

## Lecture 2: Weighted Majority and Winnow

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Lecture date: 8/28

We recall the Perceptron algorithm discussed in the last lecture. For normal vector  $\|w^*\|_2 \leq 1$ , samples  $\|x\|_2 \leq 1$ , and margin  $\gamma = \min_x |\langle w^*, x \rangle|$ , we showed that the number of mistakes by the Perceptron Algorithm is at most  $1/\gamma^2$ .

More generally, the bound we have is

$$\# \text{ of mistakes} \leq \frac{\|w^*\|_2^2 \max_x \|x\|_2^2}{\gamma^2}.$$

Viewing  $x = (x_1, \dots, x_n)$  as a feature vector.  $\|x\|_2^2$  can grow with the dimension. In many natural settings the unknown hypothesis vector could be sparse, e.g., only  $k$  out of  $n$  features are relevant. A natural question is whether we can improve the bound in this setting. In this lecture, we will discuss another algorithm that works well for sparse concepts.

## 1 Winnow Algorithm

### 1.1 Learn disjunction of $r$ relevant variables

Consider labeled data  $(x, y)$ , where  $x = (x_1, \dots, x_n) \in \{0, 1\}^n$ . There are  $r$  relevant variables out of  $n$ , denoted as  $S = \{x_{i_1}, \dots, x_{i_r}\} \subset \{x_1, \dots, x_n\}$ , the labeling function is

$$y = l(x) = x_{i_1} \vee x_{i_2} \cdots \vee x_{i_r}$$

For example, let  $x = (x_1, \dots, x_5)$ ,  $S = (x_2, x_4)$  are the relevant variables. Then

$$l(1, 0, 1, 0, 0) = 0, \quad l(1, 1, 0, 0, 0) = 1, \quad l(0, 0, 0, 1, 1) = 1, \dots$$

The labeling function can also be written as  $\mathbf{1}(\sum_{x \in S} x \geq 1)$ , where  $\mathbf{1}$  is the indicator function.

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**Algorithm 1** Winnow Algorithm to learn a disjunction of  $r$  variables

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Start with  $w_i = 1, 1 \leq i \leq n$ .

**for** each input  $x$  **do**

    Predict + if  $\sum_{i=1}^n w_i x_i \geq n$  and  $-$  otherwise.

    For a mistake on a positive example, for all  $i$  with  $x_i = 1$ , set  $w_i \leftarrow 2w_i$ .

    For a mistake on a negative example, for all  $i$  with  $x_i = 1$ , set  $w_i \leftarrow w_i/2$ .

**end for**

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**Theorem 1.** *The number of mistakes made by Winnow on any possible sequence is at most  $3r \log_2 n + 1$ .*

*Proof.* Denote  $M_+$  as # of mistakes on positive examples, and  $M_-$  as # of mistakes on negative examples. Each time the algorithm makes a mistake on a positive example, we will double  $w_i$ . However,  $w_i$  cannot exceed  $n$ . So we can bound  $M_+$  as

$$M_+ \leq r \log_2 n.$$

On a mistake of a positive example, the total weight increases by at most  $n$ . On a mistake of a negative example, the total weight decreases by at least  $n/2$ . Since the sum of weights remains nonnegative, we have

$$M_- \leq 2M_+ + 1$$

where the  $+1$  is to account for the fact that the weights start out at a total of  $n$ . By combining all mistakes, we have

$$M_- + M_+ \leq 3r \log_2 n + 1.$$

□

## 1.2 Learn $k$ -out-of- $r$ function

We here generalize the hypothesis class. Let  $x_i \in \{0, 1\}, 1 \leq i \leq n$ . We label the data  $x = (x_1, \dots, x_n)$  as

$$l(x) = \mathbf{1}(x_1 + \dots + x_r \geq k).$$

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**Algorithm 2** Winnow Algorithm to learn  $k$ -out-of- $r$  function

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Start with  $w_i = 1, 1 \leq i \leq n$ .

**for** each input  $x$  **do**

    Predict  $+$  if  $\sum_{i=1}^n w_i x_i \geq n$  and  $-$  otherwise.

    For a mistake on a positive example, for all  $i$  with  $x_i = 1$ , set  $w_i \leftarrow w_i(1 + \epsilon)$ .

    For a mistake on a negative example, for all  $i$  with  $x_i = 1$ , set  $w_i \leftarrow w_i/(1 + \epsilon)$ .

**end for**

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The algorithm is a slight generalization of Algorithm 1.1. By choosing  $\epsilon = 1$ , the algorithm is the same as Algorithm 1.1. It has the following guarantee.

**Theorem 2.** *The number of mistakes made by Winnow is  $O(rk \log n)$ .*

*Proof.* Denote  $M_+$  as # of mistakes on positive examples, and  $M_-$  as # of mistakes on negative examples. We note that the total increase in weight on a mistake of positive example  $\leq \epsilon n$ . After  $M_+$  mistakes on positive examples, the total increase in weight on a mistake of positive examples  $\leq \epsilon n M_+$ . Similarly, after  $M_-$  mistakes on negative examples, the total decrease in weight on a mistake of negative examples is at least  $(n - \frac{n}{1+\epsilon})M_- = \frac{\epsilon n}{1+\epsilon}M_-$ . Since the total weight is initialized at  $n$ , and stays non-negative, we have

$$n + \epsilon n M_+ \geq \frac{\epsilon n}{1 + \epsilon} M_-$$

This implies

$$M_- \leq \frac{1 + \epsilon}{\epsilon} + (1 + \epsilon)M_+$$

On a mistake on a positive example, the weights of at least  $k$  relevant variables increase by  $(1 + \epsilon)$  factor. On a mistake on a negative example, the weights of at most  $k - 1$  relevant variables decrease by a  $(1 + \epsilon)$  factor. Then by considering the total change of the relevant variables in terms of the number of factors of  $(1 + \epsilon)$ , we have

$$kM_+ - (k - 1)M_- \leq r \log_{1+\epsilon} n$$

Substituting the bound on  $M_-$ , we have

$$M_+(k - (k - 1)(1 + \epsilon)) \leq r \log_{1+\epsilon} n + (k - 1) \frac{1 + \epsilon}{\epsilon}$$

By choosing  $\epsilon = \frac{1}{2(k-1)}$ , we get

$$\frac{1}{2}M_+ \leq r \log_{1+\frac{1}{2(k-1)}} n + 2(k - 1)^2 \left(1 + \frac{1}{2(k - 1)}\right)$$

So

$$M_+ = O(rk \log n),$$

and the total number of mistakes can be bounded

$$M_+ + M_- = O(rk \log n).$$

□

### 1.3 Learning halfspaces

Here we consider learning the halfspace  $w_1^*x_1 + \dots + w_n^*x_n \geq w_0^*$ . We first do the following three pre-processing steps. Since we do not know  $w^*$  in advance, the third step is for analysis only.

1. Scale and shift such that  $x_i \in [0, 1], w_i^* \in \mathbb{Z}$ .
2. If some  $w_i^* < 0$ , we can use  $y_i = 1 - x_i$ , and the corresponding term

$$w_i^*x_i = x_i^*(1 - y_i) = w_i^* - w_i^*y_i$$

This step ensures that  $w_i^* \geq 0$ .

3. For each term  $i$ , we make  $w_i^*$  copies of  $x_i$ . Define  $W^* = \sum_{i=1}^n w_i^*$ .

This reduces the problem to learning a  $w_0^*$ -out-of- $W^*$  function, and we can apply Algorithm 1.2. We give the guarantee as follows.

**Theorem 3.** *The number of mistakes made by the Winnow Algorithm is at most  $O(\|w^*\|_1^2 \log(n\|w^*\|_1))$ .*

Since we assume that the parameters are integers by doing the pre-processing steps, the margin here was 1. More generally, we get the following bound.

$$\# \text{ of mistakes} \leq O\left(\frac{\|w^*\|_1^2 \|x\|_\infty^2 \log(n\|w^*\|_1)}{\gamma^2}\right), \text{ where } \gamma := \min_x |\langle w^*, x \rangle|.$$

We can compare it to the bound of Perceptron algorithm, where the number of mistakes is upper bounded by  $O\left(\frac{\|w^*\|_2^2 \max_x \|x\|_2^2}{\gamma^2}\right)$ .