

# OWEN MOOGK

Mechatronics Engineering Student  
at the University of Waterloo

226-989-0602  
owenmoogk@gmail.com  
linkedin.com/in/owenmoogk  
owenmoogk.github.io

## SKILLS

**Software Development:** Python (4 years), JavaScript/jQuery (4 years), C++ (2 years), C# (1 year), Java (1 year), and SQL (1 year).

**Frameworks / Tools:** MVC/ASP.NET (1 year), ReactJS (3 years), HTML/CSS/Bootstrap (5 years), Django (1 year), Visual Studio.

**Design & Engineering:** SolidWorks (6 years), AutoCAD (1 year), and Onshape (1 year) for 3D printing and manufacturing.

**Other:** Experience working closely with a team, using agile development techniques, including version control with Git / TFS.

## EXPERIENCE

### Software Developer (Co-op) – BusPlanner Inc.

May 2023 – September 2023

- Developed and maintained web applications using the MVC ASP.NET framework, ensuring robust solutions for clients.
- Implemented and improved many web application features, directly affecting hundreds of clients across North America.
- Resolved issues on both the frontend and backend, employing debugging skills to identify and fix bugs, optimize performance, and enhance application usability with tools including C#, JavaScript/jQuery, and Bootstrap.
- Designed SQL database solutions and advanced SQL queries for efficient data retrieval and manipulation.
- Improved codebase structure, refactoring and optimizing existing code to enhance performance, reusability, and scalability.
- Utilized Azure DevOps and TFS version control to manage source code and participate in code reviews among team members.
- Conducted thorough testing of web applications to identify issues, ensuring optimal functionality and user experiences.

### Subteam Lead – FIRST Robotics Team

August 2018 – September 2022

- Led a subteam of students using project management and teamwork skills to design and build a robotic subsystem.
- Designed flexible assemblies and robotic systems in SolidWorks for manufactured and 3D printed fabrication.
- Fabricated complex parts and assembled robotic systems, troubleshooting and optimizing mechanical systems.
- Led the team's sponsorship program, using networking and interpersonal skills to attract and retain sponsorship for the team.

### Drivetrain Lead – Electric Racecar Team

September 2021 – June 2022

- Designed and manufactured a fully electric racecar in under a year, optimizing drivetrain systems to increase efficiency.
- Developed offboard battery management system in Python, tailoring power use and energy deployment in competition.
- Designed a 3D printed emergency stopping system in OnShape, ensuring safety and ease of use in emergencies.

### Personal Projects

- Developed complex full-stack webpages using HTML, CSS, JavaScript, ReactJS and Django (Python).
- Implemented advanced algorithms and data structures to solve a variety of computing problems.
- Built a responsive personal portfolio web app, showcasing many personal projects and endeavours (linked above).

## ACHIEVEMENTS

**SHAD Canada:** Engineered an award-winning solution interfacing Canadians with their water consumption habits.

**JamHacksV Hackathon Winner:** Won first place, where I designed and built a complete 3D-printed cat feeding robot in 48 hours.

**AP Scholars Award:** Awarded for exceptional performance on the Chemistry, Physics, and Economics advanced placement exams.

**Duke of Edinburgh's Award:** Awarded the prestigious Bronze and Silver Duke of Edinburgh awards for exceptional community service and personal growth.

## EDUCATION

### Mechatronics Engineering – University of Waterloo

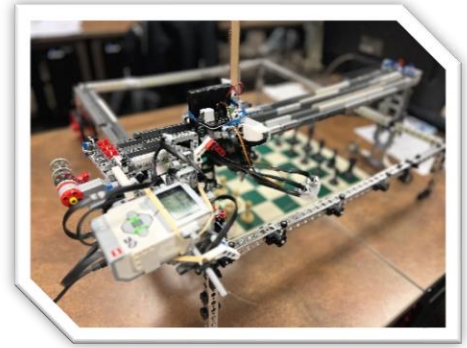
2022 – 2027

- Candidate for Bachelor of Applied Science studying Mechatronics Engineering, with a grade average of 95% / 4.0 GPA.
- Working with likeminded students building collaboration, time management, and technical skills.
- Relevant courses: Circuits, Digital Logic, Data Structures and Algorithms, Statics / Dynamics, Linear Algebra, Materials.

# PROJECTS

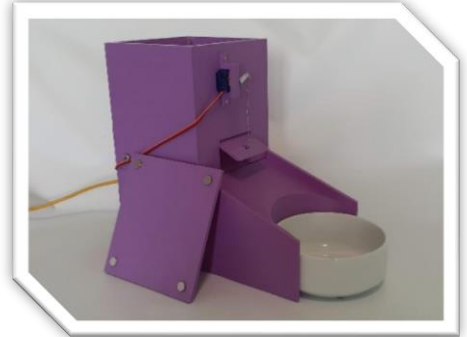
## Chess Robot

- Designed and built an **autonomous** chess robot, which performs moves against players.
- Capabilities include maneuvering chess pieces, executing moves, receiving player input, and chess clock integration.
- Designed and assembled a robotic claw, pulley systems, and precise actuation mechanisms, using **3D printed** and **laser-cut** parts.
- **Debugged** mechanical and software systems, solving integration issues.
- Programmed the robot in **C++** and **RobotC**. Built feedback loops with the use of color sensors and motor encoders.
- Project details: <https://owenmoogk.github.io/projects/chess-bot>



## AI-Powered Cat Feeding Robot

- Designed and programmed a **3D printed** robot to autonomously feed pets.
- Developed CAD models for 3D printing in **SolidWorks**.
- Built microcontroller circuits, integrating an **Arduino** with other simple electronic components, such as LEDs, limit switches, and servos.
- Utilized **Computer Vision** to detect a cat via an onboard webcam.
- Programmed the robot in **C++** and **Python** to detect a cat's presence and dispense food, given specific criteria.
- Project details: <https://owenmoogk.github.io/projects/cat-feeder>



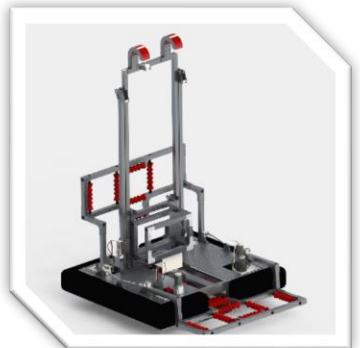
## Custom Built MacroPad

- Designed, built, and programmed a complete MacroPad. Capabilities include executing complex keystroke instructions, Spotify API calls, and much more.
- Designed the custom **3D printed** housing and keycaps in **SolidWorks**.
- Designed a custom **PCB (printed circuit board)** for ease of integration.
- Built a custom mounting system that allowed integration with existing keyboards.
- Integrated hardware switches with an **Arduino Nano**, which interfaces with a PC.
- Programmed logic with **C++** and **Python**.
- Project Details: <https://owenmoogk.github.io/projects/macropad>



## Vortex - FRC Robot Design Challenge

- Designed a complete FRC Robot in **SolidWorks**, with the design intended to be used in a competitive robotics match.
- Integrated object intake systems with a robot feeder and shooter, giving full control to game pieces.
- Designed an object elevator, opening additional manipulation and movement opportunity.
- Designed a swerve drive system for optimal movement and drivability.
- Project Details: <https://owenmoogk.github.io/projects/vortex>



These are some of my favourite and most applicable projects.

For a complete list of projects and more details, please visit my website's project page, located at:

<https://owenmoogk.github.io/projects>