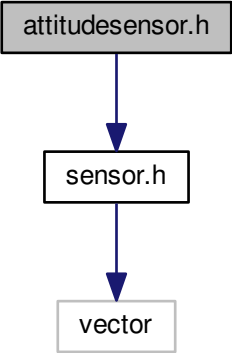


attitudesensor.h



```
graph TD; A[attitudesensor.h] --> B[sensor.h]; B --> C[vector];
```

sensor.h

vector