

SHENGXIANG SUN

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EDUCATION

University of Toronto

Sep 2022 – (expected) Apr 2026

Honours Bachelors of Science in Computer Science

- GPA: 3.83/4.00

RESEARCH EXPERIENCE

- **Visiting Research Assistant, Stanford University** May 2025 – Present
Topic: Long-Horizon Contact-Rich Manipulation by Learning from RGB Videos Advisor: Dr. Weiyu Liu
- **Visiting Research Assistant, National University of Singapore** Oct 2024 – May 2025
Topic: Autonomous Furniture Assembly by Reading IKEA Manuals with VLMs Advisor: Prof. Lin Shao
- **Full-Time Research Assistant, University of Toronto** May 2024 – Oct 2024
Topic: Failure Detection in Vision Language Action Models Advisor: Prof. Florian Shkurti

PUBLICATIONS & PREPRINTS

- 1 [NeurIPS 2025 (Under Review)] Qiao Gu, Yuanliang Ju, **Shengxiang Sun**, Igor Gilitschenski, Haruki Nishimura, Masha Itkina, Florian Shkurti, “SAFE: Multitask Failure Estimation for Vision-Language-Action Models” [\[Paper\]](#) [\[Website\]](#)
- 2 [RSS 2025] Chenrui Tie*, **Shengxiang Sun***, Jinxuan Zhu, Yiwei Liu, Yue Hu, Jingxiang Guo, Haonan Chen, Ruihai Wu, Junting Chen, Lin Shao, “Manual2Skill: Learning to Read Manuals and Acquire Robotic Skills for Furniture Assembly Using Vision-Language Models” [\[Paper\]](#) [\[Website\]](#)

RESEARCH PROJECTS

Long-Horizon Contact-Rich Manipulation by Learning from RGB Videos (Ongoing)

Advisor: Dr. Weiyu Liu, Postdoctoral Scholar, Stanford, CS

May 2025 – Present

- Evaluating Nvidia FoundationPose on human-performed furniture assembly videos recorded via smartphone.
- Leveraging Nvidia IsaacGym to test FurnitureBench’s robotic manipulation performance.

Autonomous Furniture Assembly by Reading IKEA Manuals with VLMs

Advisor: Prof. Lin Shao, Assistant Professor, NUS, CS

Oct 2024 – May 2025

- Generated a synthetic dataset of over 10,000 furniture parts using a novel automated pipeline in Blender to simulate realistic assembly scenes. Fine-tuned QWEN-2.5B using LoRA to predict furniture part connections.
- Employed vision-language models to generate high-level furniture assembly plans from IKEA manuals, achieving generalization across diverse furniture types and exceeding previous baselines by over 300%.

Failure Detection in Vision Language Action Models

Advisor: Prof. Florian Shkurti, Assistant Professor, University of Toronto, CS

May 2024 – Oct 2024

- Developed a pipeline using PyTorch and SimplrEnv to fine-tune VLAs (eg. Open-Pi-Zero) on mixed datasets from Open-X-Embodiment, achieving generalization across diverse simulation environments.
- Estimated uncertainty through Nvidia IsaacSim in VLM-based robotic models such as ReKep, producing three diverse uncertainty quantification methods and 50+ samples.
- Tested 2D and 3D part segmentation models on High-Performance Computing Clusters with SLURM.

RESEARCH INTERESTS

My research interests span **Robotics and 3D Computer Vision**, with a focus on **generalizable and safe robot manipulation**. I am particularly passionate about developing algorithms that enable robots to perform complex, long-horizon tasks through simple human instructions, such as “cook the egg.”

SCHOLARSHIPS & AWARDS

- **2024 Summer NSERC Math & Computer Science Research Award** (CA\$8,000)
- **2022-2024 General In-Course Scholarship** (For maintaining a cumulative GPA of at least 3.7/4.0) (CA\$9,000)
- **2023-2024 Dean List Scholar**

WORK EXPERIENCE

Loblaw Digital	Toronto (CA)
<i>Machine Learning Engineer Co-op - Generative AI Team</i>	<i>Jan 2024 – Apr 2024</i>

- Enhanced an automated email reply system using Google’s Gemini Pro, Python, Docker, CI/CD, Few-Shot and Chain-of-Thought prompt engineering, which resulted in over 3400 correctly automated email replies per week.
- Developed an end-to-end machine learning pipeline for enhanced shopping experience, with OpenAI’s GPT-4 Vision, Python, Pandas, SQL, Apache Airflow DAGs, and Google Cloud Platform, which automatically generated product descriptions for 154,286 products sold at Loblaws, Shoppers Drug Mart, and Joe Fresh

New H3C Technologies (Founded by Huawei)	Beijing (CN)
<i>Machine Learning Research Intern</i>	<i>Jul 2023 – Aug 2023</i>

- Designed training & testing pipelines of Llama2, Dreambooth, InstructPix2Pix on MobaXterm and WebUI, by using PyTorch and HuggingFace, which doubled the team’s testing data outputs
- Enabled automated downloads of Python dependencies with bash scripting, reducing installation steps by 40%

EXTRACURRICULAR EXPERIENCE

GenAI Genesis	
<i>Hackathon Winner - InterView Team</i> <u>github.com/InterView</u>	<i>March 30th, 2024 - March 31st, 2024</i>

- **First-Place: Best AI in Safety & Responsible AI**
- Developed an AI interview helper for junior HR and hiring managers, using Google’s Gemini Pro, LangChain for RAG, and Speech-To-Text API, which achieved 80% accuracy in real-time detection of biased interview questions

HackTheValley - 8	
<i>Hackathon Participant - QuickScan Team</i> <u>github.com/QuickScan</u>	<i>October 13th, 2023 - October 15th, 2023</i>

- Trained a CNN and RNN model using TensorFlow, CUDA, cuDNN, and CTC loss function, achieving 83% accuracy in predicting and converting handwritten text to digital text

PROGRAMMING SKILLS & LANGUAGE SKILLS

Proficient Python, LaTeX, HTML	Familiar PyTorch, Linux, C, Java, Git
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Chinese (Native), English (Fluent), French (Intermediate)