

Finken::updatePos



```
graph LR; A[Finken::updatePos] --> B[Finken::getSensors]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'Finken::updatePos'. The right box is white and contains the text 'Finken::getSensors'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

Finken::getSensors