

Ex: A 10kW DC Shunt motor connected to 200V supply, and driving a load with the following characteristics.

$$P_e = k n^2 = 3.9 \cdot 10^{-3} n^2 \text{ (speed in rpm)}$$

Friction losses is const = 250kW

$$R_f = 40\Omega$$

2) Calculate the motor speed if the motor is supplying rated power from its shaft at steady-state.

$$2) P_{out} = 10 \text{ kW} \quad (\text{rated power of motor})$$

output
shaft
power

$$\text{steady state} \Rightarrow P_{out} = P_{mech}$$

$$10.000 = 3.9 \cdot 10^{-3} \cdot n^2$$

$$\underline{n = 1601 \text{ rpm}}$$

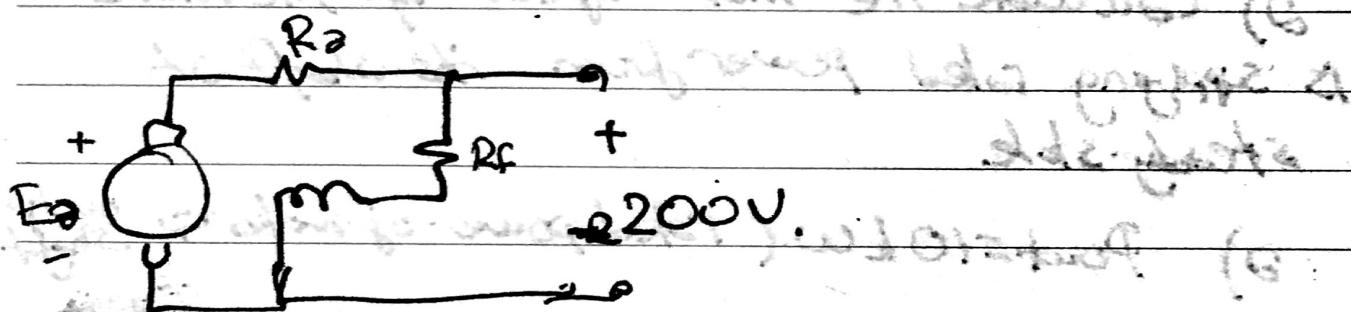
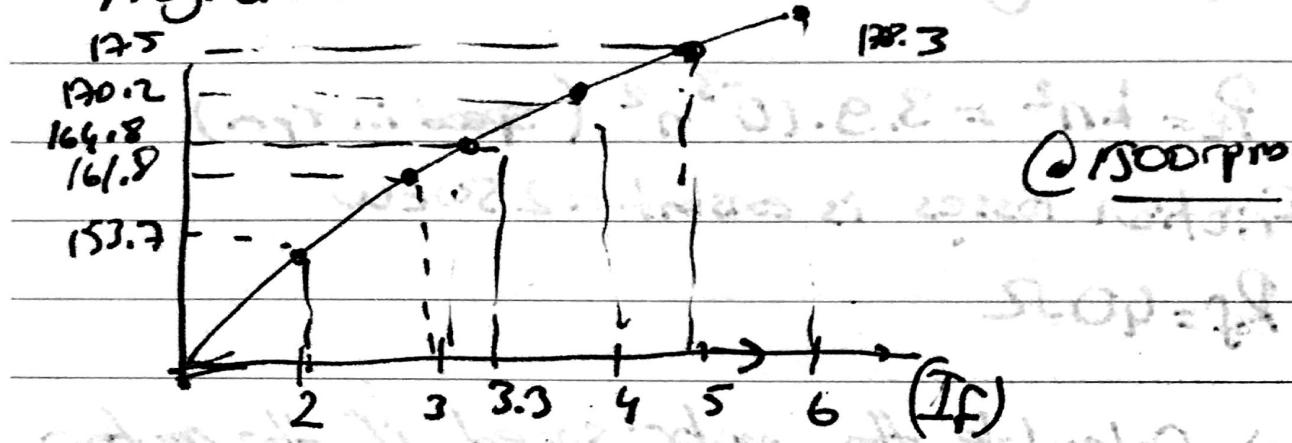
$$\omega = 2\pi \cdot \frac{1600}{60} = 168 \text{ rad/s}$$

Hz

$$T_e = \frac{P_o}{\omega_m} = \frac{10.000}{168} = 59.6 \text{ Nm}$$

b) Determine the armature current and armature resistance of the motor at rated load.

Magnetization characteristics.



$$R_f = 40 \Omega \Rightarrow I_f = \frac{200}{40} = 5 \text{ A}$$

$$I_f = 5 \text{ A} \Rightarrow n_r = 1500 \text{ rpm} \Rightarrow E_d = 175 \text{ V}$$

$$n = 1601 \text{ rpm} \Rightarrow I_f = 5 \text{ A} \Rightarrow E_d = 175 \cdot \frac{1601}{1500} = 187 \text{ V}$$

$$\underline{\underline{E_d = 187 \text{ V}}}$$

$$P_e = P_{out} + P_{friction}$$

$$P_e = 10.000 + 250 = \underline{\underline{10.250 \text{ W}}}$$

$$P_e = E_d \cdot I_d = 10.250 \text{ W}$$

$$I_d = \frac{10.250}{187} = \underline{\underline{54.8 \text{ A}}}$$

$$R_2 = \frac{V_f - E_d}{I_d} = \frac{200 - 187}{54.8} = \underline{0.24\Omega}$$

c) Calculate the total current drawn from the power source.

$$I_t = I_d + I_f$$

$$= 54.8 + 5 = 59.8A$$

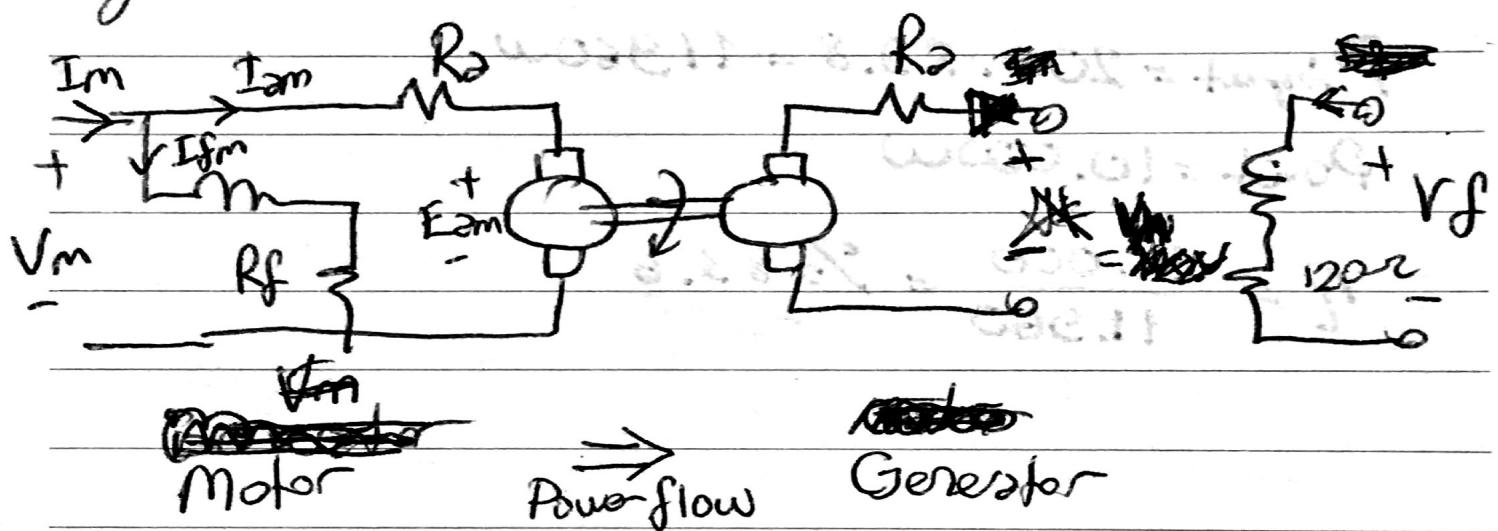
$$P_{\text{input}} = 200 \cdot 59.8 = 11960W$$

$$P_{\text{out}} = 10.000W$$

$$\eta = \frac{10.000}{11.960} = \underline{\underline{\% 83.6}}$$

Ex: Consider two identical DC machines having an armature resistance $R_a = 0.2 \Omega$ and a field winding resistance of $R_f = 120\Omega$

One of the machines is used as a shunt motor to drive the other as a separately excited generator.



The shunt motor draws 6kW from a constant voltage source of $V_t = 120V$. The excitation currents of both machines are equal and the ~~total~~ rotational loss is constant $P_{rot} = 2000W$ per machine.

2) Draw the complete circuit diagram

b) Calculate the induced voltage and efficiency of the motor

$$P_{im} = 6 \text{ kW} \quad I_m = \frac{6000}{120} = 50 \text{ A}$$

$$V_m = 120 \text{ V}$$

$$I_{fm} = \frac{120 \text{ V}}{120 \Omega} = 1 \text{ A}$$

$$I_{am} = 50 - 1 = 49 \text{ A}$$

$$R_a = 0.2 \Omega$$

$$E_{ad} = V_m - R_a \cdot I_{am} = \\ = 120 - 0.2 \cdot 49 = 110.2 \text{ V}$$

$$P_{elec(m)} = E_{ad} \cdot I_a = 110.2 \cdot 49 = 5400 \text{ W}$$

$$P_{out(m)} = P_{elec} - P_{friction} = 5400 - 200 = \underline{\underline{5200 \text{ W}}}$$

$$\eta = \frac{P_{out}}{P_{in}} = \frac{5200}{6000} = \underline{\underline{86.67\%}}$$

c) Assuming the induced voltage of the generator is 110.2 V. Find the armature current, output power and efficiency of the generator.

$$E_g = 110.2 \text{ V}$$

$$P_{om} = 5200 \text{ W}$$

$$P_{eg} = P_{ig} - P_{friction} = 5200 - 200 = 5000 \text{ W}$$

$$I_{ag} = \frac{E_{ag}}{R_a} = \frac{5000}{110.2} = 45.37 A$$

$$V_{tg} = E_{ag} - R_a I_{ag} = 110.2 - 110.2 \cdot 45.37 \\ = 101.1 V$$

$$P_{ag} = R_a I_{ag}^2 = 0.2 \cdot (45.37)^2 = 411.7 W \quad \begin{matrix} \text{(Generator)} \\ \text{(Armature)} \\ \text{Loss} \end{matrix}$$

If $I_f^2 = 120 W$ (given) (same current $I_f = 1 A$)
to induce same voltage.

$$P_{ig} = 5200 + 120 = 5320 W$$

$$P_{out} = V_{tg} \cdot I_{ag} \\ = 4588$$

$$\eta = \frac{4588}{5320} = 86.25\%$$

$$\text{or } P_{loss} =$$

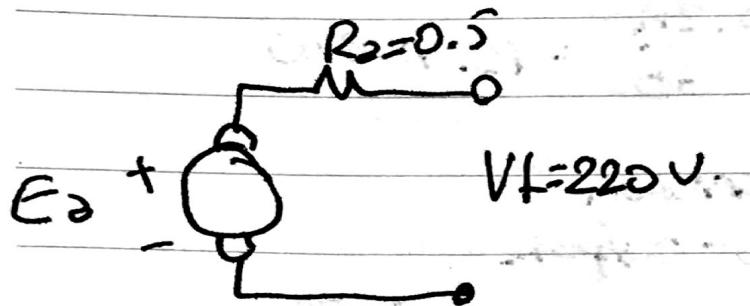
$$P_{out} + P_{field} + P_{arm} \\ = 200 + 0.2 \cdot (45.37)^2 \\ + 120 \cdot (1)^2 \\ = 732 W$$

$$\eta_g = \frac{5320 - 732}{5320} = 86.25\%$$

d) Overall efficiency

$$\eta_s = \frac{P_{out}}{P_{in}} = \frac{4588}{6000 + 120} = 75\% \\ \text{field of the generator}$$

(EE361-2015 Final Q4) (Munmer hce)



no load speed = 1500 rpm

b) no load, (no friction) $\Rightarrow I_d = 0$

$$E_d = V_f = 220V \text{ @ } 1500 \text{ rpm}$$

b) $T_L = 100 \text{ Nm} (\text{constant})$

$V_f = ?$ to drive it at 1500 rpm

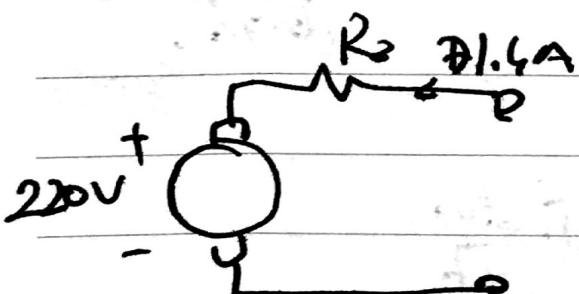
$$\underline{E_d = k_d \phi \cdot \omega = 220}$$

$$k_d \phi \cdot \frac{1500}{60} \cdot 2\pi = 220 \Rightarrow k_d \phi = \underline{\underline{1.4}}$$

$$T_e = T_L + T_{fric} = 100 + 0 = 100 \text{ Nm}$$

$$T_e = k_d \phi \cdot I_d = 100$$

$$1.4 \cdot I_d = 100 \Rightarrow I_d = \underline{\underline{71.4A}}$$



$$V_f = 220 + 71.4 \cdot 0.5 = 255.7V$$

or use the given eq.

$$\omega_r = \frac{V_f}{k_d \phi} - \frac{R_d}{(k_d \phi)^2} T_L$$

$$\frac{1500 \cdot 2\pi}{60} = \frac{V_f}{1.4} - \frac{0.5}{(1.4)^2} \cdot 100$$

$$V_f = 255.7V$$

Gross M

$$P_{output} = T_e \cdot w_r = T_L \cdot w_r + T_{friction} \cdot w_r$$

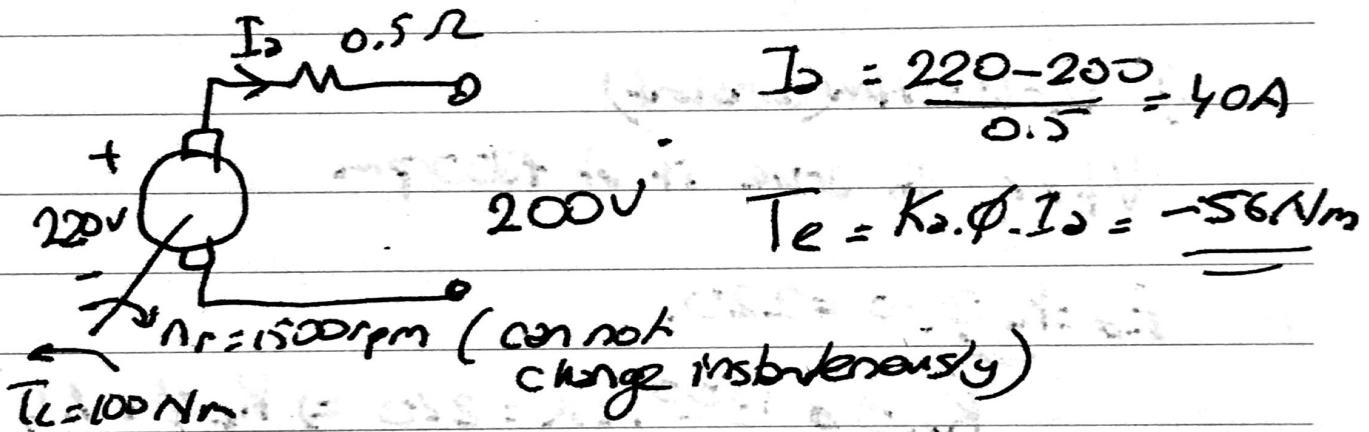
$$100 \cdot 1500 \cdot \frac{2\pi}{60} = 15.708 \text{ W}$$

or since there is no friction
gross mechanical power output

$$P_o = E_a \cdot I_a = 220 \cdot 71.4 = 15.708 \text{ W}$$

Part III)

V_f is suddenly reduced to 200V. $K_a \phi = 1.4$



Gross mechanical output power $P_m = T_e \cdot w_r = E_a \cdot I_d$

$$= 220 \cdot 40 = 8800 \text{ W}$$

↑
mechanical power converted to electrical form.

Operation mode: generator.

$$T_e - (T_{load} + T_{friction}) = J \cdot \frac{dw}{dt}$$

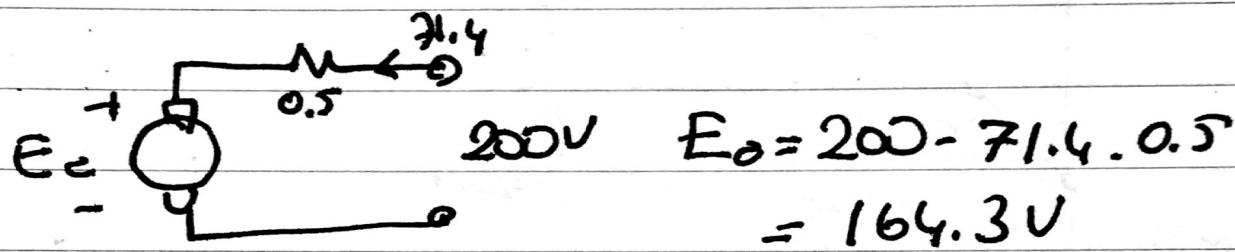
$$-56 - 100 = -156 \text{ Nm} = J \frac{dw}{dt}$$

↳ negative

decelerates and shaft's speed reaches zero steadily.

I_a is negative (generating mode) until $E_d = V_f = 200V$, from this point - the machine starts in the motoring mode, but the torque is still not enough. The speed continue to decrease until $T_e = T_{mech} = 100 \text{ Nm}$.

$$T = K_s \cdot \Phi \cdot I_a \Rightarrow I_a = 71.4 \text{ A}$$

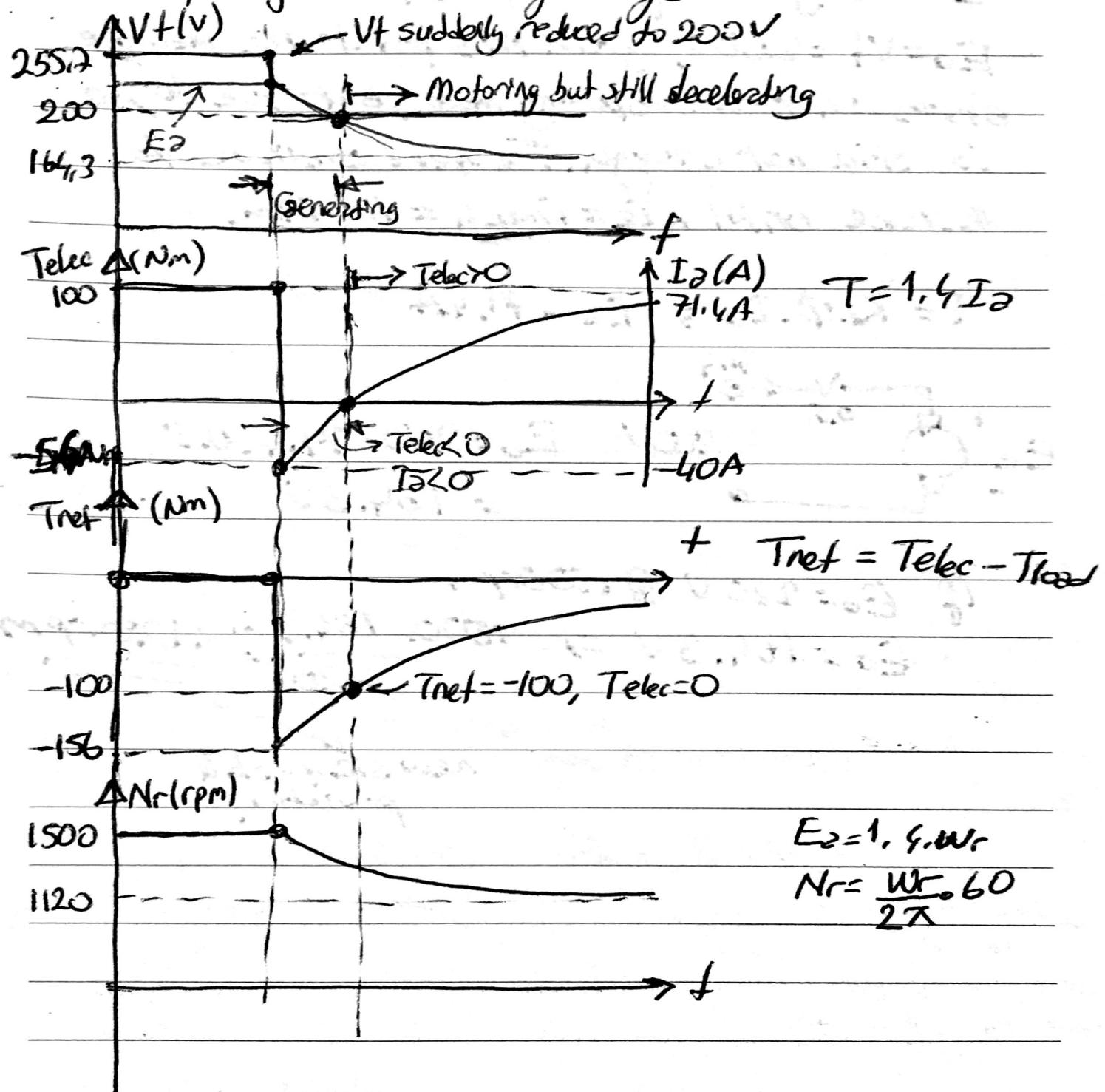


If $E_d = 220 \text{ V}$ @ 1500 rpm

$$E_d = 164.3 \text{ V} \Rightarrow 1500 \cdot \frac{164.3}{220} \approx \underline{\underline{1120 \text{ rpm}}}$$

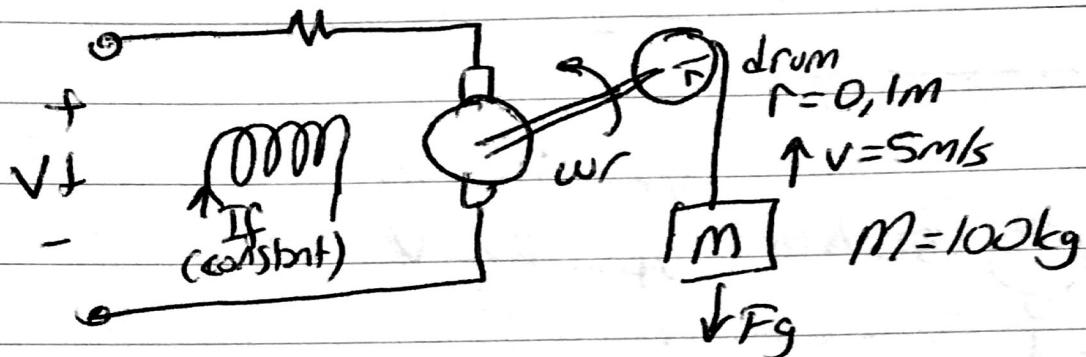
~~new steady state position~~

Graphs after terminal voltage change



Ex-3

A separately excited DC motor is operating in a crane hoist. Its field excitation is kept constant. $R_d = 0.5 \Omega$ $I_d = \underline{100A}$ are given.



2) Find the applied armature voltage (V_f) in order to rise (ascend) the load at a constant speed of $v = 5 \text{ m/s}$

\Rightarrow Since speed is constant, no accelerating $\Rightarrow T_{net} = J \cdot \frac{d\omega}{dt}$

$$T_{net} = 0 \Rightarrow T_{elec} = T_{load}$$

$$T_{load} = \frac{M \cdot g \cdot r}{F_g} = 100 \cdot 10 \cdot 0.1 = 100 \text{ Nm}$$

$$W_r \cdot r = V \leftarrow \text{linear speed}$$

\uparrow rotational speed.

$$W_r = \frac{5}{0.1} = 50 \text{ rad/s.}$$

$$N_r = \frac{50}{2\pi} \cdot 60 = 477.5 \text{ rpm}$$

$$T = K_d \cdot \phi \cdot I_d$$

$$E_d = K_d \cdot \phi \cdot W_r$$

$$100 = K_d \cdot \phi \Rightarrow E_d = 50V \quad (\text{motoring mode})$$

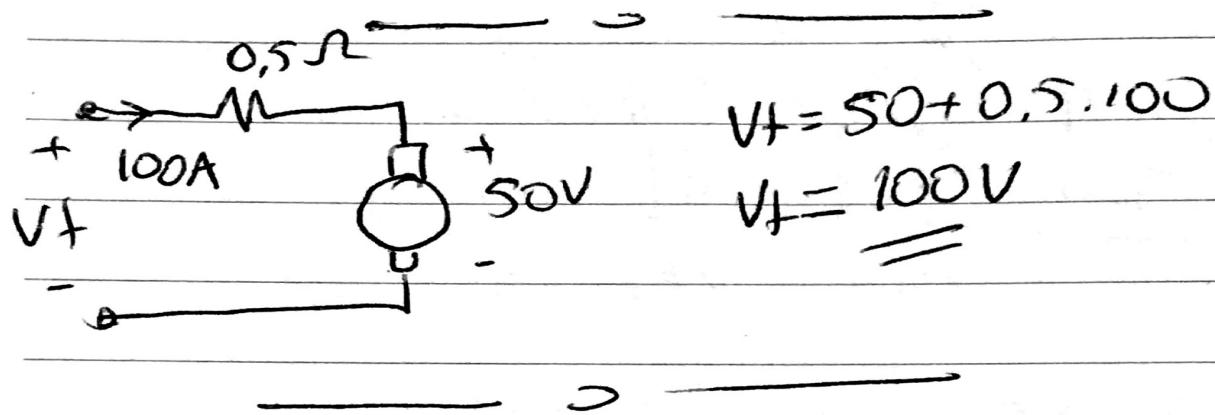
$$\underline{K_d \phi = 1}$$

Alternatively use energy conservation.

$$P_{\text{mech}} = F \cdot v = \underbrace{100 \cdot 10}_{F_g} \cdot 5 = \underline{\underline{5 \text{ kW}}}$$

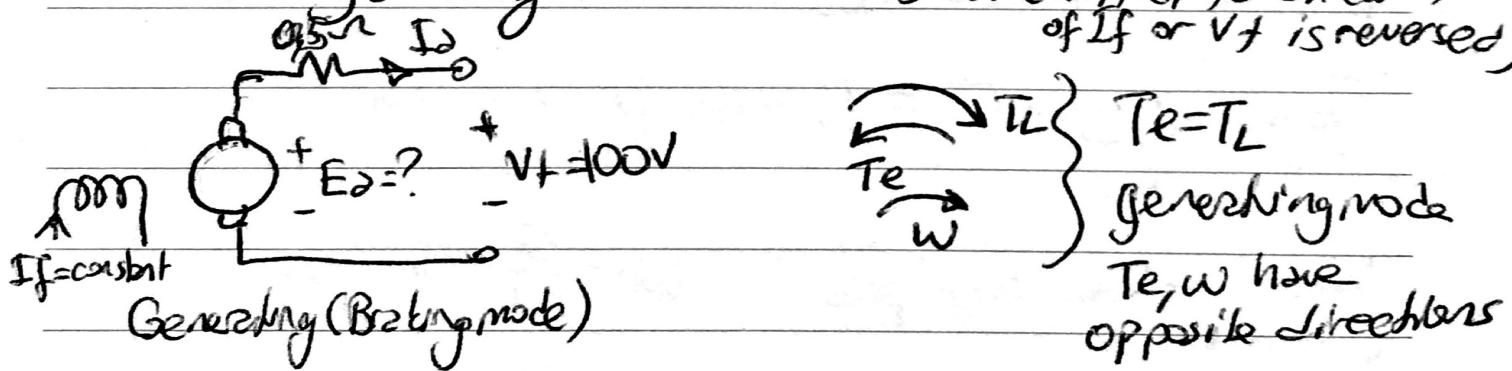
$$P_{(\text{motor-out})} = E_d \cdot I_d = \underline{\underline{E_d \cdot 100 = 5 \text{ kW}}}$$

$$\underline{\underline{E_d = 50 \text{ V}}}$$



b) Now, assume the motor lowers (descends) the load at constant speed. (which is called overhauling).

Find the speed at which the DC machine can over haul the load by assuming that V_f remains same. (but note that if I_f or V_f is reversed)



$$T = K_s \cdot \Phi \cdot I_d$$

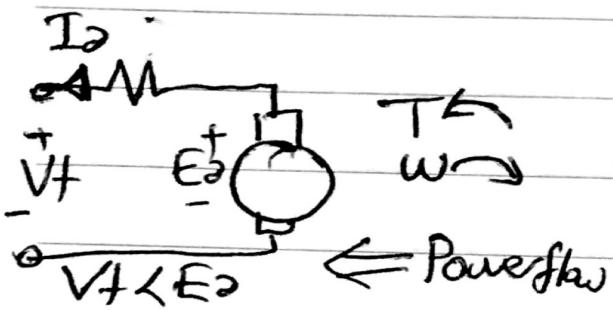
$I_d = 100 \text{ A}$ (opposite direction).

$$\begin{aligned} E_d &= V_f + R_s I_d \\ &= 100 + 0.5 \cdot 100 \\ &= \underline{\underline{150 \text{ V}}} \end{aligned}$$

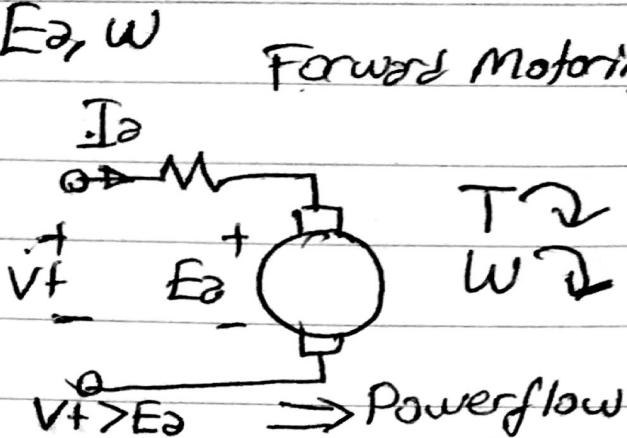
$$\begin{aligned} E_d &= K_s \cdot \Phi \cdot \underline{\underline{w}} \\ w_f &= 150 \text{ rad/sec} \\ n_n &= 1432.5 \text{ rpm} \end{aligned}$$

4 Quadrant Operation

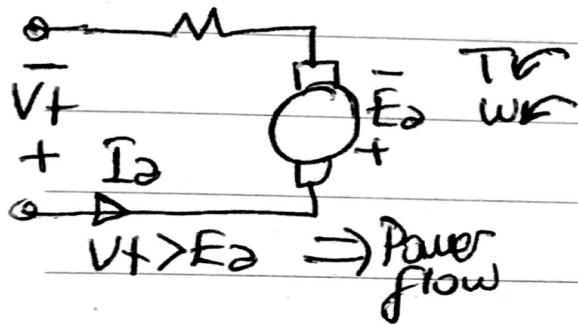
Forward Generating



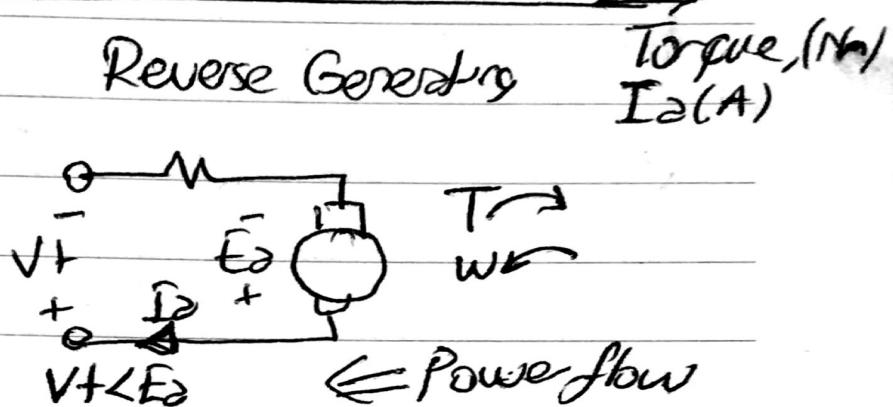
Forward Motoring



Reverse Motoring



Reverse Generating



Torque, (Nm)
 $I_a(A)$