PHY 2323 Summary Sheet

1 Math Introduction

There are 3 main coordinate systems:

1. Cartesian (x, y, z)

2. Cylindrical (ρ, ϕ, z)

3. Spherical (r, ϕ, θ)

We have a few charts to help us convert between the systems:

$$\begin{bmatrix} A_\rho \\ A_\phi \\ A_z \end{bmatrix} = \begin{bmatrix} cos\phi & sin\phi & 0 \\ -sin\phi & cos\phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} \qquad \begin{bmatrix} A_r \\ A_\theta \\ A_\phi \end{bmatrix} = \begin{bmatrix} sin\theta cos\phi & sin\theta sin\phi & cos\theta \\ cos\theta cos\phi & cos\theta sin\phi & -sin\theta \\ -sin\phi & cos\phi & 0 \end{bmatrix} \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix}$$

When integrating, the differential line/surface/volume elements can be found in the following chart:

Differential elements	Coordinate system		
	Rectangular (Cartesian)	Cylindrical	Spherical
Length $\vec{d\ell}$	$dx\,\vec{\mathbf{a}}_x$	$d\rho\,\vec{\mathbf{a}}_\rho$	$dr\,\vec{\mathbf{a}}_r$
	$+dy\,\vec{\mathbf{a}}_y$	$+\rho\,d\phi\,\vec{\mathbf{a}}_\phi$	$+r\,d\theta\,\vec{\mathbf{a}}_\theta$
	$+dz\,\vec{\mathbf{a}}_z$	$+dz\,\vec{\mathbf{a}}_z$	$+r\sin\theta\,d\phi\,\vec{\mathbf{a}}_\phi$
Surface $\vec{ds}$	$dy\,dz\,\vec{\mathbf{a}}_x$	$\rho\,d\phi\,dz\,\vec{\mathbf{a}}_\rho$	$r^2\sin\theta\,d\theta\,d\phi\,\vec{\mathbf{a}}_r$
	$+dx\,dz\,\vec{\mathbf{a}}_y$	$+d\rho\,dz\,\vec{\mathbf{a}}_\phi$	$+r\,dr\,\sin\theta\,d\phi\,\vec{\mathbf{a}}_\theta$
	$+dx\,dy\,\vec{\mathbf{a}}_z$	$+\rho\,d\rho\,d\phi\,\vec{\mathbf{a}}_z$	$+r\,dr\,d\theta\,\vec{\mathbf{a}}_\phi$
Volume dv	$dx\,dy\,dz$	$\rho\,d\rho\,d\phi\,dz$	$r^2dr\,\sin\theta\,d\theta\,d\phi$

Tables taken from PHY2323 Course Formula Sheet.

2 Electric Fields

We have 2 ways to talk about electric fields. There is the **Electric Field $\vec{E}$**, and the **Elecric Flux Density $\vec{D}$**.

$$\vec{D} = \epsilon\vec{E}$$

2.1   Coulombs Law

Coulomb's law is used to sum up all the charges in a location which will give an electric field E.

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_S \frac{\rho(\vec{r}\prime)(\vec{r} - \vec{r}\prime)}{|\vec{r} - \vec{r}\prime|^3} \mathrm{d}l$$

This can also be extended to a surface with $\mathrm{d}s$ and 2 integrals, or volume with $\mathrm{d}v$

Note that anything with the $\prime$ means that it is related to the **surface of charge**, and anything without the prime is related to the **observation point.**

> **Ex.**

2.2   Gausses Law

Gausses Law is basically a shorter way of finding the $\vec{E}$ field rather than using Coulomb's equation. It works well when there is **symmetry**.

It can be used on a **closed surface** where we make a guassian surface (such as a sphere, or cylander) at the point of interest.

$$\int_S \vec{E}\mathrm{d}\vec{s} = \frac{Q_{enc}}{\epsilon}$$

We also have the $\vec{D}$ field which is the *Electric Flux Density.*

$$\int_S \vec{D}\mathrm{d}\vec{s} = Q_{enc}$$

Finally, we have the flux ψ, a scalar.

$$\psi = \epsilon \int_s \vec{E}\mathrm{d}\vec{s} = \int \vec{D}\mathrm{d}\vec{s}$$

This is useful in 3 main cases.

1. Spherical Symmetry is present

2. Cylindrical symmetry is present (long line of charge with uniform ρ or cylinder with no angular dependance)

3. Planar Symmetry (Long 2D surface of charge)

A useful piece of information is if we want to find the Q_{enc}, we can often just integrate the charge density in a volume V (or surface S).

$$Q_{enc} = \iiint_V \rho\mathrm{d}V$$

Also, the $\vec{D}$ field is just the $\vec{E}$ field times a factor of ϵ ($\vec{D} = \epsilon\vec{E}$)

> **Ex.**

2.3   Energy Stored in an Electric Field

We say that W is the energy stored in an electric field, or the **energy required to assemble a charge distribution**.

We can calculate this by summing up the product of the charge density and potential difference across a line/surface/volume.

$$W = \frac{1}{2}\int_{S\prime} \rho_s(\vec{r}\prime) * V(\vec{r}\prime)\mathrm{d}v\prime$$

3   Electric Potential

This is the potential energy per unit charge. AKA the voltage. This is a **scalar field**. This is *independant of the path chosen.*

$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0}\int_{l\prime} \frac{\rho_l \mathrm{d}l\prime}{|\vec{r} - \vec{r}\prime|}$$

This can be extended into 2d or 3d space by changing the $l\prime$ and $\mathrm{d}l\prime$ for $s\prime, \mathrm{d}s\prime$ or $v\prime, \mathrm{d}v\prime$.

Then we can relate the change in voltage to the electric field:

$$\vec{E} = -\nabla V \qquad \nabla V = -\int \vec{E} \cdot \mathrm{d}\vec{l}$$

> **Ex.**

3.1   Electric Dipole

A **dipole** is a pair of equal and opposite charges that are very close to each other relative to the point of observation.

This means that at the point of observation, they **seem** as though they are only one charge.

We have an equation that relates the charge of each end of the dipole q, the distance between the charges d, and the vector between the dipole and the observation point $\vec{r}$. This vector must be large compared to d.

$$V(\vec{r}) = \frac{(qd)\hat{z} \cdot \hat{r}}{4\pi\epsilon|r|^2}$$

3.2   Capacitors

The **capacitence** C can be calculated using the following formula:

$$C = \frac{Q}{\Delta V}$$

In practice, we use the following 3 step procedure:

1. Find E
2. Find ΔV
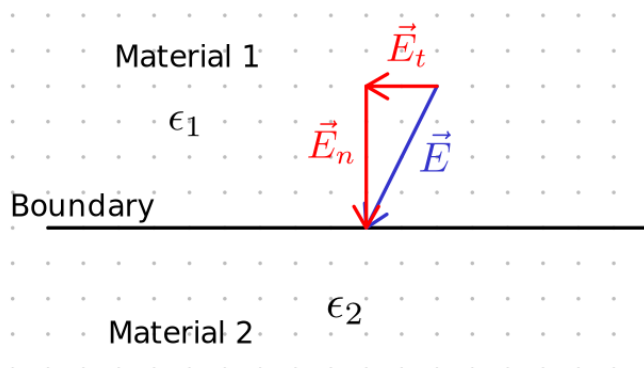3. Find C using $C = \frac{Q}{\Delta V}$

Ex.

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4   Materials in Electric Fields

There are 3 types of materials:

1. Conductors

2. Insulators

3. Semiconductors

We have rules concerning the **normal** and **tangential** part of the boundary between 2 materials, so we need to break up the field into those two components.

To obtain the **normal direction**, we take the unit vector of the boundary, and this is our normal unit vector $(\hat{n} = \frac{\vec{n}}{|n|})$.

If we then want to get the **normal part** of E, we dot product it with $\hat{n}$, then append n to keep direction $(\vec{E}_n = (\vec{E} \cdot \hat{n})\hat{n})$

The **tangential part** is just $\vec{E}_t = \vec{E} - \vec{E}_n$

4.1   Boundary between 2 Dielectrics

If we have 2 electric fields between 2 **dielectric** (insulators) surfaces, we have the following formulas for the bounds:

$$E_{1t} = E_{2t} \qquad \epsilon_1 E_{1n} - \epsilon_2 E_{2n} = \rho_s$$

4.2   Surface of a Conductor

If we have an electric field at the **surface** of a **conductive** surface (note that inside the surface $E = 0$), we have the following formulas for the bounds:

$$E_{1t} = E_{2t} = 0 \qquad E_n = \frac{\rho_s}{\epsilon_0}$$

Ex.

5   Laplace and Poisson Equations

These equations will give us a **general form of the equation** for the solution, and then using **2 conditions** (such as points) we can sub them into the form of the equation and solve the equation.

The whole laplacian equation is very complicated, but we have 2 special cases of note:

$$\nabla^2 V = \frac{-\rho_v}{\epsilon} \qquad \text{or if no charge density (charges on surface): } \nabla^2 V = 0$$

Ex. As a very general example, if we want to find the voltage in a conductor (charges just on surface)

We start by using the laplace equation:

$$\nabla^2 V = 0 \implies \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = 0$$

For simplicity, I will consider a situation where the V only exists in the z direction, hence the x and y components will be 0.

$$\frac{\partial^2 V}{\partial z^2} = 0$$

Since $\frac{\partial^2 V}{\partial z^2} = 0$, then we must say that $\frac{\partial V}{\partial z} = a$ where a is a constant. We must then say that $V = az + b$ where a and b are constants.

This is because integrating $\frac{\partial^2 V}{\partial z^2} = 0$ once gives us $\frac{\partial V}{\partial z} = a$ and then a second time gives $V = az + b$

Then we must have some boundary conditions given such as when $z = 0$, $V = 0$, and when $z = 1$, $V = 5$. Then we can sub in and solve for a and b.
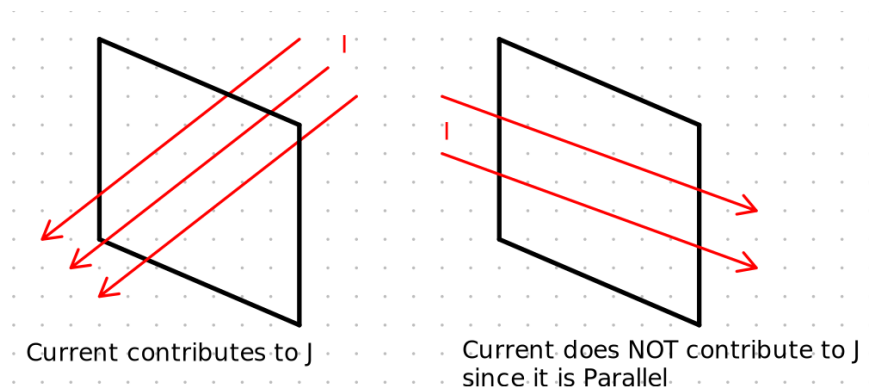
Then we have V at any point.

We can also do this for spherical or cylindrical coordinates, except for the laplacian (∇^2) is different.

6 Currents

Current is just the rate of which charge travels with respect to time. Measured in either $\frac{C}{s}$ or A.

By definition, the current density is just the **amount of current** passing through a **cross sectional area**. Note that this does NOT include parallel current since this current does not actually traverse **through** the cross sectional area.

$$\vec{J} = \frac{I}{A} \qquad I = \int_S \vec{J} \cdot \mathrm{d}\vec{s}$$

Current contributes to J

Current does NOT contribute to J since it is Parallel

6.1 Resistance

Resistance is defined as:

$$R = \frac{L}{\sigma A} = \frac{\rho L}{A}$$

These are equivalent since $\sigma = \rho^{-1}$ where ρ is the **resistivity**, and σ is the **conductivity**.

Those equations work fine for a single area, but if we need to sum up the areas, we have 2 techniques. The first is just by summing up the above equation using an integral. The second is based on Ohms law.

$$R = \frac{L}{\sigma A} = \int_l \frac{\mathrm{d}\vec{l}}{\iint_S \sigma \mathrm{d}\vec{s}} \qquad\qquad R = \frac{\Delta V}{I} = \frac{-\int_l \vec{E} \cdot \mathrm{d}\vec{l}}{\int_S \vec{J} \cdot \mathrm{d}\vec{s}}$$

> **Ex.** We have a long cable (length = L) made of 2 materials. The inner one is copper, and the outer one is aluminium. They have outer radius of r_o and inner radius of r_i. It carries current I. We want to find the resistance.
>
> First we can draw a diagram of the situation.
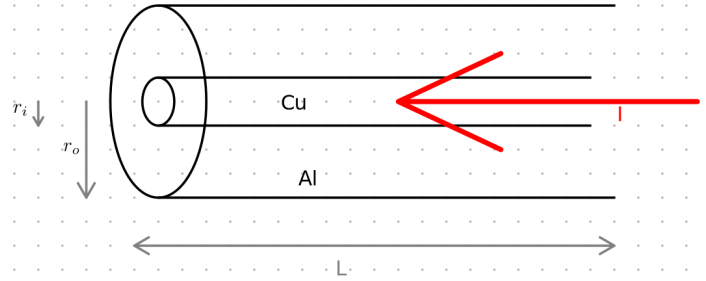
We will break this up into cross sectional disks, and then sum them all up along the length. I need to do this for each material. For the outer material Al, I need to subtract the inner part since that does not exist. Then we can add up both materials (Al + Cu).

$$R_{Cu} = \int_l \frac{\mathrm{d}\vec{l}}{\iint_s \sigma \mathrm{d}\vec{s}} = \int_0^L \frac{\mathrm{d}l}{\sigma_{cu}\pi r_i^2} = \frac{L}{\sigma_{cu}\pi r_i^2}$$

We do not really have to do the bottom integral since the density is constant, and each slice has the same area of πr^2. However if we wanted to, we could take the integral of the disk to get $\int_0^{2\pi} \int_0^{r_i} \rho \mathrm{d}\rho \mathrm{d}\phi = 2\pi \left(\frac{\rho^2}{2} \right)_0^{r_i} = \pi r_i^2$

To get the resistance for the Al part, we need to integrate both the radius from 0 to r_o, and from 0 to r_i, and then subtract the inner component.

$$R_{Al} = \int_0^L \frac{\mathrm{d}l}{\sigma_{Al}\pi r_o^2} - \int_0^L \frac{\mathrm{d}l}{\sigma_{Al}\pi r_i^2} = \frac{L}{\sigma_{Al}\pi(r_o^2 - r_i^2)}$$

Then the entire resistance would be the inverse sum of both of thse since they are in parallel.

$$R_{tot} = \frac{1}{\frac{1}{R_{Al}} + \frac{1}{R_{Cu}}}$$

If we want the current say through the Cu part, we can just use a current dividor by doing:

$$I_{Cu} = I \cdot \frac{R_{Al}}{R_{Al} + R_{Cu}}$$

If we want the current density through this Copper part, we just do the current over the area:

$$J_{Cu} = \frac{I}{A} = \frac{I_{Cu}}{\pi r_i^2}$$

6.2   Equation of Continuity

This basically says that if there is a current going **out of an object**, then there will be **less charges** in that object.

$$\nabla \cdot \vec{J} = -\frac{\partial \rho_v}{\partial t}$$

The **relaxation time** is the amount of time it takes for electrons to settle into their equilibrium. This (τ) is: $\tau = \frac{\epsilon}{\sigma}$

7   Magnetic Fields

Similarly to electric fields, we have 2 fields differentiated only by a constant μ_0. There is the $\vec{B}$ field (**Magnetic Flux Density**) and the $\vec{H}$ field (**Magnetic Field**). $\vec{H} = \frac{\vec{B}}{\mu_0}$

7.1   Biot-Savard

This law is how we calculate the magnetic field. This is **similar to coulombs law** (for electric fields) but for magnetic fields. Although, the versions for L, S, and V are slightly different (Line uses I, Surface and Sphere use J_S and J_V.)

$$\vec{B} = \frac{\mu_0}{4\pi} \int_{l\prime} \frac{I d\vec{l}\prime \times (\vec{r} - \vec{r}\prime)}{|\vec{r} - \vec{r}\prime|^3} \qquad \vec{B} = \frac{\mu_0}{4\pi} \int_{S\prime} \frac{J_s \times (\vec{r} - \vec{r}\prime) d\vec{S}\prime}{|\vec{r} - \vec{r}\prime|^3} \qquad \vec{B} = \frac{\mu_0}{4\pi} \int_{V\prime} \frac{J_V \times (\vec{r} - \vec{r}\prime) d\vec{V}\prime}{|\vec{r} - \vec{r}\prime|^3}$$

We can use the right hand rule to see the direction of the generated field due to the cross product inside the calculation.
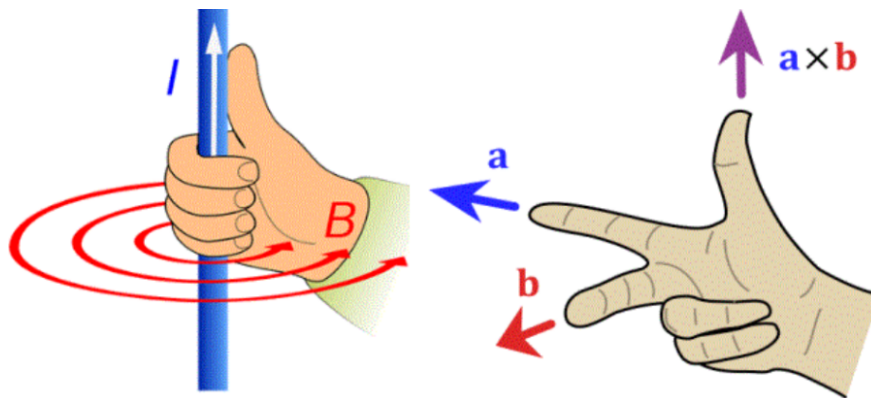
This direction will be perpendicular to both the current, and the $\vec{r} - \vec{r}\prime$ vector.

Ex.   We have a solenoid with radius b and length L with N turns of tightly wound wire. This wire carries current I. We want the $\vec{B}$ field anywhere on the z axis.
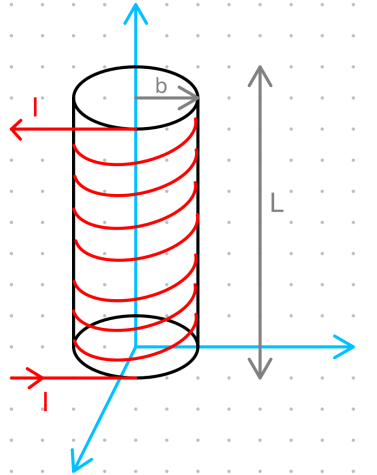
We will use the biot savart law, although we could also use Amperes law with no problem.

We need to use the 2D version of this since we have a surface of charge (the wire can be treated as a solid surface since the wire is **tightly wound**)

$$\vec{B} = \frac{\mu_0}{4\pi} \int_{S\prime} \frac{J_s \times (\vec{r} - \vec{r}\prime) d\vec{S}\prime}{|\vec{r} - \vec{r}\prime|^3} \qquad \vec{r} = z\hat{z} \qquad \vec{r}\prime = b\hat{\rho} + z\prime\hat{z} \qquad \mathrm{d}s\prime = b\mathrm{d}\phi\mathrm{d}z$$

Since the field is going in the ρ direction, we use that differential surface element which is $\rho\mathrm{d}\phi\mathrm{d}z$.

We also need to get J_S which is just NIL^{-1} in the $\hat{\phi}$ direction since it is the product of the number of turns, the current going through the wire, and all that divided by the length.

Then we can plug all this into the B-S equation and solve.

$$\vec{B} = \frac{\mu_o}{4\pi} \frac{NI}{L} \int_0^{2\pi} \int_0^L \frac{\hat{\phi} \times (z - z\prime)\hat{z} - b\hat{\rho}}{(b^2 + (z + z\prime)^2)^{3/2}} \mathrm{d}z\mathrm{d}\phi$$

Doing the cross prouct we get $(z - z\prime)\hat{\rho} + b\hat{z}$. Since the resulting field is only in the z direction, then ρ goes to 0.

$$\vec{B} = \frac{\mu_o NIb}{4\pi L} \int_0^{2\pi} \int_0^L \frac{\mathrm{d}z\mathrm{d}\phi}{(b^2 + (z + z\prime)^2)^{3/2}} \hat{z} = \mathrm{CALC}$$

7.2   Amperes Law

This is just like gausses law for electric fields in that it allows us to simplify the calculations for magnetic fields, but only under specific curcumstances.

Basically, we create an **amperian loop** (path) that when taken the dot product with the

$\vec{H}$ field creates a nice math situation.

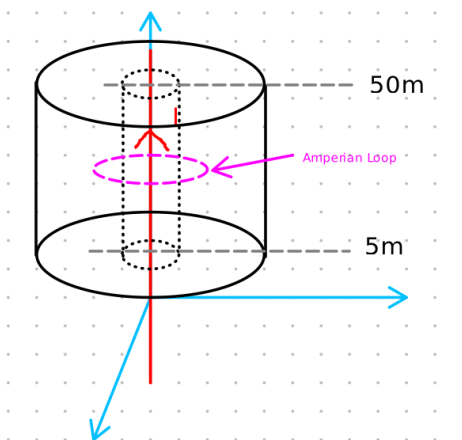$$\oint \vec{H} \cdot \mathrm{d}\vec{l} = I_{enclosed}$$

1. Predict Direction of $\vec{H}$
2. Choose amperian path
3. Calculate

7.3   Magnetic Flux

The **magnetic flux** Φ going through a surface is simply defined as:

$$\text{FLUX} = \Phi = \oint \vec{B} \cdot \mathrm{d}\vec{s}$$

Ex. We have a long straight thin wire carrying current I. We want to find the flux going through a plane with rardius going from 1m to 10m, and height going from 5m to 50m.

I know the flux formula is $\Phi = \oint \vec{B} \cdot \mathrm{d}\vec{s}$. So I need to get the magnetic field $\vec{B}$. Since the flux is just through the surface, it will be $\mathrm{d}\rho \mathrm{d}z$.

I will use Amperes Law to find the B field with an amperian loop around the current wire.

$$\int \vec{H} \mathrm{d}l = I_{enc} \implies \int \vec{B} \mathrm{d}l = I_{enc}\mu_o \implies H_\phi \hat{\phi} \cdot 2\pi\rho = I\mu_o \implies \vec{H} = H_\phi = \frac{I\mu_o}{2\pi\rho}\hat{\phi}$$

Now I need to get the flux:

$$\Phi = \oint \vec{B} \cdot \mathrm{d}\vec{s} = \int_1^{10} \int_5^{50} \frac{I\mu_o \hat{\phi} \cdot \mathrm{d}\rho \mathrm{d}z \hat{\phi}}{2\pi\rho} = \frac{I\mu_o}{2\pi} \int_1^{10} \int_5^{50} \frac{\mathrm{d}\rho \mathrm{d}z}{\rho} = \mathrm{CALC}$$

7.4   Magnetic Forces

We say that the magnetic force produced by **a wire** 1 on **another wire** 2 is:

$$\vec{F}_2 = \int I_2 \mathrm{d}\vec{l}_2 \times \vec{B}_1$$

So basically we need to get $\vec{B}$ using probably amperes law, and then assuming we know I, we can calculate the magnetic force $\vec{F}_m$.

Ex.

7.5   Torques

The torque caused on a magnetic field uses the **magnetic dipole moment** $\vec{m}$.

$$\vec{m} = I \int \mathrm{d}\vec{s} = IA\hat{n}$$

This is in the direction **perpendicular to the surface**. Hence why it is a normal vector ($\hat{n}$).

$$\vec{\tau} = \vec{m} \times \vec{B}$$

The torque $\vec{\tau}$ is just the cross product between the magnetic field and the magnetic dipole moment vectors.

Ex.

7.6   Boundary Conditions

This is the same idea as boundary conditions for elecctric fields. If we have 2 magnetic fields at a boundary, we split it up into **normal and tangential components**. Then we apply the following conditions:

$$B_{n1} = B_{n2} \qquad\qquad\qquad\qquad H_{t1} - H_{t2} = J_s$$

Note that $H = \frac{B}{\mu}$ and often $\mu_1 \neq \mu_2$. Also, often $J_S = 0$ which means $H_{t1} = H_{t2}$

> This is very similar to boundary conditions in Electric Fields, so an example can be found in that section.

8 Dynamic Currents

This section is about **changing currents**. These are currents that vary with time.

8.1 EMF

We call ϵ the Electromotive Force (EMF) which is not actually a force, but a **voltage** measured in volts. It is caused by motion in a field.

$$\epsilon = \int (\vec{v} \times \vec{B}) \cdot d\vec{l} = -\frac{d\Phi}{dt} \qquad \text{Faraday's Law}$$

Basically if we know the velocity and $\vec{B}$ field, we can find the EMF, or if we know the magnetic flux Φ, we can derive it with respect to time and get the EMF.

The reason for the negative in front of the derivative is that the **direction of the induced current** will oppose the **change in magnetic flux**. This is known as Lenz's law.

> **Ex.**