported.

If only the name of the type is exported, the other module cannot create values of type \mathbb{T} . This means that the exporting module (A) must provide functions and/or operations to directly create and manipulate values of type \mathbb{T} by means of the constructors related to the representation of \mathbb{T} .

If we export the structure of the type by using the keyword **struct**, the other module can create and manipulate values of type T (it can also use mk_{-} keyword and the is_{-} keyword for this type if it is a record type).

If the type also defines an invariant, the invariant predicate function is only exported if the structure of the type is exported.

Operations: In a module, a state that is global for the module can be defined. All operations within the module can manipulate that state. If operations are exported from a module, they manipulate the state in the exporting module, i.e. the state in the module where they are defined.

If an exported function or an operation defines a pre- and/or post-condition, the corresponding predicate functions (see chapter 5) are also exported.

Examples: Consider a model of a bank account. An account is characterised by the name of the holder, the account number, the bank branch at which the account is maintained, the balance, and an encrypted PIN code for the ATM card. We might model this as follows:



```
types
 digit = nat
  inv d == d < 10;
  account:: holder : seq1 of char
             number : seq1 of digit
             branchcode : seq1 of digit
             balance: real
             epin: nat
  inv mk_account (holder, number, branchcode, -, -) ==
    len number = 8 and len branchcode = 6
functions
    digval : digit -> nat
    digval(d) == d;
    deposit: account * real -> account
    deposit (acc, r) ==
      mu(acc,balance |-> acc.balance + r);
    withdrawal : account * real -> account
    withdrawal (acc,r) ==
      mu(acc,balance |-> acc.balance - r);
    isPin : account * nat -> bool
    isPin(acc,ep) ==
      ep = acc.epin;
    requestWithdrawal : account * nat -> bool
    requestWithdrawal (acc,amt) ==
      acc.balance > amt
end BankAccount
```

In this module we export two types and five functions. Note that since we have enumerated the entities we are exporting, but have not exported digit or account using the **struct** keyword, the internals of account values may not be accessed by other modules, neither may the invariant for digit. If such access is necessary, the types should be exported with the **struct** keyword, or all constructs in the module should be exported using the



exports all clause.

The module Keypad given below models the keypad interface of an ATM machine. The state variable maintains a buffer of data typed at the keypad by the user.

```
module Keypad
imports
from BankAccount types digit
exports all
definitions
state buffer of
  data : seq of BankAccount 'digit
end
operations
    DataAvailable : () ==> bool
    DataAvailable () ==
      return(data <> []);
    ReadData : () ==> seq of BankAccount 'digit
    ReadData () ==
      return (data);
    WriteData : seq of BankAccount 'digit ==> ()
    WriteData (d) ==
      data := data^d
end Keypad
```

In this module all constructs are exported. Since the only entities defined are the state and operations on it, this means that all of the operations may be accessed by an importing module. The state is not accessible to importing modules, but remains private to this module. However the state constructor **mk**_Keypad 'buffer is accessible.

The Imports Section

```
Syntax: interface = [ import definition list ],
```



```
export definition;
import definition list = 'imports', import definition,
                       { ', ', import definition } ;
import definition = 'from', identifier, import module signature;
import module signature = 'all'
                           import signature,
                           { import signature };
import signature = import types signature
                   import values signature
                   import functions signature
                   import operations signature;
import types signature = 'types', type import,
                         { '; ', type import }, [ '; '];
type import = name, [ 'renamed', name ]
              type definition, [ 'renamed', name ];
import values signature = 'values', value import,
                          { '; ', value import }, [ '; '];
value import = name, [':', type], ['renamed', name];
import functions signature = 'functions', function import,
                             { '; ', function import }, [ '; '];
function import = name, [ [ type variable list ], ':', function type ],
                   ['renamed', name];
import operations signature = 'operations', operation import,
                              { '; ', operation import }, [ '; '];
operation import = name, [':', operation type],
                    ['renamed', name];
```

Semantics: The imports section is used to state what constructs are used from other modules with the restriction that only visible constructs can be imported. If all the visible constructs from a module are going to be used, the keyword **all** is used, unless one or more constructs are going to be renamed. With renaming, an imported construct is given a new name which can be used instead of the original name preceded by the exporting module name. In general this has the form:



```
name renamed new_name
```

where name is the name of the imported construct, and new_name is the new name for the construct. This way, more meaningful names can be given to constructs. Note that in the importing module it is not possible to refer to DefModule 'name (where DefModule is the name of the defining module) any longer but only to newname.

It is possible to include type information in the imports section, such that this information will only be used by the static semantics check of the complete module. If no type information is given, the static semantics can also find this information in the exporting module.

When a type which has been exported with the **struct** keyword (with its structure) is imported the importing module may only make use of this structure if it repeats the type definition from the exporting module in its type import. In case such a type is a composite type and it is also renamed this has the consequence that the tag is renamed as well.

Examples: We can model an ATM card as consisting of a card number and an expiry date. This requires the digit type defined in the module BankAccount. It also uses the function digval from the same module.



```
getCardnumber (atmc) ==
  atmc.cardnumber
end ATMCard
```

Here the invariant on the type atmc states that expiry dates must represent valid dates, and card numbers must be at least 8 digits long. Note that since digit is not exported with the **struct** keyword from the module BankAccount, we cannot access the invariant for digit in module ATMCard. However this notwithstanding, all values of type digit manipulated in ATMCard must satisfy the invariant.

13.2 Top-level Specification in VDM++ and VDM-RT

In the previous chapters VDM constructs such as types, expressions, statements, functions and operations have been described. A number of these constructs can constitute the definitions inside a class definition. A top-level specification, or document, is composed by one or more class definitions. Note that only in VDM-RT it is possible to have a **system** class.

```
Syntax: document = class | system, { class | system };
```

13.3 System (VDM-RT)

In order to be able to describe distributed systems in VDM-RT includes a notion of a system that describes how different parts of the system modelled are deployed to different Core Processing Units (CPUs) and communication busses connecting the CPUs together. Syntactically the system is described exactly like ordinary classes described below in Section 13.3.1, except that the keyword "system" instead of the keyword "class".



Semantics: Each system description has the following parts:

- A system header with the system name.
- An optional system body.
- A system tail.

The system name as given in the system header is the defining occurrence of the name of the class. A system name is globally visible, i.e. visible in all other classes/systems in the specification.

The system name in the class header must be the same as the system name in the system tail. Furthermore, defining system names must be unique throughout the specification.

The special thing about the system is that it can make use of special implicitly defined classes called CPU and BUS. It is not possible to create instances of the system, but instances made of CPU and BUS will be created at initialisation time. Note that CPU and BUS cannot be used outside the system definition.

The instances of CPU and BUS must be made as instance variables and the definition must use constructors. The constructor for the CPU class takes two parameters: the first one indicate the primary scheduling policy used for the CPU whereas the second parameter provides the capacity of the CPU (indicated as number of instructions Per Second or Hz - NB. the (time unit) step size of time is 1 nanosecond). The constructor for the BUS class takes three parameters. The first one indicates the kind of bus, the second one the capacity of the bus (its band width in bytes per second) and finally the third parameter gives a set of CPU instances connected together by the given BUS instance.

The currently supported primary scheduling policies for the CPU are:

<FP>: Fixed Priority

<FCFS>: First Come First Served

The currently supported primary scheduling policy for the BUS is:

<FCFS>: First Come First Served

The CPU class have member operations called deploy and setPriority. The deploy operation takes one significant parameter which must be an object that is declared as a static instance variable inside the system¹. The semantics of the deploy operation is that execution of all functionality inside this object will take place on the CPU that it has been deployed to. The setPriority operation takes two parameters where the first must be the name of a public operation that has been deployed to the CPU and the second parameter is a natural number. The semantics of the setPriority operation is that the given operation is assigned the given priority (the second parameter). This will be used when fixed priority

¹It is also allowed to take a string as a second parameter for future extensions but that is ignored at the moment.



scheduling is used on the given CPU. Per default operations that are not explicitly assigned a priority using the setPriority operation are assigned a default priority of 1.

The system "class" is limited in the way that it can only contain:

Instance variables: The only instances that can be declared in the system "class" is of the special classes CPU and BUS as well as static instances of the different system components that one wish to allocate to different CPU's.

Constructor: The actual deployment of instances to CPU's and setting of priorities for the different operations is set inside the constructor which is the only operation that can be placed in the system "class". The only kind of statements that can be used inside this constructor is a block statement with a sequence of invocations of the special deploy and setPriority operations.

In addition there are limitations with respect to the use of static declarations for instances that are deployed to different CPU's. Basically the user should ensure that only one instance is deployed to a CPU if the class the instance comes from contains any static operations or functions. In case a static instance variable is used it is accessed directly (without any communication over the busses, so this in essence not proper from a distribution standpoint. Thus, all instance variables of instances to be deployed should only be accessed through the use of operations.

Example: The system class could for example be defined as:

```
system Simple
instance variables
  static public a : A := new A();
  static public b : B := new B();
  -- define the first CPU with fixed priority scheduling
  -- and 22E6 Hz
  CPU1 : CPU := new CPU (<FP>, 22E6);
  static public c : C := new C();
  -- define the second CPU with fixed priority scheduling
  -- and 11E6 Hz
  CPU2 : CPU := new CPU (<FP>, 11E6);
  -- create a communication bus that links the three
  -- CPU's together
  BUS1 : BUS := new BUS (<CSMACD>, 72E3, {CPU1, CPU2})
operations
 public Simple: () ==> Simple
```



```
Simple () ==
    ( -- deploy a on CPU1
        CPU1.deploy(a);
        -- deploy b on CPU1
        CPU1.deploy(b);
        -- deploy c on CPU2
        CPU2.deploy(c,"CT");
        -- "CT" is a label here which is ignored
    );
end Simple
```

where A, B and C all are defined as classes.

13.3.1 Classes

Compared to the standard VDM-SL language, VDM++ and VDM-RT have been extended with classes. In this section, the use of classes to create and structure a top-level specification will be described. With the object oriented facilities offered by VDM++ and VDM-RT it is possible to:

- Define classes and create objects.
- Define associations and create links between objects.
- Make generalisation and specialisation through inheritance.
- Describe the functional behaviour of the objects using functions and operations.
- Describe the dynamic behaviour of the system through threads and synchronisation constraints.

Before the actual facilities are described, the general layout of a class is described.



definition block = type definitions
| value definitions
| function definitions
| operation definitions
| instance variable definitions
| synchronization definitions
| thread definitions
| traces definitions;

Semantics: Each class description has the following parts:

- A class header with the class name and an optional *inheritance clause*.
- An optional *class body*.
- A class tail.

The class name as given in the class header is the defining occurrence of the name of the class. A class name is globally visible, i.e. visible in all other classes in the specification.

The class name in the class header must be the same as the class name in the class tail. Furthermore, defining class names must be unique throughout the specification.

The (optional) class body may consist of:

- A set of *value definitions* (constants).
- A set of *type definitions*.
- A set of function definitions.
- A set of *instance variable definitions* describing the internal state of an object instantiated from the class. State invariant expressions are encouraged but are not mandatory.
- A set of *operation definitions* that can act on the internal state.
- A set of the *synchronization definitions*, specified either in terms of permission predicates or using mutex constraints.
- A set of *thread definitions* that describe the thread of control for active objects.
- A set of *traces* that are used to indicate the sequences of operation calls for which test cases are desired to be produced automatically.

In general, all constructs defined within a class must have a unique name, e.g. it is not allowed to define an operation and a type with the same name. However, it is possible to *overload* function and operation names (i.e. it is possible to have two or more functions with the same name and two or more operations with the same name) subject to the restriction that the types of their input parameters should not overlap. That is, it should be possible using static type checking alone to determine uniquely and unambiguously which function/operation definition corresponds to each function/operation call. Note that this applies not only to



functions and operations defined in the local interface of a class but also to those inherited from superclasses. Thus, for example, in a design involving multiple inheritance a class C may inherit a function from a class A and a function with the same name from a class B and all calls involving this function name must be resolvable in class C.

13.3.2 Inheritance

The concept of inheritance is essential to object orientation. When one defines a class as a subclass of an already existing class, the definition of the subclass introduces an extended class, which is composed of the definitions of the superclass together with the definitions of the newly defined subclass.

Through inheritance, a subclass inherits from the superclass:

- Its instance variables. This also includes all invariants and their restrictions on the allowed modifications of the state.
- Its operation and function definitions.
- Its value and type definitions.
- Its synchronization definitions as described in section 14.2.
- Its thread definitions as described in chapter 15.

A name conflict occurs when two constructs of the same kind and with the same name are inherited from different superclasses. Name conflicts must be explicitly resolved through *name qualification*, i.e. prefixing the construct with the name of the superclass and a '-sign (back-quote).

Example: In the first example, we see that inheritance can be exploited to allow a class definition to be used as an abstract interface which subclasses must implement:

```
class Sort

instance variables
  protected data : seq of int

operations

initial_data : seq of int ==> ()
  initial_data (1) ==
    data := 1;

sort_ascending : () ==> ()
  sort_ascending () == is subclass responsibility;
```



```
end Sort
class SelectionSort is subclass of Sort
  functions
    min_index : seq1 of nat -> nat
    min index(1) ==
      if len 1 = 1
      then 1
      else let mi = min_index(tl 1)
           in
             if 1(mi+1) < hd 1
             then mi+1
             else 1
  operations
    sort_ascending : () ==> ()
    sort_ascending () == selectSort(1);
    selectSort : nat ==> ()
    selectSort (i) ==
      if i < len data</pre>
      then (dcl temp: nat;
            dcl mi: nat := min_index(data(i,...,len data)) +
                           i - 1;
           temp := data(mi);
           data(mi) := data(i);
           data(i) := temp;
           selectSort(i+1)
end SelectionSort
```

Here the class Sort defines an abstract interface to be implemented by different sorting algorithms. One implementation is provided by the SelectionSort class.

The next example clarifies how name space clashes are resolved.

```
class A
```



```
instance variables}
  i: int := 1;
  j: int := 2;
end A
class B is subclass of A
end B
class C is subclass of A
instance variables
  i: int := 3;
end C
class D is subclass of B, C
operations
  GetValues: () ==> seq of int
  GetValues() ==
    return [
        A'i, -- equal to 1
        B'i, -- equal to 1 (A'i)
        C'i, -- equal to 3
          -- equal to 2 (A'j)
 end D
```

In the example objects of class D have 3 instance variables: A'i, A'j and C'j. Note that objects of class D will have only one copy of the instance variables defined in class A even though this class is a common super class of both class B and C. Thus, in class D the names B'j, C'j, D'j and j are all referring to the same variable, A'j. It should also be noticed that the variable name i is ambiguous in class D as it refers to different variables in class B and class C.

13.3.3 Interface and Availability of Class Members

In VDM++ and VDM-RT definitions inside a class are distinguished between:

Class attribute: an attribute of a class for which there exists exactly one incarnation no matter how many instances (possibly zero) of the class may eventually be created. Class attributes in VDM++ and VDM-RT correspond to **static** class members in languages like C++ and Java. Class (static) attributes can be referenced by prefixing the name of the attribute with the name of the class followed by a '-sign (back-quote), so that, for example, ClassName 'val refers to the value val defined in class ClassName.



Instance attribute: an attribute for which there exists one incarnation for each instance of the class. Thus, an instance attribute is only available in an object and each object has its own copy of its instance attributes. Instance (non-static) attributes can be referenced by prefixing the name of the attribute with the name of the object followed by a dot, so that, for example, object.op() invokes the operation op in the object denoted by object (provided that op is visible to object).

Functions, operations, instance variables and constants² in a class may be either class attributes or instance attributes. This is indicated by the keyword **static**: if the declaration is preceded by the keyword **static** then it represents a class attribute, otherwise it denotes an instance attribute.

Other class components are by default always either class attributes or instance attributes as follows:

- Type definitions are always class attributes.
- Thread definitions are always instance attributes. Thus, each active object has its own thread(s).
- Synchronization definitions are always instance attributes. Thus, each object has its own "history" when it has been created.

In addition, the interface or accessibility of a class member may be explicitly defined using an access specifier: one of **public**, **private** or **protected**. The meaning of these specifiers is:

public: Any class may use such members

protected: Only subclasses of the current class may use such members

private: No other class may use such members - they may only be used in the class in which they are specified.

The default access to any class member is **private**. That is, if no access specifier is given for a member it is private.

This is summarized in table 13.1. A few provisos apply here:

- Granting access to instance variables (i.e. through a **public** or **protected** access specifier) gives both read and write access to these instance variables.
- Public instance variables may be read (but not written) using the dot (for object instance variables) or back-quote (for class instance variables) notation e.g. a public instance variable v of an object o may be accessed as o.v.
- Access specifiers may only be used with type, value, function, operation and instance variable definitions; they cannot be used with thread or synchronization definitions.

²In practice, constants will generally be static – a non-static constant would represent a constant whose value may vary from one instance of the class to another which would be more naturally represented by an instance variable.



	public	protected	private
Within the class			
In a subclass			×
In an arbitrary external class	$\sqrt{}$	×	×

Table 13.1: Summary of Access Specifier Semantics

- It is not possible to convert a class attribute into an instance attribute, or vice-versa.
- For inherited classes, the interface to the subclass is the same as the interface to its superclasses extended with the new definitions within the subclass.
- Access to an inherited member cannot be made more restrictive e.g. a public instance variable in a superclass cannot be redeclared as a private instance variable in a subclass.

Example In the example below use of the different access specifiers is demonstrated, as well as the default access to class members. Explanation is given in the comments within the definitions.

```
class A
types
public Atype = <A> | <B> | <C>
values
public Avalue = 10;
functions
public compare : nat -> Atype
compare(x) ==
  if x < Avalue</pre>
 then <A>
  elseif x = Avalue
  then <B>
  else <C>
instance variables
public v1: nat;
private v2: bool := false;
protected v3: real := 3.14;
operations
```



```
protected AInit : nat * bool * real ==> ()
AInit(n,b,r) ==
  (v1 := n;
  v2 := b;
  v3 := r)
end A
class B is subclass of A
instance variables
v4 : Atype --inherited from A
operations
BInit: () ==> ()
BInit() ==
  (AInit(1, true, 2.718); --OK: can access protected members
                        --in superclass
  v4 := compare(v1); --OK since v1 is public
                       --OK since v3 protected and this
  v3 := 3.5;
                       --is a subclass of A
  v2 := false
                       --illegal since v2 is private to A
end B
class C
instance variables
a: A := new A();
b: B := new B();
operations
CInit: () ==> A'Atype--types are class attributes
CInit() ==
  (a.AInit(3, false, 1.1);
                     --illegal since AInit is protected
  b.BInit();
                     --illegal since BInit is (by default)
                     --private
   let - = a.compare(b.v3) in skip;
                     --illegal since C is not subclass
```



```
--of A so b.v3 is not available

return b.compare(B`Avalue)

--OK since compare is a public instance

--attribute and Avalue is public class

--attribute in B

)

end C
```



Chapter 14

Synchronization Constraints (VDM++ and VDM-RT)

In general a complete system contains objects of a passive nature (which only react when their operations are invoked) and active objects which 'breath life' into the system. These active objects behave like virtual machines with their own processing thread of control and after start up they do not need interaction with other objects to continue their activities. In another terminology a system could be described as consisting of a number of active clients requesting services of passive or active servers. In such a parallel environment the server objects need synchronization control to be able to guarantee internal consistency, to be able to maintain their state invariants. Therefore, in a parallel world, a passive object needs to behave like a Hoare monitor with its operations as entries.

If a sequential system is specified (in which only one thread of control is active at a time) only a special case of the general properties is used and no extra syntax is needed. However, in the course of development from specification to implementation more differences are likely to appear.

The following default synchronization rules for each object apply in VDM++ and VDM-RT:

- operations are to be viewed as though they are atomic, from the point of the caller;
- operations which have no corresponding permission predicate are subject to no restrictions at all;
- synchronization constraints apply equally to calls within an object (i.e. one operation within an object calls another operation within that object) and outside an object (i.e. an operation from one object calls an operation in another object);
- operation invocations have the semantics of a rendez-vous (as in Ada, see [Ada LRM]) in case two active objects are involved. Thus if an object O_1 calls an operation o in object O_2 , if O_2 is currently unable to start operation o then O_1 blocks until the operation may be executed. Thus invocation occurs when both the calling object and the called object are ready. (Note here a slight difference from the semantics of Ada: in Ada both parties to the rendez-vous are active objects; in VDM++ and VDM-RT only the calling party is active).



The synchronization definition blocks of the class description provide the user with ways to override the defaults described above.

```
Syntax: synchronization definitions = 'sync', [ synchronization ]; synchronization = permission predicates;
```

Semantics: Synchronization is specified in VDM++ and VDM-RT using permission predicates.

14.1 Permission Predicates

The following gives the syntax used to state rules for accepting the execution of concurrently callable operations. Some notes are given explaining these features.

Semantics: Permission to accept execution of a requested operation depends on a guard condition in a (deontic) permission predicate of the form:

```
per operation name => guard condition
```

The use of implication to express the permission means that truth of the guard condition (expression) is a necessary but not sufficient condition for the invocation. The permission predicate is to be read as stating that if the guard condition is false then there is non-permission. Expressing the permission in this way allows further similar constraints to be added without risk of contradiction through inheritance for the subclasses. There is a default for all operations:

```
per operation name => true
```

but when a permission predicate for an operation is specified this default is overridden. Guard conditions can be conceptually divided into:

- a history guard defining the dependence on events in the past;
- an *object state guard*, which depends on the instance variables of the object, and



• a *queue condition guard*, which depends on the states of the queues formed by operation invocations (messages) awaiting service by the object.

These guards can be freely mixed. **Note** that there is no *syntactic* distinction between these guards - they are all expressions. However they may be distinguished at the semantic level.

A mutex predicate allows the user to specify either that all operations of the class are to be executed mutually exclusive, or that a list of operations are to be executed mutually exclusive to each other. Operations that appear in one mutex predicate are allowed to appear in other mutex predicates as well, and may also be used in the usual permission predicates. Each mutex predicate will implicitly be translated to permission predicates using history guards for each operation mentioned in the name list. For instance,

```
sync
mutex(opA, opB);
mutex(opB, opC, opD);
per opD => someVariable > 42;
```

would be translated to the following permission predicates:

Note that it is only permitted to have one "stand-alone" permission predicate for each operation. It is also important to note that if permission predicates are made over operations that are overloaded (see Section 13.3.1) then it will incorporate all of their history counters as the same operation. The **#active** operator is explained below.

A mutex (all) constraint specifies that all of the operations specified in that class *and any* superclasses are to be executed mutually exclusively.

14.1.1 History guards

Semantics: A history guard is a guard which depends on the sequence of earlier invocations of the operations of the object expressed in terms of history expressions (see section 6.23). History expressions denotes the number of activations and completions of the operations, given as functions



#act and **#fin**, respectively.

```
#act: operation name \rightarrow \mathbb{N} #fin: operation name \rightarrow \mathbb{N}
```

Furthermore, a derived function #active is available such that #active (A) = #act (A) - #fin (A), giving the number of currently active instances of A. Another history function

- #req - is defined in section 14.1.3.

Examples: Consider a Web server that is capable of supporting 10 simultaneous connections and can buffer a further 100 requests. In this case we have one instance variable, representing the mapping from URLs to local filenames:

```
instance variables
  site_map : map URL to Filename := { |->}
```

The following operations are defined in this class (definitions omitted for brevity):

```
ExecuteCGI: URL ==> File Execute a CGI script on the server
RetrieveURL: URL ==> File Transmit a page of html
UploadFile: File * URL ==> () Upload a file onto the server
ServerBusy: () ==> File Transmit a "server busy" page
DeleteURL: URL ==> () Remove an obsolete file
```

Since the server can support only 10 simultaneous connects, we can only permit an execute or retrieve operation to be activated if the number already active is less than 10:

14.1.2 The object state guard

Semantics: The object state guard is a boolean expression which depends on the values of one (or more) instance variable(s) of the object itself. Object state guards differ from operation pre-conditions in that a call to an an operation whose permission predicate is false results in the caller blocking until the predicate is satisfied, whereas a call to an operation whose pre-condition is false means the operation's behaviour is unspecified.

Examples: Using the web server example again, we can only allow file removal if some files already exist:



```
per DeleteURL => dom site_map <> {}
```

Constraints for safe execution of the operations Push and Pop in a stack object can be expressed using an object state guard as:

```
per Push => length < maxsize;
per Pop => length > 0
```

where maxsize and length are instance variables of the stack object.

It is often possible to express such constraints as a consequence of the history, for example the empty state of the stack:

```
length = 0 <=> #fin(Push) = #fin(Pop)
```

However, the size is a property which is better regarded as a property of the particular stack instance, and in such cases it is more elegant to use available instance variables which store the effects of history.

14.1.3 Queue condition guards

Semantics: A queue condition guard acts on requests waiting in the queues for the execution of the operations. This requires use of a third history function #req such that #req(A) counts the number of messages which have been received by the object requesting execution of operation A. Again it is useful to introduce the function #waiting such that: #waiting(A) = #req(A) - #act(A), which counts the number of items in the queue.

Examples: Once again, with the web server we can only activate the ServerBusy operation if 100 or more connections are waiting:

The most important use of such expressions containing queue state functions is for expressing priority between operations. The protocol specified by:

```
per B => #waiting(A) = 0
```

gives priority to waiting requests for activation of A. There are, however, many other situations when operation dispatch depends on the state of waiting requests. Full description



of the queuing requirements to allow specification of operation selection based on request arrival times or to describe 'shortest job next' behaviour will be a future development.

Note that $\#\mathbf{req}(A)$ have value 1 at the time of evaluation of the permission predicate for the first invocation of operation A. That is,

```
per A => #req(A) = 0
```

would always block.

14.1.4 Evaluation of Guards

Using the previous example, consider the following situation: the web server is handling 10 RetrieveURL requests already. While it is dealing with these requests, two further RetrieveURL requests (from objects O_1 and O_2) and one ExecuteCGI request (from object O_3) are received. The permission predicates for these two operations are false since the number of active RetrieveURL operations is already 10. Thus these objects block.

Then, one of the active RetrieveURL operations reaches completion. The permission predicate so far blocking O_1 , O_2 and O_3 will become "true" simultaneously. This raises the question: which object is allowed to proceed? Or even all of them?

Guard expressions are only reevaluated when an event occurs (in this case the completion of a Retrieveurl operation). In addition to that the test of a permission predicate by an object and its (potential) activation is an atomic operation. This means, that when the first object evaluates its guard expression, it will find it to be true and activate the corresponding operation (Retrieveurl or ExecuteCGI in this case). The other objects evaluating their guard expressions afterwards will find that #active (Retrieveurl) + #active (ExecuteCGI) = 10 and thus remain blocked. Which object is allowed to evaluate the guard expression first is undefined.

It is important to understand that the guard expression need only evaluate to **true** at the time of the activation. In the example as soon as O_1 , O_2 or O_3 's request is activated its guard expression becomes false again.

14.2 Inheritance of Synchronization Constraints

Synchronization constraints specified in a superclass are inherited by its subclass(es). The manner in which this occurs depends on the kind of synchronization.

14.2.1 Mutex constraints

Mutex constraints from base classes and derived classes are simply added. If the base class and derived class have the mutex definitions M_A and M_B , respectively, then the derived class simply



has both mutex constraints M_A , and M_B . The binding of operation names to actual operations is always performed in the class where the constraint is defined. Therefore a **mutex(all)** constraint defined in a superclass and inherited by a subclass only makes the operations from the base class mutually exclusive and does not affect operations of the derived class.

Inheritance of mutex constraints is completely analogous to the inheritance scheme for permission predicates. Internally mutex constraints are always expanded into appropriate permission predicates which are added to the existing permission predicates as a conjunction. This inheritance scheme ensures that the result (the final permission predicate) is the same, regardless of whether the mutex definitions are expanded in the base class and inherited as permission predicates or are inherited as mutex definitions and only expanded in the derived class.

The intention for inheriting synchronization constraints in the way presented is to ensure, that any derived class at least satisfies the constraints of the base class. In addition to that it must be possible to strengthen the synchronization constraints. This can be necessary if the derived class adds new operations as in the following example:

```
class A
operations
  writer: () ==> ()
  writer() == is not yet specified
  reader: () ==> ()
  reader() == is not yet specified
  sync
 per reader => #active(writer) = 0;
 per writer => #active(reader, writer) = 0;
end A
class B is subclass of A
operations
 newWriter: () ==> ()
  newWriter() == is not yet specified
  sync
 per reader => #active(newWriter) = 0;
 per writer => #active(newWriter) = 0;
 per newWriter => #active(reader, writer, newWriter) = 0;
end B
```



Class A implements reader and writer operations with the permission predicates specifying the multiple readers-single writer protocol. The derived class B adds newWriter. In order to ensure deterministic behaviour B also has to add permission predicates for the inherited operations.

The actual permission predicates in the derived class are therefore:

```
per reader => #active(writer)=0 and #active(newWriter)=0;
per writer => #active(reader, writer)=0 and #active(newWriter)=0;
per newWriter => #active(reader, writer, newWriter)=0;
```

A special situation arises when a subclass overrides an operation from the base class. The overriding operation is treated as a new operation. It has no permission predicate (and in particular inherits none) unless one is defined in the subclass.

The semantics of inheriting mutex constraints for overridden operations is completely analogous: newly defined overriding operations are not restricted by mutex definitions for equally named operations in the base class. The mutex (all) shorthand makes all inherited and locally defined operations mutually exclusive. Overridden operations (defined in a base class) are not affected. In other words, all operations, that can be called with an unqualified name ("locally visible operations") will be mutex to each other.

Chapter 15

Threads (VDM++ and VDM-RT)

Objects instantiated from a class with a *thread* part are called *active* objects. The scope of the instance variables and operations of the current class is considered to extend to the thread specification. Note that from a tool perspective the thread for the expression a user would like to evaluate in relation to a VDM model is called a debug thread. This thread has a special role in the sense that when it is finished the entire execution is completed (and thus all other threads ready to be scheduled in or running will be thrown away and aborted). If a session where a series of expressions are being evaluated this is not true (in this case the other threads will be continued when the next expression is executed, see [Larsen&10b] for more details about "sessions"). Thus if one would like to ensure a specific number of such other threads to be completed before stopping the execution one needs to block the debug thread using a synchonisation as explained in Chapter 14.

```
Syntax: thread definitions = 'thread', [ thread definition ];

thread definition = periodic thread definition | procedural thread definition;
```

Subclasses inherit threads from superclasses. If a class inherits from several classes only one of these may declare its own thread (possibly through inheritance). Furthermore, explicitly declaring a thread in a subclass will override any inherited thread.

15.1 Periodic Thread Definitions

The periodic thread definition can be regarded as the implicit way of describing the activities in a thread.

```
Syntax: periodic thread definition = periodic obligation ;
For VDM++ where time is not explicit it looks like:
    periodic obligation = 'periodic','(', numeral, ')', '(', name, ')';
```





Figure 15.1: Period (p), jitter (j), delay (d) and offset (o)

For VDM-RT where time is explicit it looks like:

```
periodic obligation = 'periodic', '(', numeral, numeral, numeral, numeral, ')', '(', name, ')';
```

Semantics: For each periodic thread four different numbers are used. They are in order of appearance (also illustrated in Figure 15.1):

- 1. **period:** This is a non-negative, non-zero value that describes the length of the time interval between two adjacent events in a strictly periodic event stream (where jitter = 0)
- 2. **jitter:** This is a non-negative value that describes the amount of time variance that is allowed around a single event. We assume that the interval is balanced [-j, j]. Note that jitter is allowed to be bigger than the period to characterize so-called event bursts.
- 3. **delay:** This is a non-negative value smaller than the period which is used to denote the minimum inter arrival distance between two adjacent events.
- 4. **offset:** This is a non-negative value which is used to denote the absolute time value at which the first period of the event stream starts. Note that the first event occurs in the interval [offset, offset+ jitter].

Given a defined time resolution ΔT , a thread with a periodic obligation invokes the mentioned operation at the beginning of each time interval with length *period*. This creates the periodic execution of the operation simulating the discrete equivalent of continuous relations which have to be maintained between instance variables, parameter values and possibly other external values obtained through operation invocations. It is not possible to dynamically change the length of the interval.

Periodic obligations are intended to describe e.g. analogue physical relations between values in formulas (e.g. transfer functions) and their discrete event simulation. It is a requirement on the implementation to guarantee that the execution time of the operation is at least smaller



than the used periodic time length. If other operations are present the user has to guarantee that the fairness criteria for the invocation of these other operations are maintained by reasoning about the time slices used internally and available for external invocations.

A periodic thread is *not* created or started when an instance of the corresponding class is created. Instead, as with procedural threads, start statements should be used with periodic threads.

Examples: Consider a timer class which periodically increments its clock in its own thread. It provides operations for starting, and stopping timing, and reading the current time.

```
class Timer
```

The Timer has two instance variables the current time and a flag indicating whether the Timer is active or not (the current time is only incremented if the Timer is active).

```
instance variables
  curTime : nat := 0;
  acti : bool := false;
```

The Timer provides straightforward operations which need no further explanation.

```
public Start : () ==> ()
Start() ==
    (acti := true;
    curTime := 0);

public Stop : () ==> ()
Stop() ==
    acti := false;

public GetTime : () ==> nat
GetTime() ==
    return curTime;

IncTime: () ==> ()
IncTime() ==
    if acti
    then curTime := curTime + 100;
```



The Timer's thread ensures that the current time is incremented. The period with which this is done is 1000 time units (nanoseconds). The allowed jitter is 10 time units and the minimal distance between two instances is 200 time units and finally no offset has been used.

```
thread
periodic(1000,10,200,0)(IncTime)
end Timer
```

15.2 Procedural Thread Definitions

A procedural thread provides a mechanism to explicitly define the external behaviour of an active object through the use of *statements*, which are executed when the object is started (see section 12.14).

Syntax: procedural thread definition = statement;

Semantics: A procedural thread is scheduled for execution following the application of a start statement to the object owning the thread. The statements in the thread are then executed sequentially, and when execution of the statements is complete, the thread dies. Synchronization between multiple threads is achieved using permission predicates on shared objects.

Examples: The example below demonstrates procedural threads by using them to compute the factorial of a given integer concurrently.

```
class Factorial
instance variables
  result : nat := 5;
operations

public factorial : nat ==> nat
factorial(n) ==
  if n = 0
  then return 1
  else (dcl m : Multiplier;
        m := new Multiplier();
        m.calculate(1,n);
        start(m);
        result:= m.giveResult();
        return result
```



```
end Factorial
class Multiplier
instance variables
  i : nat1;
  j : nat1;
  k : nat1;
  result : nat1
operations
public calculate : nat1 * nat1 ==> ()
calculate (first, last) ==
  (i := first; j := last);
doit : () ==> ()
doit() ==
( if i = j 
  then result := i
  else (dcl p : Multiplier;
        dcl q : Multiplier;
        p := new Multiplier();
        q := new Multiplier();
        start(p);
        start(q);
        k := (i + j) div 2;
        -- division with rounding down
        p.calculate(i,k);
        q.calculate(k+1,j);
        result := p.giveResult() * q.giveResult()
       )
);
public giveResult : () ==> nat1
giveResult() ==
  return result;
sync
-- cyclic constraints allowing only the
```



```
-- sequence calculate; doit; giveResult

per doit => #fin (calculate) > #act(doit);
per giveResult => #fin (doit) > #act (giveResult);
per calculate => #fin (giveResult) = #act (calculate)

thread
  doit();
end Multiplier
```

Chapter 16

Trace Definitions

In order to automate the testing process VDM-10 contains a notation enabling the expression of the traces that one would like to have tested exhaustively. Such traces are used to express combinations of sequences of operations that wish to be tested in all possible combinations. In a sense this is similar to model checking limitations except that this is done with real and not symbolic values. However, errors in test cases are filtered away so other test cases with the same prefix will be skipped automatically.



Semantics: Semantically the trace definitions provided in a class have no effect. These definitions are simply used to enhance testing of a VDM specification using principles from combinatorial testing (also called all-pairs testing). So each trace definition can be considered as a regular expression describing the test sequences in which different operations should be executed to test the VDM specification. Inside the trace definitions, bindings may appear and for each possible such binding a particular test case can be automatically derived. So one trace definition expand into a set of test cases. In this sense a test case is a sequence of operation calls executed after each other. Between each test case the VDM specification is initialised so they become entirely independent. From a static semantics perspective it is important to note that the expressions used inside trace definitions must be executed in the expansion process. This means that it cannot directly refer to instance variables, because these could be changed during the execution.

So here it makes sense to explain what kind of expansion the different kinds of trace definitions gives rise to.

The *trace definition lists* simply use a semicolon (";") and this simply result in sequencing between the *trace definition terms* used inside it.

In the *trace definition term* it is possible to introduce alternatives using the bar ("|") operator. This result in test cases for all alternatives.

The *trace binding definition* exists in two forms where the *trace let def binding* simply enables the binding introduced to be used after the 'in' in the same way as in let-expressions. Alternatively the *trace let best binding* can be used and this will expand to test cases with all the different possible bindings.



The *trace repeat definition* is used to introduce the possibility of having repetitions of the operation calls used in the trace. The different kinds of repeat patterns have the following meanings:

- '*' means 0 to n occurences (n is tool specific).
- '+' means 1 to n occurences (n is tool specific).
- '?' means 0 or 1 occurences.
- '{', n, '}' means n occurences.
- '{', n, ', ' m '}' means between n and m occurences.

The *trace core definitions* have three possibilities. These are ordinary operation calls, trace concurrency expressions and bracketed trace definitions respectively. The *trace concurrency expressions* are similar to the *nondeterministic statements* in the sense that the trace definition lists inside it will be executed in all possible permulations of the elements. This is particular useful for concurrent VDM++ models where potential deadlocks can occur under some circumstances.

Examples: In an example like the one below test cases will be generated in all possible combination starting with a call of Reset followed by one to four Pushes of values onto the stack followed again by one to three Pops from the stack.

```
class Stack
instance variables
    stack : seq of int := [];

operations

public Reset : () ==> ()
Reset () ==
    stack := [];

public Pop : () ==> int
Pop() ==
    def res = hd stack in
        (stack := tl stack;
        return res)
    pre stack <> []
    post stack = [RESULT] ^ stack;

    public Push: int ==> ()
```



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Appendix A

The Syntax of the VDM Languages

This appendix specifies the complete syntax for the VDM languages.

A.1 VDM-SL Document

A.1.1 Modules

This entire subsection is not present in the current version of the VDM-SL standard.



```
import types signature = 'types', type import,
                         { '; ', type import }, [ '; '];
type import = name, [ 'renamed', name ]
               type definition, [ 'renamed', name ];
import values signature = 'values', value import,
                          { '; ', value import }, [ '; '];
value import = name, [':', type], ['renamed', name];
import functions signature = 'functions', function import,
                             { '; ', function import }, [ '; '] ;
function import = name, [ [ type variable list ], ':', function type ],
                   ['renamed', name];
import operations signature = 'operations', operation import,
                              { '; ', operation import }, [ '; '];
operation import = name, [':', operation type], ['renamed', name];
export definition = 'exports', export module signature ;
export module signature = 'all'
                        export signature,
                           { export signature };
export signature = export types signature
                   values signature
                   export functions signature
                   operations signature;
export types signature = 'types', type export,
                         { '; ', type export }, [ '; '];
type export = ['struct'], name;
values signature = 'values', value signature,
                   { '; ', value signature }, [ '; '];
value signature = name list, ':', type;
export functions signature = 'functions' function export,
                             { '; ', function export } ;
```



A.2 VDM++ and VDM-RT Document

```
document = class | system, { class | system };
```

A.3 System (VDM-RT)

A.3.1 Classes

A.4 Definitions



```
operation definitions
instance variable definitions
synchronization definitions
thread definitions
traces definitions;
```

A.4.1 Type Definitions

```
type definitions = 'types', [ access type definition ],
                     { '; ', access type definition }, [ '; '];
  access type definition = ([ access ], [ 'static' ]) | ([ 'static' ], [ access ]),
                           type definition;
The access part is only possible in VDM++ and VDM-RT.
  access = 'public'
            'private'
             'protected';
```

```
type definition = identifier, '=', type, [ invariant ]
                  identifier, '::', field list, [invariant];
type = bracketed type
        basic type
        quote type
        composite type
        union type
        product type
        optional type
        set type
        seq type
        map type
        partial function type
        type name
        type variable;
bracketed type = '(', type, ')';
basic type = 'bool' | 'nat' | 'nat1' | 'int' | 'rat'
             'real' | 'char' | 'token' ;
```

quote type = quote literal;



```
composite type = 'compose', identifier, 'of', field list, 'end';
field list = \{ field \} ;
field = [ identifier, ':'], type
     [ identifier, ':-'], type;
union type = type, '|', type, { '|', type } ;
product type = type, '*, type, \{'*, type \};
optional type = '[', type, ']';
set type = 'set of', type ;
seq type = seq0 type
           seq1 type;
seq0 type = 'seq of', type ;
seq1 type = 'seq1 of', type ;
map type = general map type
            injective map type;
general map type = 'map', type, 'to', type ;
injective map type = 'inmap', type, 'to', type ;
function type = partial function type
             total function type;
partial function type = discretionary type, '->', type;
total function type = discretionary type, '+>', type;
discretionary type = type
                 | '(', ')';
type name = name ;
type variable = type variable identifier;
invariant = 'inv', invariant initial function;
invariant initial function = pattern, '==', expression;
```



A.4.2 The VDM-SL State Definition

A.4.3 Value Definitions

A.4.4 Function Definitions

```
function definitions = 'functions', [ access function definition ],
                        { '; ', access function definition }, [ '; ' ];
access function definition = [ access ], function definition;
function definition = explicit function definition
                      implicit function definition
                      extended explicit function definition;
explicit function definition = identifier, [type variable list], ':',
                               function type,
                               identifier, parameters list,
                               '==', function body,
                               ['pre', expression],
                               ['post', expression],
                               ['measure', name];
implicit function definition = identifier, [ type variable list ],
                               parameter types,
                               identifier type pair list,
                               ['pre', expression],
                               'post', expression;
```



In VDM-SL extended explicit function definition looks like:

In VDM++ and VDM-RT extended explicit function definition looks like:

```
extended explicit function definition = identifier, [ type variable list ],
                                        parameter types,
                                        identifier type pair list,
                                        '==', function body,
                                        ['pre', expression],
                                        ['post', expression];
type variable list = '[', type variable identifier,
                     { ', ', type variable identifier }, ']';
identifier type pair = identifier, ':', type;
parameter types = '(', [ pattern type pair list ], ')';
identifier type pair list = identifier, ':', type,
                          { ', ', identifier, ':', type } ;
pattern type pair list = pattern list, ':', type,
                        { ', ', pattern list, ': ', type } ;
parameters list = parameters, { parameters } ;
parameters = '(', [ pattern list ], ')';
function body = expression
                  'is subclass responsibility'
                  'is not yet specified';
```



A.4.5 Operation Definitions

```
operation definitions = 'operations', [ access operation definition ],
                        { '; ', access operation definition }, [ '; '];
access operation definition = (['async'][ access], ['static'])
                              (['async']['static'],[ access]),
                             operation definition;
operation definition = explicit operation definition
                     implicit operation definition
                      extended explicit operation definition;
explicit operation definition = identifier, ':', operation type,
                              identifier, parameters,
                               '==', operation body,
                              ['pre', expression],
                               ['post', expression];
implicit operation definition = identifier, parameter types,
                               [ identifier type pair list ],
                               implicit operation body;
implicit operation body = [ externals ],
                          ['pre', expression],
                           'post', expression,
                          [ exceptions ];
extended explicit operation definition = identifier, parameter types,
                                        [ identifier type pair list ],
                                        '==', operation body,
                                        [ externals ],
                                        ['pre', expression],
                                        ['post', expression],
                                        [ exceptions ];
operation type = discretionary type, '==>', discretionary type;
operation body = statement
                   'is subclass responsibility'
                   'is not yet specified';
externals = 'ext', var information, { var information } ;
```



```
var information = mode, name list, [':', type];
mode = 'rd' | 'wr';
exceptions = 'errs', error list;
error list = error, { error };
error = identifier, ':', expression, '->', expression;
```

A.4.6 Instance Variable Definitions (VDM++ and VDM-RT)

A.4.7 Synchronization Definitions (VDM++ and VDM-RT)



A.4.8 Thread Definitions (VDM++ and VDM-RT)

A.4.9 Trace Definitions



A.5 Expressions

```
expression list = expression, { ', ', expression } ;
expression = bracketed expression
              let expression
              let be expression
              def expression
              if expression
              cases expression
              unary expression
              binary expression
              quantified expression
              iota expression
              set enumeration
              set comprehension
              set range expression
              sequence enumeration
              sequence comprehension
              subsequence
              map enumeration
              map comprehension
              tuple constructor
              record constructor
```



```
record modifier
apply
field select
tuple select
function type instantiation
lambda expression
new expression
self expression
threadid expression
general is expression
undefined expression
precondition expression
isofbaseclass expression
isofclass expression
samebaseclass expression
sameclass expression
act expression
fin expression
active expression
req expression
waiting expression
time expression
name
old name
symbolic literal;
```

A.5.1 Bracketed Expressions

```
bracketed expression = '(', expression, ')';
```

A.5.2 Local Binding Expressions



A.5.3 Conditional Expressions

A.5.4 Unary Expressions

```
unary expression = prefix expression
                 map inverse;
prefix expression = unary operator, expression;
unary operator = unary plus
                  unary minus
                  arithmetic abs
                  floor
                  not
                  set cardinality
                  finite power set
                  distributed set union
                  distributed set intersection
                  sequence head
                  sequence tail
                  sequence length
                  sequence elements
                  sequence indices
                  sequence reverse
                  distributed sequence concatenation
                  map domain
                  map range
                  distributed map merge;
```



```
unary plus = +;
unary minus = '-';
arithmetic abs = 'abs';
floor = 'floor';
not = 'not';
set cardinality = 'card';
finite power set = 'power';
distributed set union = 'dunion';
distributed set intersection = 'dinter';
sequence head = 'hd';
sequence tail = 'tl' ;
sequence length = 'len';
sequence elements = 'elems' ;
sequence indices = 'inds';
sequence reverse = 'reverse';
distributed sequence concatenation = 'conc';
map domain = 'dom';
map range = 'rng';
distributed map merge = 'merge';
map inverse = 'inverse', expression ;
```



A.5.5 Binary Expressions

```
binary expression = expression, binary operator, expression;
binary operator = arithmetic plus
                   arithmetic minus
                   arithmetic multiplication
                   arithmetic divide
                   arithmetic integer division
                   arithmetic rem
                   arithmetic mod
                   less than
                   less than or equal
                   greater than
                   greater than or equal
                   equal
                   not equal
                   or
                   and
                   imply
                   logical equivalence
                   in set
                   not in set
                   subset
                   proper subset
                   set union
                   set difference
                   set intersection
                   sequence concatenate
                   map or sequence modify
                   map merge
                   map domain restrict to
                   map domain restrict by
                   map range restrict to
                   map range restrict by
                   composition
                   iterate;
arithmetic plus = '+';
arithmetic minus = '-';
arithmetic multiplication = '*;
```



```
arithmetic divide = '/';
arithmetic integer division = 'div';
arithmetic rem = 'rem';
arithmetic mod = 'mod';
less than = '<';
less than or equal = '<=';
greater than = '>';
greater than or equal = '>=';
equal = '=';
not equal = '<>';
or = 'or';
and = 'and';
imply = = '=>';
logical equivalence = '<=>';
in set = 'in set';
not in set = 'not in set';
subset = 'subset' ;
proper subset = 'psubset' ;
set union = 'union';
set difference = '\';
set intersection = 'inter';
sequence concatenate = '^';
map or sequence modify = ++;
map merge = 'munion';
map domain restrict to = <:;
map domain restrict by = <-:;
map range restrict to = ':>';
map range restrict by = :->;
composition = 'comp';
iterate = ***;
```



A.5.6 Quantified Expressions

```
quantified expression = all expression | exists expression | exists unique expression ; all expression = 'forall', bind list, '&', expression ; exists expression = 'exists', bind list, '&', expression ; exists unique expression = 'exists1', bind, '&', expression ;
```

A.5.7 The Iota Expression

```
iota expression = 'iota', bind, '&', expression;
```

A.5.8 Set Expressions

A.5.9 Sequence Expressions

A.5.10 Map Expressions



A.5.11 The Tuple Constructor Expression

```
tuple constructor = 'mk_', '(', expression, ', ', expression list, ')';
```

A.5.12 Record Expressions

A.5.13 Apply Expressions

```
apply = expression, '(', [ expression list ], ')';
field select = expression, '.', identifier;
tuple select = expression, '.#', numeral;
function type instantiation = name, '[', type, { ', ', type }, ']';
```

A.5.14 The Lambda Expression

```
lambda expression = 'lambda', type bind list, '&', expression;
```

A.5.15 The narrow Expression

```
narrow expression = 'narrow_', '(', expression, ', ', type, ')' ;
```

A.5.16 The New Expression (VDM++ and VDM-RT)

```
new expression = 'new', name, '(', [ expression list ], ')';
```

A.5.17 The Self Expression (VDM++ and VDM-RT)

```
self expression = 'self';
```

¹**Note:** no delimiter is allowed



A.5.18 The Threadid Expression (VDM++ and VDM-RT)

threadid expression = 'threadid' ;

A.5.19 The Is Expression

A.5.20 The Undefined Expression

undefined expression = 'undefined';

A.5.21 The Precondition Expression

A.5.22 Base Class Membership (VDM++ and VDM-RT)

isofbaseclass expression = 'isofbaseclass', '(', name, expression, ')';

A.5.23 Class Membership (VDM++ and VDM-RT)

isofclass expression = 'isofclass', '(', name, expression, ')';

A.5.24 Same Base Class Membership (VDM++ and VDM-RT)

A.5.25 Same Class Membership (VDM++ and VDM-RT)

²**Note:** no delimiter is allowed



A.5.26 History Expressions (VDM++ and VDM-RT)

A.5.27 Time Expressions (VDM-RT)

```
time expression = 'time';
```

A.5.28 Names

```
name = identifier, [ ' '', identifier ] ;
name list = name, { ', ', name } ;
old name = identifier, '~';
```

A.6 State Designators



A.7 Statements

```
statement = let statement
              let be statement
              def statement
              block statement
              general assign statement
              if statement
              cases statement
              sequence for loop
              set for loop
              index for loop
              while loop
              nondeterministic statement
              call statement
              specification statement
              start statement
              start list statement
              duration statement
              cycles statement
              return statement
              always statement
              trap statement
              recursive trap statement
              exit statement
              error statement
              identity statement;
```

A.7.1 Local Binding Statements



A.7.2 Block and Assignment Statements

A.7.3 Conditional Statements

A.7.4 Loop Statements



A.7.5 The Nondeterministic Statement

```
nondeterministic statement = '||', '(', statement, { ', ', statement }, ') ';
```

A.7.6 Call and Return Statements

A.7.7 The Specification Statement

```
specification statement = '[', implicit operation body, ']';
```

A.7.8 Start and Start List Statements (VDM++ and VDM-RT)

```
start statement = 'start', '(', expression, ')';
start list statement = 'startlist', '(', expression, ')';
```

A.7.9 The Duration and Cycles Statements (VDM-RT)



A.7.10 Exception Handling Statements

A.7.11 The Error Statement

```
error statement = 'error';
```

A.7.12 The Identity Statement

```
identity statement = 'skip';
```

A.8 Patterns and Bindings

A.8.1 Patterns



```
set union pattern = pattern, 'union', pattern;
seq enum pattern = '[',[ pattern list], ']';
seq conc pattern = pattern, '^', pattern;
map enumeration pattern = '{',[ maplet pattern list], '}';
maplet pattern list = maplet pattern, { ', ', maplet pattern };
maplet pattern = pattern, '|->', pattern;
map muinon pattern = pattern, 'munion', pattern;
tuple pattern = 'mk_', '(', pattern, ', ', pattern list, ')';
record pattern = 'mk_', aname, '(', [ pattern list ], ')';

pattern list = pattern, { ', ', pattern };
```

A.8.2 Bindings

³**Note:** no delimiter is allowed



Appendix B

Lexical Specification

B.1 Characters

The characters that comprise a valid VDM specification are defined in terms of Unicode codepoints. The actual character encoding of a VDM source file (for example UTF-8, ISO-Latin-1 or Shift-JIS) is not defined, and the tool support is responsible for converting whatever encoding is used into Unicode during the parse of the file.

All VDM keywords and delimiter tokens are composed of characters from the Basic Latin block ("ASCII" codepoints less than U+0080). On the other hand, user identifiers (variable names, function names and so on) can be composed of a rich variety of Unicode codepoints, reflecting the need for fully internationalized specifications.

All Unicode codepoints have a "category". Certain categories are entirely excluded from the set of codepoints that are permitted in identifiers. This prevents, say, puntuation characters from being used. On the other hand, to provide a degree of compatibility with the original VDM ISO standard, and for backward compatibility, there are different rules for the formation of user identifiers that only use ASCII characters. For example, the underscore is permitted in identifiers (U+005F), even though this is in the connecting punctuation category, which would not normally be allowed.

See http://www.fileformat.info/info/unicode/category/index.htmformore information about categories.



```
initial letter:
if
        codepoint < U+0100
then
        Any character in categories Ll, Lm, Lo, Lt, Lu or U+0024 (a dollar sign)
else
        Any character except categories Cc, Zl, Zp, Zs, Cs, Cn, Nd, Pc
following letter:
if
        codepoint < U+0100
then
        Any character in categories Ll, Lm, Lo, Lt, Lu, Nd or U+0024 (a dollar sign)
        or U+005F (underscore) or U+0027 (apostrophe)
        Any character except categories Cc, Zl, Zp, Zs, Cs, Cn
else
digit:
           2
     1
                3
                           5
                                 6
                                                  9
hexadecimal digit:
0
     1
           2
                3
                           5
                                 6
                                      7
                                            8
                                                  9
                      4
     В
           С
Α
                D
                      Ε
                           F
     b
                d
                            f
octal digit:
           2
                3
                           5
                                       7
     1
                      4
                                 6
```

Table B.1: Character set



B.2 Symbols

The following kinds of symbols exist: keywords, delimiters, symbolic literals, and comments. The transformation from characters to symbols is given by the following rules; these use the same notation as the syntax definition but differ in meaning in that no separators may appear between adjacent terminals. Where ambiguity is possible otherwise, two consecutive symbols must be separated by a separator.

```
keyword = '#act' | '#active' | '#fin' | '#req' | '#waiting' | 'abs'
           'all' | 'always' | 'and' | 'as' | 'async' | 'atomic' | 'be'
           'bool' | 'by' | 'card' | 'cases' | 'char' | 'class'
           'comp' | 'compose' | 'conc' | 'cycles' | 'dcl' | 'def'
           'definitions' | 'dinter' | 'div' | 'dlmodule' | 'do'
           'dom' | 'dunion' | 'duration' | 'elems' | 'else' | 'elseif'
           'end' | 'error' | 'errs' | 'exists' | 'exists1' | 'exit'
           'exports' | 'ext' | 'false' | 'floor'
           'for' | 'forall' | 'from' | 'functions' | 'hd' | 'if' | 'in'
           'inds' | 'inmap' | 'instance' | 'int' | 'inter'
           'imports' | 'init' | 'inv' | 'inverse' | 'iota' | 'is'
           'isofbaseclass' | 'isofclass' | 'lambda' | 'len' | 'let'
           'map' | 'measure' | 'merge' | 'mod' | 'module' | 'mu'
           'munion' | 'mutex' | 'nat' | 'nat1' | 'new' | 'nil' | 'not' | 'of'
           'operations' | 'or' | 'others' | 'per' | 'periodic' | 'post'
           'power' | 'pre' | 'private' | 'protected' | 'psubset'
           'public' | 'rat' | 'rd' | 'real' | 'rem' | 'renamed'
           'responsibility' | 'return' | 'reverse' | 'rng'
           'samebaseclass' | 'sameclass' | 'self' | 'seq' | 'seq1'
           'set' | 'skip' | 'specified' | 'st' | 'start' | 'startlist'
           'state' | 'struct' | 'subclass' | 'subset' | 'sync'
           'system' | 'then' | 'thread' | 'threadid' | 'time' | 'tixe'
           'tl' | 'to' | 'token' | 'traces' | 'trap' | 'true' | 'types'
           'undefined' | 'union' | 'uselib' | 'values'
           'variables' | 'while' | 'with' | 'wr' | 'yet' | 'RESULT' ;
identifier = initial letter, { following letter };
```

Note that in VDM-RT the CPU and BUS classes are reserved and cannot be redefined by the user. These two predefined classes contain the functionality described in Section 13.3 above.

All identifiers beginning with one of the reserved prefixes are reserved: init_, inv_, is_, mk_, post_ and pre_.

```
type variable identifier = '@', identifier;
```



```
is basic type = 'is_', ('bool' | 'nat' | 'nat1' | 'int' | 'rat'
             | 'real' | 'char' | 'token' ) ;
symbolic literal = numeric literal | boolean literal
                nil literal | character literal | text literal
numeral = digit, { digit } ;
numeric literal = decimal literal | hexadecimal literal ;
exponent = (`E' | `e'), [`+' | `-'], numeral;
decimal literal = numeral, ['.', digit, { digit } ], [ exponent ] ;
hexadecimal literal = (`0x' | `0X'), hexadecimal digit, { hexadecimal digit };
boolean literal = 'true' | 'false';
nil literal = 'nil';
character literal = '', character | escape sequence
                | '';
escape sequence = '\\' | '\r' | '\n' | '\t' | '\f' | '\e' | '\a'
                 '\x' hexadecimal digit,hexadecimal digit
                 '\u' hexadecimal digit,hexadecimal digit,
                   hexadecimal digit, hexadecimal digit
                 '\c' character
                '\' octal digit, octal digit, octal digit
'\"' | '\' | ;
text literal = '"', { '\"' | character | escape sequence }, '"';
quote literal = '<', identifier, '>';
Single-line comment = '--', { character – newline }, newline ;
Multiple-line comment = '/*', { character }, '*/';
```

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The escape sequences given above are to be interpreted as follows:



Sequence	Interpretation
' \\'	U+005C (backslash character)
'\r'	U+000D (return character)
'\n'	U+000A (newline character)
'\t'	U+0009 (tab character)
'\f'	U+000C (formfeed character)
'\e'	U+001B (escape character)
'\a'	U+0007 (alarm (bell))
'\x' hexadecimal digit, hexadecimal digit	U+00xy (hex representation of character
	(e.g. \x41 is 'A'))
'\u' hexadecimal digit, hexadecimal digit,	U+abcd (hex representation of character
hexadecimal digit, hexadecimal digit	(e.g. \u0041 is 'A'))
'\c' character	U+00nn (control character)
	(e.g. $\c A \equiv \x 01$)
'\' octal digit, octal digit, octal digit	U+00nn (octal representation of character)
'∖п'	U+0022 (double quote)
' '	U+0027 (apostrophe)

Table B.2: Escape sequences



Appendix C

Operator Precedence

The precedence ordering for operators in the concrete syntax is defined using a two-level approach: operators are divided into families, and an upper-level precedence ordering, >, is given for the families, such that if families F_1 and F_2 satisfy

$$F_1 > F_2$$

then every operator in the family F_1 is of a higher precedence than every operator in the family F_2 .

The relative precedences of the operators within families is determined by considering type information, and this is used to resolve ambiguity. The type constructors are treated separately, and are not placed in a precedence ordering with the other operators.

There are six families of operators, namely Combinators, Applicators, Evaluators, Relations, Connectives and Constructors:

Combinators: Operations that allow function and mapping values to be combined, and function, mapping and numeric values to be iterated.

Applicators: Function application, field selection, sequence indexing, etc.

Evaluators: Operators that are non-predicates.

Relations: Operators that are relations.

Connectives: The logical connectives.

Constructors: Operators that are used, implicitly or explicitly, in the construction of expressions; e.g. **if-then-elseif-else**, '|->', '...', etc.

The precedence ordering on the families is:

combinators > applicators > evaluators > relations > connectives > constructors



C.1 The Family of Combinators

These combinators have the highest family priority.

```
combinator = iterate | composition ;
iterate = '**' ;
composition = 'comp' ;
```

precedence level	combinator
1	comp
2	iterate

C.2 The Family of Applicators

All applicators have equal precedence.

C.3 The Family of Evaluators

The family of evaluators is divided into nine groups, according to the type of expression they are used in.



```
evaluator = arithmetic prefix operator
            set prefix operator
            sequence prefix operator
            map prefix operator
            map inverse
            arithmetic infix operator
            set infix operator
            sequence infix operator
            map infix operator;
arithmetic prefix operator = '+' | '-' | 'abs' | 'floor';
set prefix operator = 'card' | 'power' | 'dunion' | 'dinter' ;
sequence prefix operator = 'hd' | 'tl' | 'len'
                        'inds' | 'elems' | 'conc';
map prefix operator = 'dom' | 'rng' | 'merge' | 'inverse' ;
arithmetic infix operator = '+' | '-' | '*' | '/' | 'rem' | 'mod' | 'div';
set infix operator = 'union' | 'inter' | '\' ;
sequence infix operator = '^';
map infix operator = 'munion' | '++' | '<:' | '<-:' | ':>' | ':->' ;
```

The precedence ordering follows a pattern of analogous operators. The family is defined in the following table.

C.4 The Family of Relations

This family includes all the relational operators whose results are of type **bool**.

```
relation = relational infix operator | set relational operator ;
relational infix operator = '=' | '<>' | '<=' | '>' | '>=' ;
set relational operator = 'subset' | 'psubset' | 'in set' | 'not in set' ;
```



thb

precedence level	arithmetic	set	map	sequence
1	+ -	$\mathtt{union} \setminus$	munion ++	^
2	* /	inter		
	rem			
	mod			
	div			
3			inverse	
4			<: <-:	
5			:>:->	
6	(unary) +	card	dom	len
	(unary) –	power	rng	elems
	abs	dinter	merge	hdtl
	floor	dunion		conc
				inds

Table C.1: Operator precedence

precedence level	relation	
1	<=	<
	>=	>
	=	<>
	subset	psubset
	in set	not in set

All operators in the Relations family have equal precedence. Typing dictates that there is no meaningful way of using them adjacently.

C.5 The Family of Connectives

This family includes all the logical operators whose result is of type **bool**.

```
connective = logical prefix operator | logical infix operator ;
logical prefix operator = 'not';
logical infix operator = 'and' | 'or' | '=>' | '<=>';
```



precedence level	connective
1	<=>
2	=>
3	or
4	and
5	not

C.6 The Family of Constructors

This family includes all the operators used to construct a value. Their priority is given either by brackets, which are an implicit part of the operator, or by the syntax.

C.7 Grouping

The grouping of operands of the binary operators are as follows:

Combinators: Right grouping.

Applicators: Left grouping.

Connectives: The '=>' operator has right grouping. The other operators are associative and

therefore right and left grouping are equivalent.

Evaluators: Left grouping¹.

Relations: No grouping, as it has no meaning.

Constructors: No grouping, as it has no meaning.

C.8 The Type Operators

Type operators have their own separate precedence ordering, as follows:

1. Function types: ->, +> (right grouping).

2. Union type: | (left grouping).

3. Other binary type operators: * (no grouping).

4. Map types: map...to...and inmap...to... (right grouping).

5. Unary type operators: **seq of**, **seq1 of**, **set of**.

¹Except the "map domain restrict to" and the "map domain restrict by" operators which have a right grouping. This is not standard.



Appendix D

Differences between the Concrete Syntaxes

Whe VDM was originally developed a mathematical syntax was used and this have also been retained in the ISO/VDM-SL standard. However, most VDM tools today mainly use an ASCII syntax. Below is a list of the symbols which are different in the mathematical syntax and the ASCII syntax:

Mathematical syntax	ASCII syntax
•	&
×	*
\leq	<=
\geq	>=
 	<>
$\begin{array}{c} \times \\ \leq \\ \geq \\ \neq \\ \stackrel{o}{\rightarrow} \\ \rightarrow \\ \Rightarrow \\ \Leftrightarrow \\ \mapsto \\ \triangle \end{array}$	==>
\rightarrow	->
\Rightarrow	=> <=>
\Leftrightarrow	<=>
\mapsto	->
\triangle	==
 \(\psi \)	**
†	++
m	munion
\triangleleft	<:
\triangleright	:>
4	<-:
⊳	:->
↑ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □	psubset
\subseteq	subset
\bigcap	^
n U	dinter
U	dunion



Mathematical syntax	ASCII syntax
\mathcal{F}	power
set	set of
*	seq of
+	seq1 of
$\longrightarrow \cdots$	map to
$\ldots \stackrel{m}{\longleftrightarrow} \ldots$	inmap to
$\mid \mu \mid$	mu
$\mid \mathbb{B} \mid$	bool
N	nat
\mathbb{Z}	int
$ \mathbb{R} $	real
「一	not
\cap	inter
U ∈ ≠ ∧ ∨ ∀ ∃ ∃!	union
\in	in set
$ \notin$	not in set
\land	and
V	or
\forall	forall
Ε	exists
	exists1
λ	lambda
ι	iota
1	inverse

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