

Global Semantic Description of objects based on Prototype Theory

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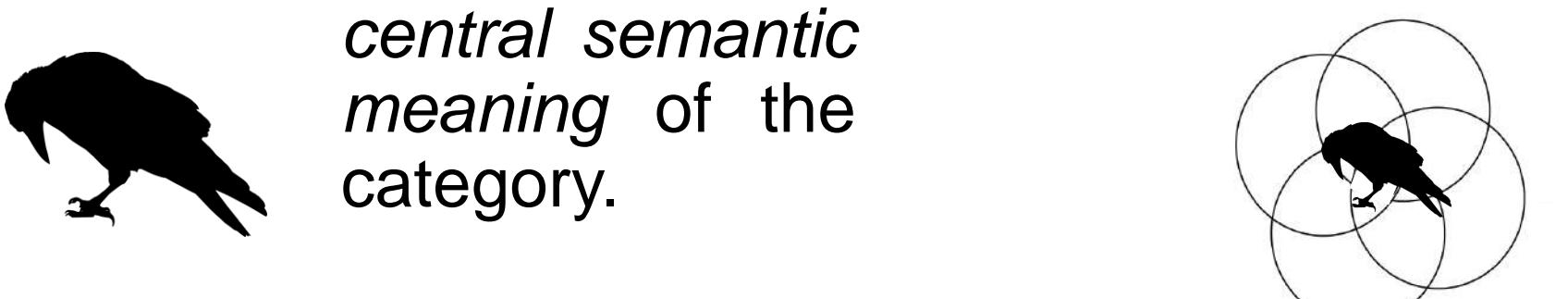
Motivation

- ✓ CNNs provide outstanding performance in image semantic processing tasks.
- ✓ CNN description models do not codify their representation based on the Cognitive Science foundations to represent the meaning.
- ✓ We bring into view the Prototype Theory as a theoretical framework to represent the semantic meaning of the visual information contained in an image.

Background

Elements of Prototype Theory

- The prototype stands for the central semantic meaning of the category.
- Category internal semantic structure:** A category member is positioned closer to the category prototype based on its typicality degree.



- Object categorization is obtained based on the similarity of a new exemplar with the learned prototypes.
- Main characteristics (prototypicality effects):

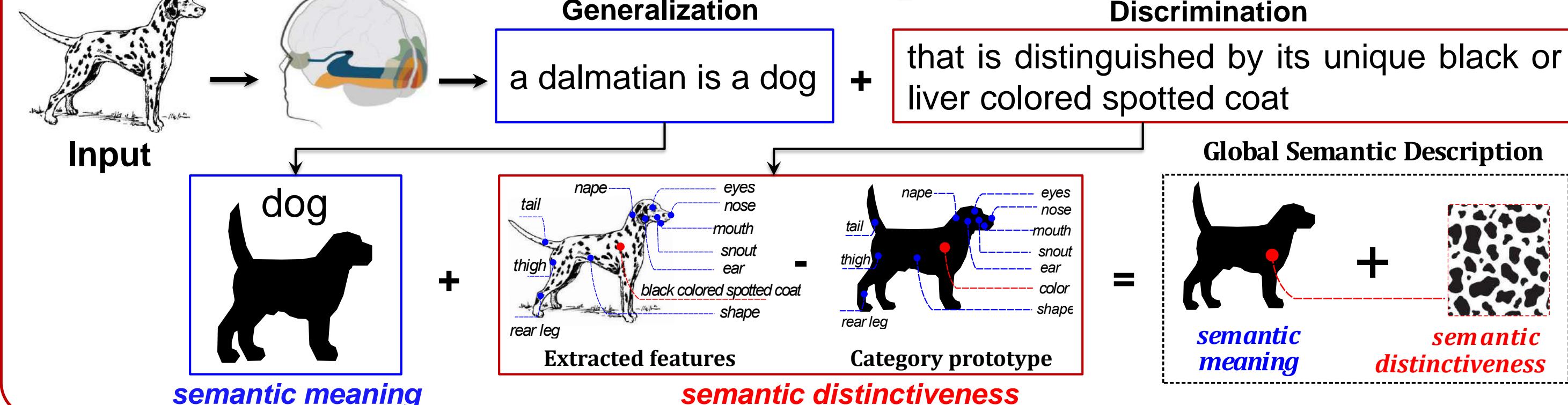
	extensional	intensional
non-equality (salience effect, core/periphery)	Difference of typicality and membership salience	Clustering into family resemblances
non-discreteness (demarcation problems, flexibly)	Fuzziness at the edges, membership uncertainty	Absence of necessary-and-sufficient definitions

Problem Statement

How to describe and stand for objects, semantically? Can a description model be developed in which objects are described using the same semantic features learned to classify them? How to include the semantic of a category prototype into the global semantic description of objects?

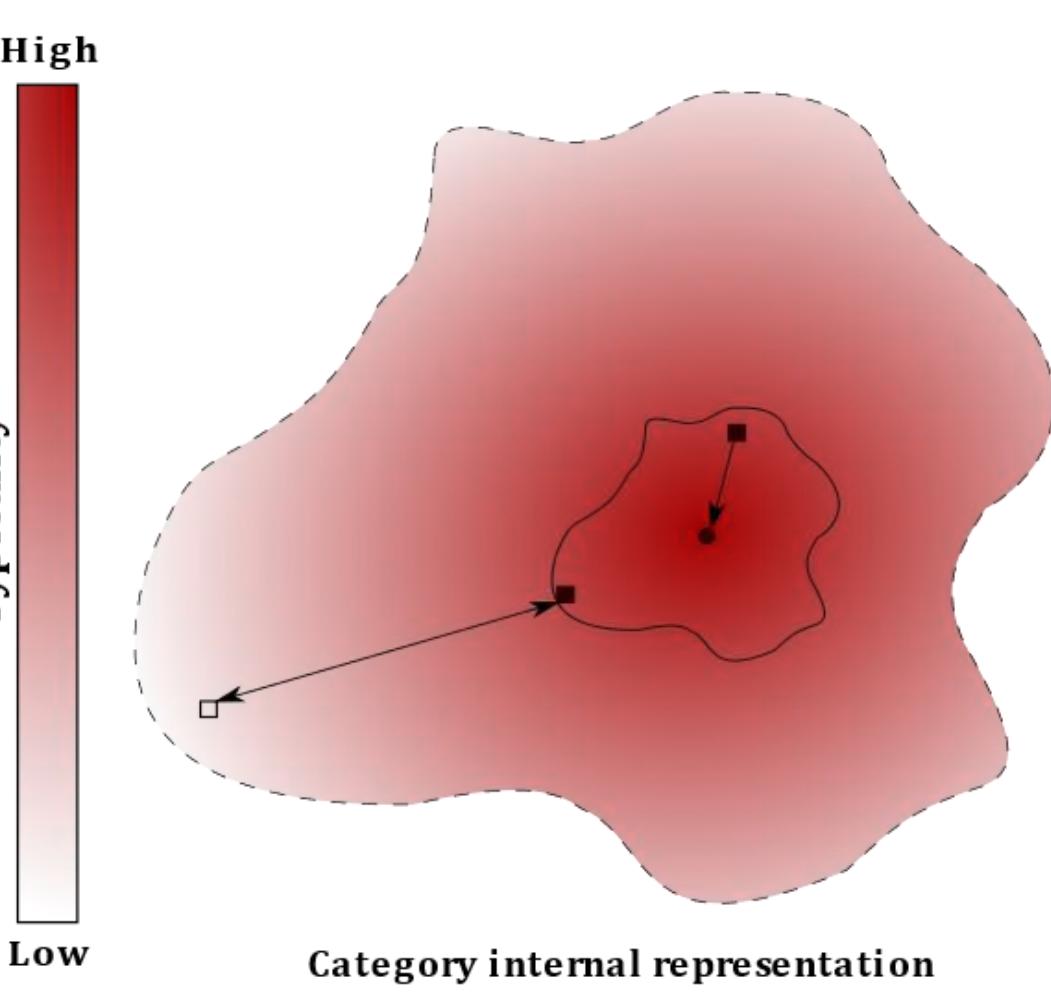
Intuition

Human description



Our Prototype Model

CNN Prototype Model



Legend

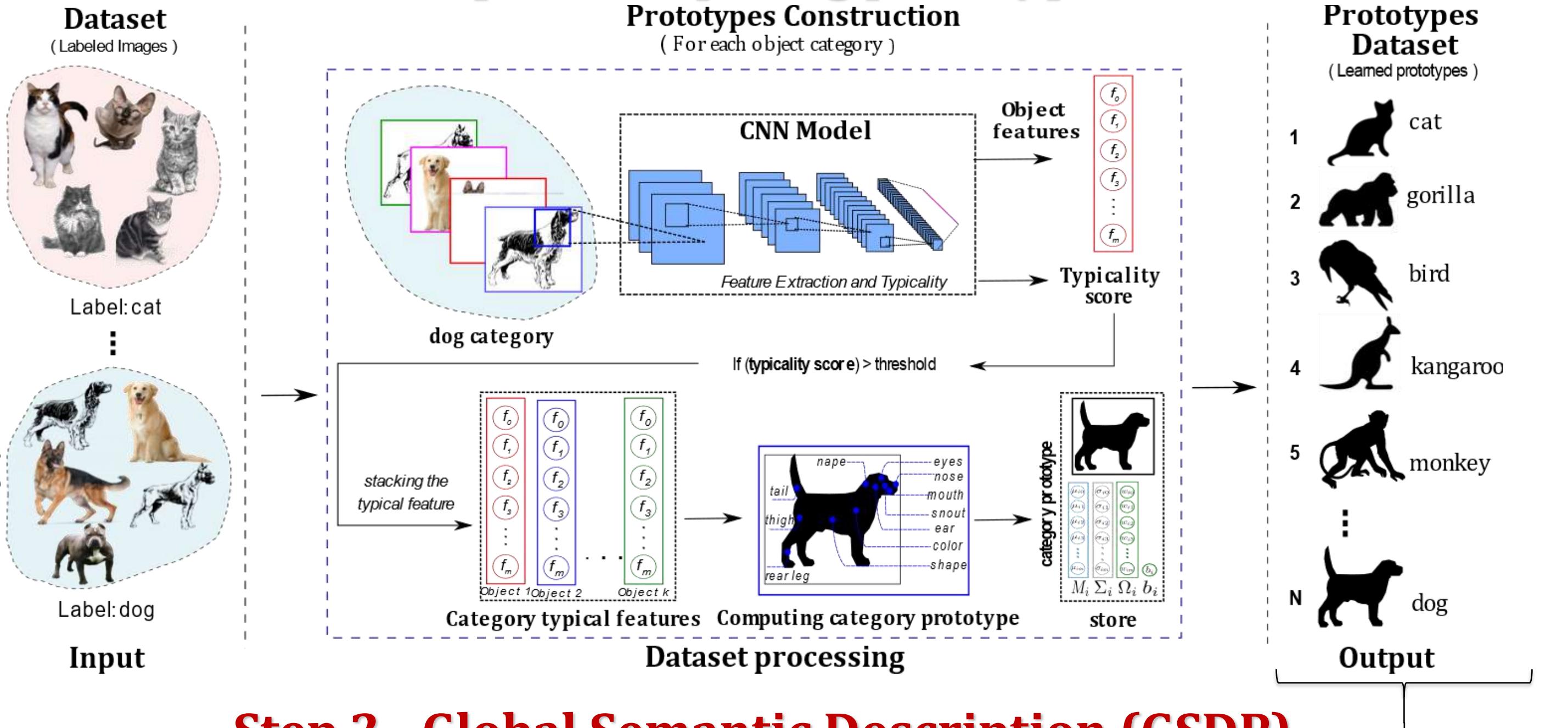
- Typical members
- Non-typical members
- Semantic Prototype
- Abstract Prototype
- Category edges (undefined)
- Semantic Prototype edges (defined)
- Prototypical distance
- Distance between objects

Definitions

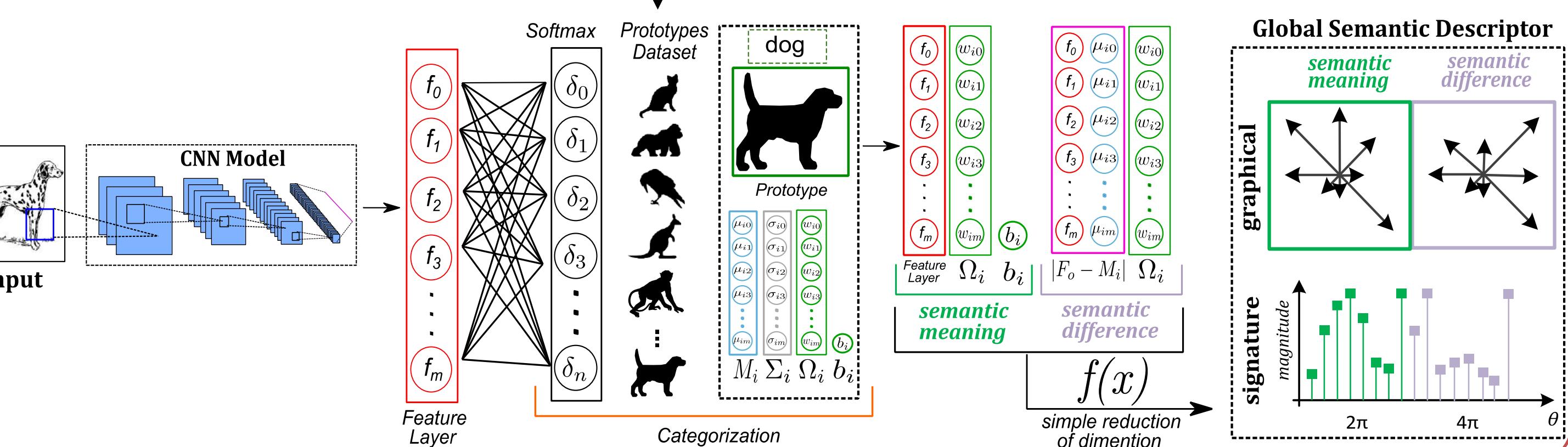
- Semantic Prototype: $P_i = (M_i, \Sigma_i, \Omega_i)$
- Abstract Prototype: $M_i \in P_i$
- Object semantic value: $\hat{z}_o = \sum_{j=1}^m \omega_{ij} f_j + b_i$
- Category semantic value: $\hat{z}_i = \sum_{j=1}^m \omega_{ij} \mu_{ij} + b_i$
- Prototypical distance: $\delta(o, P_i) = \sum_{j=1}^m |\omega_{ij}| |f_j - \mu_{ij}|$
- Distance between objects: $\delta(o_1, o_2) = \sum_{j=1}^m |\omega_{ij}| |f_j^1 - f_j^2|$

Methodology

Step 1 - Computing prototypes



Step 2 - Global Semantic Description (GSDP)



Results

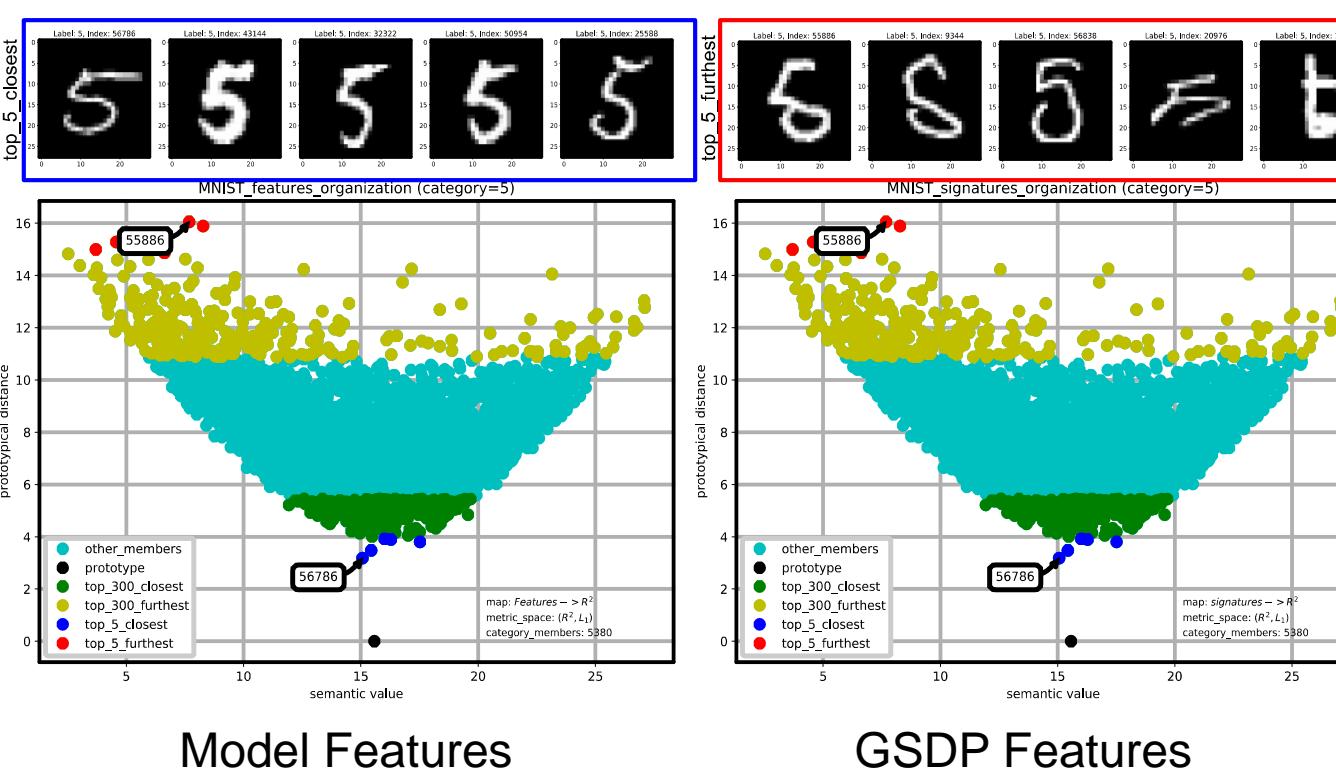
Category internal structure

Mapping the category

$$(F_{c_i}, \delta) \xrightarrow{\rho} (\mathbb{R}^2, l_1)$$

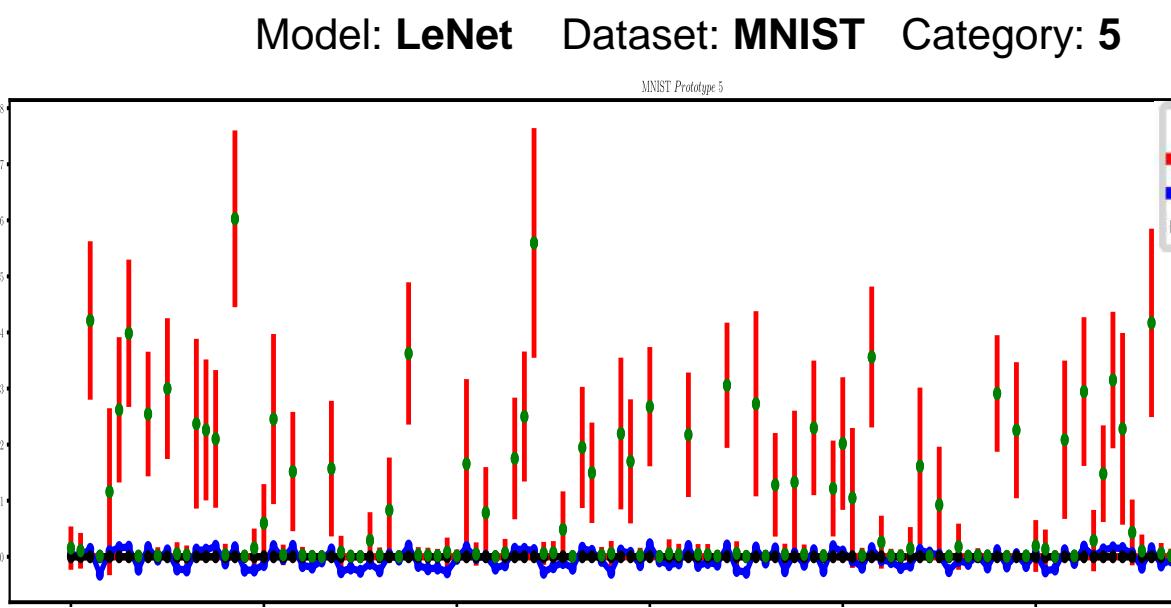
$\rho: F_{c_i} \rightarrow \mathbb{R}^2 \mid \rho(o \in O_{c_i}) = \rho(F_o) = p(\hat{z}_o, \delta(o, P_i))$

$\rho: F_{c_i} \rightarrow \mathbb{R}^2$ is continuous

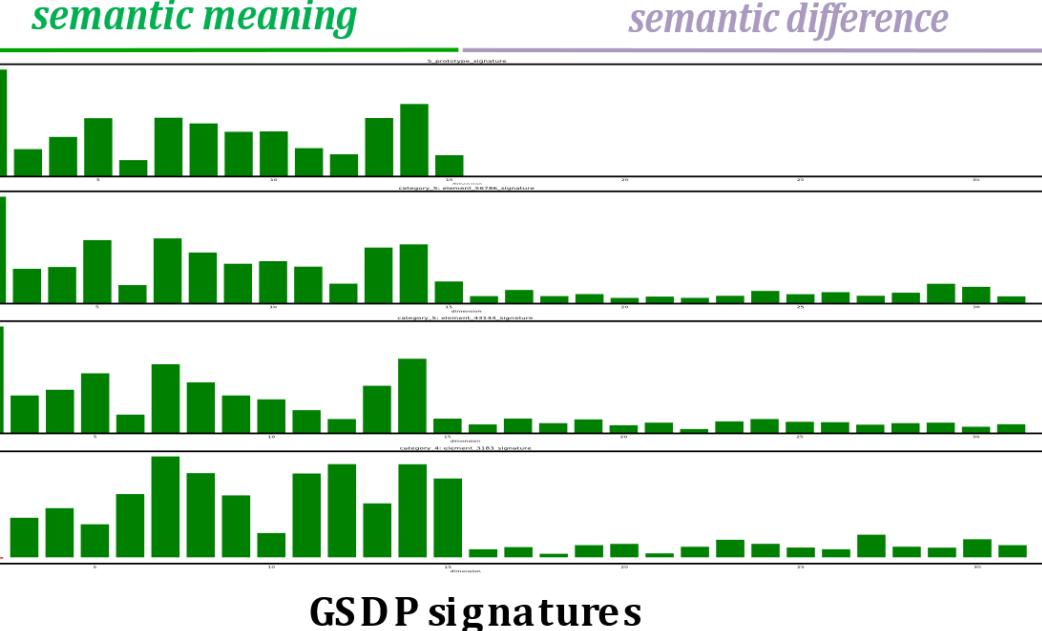


Signature taxonomies

Semantic prototype



Signatures distributions



Performance Evaluation

Cluster Metrics Scores

Descriptor	Size	Time (ms)	Metrics Scores				
			H	C	V	ARI	AMI
GIST	960	1210	0.05	0.05	0.05	0.01	0.05
LBP	512	1380	0.02	0.03	0.03	0.01	0.02
HOG	1960	25	0.04	0.04	0.04	0.01	0.03
Color64	64	125	0.12	0.12	0.12	0.04	0.11
Color_Hist	512	38	0.08	0.08	0.08	0.03	0.07
Hu_H_CH	532	145	0.04	0.04	0.04	0.01	0.02
VGG16	4096	62	0.77	0.78	0.77	0.60	0.76
VGG16_PCA_25	25	80	0.76	0.77	0.76	0.60	0.75
VGG16_PCA_256	256	80	0.76	0.77	0.77	0.59	0.76
GSDP (Our)	256	120	0.94	0.97	0.95	0.87	0.94

Our descriptor encoding significantly outperforms other image global encodings in terms of cluster metrics.

Conclusion

Our prototype-based description model proposes a starting point to introduce the theoretical foundation related to the representation of semantic meaning and the learning of visual concepts of the Prototype Theory in the CNN-Descriptors family.



Project Page