

## LINEAR PROGRAMMING

## Definition of Linear Programs

list of given variables  $x_1, \dots, x_n$  where  $x_i \in \mathbb{R}$ list of linear conditions  $\sum_{1 \leq i \leq n} a_{ij} x_i \leq$  or  $\geq$  or  $= b_j$ an objective function to maximize/minimize:  $\sum_{1 \leq i \leq n} C_i x_i$   
where  $C_i$  are real number constantslinear:  $x_1 + 2x_2 + 5x_3$ non-linear:  $x_1^2 + x_2^2, x_1 x_2, \sin x$ 

Standard Form — linear programs can be presented in matrix form

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & \dots & & \\ \vdots & \vdots & \ddots & \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

$\begin{matrix} \nearrow \text{vars} \\ \searrow \text{constraints} \end{matrix}$

enforcing constraints  
 $A \cdot \vec{x} \geq \vec{b}$

objective function

$$\rightarrow \max / \min \vec{C}^T \vec{x} \Leftrightarrow \sum_{i=1, \dots, n} C_i x_i$$

## ex1. Political Advertising Problem

4 issues to place advertisements on: roads, guns, farms, gas

3 Voting Demographics to balance: urban, suburbs, rural

for each dollar spent on issue, votes change:

	road( $x_1$ )	guns( $x_2$ )	farms( $x_3$ )	gas( $x_4$ )
urban	-2	8	0	10
suburbs	5	2	0	0
rural	3	-5	10	-2

budget limit = \$200000

need at least 50k urban, 100k suburb, 25k rural votes

WANT: minimize budget

LP — Variables:  $x_1, x_2, x_3, x_4 = \$$  spent on each issueconstraints:  $x_1, x_2, x_3, x_4 \geq 0$ 

$x_1 + x_2 + x_3 + x_4 \leq 200000$

$-2x_1 + 8x_2 + 0x_3 + 10x_4 \geq 50000$

$5x_1 + 2x_2 + 0x_3 + 0x_4 \geq 100000$

$3x_1 - 5x_2 + 10x_3 - 2x_4 \geq 25000$

objective function: minimize  $x_1 + x_2 + x_3 + x_4$ 

In standard form:

$$\begin{bmatrix} -2 & 8 & 0 & 10 \\ 5 & 2 & 0 & 0 \\ 3 & -5 & 10 & -2 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & -4 & -1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \geq \begin{bmatrix} 50 \\ 100 \\ 25 \\ 0 \\ 0 \\ 0 \\ 0 \\ -200000 \end{bmatrix}$$

ex2. A company produces 2 kinds of products A, B

can produce at most 400 units total

product A  $\rightarrow \$1$  profit max 300 unitsproduct B  $\rightarrow \$6$  profit max 200 units

Want: max profit

LP — variables  $x_A$ : \* product A to produce $x_B$ : \* product B to produce

$x_A + x_B = 400$

$x_A, x_B \geq 0$

$-x_A \geq -300 \quad -x_B \geq -200$

Objective Function:  $\max x_A + 6x_B$

ex3 Network Flow in LP

Given network  $G = (V, E)$  with  $c(e)$  for  $e \in E$ 

construct a LP to produce optimal flow

Variables:  $f(e)$  for all  $e \in E$ constraints:  $f(e) \geq 0$  for all  $e \in E$ 

$f(e) \leq c(e)$  for all  $e \in E$

$$\sum_{(u,v) \in E} f(u,v) - \sum_{(v,u) \in E} f(v,u) = 0$$

$\underbrace{\quad}_{\text{into } V} \quad \underbrace{\quad}_{\text{out of } V} \quad \text{for all } v \in V - \{s, t\}$

objective function:  $\max \sum_{(s,u) \in E} f(s,u)$

can be max flow in/out any vertex

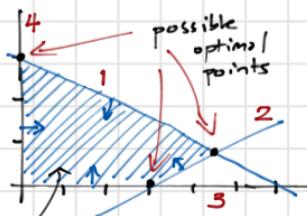
Geometric representation of a LP

$$\text{constraints: } 1. x_1 + 2x_2 \leq 6$$

$$2. 2x_1 - 3x_2 \leq 6$$

$$3. x_1 \geq 0 \quad 4. x_2 \geq 0$$

$$\max 2x_1 + 3x_2$$



Feasible Region — set of values for variables that satisfy all constraints — types of feasible regions:

1. empty  $\Rightarrow$  no solution to given constraints

$$\text{ex. } x_1 \geq 2, x_1 \leq 1$$

2. unbounded  $\Rightarrow$  no solution for max optimization

treated as bounded for min optimization

3. bounded  $\Rightarrow$  one or infinitely many solutions depending on objective function

Simplex — solve LP by moving from vertex to vertex

reason: optimality occurs on the boundary of a constraint

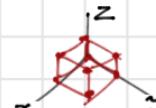
with respect to one variable  $\rightarrow$  intersecting point

with respect to multiple

but not optimal to check all points since  $n$  variables  $\Rightarrow O(2^n)$

$$\text{ex. } 0 \leq x, y, z \leq 1$$

6 points with 3 variables



Simplex starts from a given point, each time moves to an adjacent point with a higher/lower obj function value  
 $\Rightarrow$  local search based

Worst-case running time  $E$  exponential

in practice — very efficient (shown through smooth analysis)

Express MinCut in LP

maxflow problem  $\Leftrightarrow$  mincut problem

$\hookrightarrow f(S, T) \leq \text{cap}(S, T) \hookleftarrow$  find the cut with minimum capacity  
 maximize this

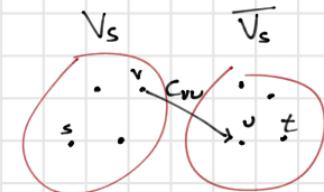
MinCut — find a cut  $X = (V_s, \bar{V}_s)$  such that  $s \in V_s, V_s \subseteq V$  and  $\text{cap}(V_s, \bar{V}_s)$  is min

introduce a new variable  $x_{v,t}$

$$0 \leq x_{v,t} \leq 1$$

$$x_{v,t} = 1 \text{ if } v \in V_s \\ = 0 \text{ if } v \notin V_s$$

$$x_s = 1; x_t = 0$$



consider an edge  $e = (v, u)$ . Want:

$$x_{vu} = \begin{cases} 1 & \text{if } v \in V_s \text{ and } u \notin V_s \\ 0 & \text{otherwise} \end{cases}$$

can be expressed as:  $x_{vu} \leq x_v \leftarrow \text{ensures } v \in V_s$

$x_v + x_{vu} \leq 1 \leftarrow \text{ensure } u \notin V_s$

Full constraints

$$0 \leq x_v \leq 1$$

$$0 \leq x_{vu} \leq 1$$

$$x_s = 1, x_t = 0$$

$$x_{vu} - x_v \leq 0$$

$$x_{vu} + x_v \leq 1$$

Objective Function:

$$\text{minimize } \sum_{v \in V} x_{vu} c_{vu}$$

2 tricks: express conditions as inequality  
 introduce new variables if needed

for every LP that is maximizing,  $\exists$  a LP that is minimizing

# OneClass

MINCUT in LP

Vars: for  $v \in V$ :  $x_v$

Intuition:  $\sum_{v \in V} x_v = 1$  iff.  $v \in S$

for  $v \in E$ :  $x_{vu}$

VU crosses the cut  
 $v \in S, u \notin S$

Constraints:  $\sum_{v \in S} x_v = 1$

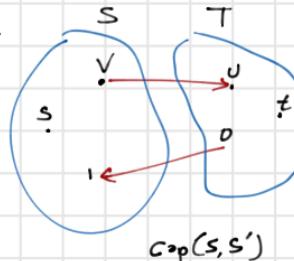
$x_t = 0 \quad t \notin S$

$0 \leq x_v \leq 1 \quad v \in V, v \neq s, t$

$0 \leq x_{vu} \leq 1 \quad v \in E$

$x_{vu} \geq x_v - x_u$

objective f:  $\min \sum_{v \in E} c_{vu} x_{vu}$



note:

1. indicator variables

$$x_v \rightarrow v \in S$$

2. new variables can make expressing validity conditions  
↳ objective functions easier

3. multiple conditions

a. cond<sub>1</sub> AND cond<sub>2</sub> → express them separately  
and put them both under LP constraints

b. cond<sub>1</sub> OR cond<sub>2</sub> →  $x_1 \geq 0$  OR  $x_2 \geq 0$   
 $\Leftrightarrow x_1 + x_2 \geq 0$

c. not cond → not  $x_1 > 0 \Leftrightarrow 1 - x_1 \geq 1$

d. if cond<sub>1</sub>, then cond<sub>2</sub> →  $x_1 > 0 \Rightarrow x_2 > 0$   
 $\Leftrightarrow x_2 \geq x_1$

e. if cond<sub>1</sub>, need a new var  $x_1$ ,  
then cond<sub>1</sub> iff  $x_1 = 1$

$$x_1 = 1 \text{ iff. } x \geq 3$$

$$\Leftrightarrow x_1 - 1 \geq x - 3$$

$$x_1 < 1 \text{ iff. } x < 3$$

$$\Leftrightarrow x_1 - 1 \leq x - 3$$

find more resources at [www.oneclass.com](http://www.oneclass.com)

Dual LP:

$$\begin{array}{l} \vec{x} \geq 0 \quad A\vec{x} \geq \vec{b} \quad \vec{y}^T A\vec{x} \leq \vec{y}^T \vec{b} \quad \vec{y} \geq 0 \\ \max \vec{c}^T \cdot \vec{x} = \max \sum_{i \in \mathbb{Z}^n} c_i x_i \quad \min \vec{y}^T \cdot \vec{b} \\ \text{Primal LP} \quad \text{Dual LP} \\ \text{Max Flow} \quad \leq \text{Cap of Min Cut} \\ \vec{c}^T \leq \vec{y}^T A\vec{x} \leq \vec{y}^T \vec{b} \end{array}$$

Sometimes the dual LP is easier to solve than primal

Single Source Shortest Path

given graph  $G = (V, E)$  and  $w(e)$  for all  $e \in E$   
find the shortest path  $s \rightarrow v$  for all  $v \in V - \{s\}$

Variable:  $x_v$  = weight of the shortest path  $s \rightarrow v$

constraint:  $x_s = 0$

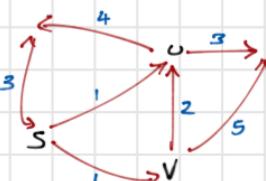
$$x_v \geq 0$$

$$x_v \leq x_u + w(u, v) \text{ for each } (u, v) \in E$$

this will eventually find the correct shortest path weight for each  $v \in V$  and set that as the upperbound limit for  $x_v$

$$\text{ex. } x_u \leq x_s + 1$$

$$x_u \leq x_v + 2$$



$$\text{objective function } \max \sum_v x_v$$

min doesn't work b/c allows algo to set  $x_v$  smaller than true distances

max works b/c constraints forces  $x_v$  to be no more than shortest distance and max forces  $x_v$  to be at least the shortest distance

Linear Programming Problem:  $\max / \min c \cdot x$   
 given constraints  $Ax \leq b$

$$\begin{aligned} A &\in \mathbb{Q}^{m \times n} \\ x &\in \mathbb{Q}^n \\ b &\in \mathbb{Q}^m \quad c \in \mathbb{Q}^m \end{aligned}$$

### ex. Simple Scheduling Problem

INPUT:  $n$  jobs with durations  $d_1, d_2, \dots, d_n \in \mathbb{Z}$  and  
 prerequisites  $P_{ij} \in \{0, 1\}$  such that

$$P_{ij} = \begin{cases} 1 & \text{if } j_i \text{ is a prerequisite of } j_j \\ 0 & \text{otherwise} \end{cases}$$

jobs cannot be interrupted.

Output —  $T =$  total time to complete all jobs  $\leftarrow$  minimize

Variables:  $x_i =$  start time of job  $i$

$T =$  total time

Constraints:  $x_i \geq 0$  for all  $i = 1, \dots, n$

$x_i \geq x_j + d_j$  if  $P_{ij}=1$  for all  $i, j = 1, \dots, n$

This constraint ensures each job only starts  
 after all of its prerequisites has completed  
 $\iff x_i \geq P_{ij}(x_j + d_j)$

$T \geq x_i + d_i$  for  $i = 1, \dots, n$

Using  $T$  ensures none of the values in the  
 solution are greater than they need to

Obj function:  $\min T$

### ex. Hitting Set Problem

INPUT: set of elements  $E = \{x_1, x_2, \dots, x_n\}$

set of subsets of  $E$ ,  $S = \{H_1, H_2, \dots, H_m\}$

Output: smallest subset  $C$  of  $E$  such that

for each set  $H_i$ ,  $C \cap H_i \neq \emptyset$

Variable:  $v_i$  for each  $x_i \in E$

constraints:  $v_i \in \{0, 1\}$  for each element, such that

$$v_i = \begin{cases} 1 & \text{if } v_i \in C \\ 0 & \text{otherwise} \end{cases}$$

$v_1 + \dots + v_k \geq 1$  for each  $H_j = \{x_1, \dots, x_k\}$

This constraint ensures atleast one element  
 from each subset  $H$  is picked.

objective function: minimize  $\sum_{i=1 \text{ to } n} v_i$

note: this is Integer Programming b/c restrict  $v_i$  to  $\{0, 1\}$ ,  
 not  $0 \leq v_i \leq 1$

$$\begin{aligned} & \text{Max } z = \dots \\ & \text{Min } -z^T x \\ & \text{S.t. } Ax \leq b \\ & \quad x \geq 0 \end{aligned}$$

~~Test 2 up to here~~

Nov. 4, 2013

\*-3.  $\max_{\text{OPT}} z^T x = \min_{\text{Dual}} -z^T x$

Dual  
Primal

• Feasibility:

$$\begin{cases} x_1 + y_1 \leq 1 + d_1 \\ x_2 + y_2 \leq -x_1 - 1 + d_2 \\ y_1 \geq -y_2 - 1 + d_3 \end{cases}$$

First valid soln:

$$\begin{cases} x = y = 0 \\ z = \max\{f(1), f(2)\} = 1 \end{cases}$$

LP vars  
that  
are not  
mined?

No answer: Make feasible sets nonempty.

IDEA for checking feasibility and finding first soln:

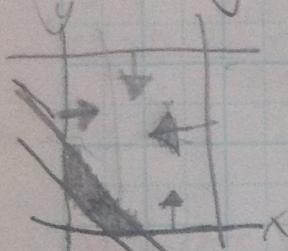
- 1) Add new vars  $\bar{d}_i$  to RHS of inequalities of constraints (weaker side)
- 2) Minimize them:  $\sum \bar{d}_i$
- 3) Check if all  $\bar{d}_i \leq 0$ . Not  $\Rightarrow$  original LP not feasible.

$$\begin{cases} \bar{A}\bar{x} \leq \bar{b} + \bar{d} \\ \text{Min } \bar{d} \end{cases}$$

\* Solve it, initial  $\bar{x} = \vec{0} \wedge \bar{d} = \max L - b$ ;  
 Check if  $\min \bar{d} \leq 0$ . Not  $\Rightarrow$  original LP not feasible.

$$\begin{aligned} x+y &\geq 0 \\ x+2y &\geq 1 \end{aligned}$$

max  $2x+y$

Unbounded regionAdd  $x+y \leq d$   
constant.(Don't want to cut bounded solns)  
(Can cut unbounded solns)Checking Unboundedness

- 1) Add new constraints that make sure new region is bounded
- 2) If original region was bounded, we don't lose any solns.
- 3) Solve new LP. If optimal is on new constraints, then original was unbounded.

$$\begin{aligned} x+y &\leq 2 \\ x+2y &\leq 1 \end{aligned}$$

max  $2x+y$

$$\begin{bmatrix} A & \bar{x} \\ -I & \bar{b} \end{bmatrix} \leq \begin{bmatrix} \bar{B} \\ \bar{0} \end{bmatrix}$$

[Lagrangian]  $\begin{bmatrix} 1 & 0 \\ 0 & -1 \\ -1 & 1 \end{bmatrix} \geq \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$

$$g^T A \geq 0$$

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \\ -1 & 1 \end{bmatrix} \geq \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$$

$$\max \begin{bmatrix} c^T \\ b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

Primal LP

$$\min \begin{bmatrix} g^T \\ b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

Dual LP

Problem:  $A[1..n]$ Find a subsequence of  $A$  w/ max sum.
$$\text{max } \{a_1, a_2, \dots, a_n\}$$

$$\{10, 5, -1, 3, 4, -20\}$$

Q: What possibilities do we have, assuming what? Think recursively:

Assume we have a max sum subsequence.

It either contains the 1st number or not.

Case 1: Contains  $a_1$ 

Then max subsequence

{ Induction  
Step }

$$\begin{array}{l} x + y \leq 2 \\ x - y \geq 0 \\ y - x \leq 1 \end{array}$$

$$\max 2x + y$$

$$\begin{array}{c} \vec{A} \\ \left[ \begin{array}{cc} 1 & 1 \\ -1 & 0 \\ 0 & -1 \\ -1 & 1 \end{array} \right] \end{array} \vec{x} \leq \begin{array}{c} \vec{b} \\ \left[ \begin{array}{c} 2 \\ 0 \\ 0 \\ 1 \end{array} \right] \end{array}$$

$$\begin{array}{c} \vec{c}^T \\ \left[ \begin{array}{c} 2 \\ 1 \end{array} \right] \end{array} \vec{x} \geq \begin{array}{c} \vec{d} \\ \left[ \begin{array}{c} 1 \\ 1 \end{array} \right] \end{array}$$

$$\max \vec{c}^T \vec{x}$$

Primal LP

$$\min \vec{c}^T \vec{x}$$

Dual LP

Problem:  $A[1..n]$

Find a substring of  $A$  w/ max sum.

$\{a_1 \dots a_n\}$   
max  $\sum_{i=1}^j a_i$

Q: What possibilities do we have, assuming what? Think recursively?

Assume we have a max sum substring.

If either contains the 1st number or not.

Case 1: Contains  $a_1$ .

case Then max substring  $M[n] = M[n-1]$

Case 2: Contains  $a_n$ .

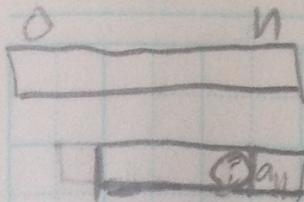
Then max substring = Max substring ending w/o  $a_{n-1}$  +  $a_n$

$$M[n] = M[n-1] + a_n$$

Max substring ending w/o  $a_n$ .

{ Induction step }





$\rightarrow$  Max substring ending w/  $a_n$

Two cases for  $N[n]$ :

- 1) Contains  $a_{n-1} \Rightarrow N[n] = N[n-1] + a_n$
- 2) ↗ Contains  $a_{n-1} \Rightarrow N[n] = \max(a_n, 0)$

↓  
considers  
empty  
string

$$N[n] = \max \{ N[n-1] + a_n, a_n, 0 \}$$

$$M[n] = \max \{ M[n-1], N[n-1] + a_n, 0 \}$$

$$M[0] = 0; N[0] = 0$$

for  $i$  from 1 to  $n$ :

$$\rightarrow N[i] = \dots$$

$$\rightarrow M[i] = \dots$$

$\left\{ \begin{array}{l} \\ \\ \\ \end{array} \right\} \text{ loop}$

Correctness: How to formulate (Case-by-case formulate).

Induction of value computed after  $i$ th iteration are correct (L.I.).  
 $(M[i]) = \bullet, N[i] = \bullet$ .

Assume true for  $j < i$ . Show true for  $i$ :

- 1)  $M[n]$  corresponds to a valid substring (cases)
- 2)  $M[n]$  is optimal

Assume  $s$  is optimal substring of  $A[1 \dots n]$ :  $s_1, \dots, s_k$ .

Show  $s \leq M[n]$ .

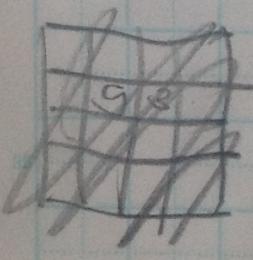
Consider substring corresponding to  $s$ .

1) Contains  $a_n$ :

$s_1, \dots, s_k \Rightarrow s_1, \dots, s_{k-1}$  is a substring in  $A[1 \dots n-1]$ .

2) ↗ Contains  $a_{n-1}$ :  $\{s_1, \dots, s_{k-1}\} \leq N[n-1] \Rightarrow M[n] = N[n-1] + a_n \geq s$ .

$s \leq M[n-1] \Rightarrow N[n] = M[n-1] \geq s$



	1	2	3	4	5
1	0	0	0	0	0
2	0	0	0	0	0
3	0	0	0	0	0
4	0	0	0	0	0

Subproblem: Max sum from square  $(i, j) =: M[i, j]$

$$M[i, j] = M[i-1, j] + a_{ij}$$

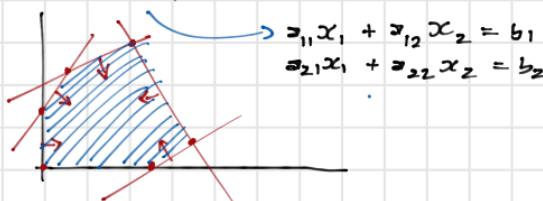
$$\max [M[i-1, j] + a_{ij}, M[i, j-1] + a_{ij}]$$

for loop: top-down.

Sign up for take home — 1 week before class ends

Algorithms for solving LP: simplex or Interior Point

LP:  $A\vec{x} \leq \vec{b}$ , min/max  $\vec{c}^T \vec{x}$



if we have  $n$  variables, each vertex corresponds to the solution of  $n$  constraints. The given  $m$  constraints total  $\Rightarrow$  vertex =  $\binom{m}{n} \in O(m^n)$

Simplex — find an initial feasible vertex

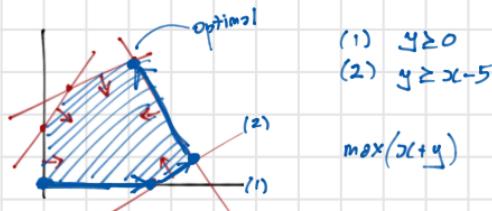
if there is none

return unfeasible

let  $V$  be the initial feasible vertex

while  $V$  is not locally optimal

{  
  {  
    find a new feasible vertex  $U$  next to  $V$  which is better  
     $V=U$   
    if there are no  $U$ , return unbounded  
  return  $V$



to find the next point:

have  $n$  constraints, peak next vertex and relax a constraint  
given the region is not convex

Best running time:  $O(nm) \times O(\# \text{ vertices})$