# **OWEN MOOGK**

Mechatronics Engineering Student at the University of Waterloo

226-989-0602 owenmoogk@gmail.com linkedin.com/in/owenmoogk owenmoogk.github.io

# **SKILLS**

Software Development: Python (4 years), JavaScript/jQuery (4 years), C++ (2 years), C# (1 year), Java (1 year), and SQL (1 year).

Frameworks / Tools: MVC/ASP.NET (1 year), ReactJS (3 years), HTML/CSS/Bootstrap (5 years), Django (1 year), Visual Studio.

Design & Engineering: SolidWorks (6 years), AutoCAD (1 year), and Onshape (1 year) for 3D printing and manufacturing.

Other: Experience working closely with a team, using agile development techniques, including version control with Git / TFS.

# **EXPERIENCE**

#### Software Developer (Co-op) - BusPlanner Inc.

May 2023 - September 2023

- Developed and maintained web applications using the MVC ASP.NET framework, ensuring robust solutions for clients.
- Implemented and improved many web application features, directly affecting hundreds of clients across North America.
- Resolved issues on both the frontend and backend, employing debugging skills to identify and fix bugs, optimize performance, and enhance application usability with tools including C#, JavaScript/jQuery, and Bootstrap.
- Designed SQL database solutions and advanced SQL queries for efficient data retrieval and manipulation.
- Improved codebase structure, refactoring and optimizing existing code to enhance performance, reusability, and scalability.
- Utilized Azure DevOps and TFS version control to manage source code and participate in code reviews among team members.
- Conducted thorough testing of web applications to identify issues, ensuring optimal functionality and user experiences.

#### Subteam Lead - FIRST Robotics Team

August 2018 - September 2022

- Led a subteam of students using project management and teamwork skills to design and build a robotic subsystem.
- Designed flexible assemblies and robotic systems in SolidWorks for manufactured and 3D printed fabrication.
- Fabricated complex parts and assembled robotic systems, troubleshooting and optimizing mechanical systems.
- Led the team's sponsorship program, using networking and interpersonal skills to attract and retain sponsorship for the team.

#### Drivetrain Lead - Electric Racecar Team

September 2021 – June 2022

- Designed and manufactured a fully electric racecar in under a year, optimizing drivetrain systems to increase efficiency.
- Developed offboard battery management system in Python, tailoring power use and energy deployment in competition.
- Designed a 3D printed emergency stopping system in OnShape, ensuring safety and ease of use in emergencies.

#### **Personal Projects**

- Developed complex full-stack webpages using HTML, CSS, JavaScript, ReactJS and Django (Python).
- Implemented advanced algorithms and data structures to solve a variety of computing problems.
- Built a responsive personal portfolio web app, showcasing many personal projects and endeavours (linked above).

## **ACHIEVEMENTS**

SHAD Canada: Engineered an award-winning solution interfacing Canadians with their water consumption habits.

JamHacksV Hackathon Winner: Won first place, where I designed and built a complete 3D-printed cat feeding robot in 48 hours.

AP Scholars Award: Awarded for exceptional performance on the Chemistry, Physics, and Economics advanced placement exams.

**Duke of Edinburgh's Award:** Awarded the prestigious Bronze and Silver Duke of Edinburgh awards for exceptional community service and personal growth.

# **EDUCATION**

#### Mechatronics Engineering – University of Waterloo

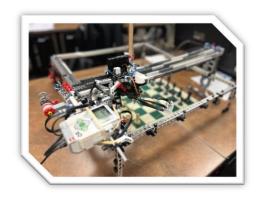
2022 - 2027

- Candidate for Bachelor of Applied Science studying Mechatronics Engineering, with a grade average of 95% / 4.0 GPA.
- Working with likeminded students building collaboration, time management, and technical skills.
- Relevant courses: Circuits, Digital Logic, Data Structures and Algorithms, Statics / Dynamics, Linear Algebra, Materials.

# **PROJECTS**

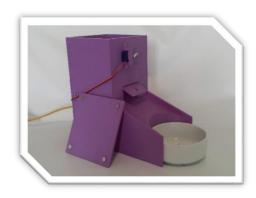
#### **Chess Robot**

- Designed and built an autonomous chess robot, which performs moves against players.
- Capabilities include maneuvering chess pieces, executing moves, receiving player input, and chess clock integration.
- Designed and assembled a robotic claw, pulley systems, and precise actuation mechanisms, using 3D printed and laser-cut parts.
- **Debugged** mechanical and software systems, solving integration issues.
- Programmed the robot in C++ and RobotC. Built feedback loops with the use of color sensors and motor encoders.
- Project details: https://owenmoogk.github.io/projects/chess-bot



## **AI-Powered Cat Feeding Robot**

- Designed and programmed a 3D printed robot to autonomously feed pets.
- Developed CAD models for 3D printing in **SolidWorks**.
- Built microcontroller circuits, integrating an Arduino with other simple electronic components, such as LEDs, limit switches, and servos.
- Utilized **Computer Vision** to detect a cat via an onboard webcam.
- Programmed the robot in C++ and Python to detect a cat's presence and dispense food, given specific criteria.
- Project details: https://owenmoogk.github.io/projects/cat-feeder



#### **Custom Built MacroPad**

- Designed, built, and programmed a complete MacroPad. Capabilities include executing complex keystroke instructions, Spotify API calls, and much more.
- Designed the custom 3D printed housing and keycaps in SolidWorks.
- Designed a custom PCB (printed circuit board) for ease of integration.
- Built a custom mounting system that allowed integration with existing keyboards.
- Integrated hardware switches with an Arduino Nano, which interfaces with a PC.
- Programmed logic with C++ and Python.
- Project Details: https://owenmoogk.github.io/projects/macropad

#### Vortex - FRC Robot Design Challenge

- Designed a complete FRC Robot in SolidWorks, with the design intended to be used in a competitive robotics match.
- Integrated object intake systems with a robot feeder and shooter, giving full control to game pieces.
- Designed an object elevator, opening additional manipulation and movement opportunity.
- Designed a swerve drive system for optimal movement and drivability.
- Project Details: https://owenmoogk.github.io/projects/vortex



## These are some of my favourite and most applicable projects.

For a complete list of projects and more details, please visit my website's project page, located at: https://owenmoogk.github.io/projects