

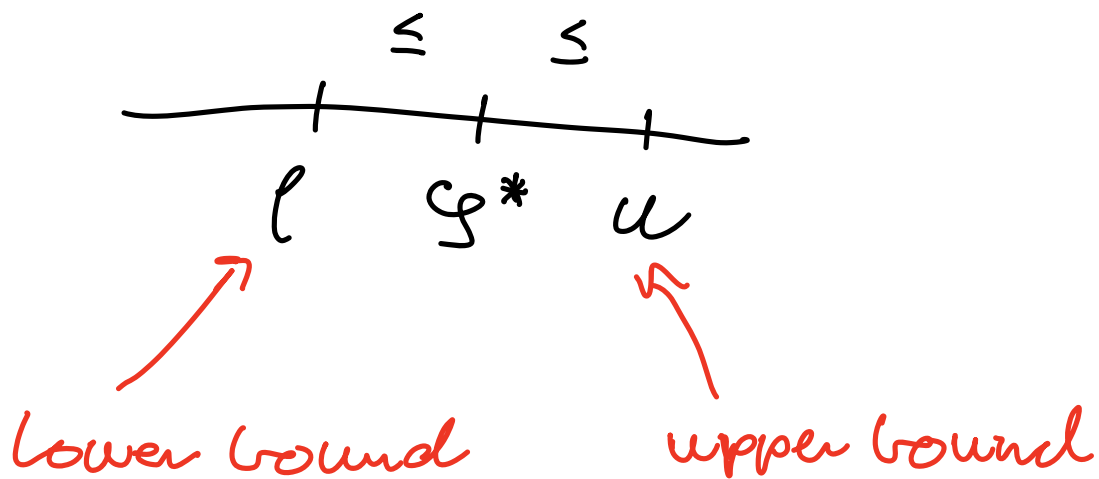
# Duality

Example for motivation

(P) = (LP)

$$\begin{array}{ll}\max & 4x_1 + x_2 + 3x_3 \\ \hline \text{s.t.} & x_1 + 4x_2 \leq 1 \\ & 3x_1 - x_2 + x_3 \leq 3 \\ & x_i \geq 0, i=1,2,3\end{array}$$

In practice one is interested in an upper and a lower bound for the optimal obj. f. value  $g^*$ .



Choose any feasible point :

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \text{ is feasible. } \quad \begin{aligned} \bar{c}^T x &= 4 \cdot 1 + 1 \cdot 0 + 3 \cdot 0 \\ &= 4 \end{aligned}$$

$$\Rightarrow 4 \leq g^*$$

another point:

4 is a lower bound

$\begin{pmatrix} 0 \\ 0 \\ 3 \end{pmatrix}$  is feasible.

$$c^T x = 9 \leq g^*$$

a better  
lower bound

How to get an upper bound:  
combine linearly the constraints

" $2 \cdot (1) + 3(2)$ ":

$$2(x_1 + 4x_2) \leq 2 \cdot 1$$

$$3(3x_1 - x_2 + x_3) \leq 3 \cdot 3$$

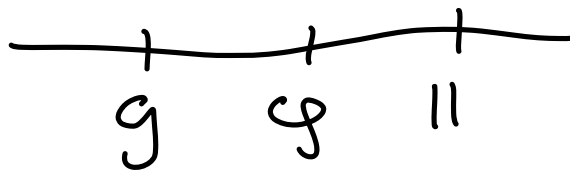
$$11x_1 + 5x_2 + 3x_3 \leq 11$$

Since  $x_i \geq 0$ ,  $i = 1, 2, 3$

$$4x_1 + x_2 + 3x_3 \leq 11x_1 + 5x_2 + 3x_3 \leq 11$$



g



$$(2 \cdot (1) + 3 \cdot (2))$$

choice of the linear comb.  
was done in such a way that  
we get an upper bound (coeff  
are greater and eq than those in  
g).


However, was this (11) the lightest/  
best combination to get an  
upper bound?

More generally: Search for  
coeff.  $y_1, y_2$  s.t.  $y_1, y_2 \geq 0$ :

$$y_1(x_1 + 4x_2) \leq y_1 \cdot 1$$

$$+ y_2(3x_1 + x_2 + x_3) \leq y_2 \cdot 3$$

" $y_1(1) + y_2(2)$ ":

$$(y_1 + 3y_2)x_1 + (4y_1 - y_2)x_2 + y_2 \cdot x_3$$
$$\leq y_1 + 3y_2$$


$$\begin{array}{ccc} & \geq 4 & \geq 1 & \geq 3 \\ & \text{coeff. of } y. \end{array}$$

Comparing this comb. with  $g$   
delivers upper bound for  $g^*$ .

$$\begin{aligned} g &= 4x_1 + x_2 + 3x_3 \leq \\ (y_1 + 3y_2)x_1 + (4y_1 - y_2)x_2 + y_2x_3 &\leq \\ y_1 + 3y_2. \end{aligned}$$

Wanted: upper bound should  
be nearest to  $g^*$  as possible.

$$\begin{array}{c|c} & \\ \hline c_j^* & y_1 + 3y_2 \end{array}$$

$$\begin{array}{llll} \min & y_1 + 3y_2 & & \\ \text{s.t.} & y_1 + 3y_2 & \geq & 4 \\ & 4y_1 - y_2 & \geq & 1 \\ & & y_2 & \geq 3 \\ & y_1, y_2 & \geq & 0 \end{array} \quad \left. \vphantom{\begin{array}{l} \min \\ \text{s.t.} \end{array}} \right\} \begin{array}{l} (D) \\ \text{dual pr.} \end{array}$$

How to get the dual problem  
(D) from (P): (using a formula)

$$\begin{aligned}
 \max. \quad & 4x_1 + 1x_2 + 3x_3 \\
 \text{s.t.} \quad & 1x_1 + 4x_2 + 0x_3 \leq 1 \\
 & 3x_1 - 1x_2 + 1x_3 \leq 3 \\
 & x_i \geq 0 \quad i = 1, 2, 3
 \end{aligned}
 \tag{P}$$

$$\begin{aligned}
 \min. \quad & 1y_1 + 3y_2 \\
 \text{s.t.} \quad & 1y_1 + 3y_2 \geq 4 \\
 & 4y_1 + 1y_2 \geq 1 \\
 & 0y_1 + 1y_2 \geq 3 \\
 & y_i \geq 0, \quad i = 1, 2
 \end{aligned}
 \tag{D}$$



In general:

$$\begin{array}{ll} \max & c^T x \\ \text{s.t.} & Ax \leq b \\ & x \geq 0 \end{array} \quad (P)$$

$$\begin{array}{ll} \min & b^T y \\ \text{s.t.} & A^T y \geq c \\ & y \geq 0 \end{array} \quad (D)$$

notice  $A$  becomes transposed

$$\begin{array}{ll}
 \max & \bar{c}^T \\
 & (4 \quad 1 \quad 3) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \\
 \text{s.t.} & \begin{pmatrix} 1 & 4 & 0 \\ 3 & -1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \leq \begin{pmatrix} 1 \\ 3 \end{pmatrix} \quad (P) \\
 & \quad \quad \quad A \quad \quad \quad b
 \end{array}$$

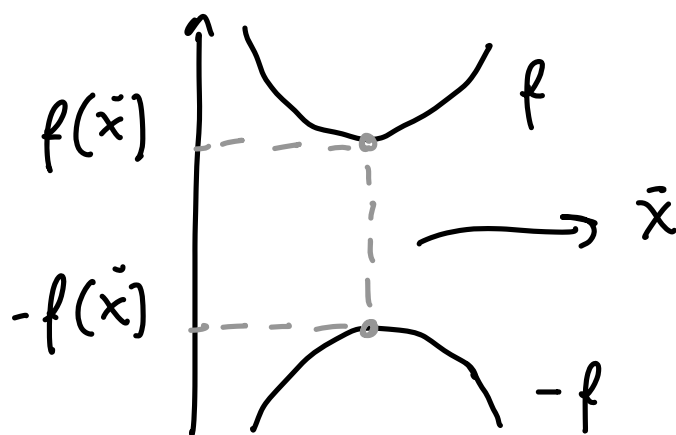

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$$\begin{array}{ll}
 \min & (1 \quad 3) \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \\
 \text{s.t.} & \begin{pmatrix} 1 & 3 \\ 4 & -1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \geq \begin{pmatrix} 4 \\ 1 \\ 3 \end{pmatrix} \quad (D) \\
 & \quad \quad \quad A^T \quad \quad \quad c
 \end{array}$$

Note that the dual of the dual is the original problem.

The dual problem into its std. form:

$$\begin{array}{ll} \text{(D)} \quad \min. & b^T y \\ \text{s.t.} & A^T y \geq c \\ & y \geq 0 \end{array} \xrightarrow{\text{std. form}} \begin{array}{ll} -\max & -b^T y \\ \text{s.t.} & -A^T y \leq c \\ & y \geq 0 \end{array}$$



now the dual prob. is in std. form.

What is the dual problem  $(\bar{D})$  of  $(D)$ ?

$$\begin{array}{ccc} -\min & -c^T x & \xrightarrow{\text{std. form}} \max c^T x \\ \text{s.t.} & -Ax \leq -b & \text{s.t. } Ax \leq b \\ & x \geq 0 & x \geq 0 \end{array}$$

our original problem  $(P)$ .  $\rightarrow$  \* holds.

General rules for  $(P)$  and  $(D)$ :

# of variables of  $(P)$  = # of constr. of  $(D)$

# of constraints of  $(P)$  = # of variables of  $(D)$

Using SM, you will get both the solution to (P) and (D).

(P)	(D)
max. in (P)	min in (D)
$\leq$ - constr.	$\geq$ - constr.
$g = c^T x$	$c$ becomes RHS of the constraints.
RHS of the constr. in (P)	$b^T y$ becomes obj. f. of (D).
$A$	$A^T$

Example:

$$\begin{aligned} \max. \quad & 3x_1 + 2x_2 \\ \text{s.t.} \quad & x_1 + 2x_2 \leq 4 \\ & 2x_1 + x_2 \leq 4 \\ & x_i \geq 0, i=1,2 \end{aligned} \quad (P)$$

$$\begin{aligned} \min \quad & 4y_1 + 4y_2 \\ \text{s.t.} \quad & 1y_1 + 2y_2 \geq 3 \\ & 2y_1 + y_2 \geq 2 \\ & y_i \geq 0, i=1,2 \end{aligned} \quad (D)$$

solve this at home!

Optimal dictionary:

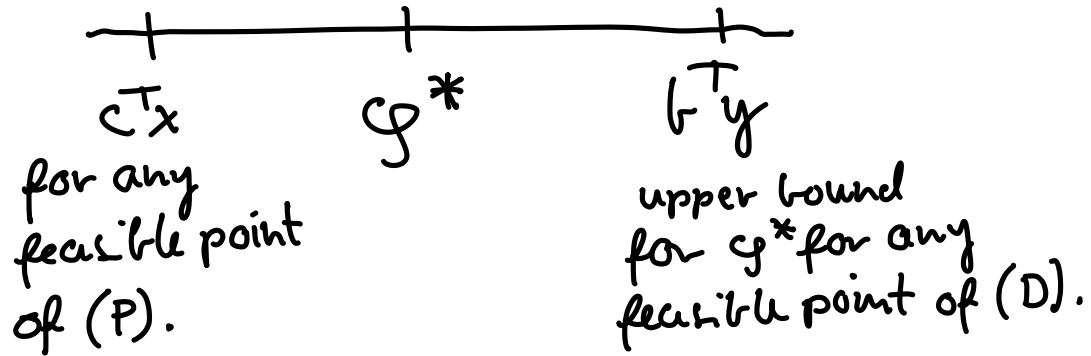
$$g = 6\frac{2}{3} - \frac{1}{3}w_2 - \frac{1}{3}w_1$$

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$$x_2 = \frac{4}{3} + \frac{1}{3}w_2 - \frac{2}{3}w_1$$

$$x_1 = \frac{4}{3} - \frac{2}{3}w_2 + \frac{1}{3}w_1$$

$$x^* = \begin{pmatrix} \frac{4}{3} \\ \frac{4}{3} \end{pmatrix}, \quad g^* = 6\frac{2}{3}$$



Weak duality theorem:

Let  $x \in \mathbb{R}^n$  and  $y \in \mathbb{R}^m$  be feasible points of (P) and (D) respectively.

Then:

$$c^T x \leq b^T y$$

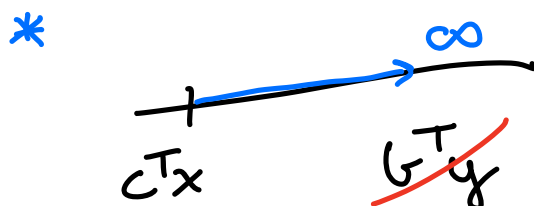


Proof:

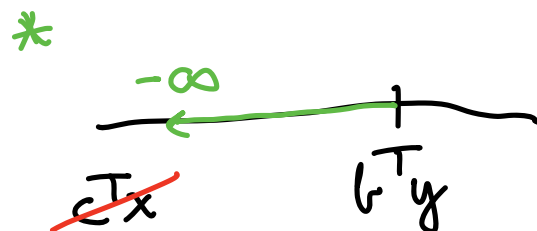
$$c^T x \leq y^T A x \leq y^T b$$

$$\left\{ \begin{array}{l} (AB)^T = A^T B^T \\ A^T y \geq c \\ y^T A \leq c^T \end{array} \right.$$

• If (P) is unbounded (that is,  $c^T x \rightarrow \infty$  for feasible  $x$  of (P)) then (D) is infeasible (doesn't exist) \*



• If (D) is unbounded, (P) is infeasible. \*



## Strong duality theorem

If (P) has an optimal solution  $x^* \in \mathbb{R}^n$ , then (D) has an optimal sol.

$y^* \in \mathbb{R}^m$  with:

$$\boxed{c^T x^* = b^T y^*}.$$

◦ Both (P) and (D) have a corresponding solution ( $x^*$  and  $y^*$ , respectively) or none of them has a solution.

- We will see that SM delivers both solutions in the dictionary.
- If solutions of (P) and (D) exist then there is no **duality gap**, that is, (P) and (D) have the same optimal obj. func. value.

