

Iterative Quadratic Sorting Algorithms Paolo Camurati

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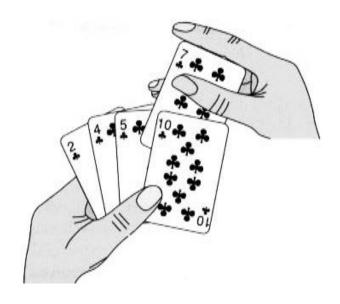
 $O(n^2)$

Outline

- Insertion sorting
- Bubble/exchange Sorting
- Selection sorting
- Shell sorting

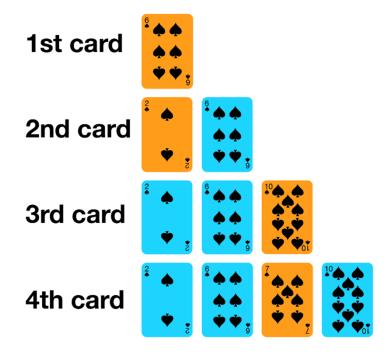
Insertion Sort

Sorting algorithm that builds the final sorted **array** (or list) one item at a time by **comparisons**



Insertion Sort

- Start with one card in your hand,
- Pick the next card and insert it into its proper sorted order,
- Repeat previous step for all cards.



Insertion Sort

Let N integers be stored in an array A whose indices range from i=0 and r=N-1.

Conceptually array A consists of 2 subarrays:

- the left one: already sorted
- the right one: not yet sorted

Initially the left subarray contains **1 item**, the right subarray contains **N-1** items.

An array with just **1 item** is sorted by definition.



Approach

Incremental paradigm:

- At each step, we expand the already sorted left subarray inserting an item taken from the still unsorted right subarray
- Insertion must guarantee that the left subarray remains sorted after inserting the item (invariance of the sorting property)
- termination: all items have been properly inserted, the left subarray contains N items, the right subarray is empty

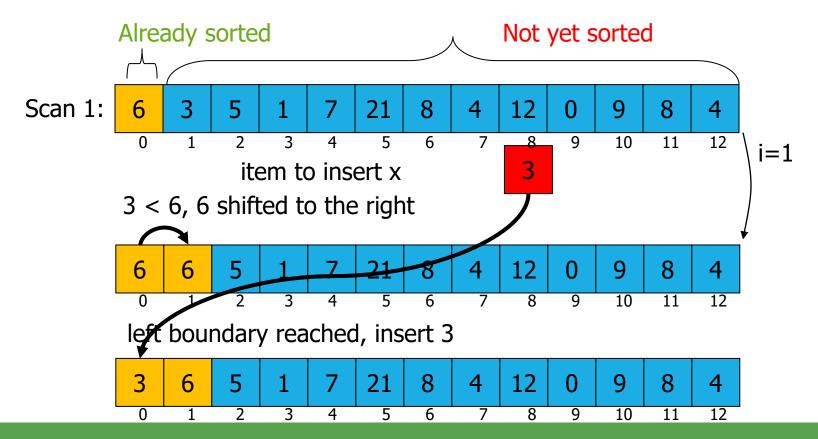


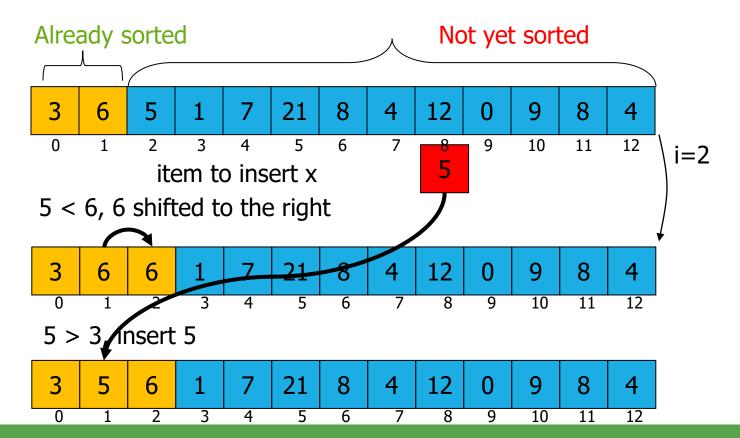
Step *i*: sorted insertion

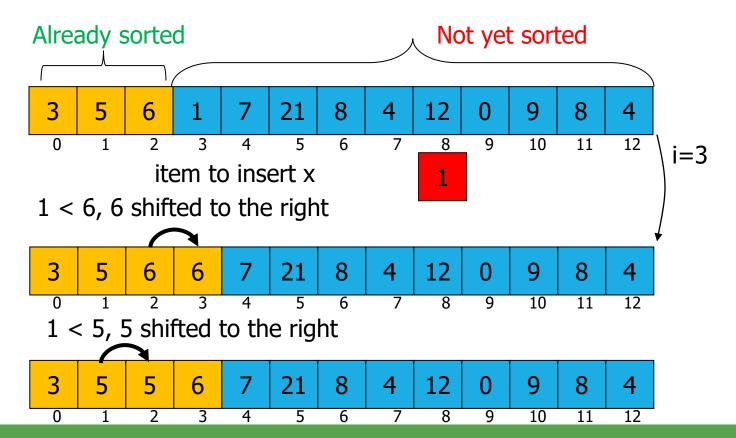
At step *i* item $\mathbf{x} = \mathbf{A_i}$ is stored at the correct position in the **left subarray**:

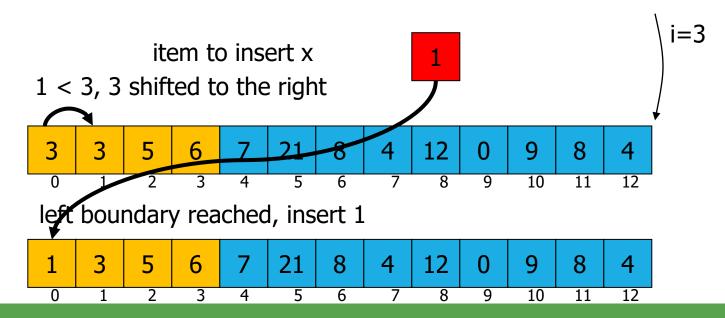
- the **left subarray** (already sorted and ranging from A_{i-1} downto A_0) is scanned until an item is found such that $A_i > A_i$
- during the scan, items in the range from A_j to A_{i-1} are shifted to the right by 1 position

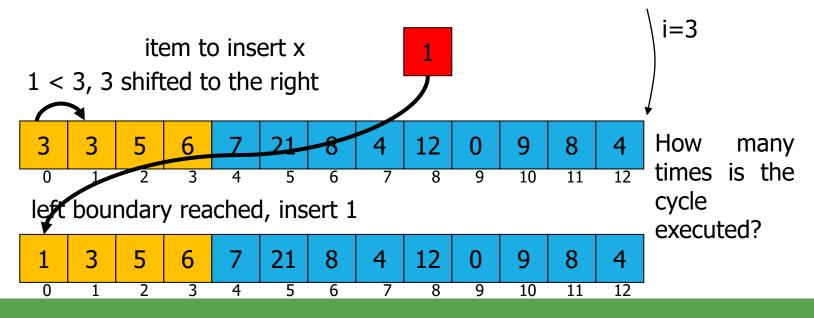
When the **loop** terminates, the correct position for inserting A_i has been found











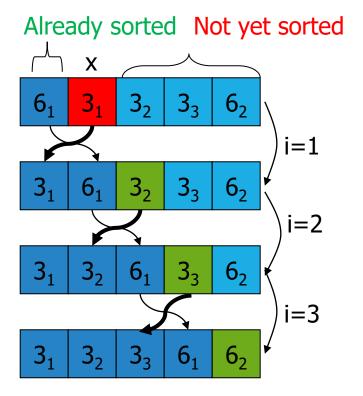
Example of functions implementing the insertion sorting algorithm

```
void InsertionSort(int A[], int N)
  int i, j, l=0, r=N-1, x;
  for (i = 1+1; i <= r; i++) {
    x = A[i]:
    j = i - 1;
    while (j >= 1 \&\& x < A[j]){
      A[j+1] = A[j];
   A[j+1] = x;
```

Is insertion sorting an algorithm or a procedure?

Insertion sort Features

- in place: used only array A and variable x
- stable: if the item to insert is a duplicate key, it can't jump over to the left a previous occurrence of the same key



Complexity Analysis of Insertion sort

Worst-case asymptotic analysis:

- Based on each step of the statements used
- Based on the high-level behaviour of the statements used

to estimate:

- The number of comparisons
- The number of swaps

Assumption:

- All instructions have unit cost
- i starts from 1 and increases to N-1 (for simplicity no use of I and r)

instructions

```
for(i=1; i<N; i++) {</pre>
```

executions

2N

- 2 instructions at each step (< and +)
- N executions taking into account the last one as well when the condition i<N fails

instructions

```
for(i=1; i<N; i++) {
    x = A[i];
    j = i-1;</pre>
```



N-1 executions only when condition i<N holds

instructions

```
for(i=1; i<N; i++) {
    x = A[i];
    j = i-1;
    while (j>=0 && x<A[j]){</pre>
```

executions

2N

N-1

N-1

 $2\sum_{j=2}^{N} j$

- 2 instructions at each step (>=and <)
- N-1 executions of the loop in the worst case (array already sorted in descending order)
- j operations at each loop execution taking into account as well the last one when condition j>=0 fails

instructions

```
for(i=1; i<N; i++) {
    x = A[i];
    j = i-1;
    while (j>=0 && x<A[j]){
        A[j+1] = A[j];
        j--;
    }</pre>
```

executions

2N

N-1

N-1

 $2\sum_{j=2}^{N} j$ $\sum_{j=2}^{N} (j-1)$

 $\sum_{j=2}^{N} (j-1)$

- N-1 executions of the loop in the worst case (array already sorted in descending order)
- j-1 operations at each loop execution only when the loop condition holds

```
instructions
                                       # executions
for(i=1; i<N; i++) {
                                       2N
                                        N-1
  X = A[i];
  i = i-1;
                                       N-1
                                       2\sum_{j=2}^{N} j
  while (j>=0 \&\& x<A[j]){
                                                     N-1 executions only when condition
                                       \sum_{j=2}^{N} (j-1)
     A[i+1] = A[i];
                                                     i<N holds
                                       \sum_{j=2}^{N} (j-1)
     j--;
  A[j+1] = x;
```

Thus:

$$T(N) = 2N + (N-1) + (N-1) + 2\sum_{j=2}^{N} j + \sum_{j=2}^{N} (j-1) + \sum_{j=2}^{N} (j-1) + (N-1)$$

Recalling that:

$$\sum_{j=2}^{N} j = 2+3+...N = N(N+1)/2 -1$$

$$\sum_{j=2}^{N} (j-1) = N(N-1)/2$$

$$T(N) = 2N + 3(N-1) + 2(N(N+1)/2 - 1) + 2(N(N-1)/2) = 2N^2 + 6N - 6$$

$$T(N) = O(N^2) : \text{the number of comparisons in the worst case grows}$$

$$\text{quadratically.}$$

High-level Complexity Analysis

Two nested loops:

- Outer loop: N-1 executions
- Inner loop in the worst case: i executions at the i-th iteration of the outer loop

Complexity:

$$T(N) = 1+2+3+ ... + (N-2)+(N-1)$$

= $\sum_{1 \le i \le N} i = N(N-1)/2$

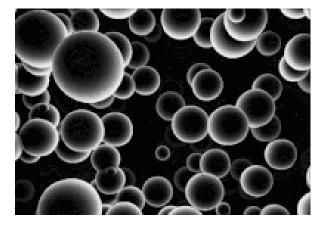
T(N) grows quadratically with N.

Finite arithmetic progression with ratio 1 (Gauss, end of XVII cent.)

 $T(N) = O(N^2)$: the number of comparisons and of swaps grows quadratically.

Bubble/Exchange sort

Also known as *sinking sort*. It is a sorting algorithm that is used to sort the elements in **an ascending order**. It uses less storage space.



Bubble/Exchange sort

Let **N** integers be stored in an array **A** whose indices range from **I**=0 and **r**=**N**-1. Conceptually array **A** consists of 2 **subarrays**:

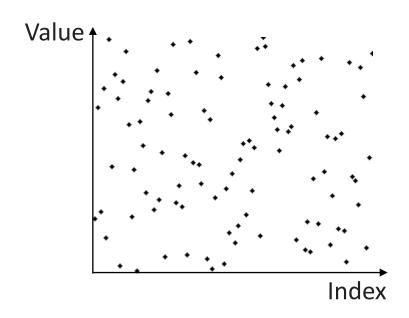
- the right one: already sorted
- the left one: not yet sorted

Initially the **right subarray** is empty, the left one contains **N** items.

The basic operation is a comparison between adjacent items of array A (A[j] and A[j+1]), swapping them if A[j] > A[j+1].

Bubble/Exchange sort





Approach

Incremental paradigm:

- At each step expand the already sorted right subarray by inserting an item taken from the not yet sorted left subarray
- Insertion must guarantee that the right subarray remains sorted after insertion (invariance of the sorting property)
- At iteration i insert the largest item of the left subarray (A₁ ... A_{r-i+l}) into the leftmost position of the right subarray A[r-i+l]. The sorted right subarray grows by 1 in size to the left, dually the unsorted left one decreases in size by 1
- Termination: all items have been properly inserted, the right subarray contains N items, the left one is empty.

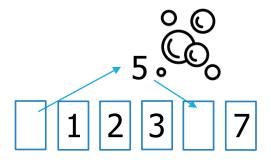
6 5 3 1 8 7 2 4

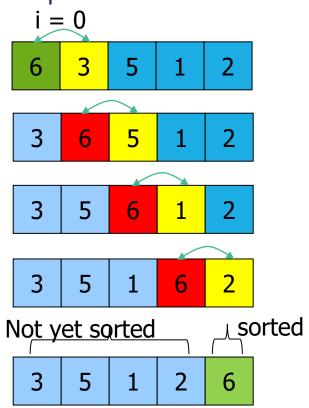
Step i: identifying the maximum

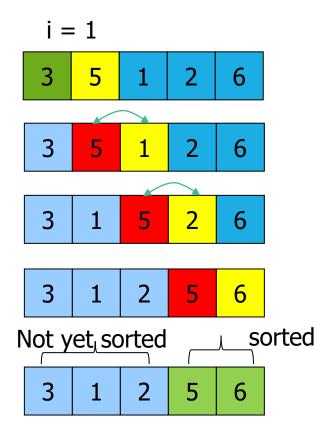
Identification of the **largest item** in the left subarray at step i

scan the left subarray comparing item pairs A[j] and A[j+1] and swapping them if A[j] > A[j+1].

When the loop ends, the largest item has «floated» like a «bubble» to the correct position at the leftmost location of the sorted right subarray.







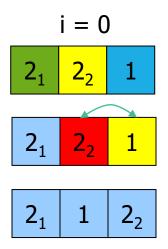
Example of functions implementing the bubble sorting algorithm

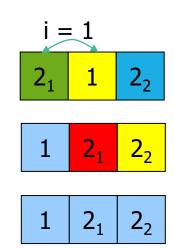
```
void BubbleSort(int A[], int N){
  int i, j, l=0, r=N-1;
  int temp;
  for (i = 1; i < r; i++) {
   for (j = 1; j < r - i + 1; j++)
     if (A[j] > A[j+1])
        temp = A[i];
        A[i] = A[i+1];
        A[i+1] = temp;
  return;
```

i-l is the size of the already sorted right subarray

Bubble/Exchange sort Features

- in place: used only array A and variable temp
- **stable:** if there are several duplicate keys the rightmost none takes the rightmost position and no other identical key jumps over it to the right:





High-level Complexity Analysis

Two nested loops:

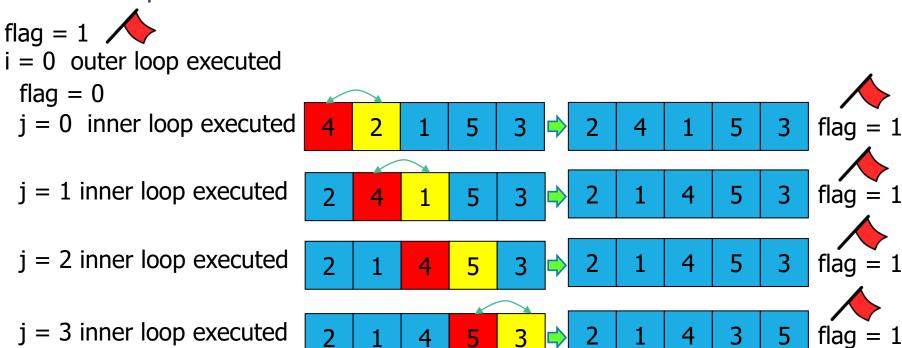
- Outer loop: always executed N-1 times
- Inner loop: at the i-th iteration executed always N-1-i times

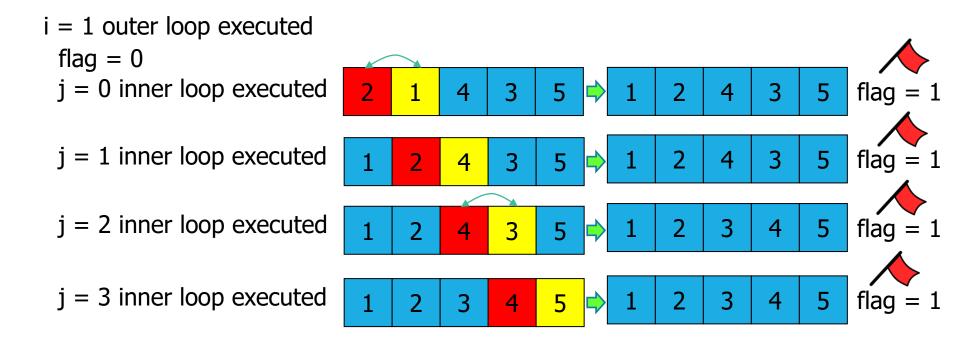
```
T(N) = (N-1) + (N-2) + ... 2 + 1
= \sum_{1 \le i < N} i = N(N-1)/2
T(N) = \Theta(N^2).
Finite arithmetic progression with ratio 1 (Gauss, end of XVII cent.)
```

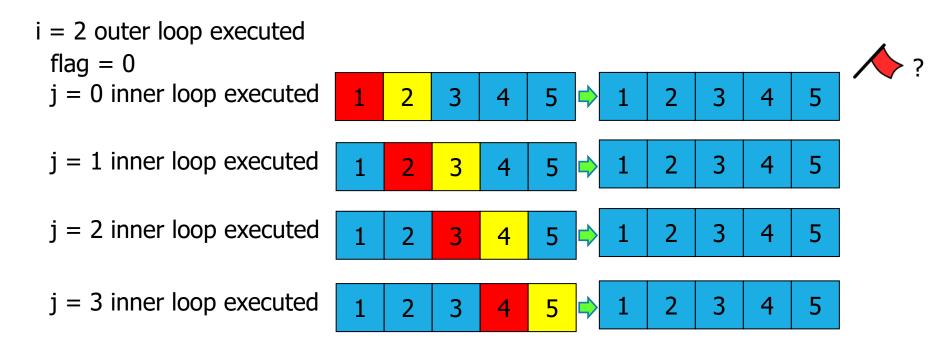
- Number of swaps in the worst case: O(N²): a swap doesn't necessarily occur
- Number of comparisons in the worst case: $\Theta(N^2)$: a comparison always takes place

Optimization

- Use a flag to mark whether there has been swaps. Execution continues only if there have been swaps
 - The outer loop is executed at most N-1 times
 - The inner loop at the i-th iteration is executed always N-1-i times
- Number of comparisons in the worst case: $O(N^2)$: a comparison doesn't necessarily take place
- Average case complexity is improved, no change in worst case complexity.







i = 3 but **flag = 0** as there has been **no swaps**, outer loop not executed

Example of functions implementing the optimized bubble sorting algorithm

```
void OptBubbleSort(int A[], int N) {
  int i, j, l=0, r=N-1, flag=1;
  int temp;
  for (i = 1; i < r && flag==1; i++)
     flag = 0;
    for (j = 1; j < r - i + 1; j++) {
        if (A[i] > A[i+1])
           flag = 1;
           temp = A[i]:
           A[i] = A[i+1];
           A[j+1] = temp;
    return;
```

Question?

Whats the best way to sort one million 32-bit integers?

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Former Google CEO Eric Schmidt asked Barack Obama during an interview:

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Former Google CEO Eric Schmidt asked Barack Obama during an interview:

Whats the best way to sort one million 32-bit integers?

Obama paused for a moment and replied:

"I think the bubble sort would be the wrong way to go"

The Internet Sort

It's just a **bubble sort**, but perform every comparison by searching the internet. For example, "Which is greater – 0.211 or 0.75?".

Selection sort

It is a **simple** and **efficient** sorting algorithm that works by repeatedly selecting the **smallest** (**or largest**) **element** from the **unsorted** portion of the list and moving it to the **sorted portion** of the list.



Selection sort

Let N integers be stored in an array A whose indices range from I=0 and r=N-1.

Conceptually array A consists of 2 subarrays:

- Left subarray: already sorted
- Right subarray: not yet sorted

Initially the **left subarray is empty**, the right one contains **N** items.

Approach

Incremental paradigm:

- At each step expand the already sorted left subarray inserting an item taken from the not yet sorted right subarray
- Insertion must guarantee that the **left subarray remains sorted** after insertion (*invariance of the sorting property*). This is guaranteed by identifying the **smallest item** in the right subarray ($A_i \dots A_r$) and assigning it to A[i]. The sorted left subarray **grows** by I in size to the right, dually the **not** yet sorted right one **decreases** in size by I
- Termination: all items have been properly inserted, the left subarray contains N items, the right one is empty.

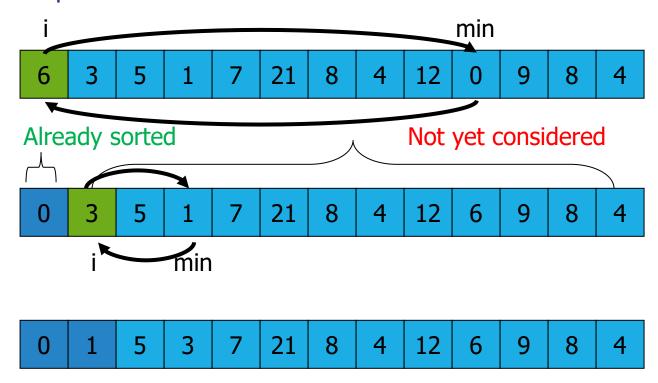
Step *i*: identifying the minimum

Identification of **the smallest item** of the right subarray at the **i-th** step:

Scan the **right subarray**, assuming that the smallest item is in **A[i]** and updating the smallest item at each comparison with the following items

When the **loop** ends, the smallest item has been identified by means of its position (*index in A*) and **swapped** with **A[i]**.

Example

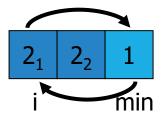


Example of function implementing the selection sorting algorithm

```
void SelectionSort(int A[], int N) {
 int i, j, l=0, r=N-1, min;
 int temp;
 for (i = 1; i < r; i++) {
   min = i:
   for (j = i+1; j <= r; j++)
     if (A[j] < A[min])
         min = j;
   if (min != i) {
     temp = A[i];
     A[i] = A[min];
     A[min] = temp;
 return;
```

Selection sort Features

- in place: only array A and variable temp are used
- non stable: a swap of 2 «far away» items may allow a duplicate key to jump to the left of a previous identical key:





High-level Complexity Analysis

Two nested loops:

- Outer loop: always executed N-1 times
- Inner loop: at the i-th iteration always executed N-1-i times

```
T(N) = (N-1) + (N-2) + ... 2 + 1
= \sum_{1 \le i < N} i = N(N-1)/2
T(n) = \Theta(N^2).
Finite arithmetic progression with ratio 1 (Gauss, end of XVII cent.)
```

- Number of swaps in the worst case: O(N): it may happen to always swap the current item with the current smallest one, but this occurs at most N times
- Number of comparisons in the worst case: $\Theta(N^2)$: comparisons always occur
- The algorithm is quadratic, as complexity depends on the number of comparisons, not on the number of swaps.

Quick summary

Big O of Sorting Algorithms

Algorithm	Time Complexity (Best)	Time Complexity (Average)	Time Complexity (Worst)	Space Complexity
Bubble Sort	O(<i>n</i>)	$O(n^2)$	O(n ²)	O(1)
Insertion Sort	O(n)	O(n ²)	O(n ²)	O(1)
Selection Sort	O(n ²)	O(n ²)	O(n ²)	O(1)

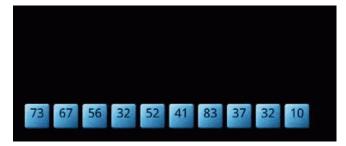
Shell sort (Shell, 1959)





Donald Shell

D. L. Shell. 1959. "A high-speed sorting procedure". Commun. ACM 2, 7 (July 1959), 30-32.



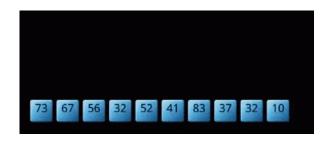
Shell sort (Shell, 1959)

It is a **generalized** version of the insertion sort algorithm. It first sorts elements that are **far apart** from each other and successively reduces the interval between the elements to be sorted.

Limit of Insertion sort: only adjacent items are compared and possibly swapped.

Shell sort approach:

- Compare and possibly swap items at distance h
- Define a decreasing sequence of integers h that end at 1. The last step is Insertion sort.



Linear Sequences

Finite set of consecutive items. Each item is uniquely associated to an index

A predecessor/successor relationship is defined on pairs of consecutive items:

$$\mathbf{a}_{i+1} = \operatorname{succ}(\mathbf{a}_i)$$
 $\mathbf{a}_i = \operatorname{pred}(\mathbf{a}_{i+1})$

- Storage and access:
 - Array: contiguous data in memory with direct access:
 - Given index i, it is possible to access item a_i without scanning the linear sequence
 - Cost of access doesn't depend on the position of the item in the linear sequence, thus it is O(1)
 - list: non contiguous data in memory with sequential access. Topic of the second year course.

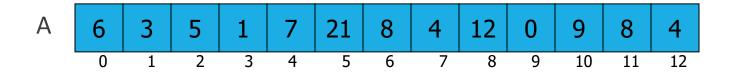
Subarrays and Subsequences

Given a linear sequence of N integers stored in array A

$$A = (a_0, a_1, ... a_{N-1})$$

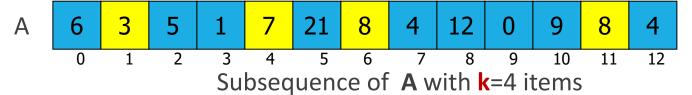
- a subsequence of A of length k ($k \le N$) is any tuple Y of k items of A with increasing and not necessarily contiguous indices i_0 , i_1 , \cdots , i_{k-1}
- a subarray of A of length k ($k \le N$) is any tuple Y of k items of A with increasing and contiguous indices i_0 , i_1 , \cdots , i_{k-1} .

Example





Subarray of A with k=4 items with increasing and contiguous indices i_4 , i_5 , i_6 , i_7

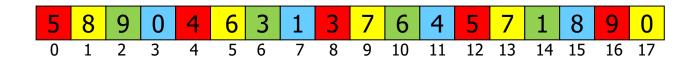


with increasing and non contiguous indices i_1 , i_4 , i_6 , i_{11}

Subsequences in Shell sort

Shell sort works with **subsequences** composed by array items whose indices at distance **h** from each other.

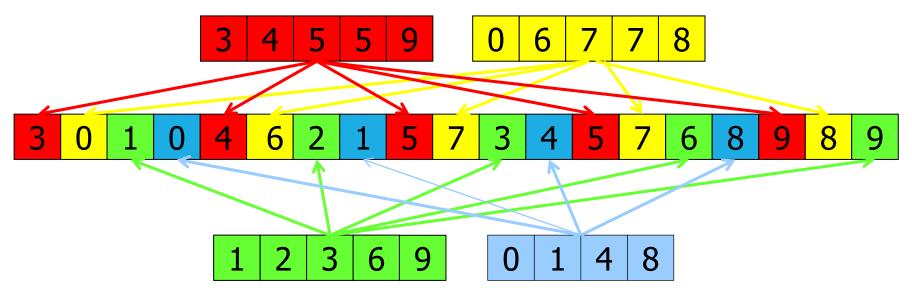
Example: h=4



Subsequences in Shell sort

If the **subsequences** containing items at distance **h** are sorted, the array is **h-sorted**.

Example: h=4

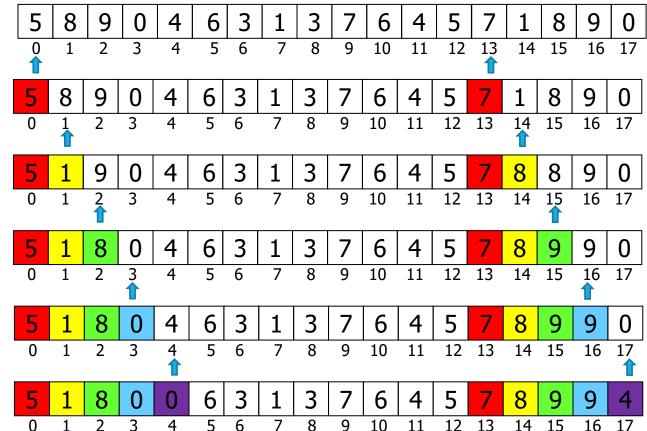


Subsequences in Shell sort

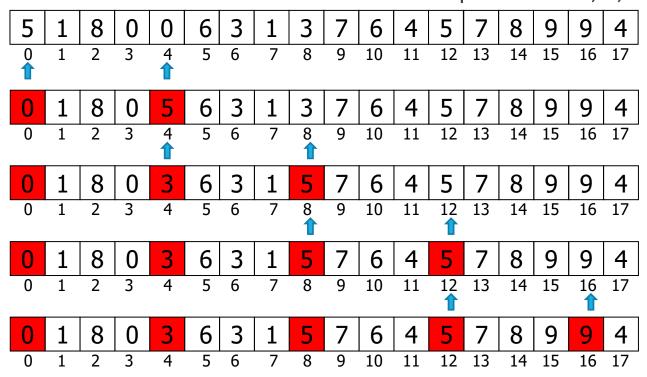
For each **subsequence** apply Insertion sort. The items of the **subsequence** are the items at distance **h** from the current one.

```
for i = l+h; i <= r; i++) {
    j = i; x = A[i];
    while (j>= l+h && x < A[j-h]) {
        A[j] = A[j-h];
        j -=h;
    }
    A[j] = x;
}</pre>
```

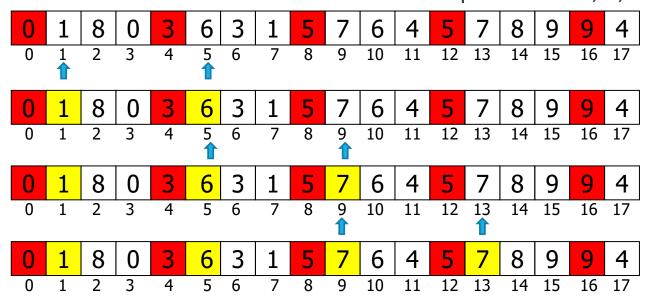
Example



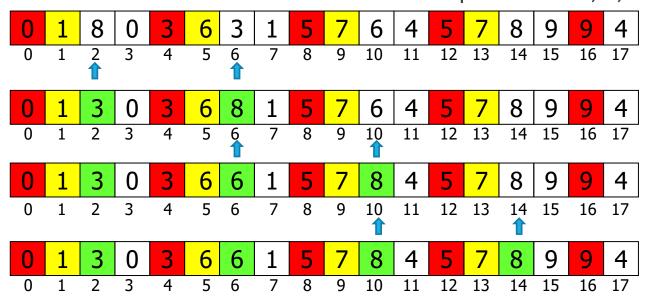
Step 1: h=13



Step 2: h=4



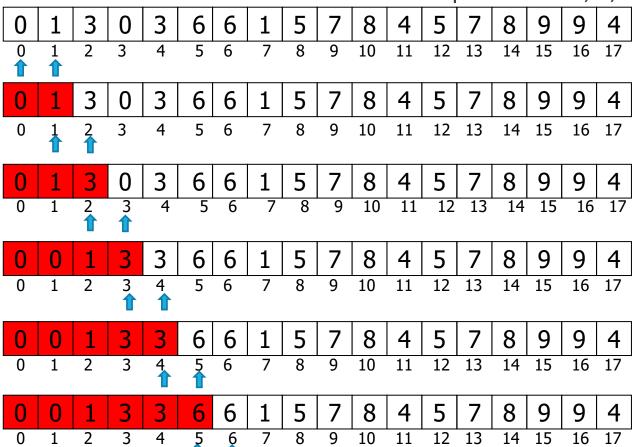
Step 2: h=4



Step 2: h=4

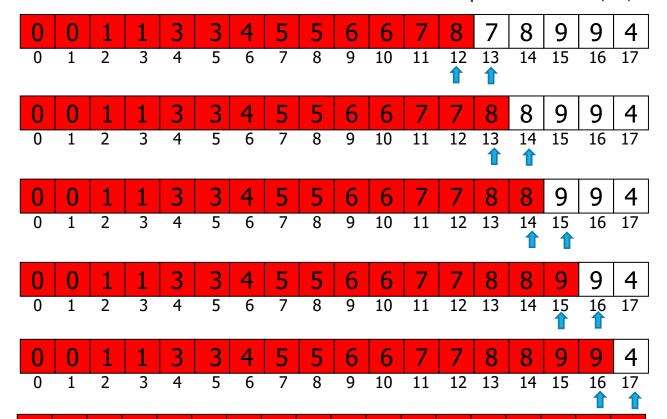
sequence h: 13, 4, 1 12 13 14 15

Step 2: h=4



Step 3: h=1

Step 3: h=1



Step 3: h=1

9

Sequences

• Shell's sequence (1959) $h_i = 2^{i-1}$

$$h_1 = 1$$
, $h_2 = 2$, $h_3 = 4$, $h_4 = 8$, $h_5 = 16$, ...

• **Hibbard's sequence** (1963): $h_i = 2^i - 1$

$$h_1 = 1$$
, $h_2 = 3$, $h_3 = 7$, $h_4 = 15$, $h_5 = 31$, ...

Pratt's sequence (1971):

1, 2, 3, 4, 6, 8, 9, 12, 16, ..., 2^p3^q , ...

• Knuth's (1973): initially $h_0=0$ then $h_i=3h_{i-1}+1$

$$h_1 = 1$$
, $h_2 = 4$, $h_3 = 13$, $h_4 = 40$, $h_5 = 121$, ...

Sedgewick's sequence (1986):

1, 5, 19, 41, 109, 209, 505, 929, 2161, 3905, ...

Hibbard, T. N. (1963). An empirical study of minimal storage sorting. Communications of the ACM, 6(5), 206-213.

Pratt, V. R. (1972). Shellsort and sorting networks (Vol. 72, No. 260). C. S. Department, Stanford University.

```
void ShellSort(int A[], int N) {
 int i, j, x, l=0, r=N-1, h=1;
                                            Knuth's sequence
  while (h \leq N/3)
    h = 3*h+1;
  while(h >= 1) {
    for (i = 1 + h; i <= r; i++) {
     j = i;
      x = A[i];
      while(j >= 1 + h && x < A[j-h]) {
       A[i] = A[i-h];
       i -=h:
     A[i] = X;
    h = h/3;
```

Shell sort Features

- in place: apart from array A only variable x is used
- non stable: a swap between «distant» items can force a duplicate key to jump to the lest of a previous occurrence:

$$\begin{bmatrix} 2_1 & 2_2 & 2_3 & 2_4 & 2_5 & 0 \end{bmatrix}$$

High-level Complexity Analysis

- With Shell's sequence: 1 2 4 8 16 ... $T(N) = O(N^2)$
- With **Hibbard's sequence:** 1 3 7 15 31 ... $T(N) = O(N^{3/2})$
- With Pratt's sequence: 1 2 3 4 6 8 9 12 ... T(N) = O(Nlog²N)
- With Knuth's sequence: 1 4 13 40 121 ... $T(n) = O(N^{3/2})$
- With Sedgewick's sequence: 1, 5, 19, 41, 109, 209, ... $T(N) = O(N^{4/3})$