A can be split into submatrices
$$A = (B N) m$$

B is quadratic and non-singular.

Initially, first on columns is the basis variables and the first on columns is the non-verse variables.

$$x = \begin{pmatrix} x_B \\ x_N \end{pmatrix}$$
,  $c = \begin{pmatrix} c_B \\ c_N \end{pmatrix}$ 
Thuse our zero

Remember:

$$A \times = (B N) \begin{pmatrix} x_B \\ x_N \end{pmatrix} = A \times_N + A \times_B = b$$

multiply from left by B1.

$$B'B \times_B + B'N \times_N = B'b$$

$$I^m = 0, because they are NBV.$$

$$\times_B$$

$$x_B = B^{-1}b - B^{-1}Nx_N$$

$$\begin{pmatrix} \times_{\mathcal{B}} \\ \times_{\mathcal{N}} \end{pmatrix} = \begin{pmatrix} \mathcal{B}^{-1} \mathcal{G} \\ \mathcal{G} \end{pmatrix} \quad \text{Feasible} \iff \mathcal{B}^{-1} \mathcal{G} \Rightarrow \mathcal{G}$$

#### Example:

$$I^{m} (slach vaniables)$$

$$A = \begin{pmatrix} -2 & 4 & 1 & 0 \\ 0 & -1 & 0 & 1 \end{pmatrix}, \quad f^{-} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

which two submatr. of A can be chosen as B s.t. B is non-sing. (columns of B belong to the BV.

$$\frac{4\cdot 3}{2\cdot 1} = \begin{pmatrix} 4\\2 \end{pmatrix} = 6$$
 comb. of two matr.

$$12 \Rightarrow x_1, x_2 \quad B_{12} \quad \begin{pmatrix} -2 & 4 \\ 0 & -1 \end{pmatrix}$$

Is it non-singular (i.e. does the enverse matrix exist) ?

In general, if we have 
$$D = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$
:
$$D^{-1} = \frac{1}{det D} \begin{pmatrix} d & -b \\ c & a \end{pmatrix}$$

$$(D^{-1} \text{ exists} \iff club D \neq 0)$$

$$D^{-1} = \frac{1}{\det D} \begin{pmatrix} d - b \\ c & a \end{pmatrix}$$

$$(D^{-1} \text{ exists} \iff \text{clut } D \neq 0)$$

Hence, we can choose X, and Xz a vanis variables here.

Feasibility check:

$$\mathcal{B}_{12}^{-1}b = \frac{1}{2}\begin{pmatrix} -1 & -4 \\ 0 & -2 \end{pmatrix}\begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} -92 \\ -42 \end{pmatrix}$$

Infeas. bécause we have at lest on mg. coeff.

The vertex 
$$\begin{pmatrix} -92 \\ -92 \\ 0 \\ 6 \end{pmatrix}$$
 is not a fear-ble point.

Now let's look at X, and X3:

$$B_{13} = \begin{pmatrix} -2 & 1 \\ 0 & 0 \end{pmatrix}$$

Déterminant is zero/inverse matr. class not exist.

{x, x3} does not form a basis.

Now let's look at X, and X4:

$$B_{14}^{-1}$$
 exists

$$X_{B} = B_{14}^{-1} G = \begin{pmatrix} -\frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$$

Now let's look at x2 and x3:

$$B_{23}^{-1} = -\frac{1}{2}\begin{pmatrix} 1 & 0 \\ 0 & -2 \end{pmatrix}$$
 not feamble.  
 $X_{B} = B_{23}^{-1}b = \begin{pmatrix} -2 \\ 9 \end{pmatrix}$ 

Now let's look at x2 and x4:

$$\mathcal{B}_{24}^{-1} = \frac{1}{4} \begin{pmatrix} 1 & 0 \\ 1 & 4 \end{pmatrix}$$

$$\chi_{B} = \mathcal{B}_{24}^{-1} b = \begin{pmatrix} 1/4 \\ 9/4 \end{pmatrix} \quad \text{Feasible!}$$

$$/0/\chi_{1} \quad \text{NBV}$$

$$\Longrightarrow \begin{pmatrix} \sqrt{4} & \sqrt{2} & 80 \\ \sqrt{4} & \sqrt{4} & 80 \\ \sqrt{4} & 80 \\ \sqrt{4} & \sqrt{4} &$$

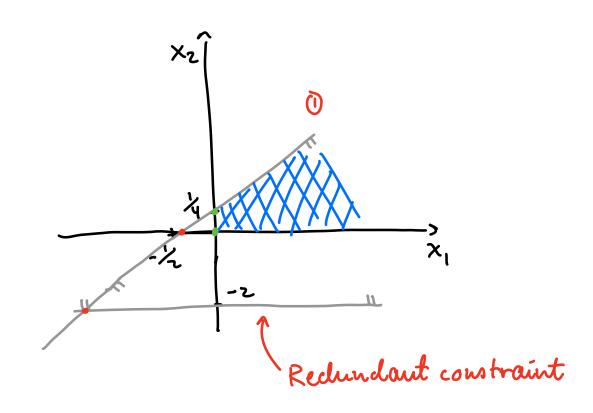
Now let's look at x3 and x4:

$$\mathcal{B}_{3n} = \mathbf{T}^m = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$A = \begin{pmatrix} -2 & 4 & 1 & 0 \\ 0 & -1 & 0 & 1 \end{pmatrix}, b = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$-2x_1 + 4x_2 \le 1$$

## Let's graph our program:



Only to fearible points! (green dots)

Consider the obj. func.

$$\mathcal{G} = c^{\mathsf{T}} \times = \left( c^{\mathsf{T}}_{\mathsf{B}} + c^{\mathsf{T}}_{\mathsf{N}} \right) \left( c^{\mathsf{B}}_{\mathsf{N}} \right)$$

= 
$$C_B^T \times_B + C_N^T \times_N$$
Using formula in 2\*

$$= c_{\mathcal{B}}^{\mathsf{T}} \left( \mathcal{B}^{\mathsf{I}} \mathcal{G} - \mathcal{B}^{\mathsf{I}} \mathcal{N} \times_{\mathsf{N}} \right) + c_{\mathsf{N}}^{\mathsf{T}} \times_{\mathsf{N}}$$

In the dict. we get the following:

The obj. value

This is 0 (NBVi)

$$9 = C_B^T B^{-1} b - ((B^{-1} N)^T C_B - C_N)^T \times N$$

BV XB = B-IR - (B-IN)XN

Presented vertex: 
$$\begin{pmatrix} x_B \\ x_N \end{pmatrix} = \begin{pmatrix} B^- b \\ B \end{pmatrix}$$

Recall the notations for the click. after zero or more pivot steps:

$$g = \bar{g} + \sum_{j \in N} c_j x_j$$

In matrix form:

$$\bar{g} = C_B B'b$$
 $[C_j] = C_N - (B'N) C_B$ 

Vector with components  $C_j$ ,  $j \in N$ 

$$X_i = \bar{f}_i - \sum_{j \in N} \bar{a}_{ij} \times_j, i \in B$$

[bi] = Bb   
This is from the BV above [aij] = Bb   

$$i \in B, j \in N$$

## For the dual dictionary:

Define variables  $\begin{pmatrix} y \\ z \end{pmatrix} \in \mathbb{R}^n$ 

Recall, for (P) we had  $\begin{pmatrix} x \\ w \end{pmatrix}$  and for (D) we had  $\begin{pmatrix} z \\ y \end{pmatrix}$ .

Z<sub>1</sub>...Z<sub>n</sub>, Z<sub>n+1</sub>...Z<sub>n+m</sub>

Corresponds to X<sub>1</sub>, X<sub>2</sub>,..., X<sub>n+m</sub> in (P).

Remember, everything above is only notation. There is nothing new here!

# Example:

max 
$$5x_1 + 4x_2 + 3x_3$$
  
s.t.  $2x_1 + 3x_2 + x_3 \le 5$   
 $4x_1 + x_2 + 2x_3 \le 11$   
 $3x_1 + 4x_2 + 2x_3 \le 6$   
 $x_1, x_2, x_3 \ge 0$ 

### Introduce sluch vars;

max 
$$5x_1 + 4x_2 + 3x_3$$
  
 $2x_1 + 3x_2 + x_3 + x_4 = 5$   
 $4x_1 + x_2 + 2x_3 + x_5 = 11$   
 $3x_1 + 4x_2 + 2x_3 + x_6 = 8$   
 $x_1 \ge 0, i = 1...6$ 

#### Now write it in matrix notation:

$$\begin{pmatrix}
2 & 3 & 1 & 1 & 0 & 0 \\
4 & 1 & 2 & 0 & 1 & 0 \\
3 & 4 & 2 & 0 & 0 & 1
\end{pmatrix}
\begin{pmatrix}
x_1 \\
x_2 \\
x_3 \\
x_4 \\
x_5 \\
x_6
\end{pmatrix} = \begin{pmatrix}
5 \\
11 \\
8
\end{pmatrix}$$
This is our our init. N initial B.

curiuit. N initial B.

$$C^{T}x = (5 4 3 0 0 0) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{pmatrix}$$

Initial vertex:

BV: 
$$x_4 = 5$$
 NBV:  $x_1 = 0$   
 $x_5 = 11$   $x_2 = 0$   
 $x_6 = 8$   $x_3 = 0$ 

Initial index sets:

$$B = \{4, 5, 6\}, N = \{1, 2, 3\}$$

$$\begin{pmatrix}
5 \\
11 \\
8
\end{pmatrix} = Ax = Bx_B + Nx_N =$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_{4} \\ x_{5} \\ x_{6} \end{pmatrix} + \begin{pmatrix} 2 & 3 & 1 \\ 4 & 1 & 2 \\ 3 & 4 & 2 \end{pmatrix} \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \end{pmatrix}$$

Since 
$$B = I^3$$
,  $B = B^1$ 
 $X_B = B^1b - B^1N \times N$ 

This is from the general formula.

Note that the reason matrix notation is important is that it is more convenient when we work with LPs containing a lot of variables.

$$\times_{\mathcal{B}} = \begin{pmatrix} 5 \\ 11 \\ 8 \end{pmatrix} - \begin{pmatrix} 2 & 3 & 1 \\ 4 & 1 & 2 \\ 3 & 4 & 2 \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \\ X_3 \end{pmatrix}$$

After one pivot step, where we interchange  $x_1$  and  $x_4$ , we get the following system:

BV:  $X_1$ ,  $X_5$ ,  $X_6$ ,  $B = \{1, 5, 6\}$ NBV:  $X_2$ ,  $X_3$ ,  $X_4$ ,  $N = \{2, 3, 4\}$ 

# Note that this is a new B now

Now matrix B consists of the columns 1,5 and 6:

$$Ax = \begin{pmatrix} 2x_1 + 3x_2 + x_3 + x_4 \\ 4x_1 + x_2 + 2x_3 \\ 3x_1 + 4x_2 + 2x_3 \end{pmatrix}$$

B now consist of the following columns.

We can recurange it like this (commutative property):

$$= \begin{pmatrix} 2x_{1} & +3x_{2} + x_{3} + x_{4} \\ 4x_{1} + x_{5} & +x_{2} + 2x_{3} \\ 3x_{1} & +x_{6} + 4x_{2} + 2x_{3} \end{pmatrix}$$

$$N$$

$$= \begin{pmatrix} 2 & 0 & 0 \\ 4 & 1 & 0 \\ 3 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_5 \\ x_6 \end{pmatrix} + \begin{pmatrix} 3 & 1 & 1 \\ 1 & 2 & 0 \\ 4 & 2 & 0 \end{pmatrix} \begin{pmatrix} x_3 \\ x_4 \\ x_5 \end{pmatrix}$$

$$\rightarrow X_{R} + N \cdot X_{N}$$

#### The solution to this instance is:

$$B = \begin{pmatrix} 2 & 0 & 0 \\ 4 & 1 & 0 \\ 3 & 0 & 1 \end{pmatrix}, B^{-1} = \begin{pmatrix} \frac{1}{2} & 0 & 0 \\ -2 & 1 & 0 \\ -\frac{3}{2} & 0 & 1 \end{pmatrix}$$

Entries in dict:

$$\begin{bmatrix} \overline{G}_{i} \end{bmatrix} = \chi_{B} = B^{-1}G = \begin{pmatrix} \frac{1}{2} & 0 & 0 \\ -2 & 1 & 0 \\ -\frac{3}{2} & 0 & 1 \end{pmatrix} \begin{pmatrix} 5 \\ 11 \\ 8 \end{pmatrix}$$

$$=\begin{pmatrix} \frac{5}{2} \\ 1 \\ \frac{1}{2} \end{pmatrix} \quad \text{(feasible!)}$$

$$[aij] = B^{-1}N: \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ -3/2 & 0 & 1 \end{pmatrix} \begin{pmatrix} 3 & 1 & 1 \\ 1 & 2 & 0 \\ 4 & 2 & 0 \end{pmatrix}$$
if B, jen

$$\begin{pmatrix} 4 \\ 3 \\ 0 \end{pmatrix} - \begin{pmatrix} \frac{3}{2} & -5 & -\frac{1}{2} \\ \frac{1}{2} & 0 & \frac{1}{2} \\ \frac{1}{2} & -2 & -\frac{3}{2} \end{pmatrix} \begin{pmatrix} 5 \\ 0 \\ 6 \end{pmatrix} = -\frac{1}{2} \begin{pmatrix} 7 \\ -1 \\ 5 \end{pmatrix}$$

$$C_{N}$$

$$\begin{pmatrix} 3^{2} & -5 & -\frac{1}{2} \\ \frac{1}{2} & 0 & \frac{1}{2} \\ \frac{1}{2} & -2 & -\frac{3}{2} \end{pmatrix} \begin{pmatrix} 5 \\ 0 \\ 6 \end{pmatrix} = -\frac{1}{2} \begin{pmatrix} 7 \\ -1 \\ 5 \end{pmatrix}$$

$$C_{N}$$

$$\begin{pmatrix} 3^{2} & -5 & -\frac{1}{2} \\ -1 \\ 5 \end{pmatrix}$$

$$\frac{1}{2} = \frac{1}{2} \frac{1}{2} \frac{1}{2} = \frac{1}{$$

Obj. value in our given solution

$$\bar{X}_{B} = \bar{B}^{-1}G = \begin{pmatrix} \frac{5}{2} \\ \frac{1}{2} \end{pmatrix}, \quad \bar{X}_{N} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$x^{T} = (\frac{5}{2}, 0, 0, 0, 1, \frac{1}{2})$$

This is the vertex in our given solution