

A tale of two negative results

Dhruv Batra



three

A tale of ~~two~~ negative results

Dhruv Batra



three negative-ish

A tale of two ~~negative~~ results

Dhruv Batra



three negative-ish

A tale of two ~~negative~~ results

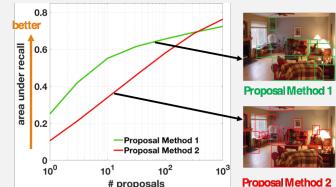
and a rant about vision reviewing!

Dhruv Batra

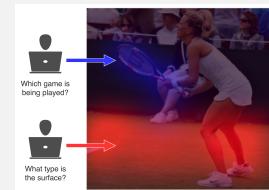


Outline

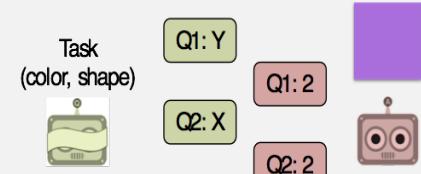
Object-Proposal Evaluation
Protocol is ‘Gameable’ [CVPR ‘16]



Human Attention in VQA:
Do Humans and Deep Networks
Look at the Same Regions? [EMNLP ‘16]



Natural Language Does Not Emerge
‘Naturally’ in Multi-Agent Dialog [EMNLP ‘17]



Rant about Vision vs NLP reviewing!

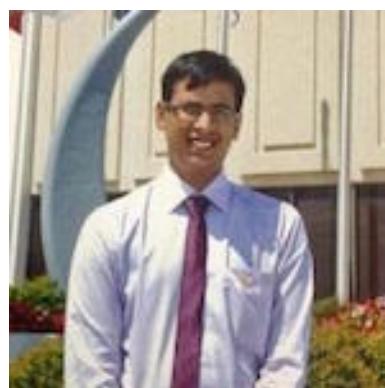


Object-Proposal Evaluation Protocol is ‘Gameable’

[CVPR ‘16]



Neelima Chavali*



Harsh Agrawal*



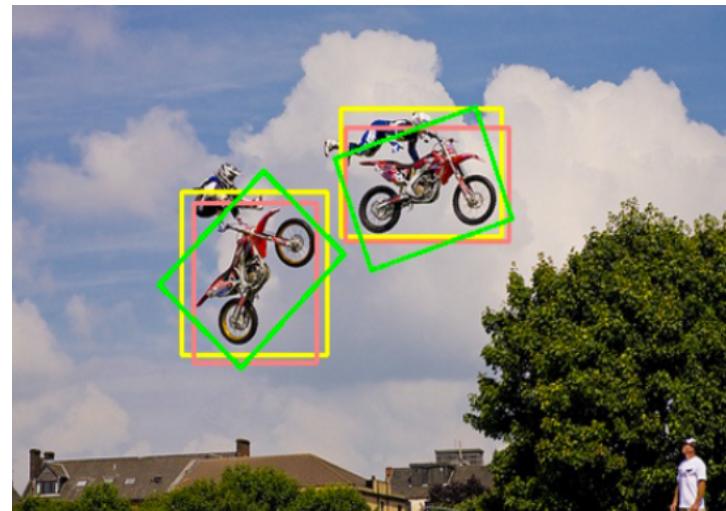
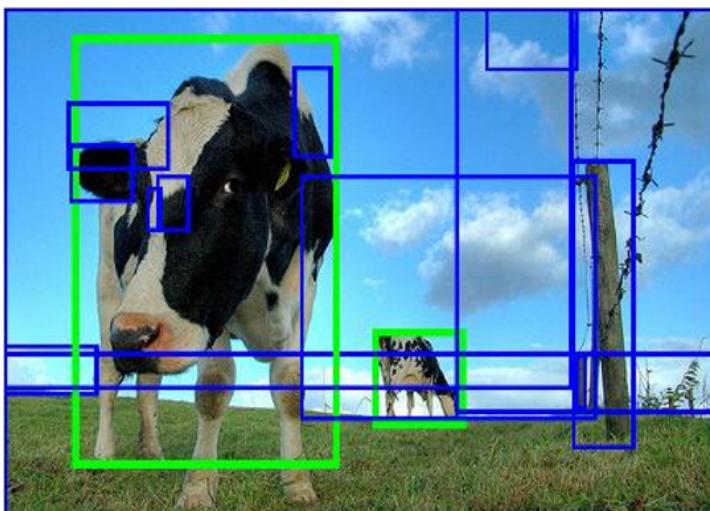
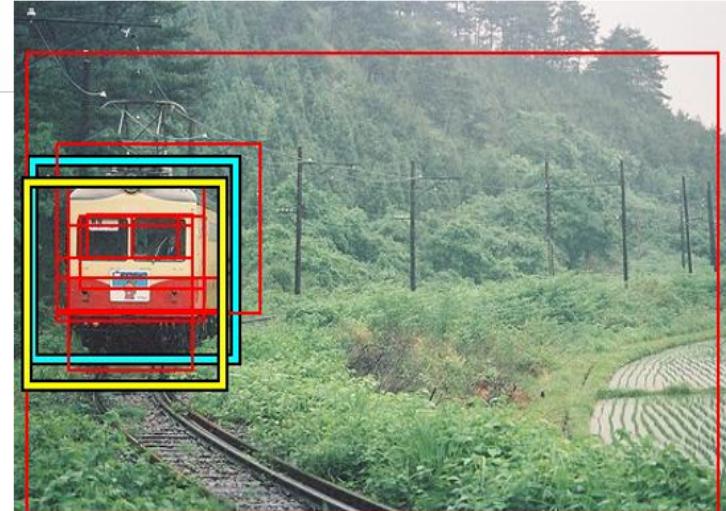
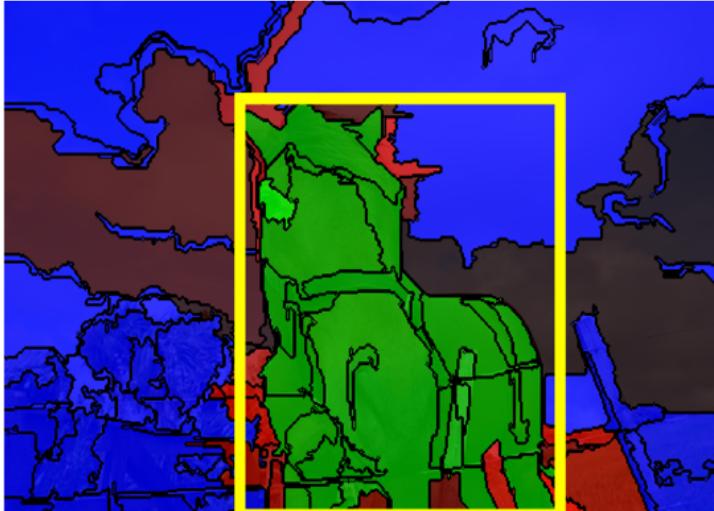
Aroma Mahendru*



Dhruv Batra

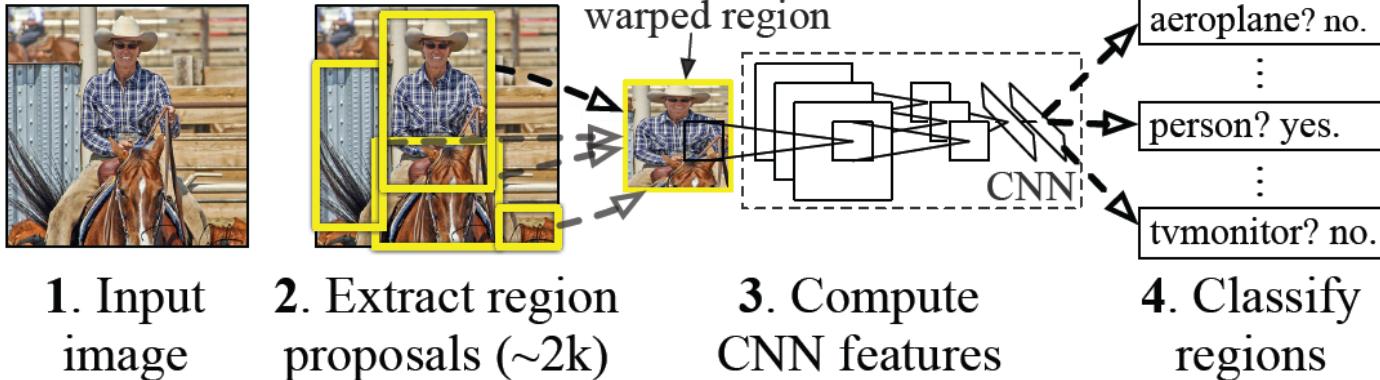
What are object proposals?

A candidate set of regions or boxes that may contain an object.

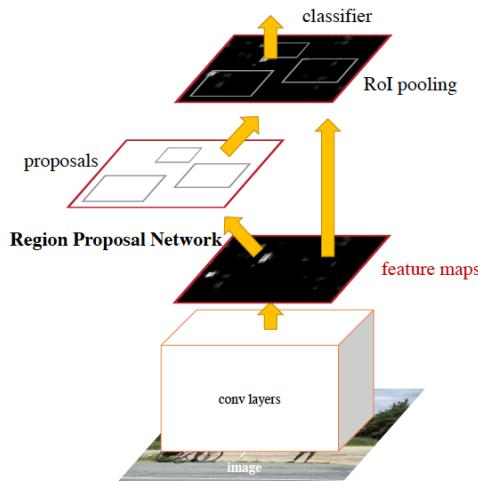


Pipeline: R-CNN

R-CNN: *Regions with CNN features*



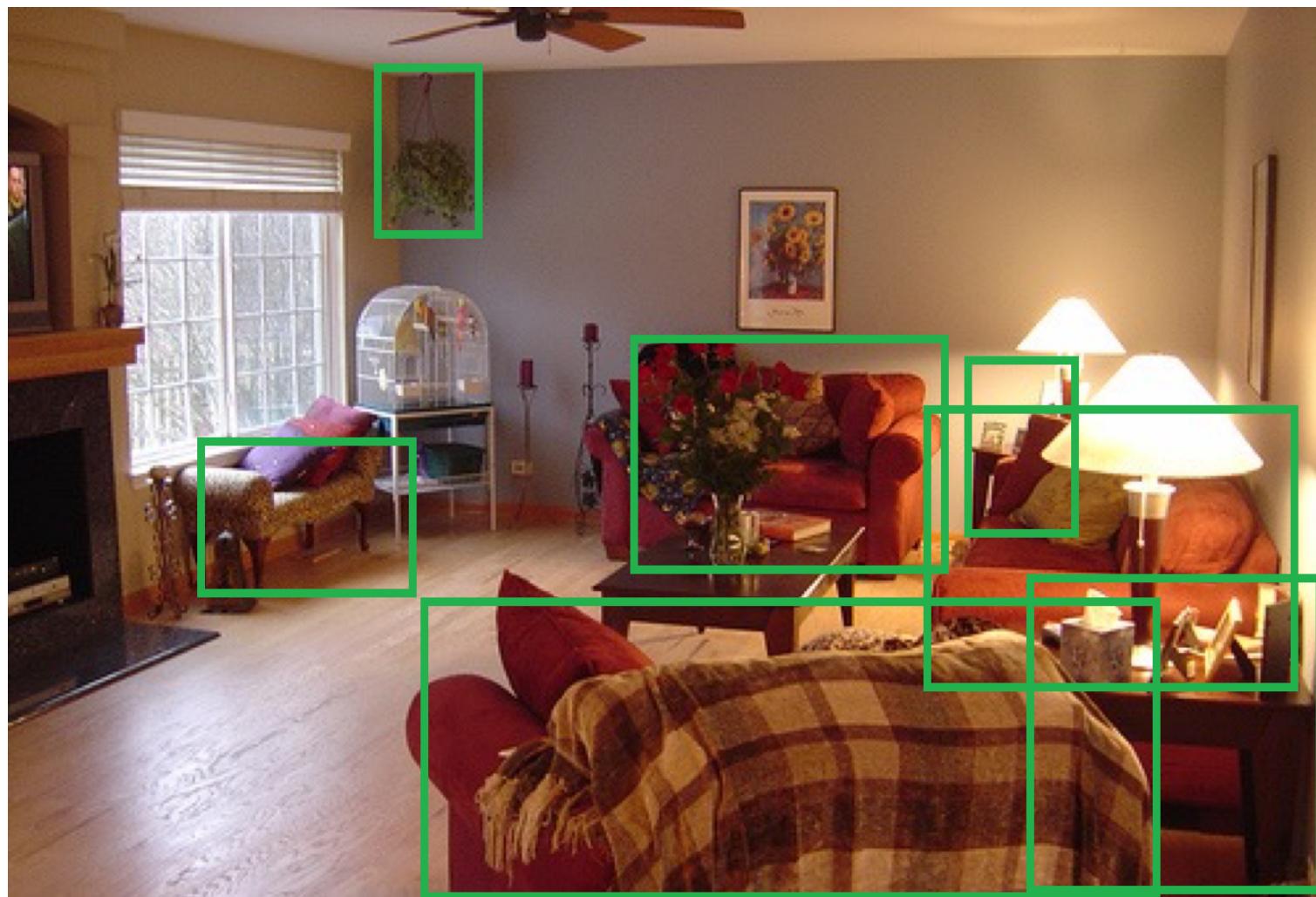
End-to-End: Faster R-CNN



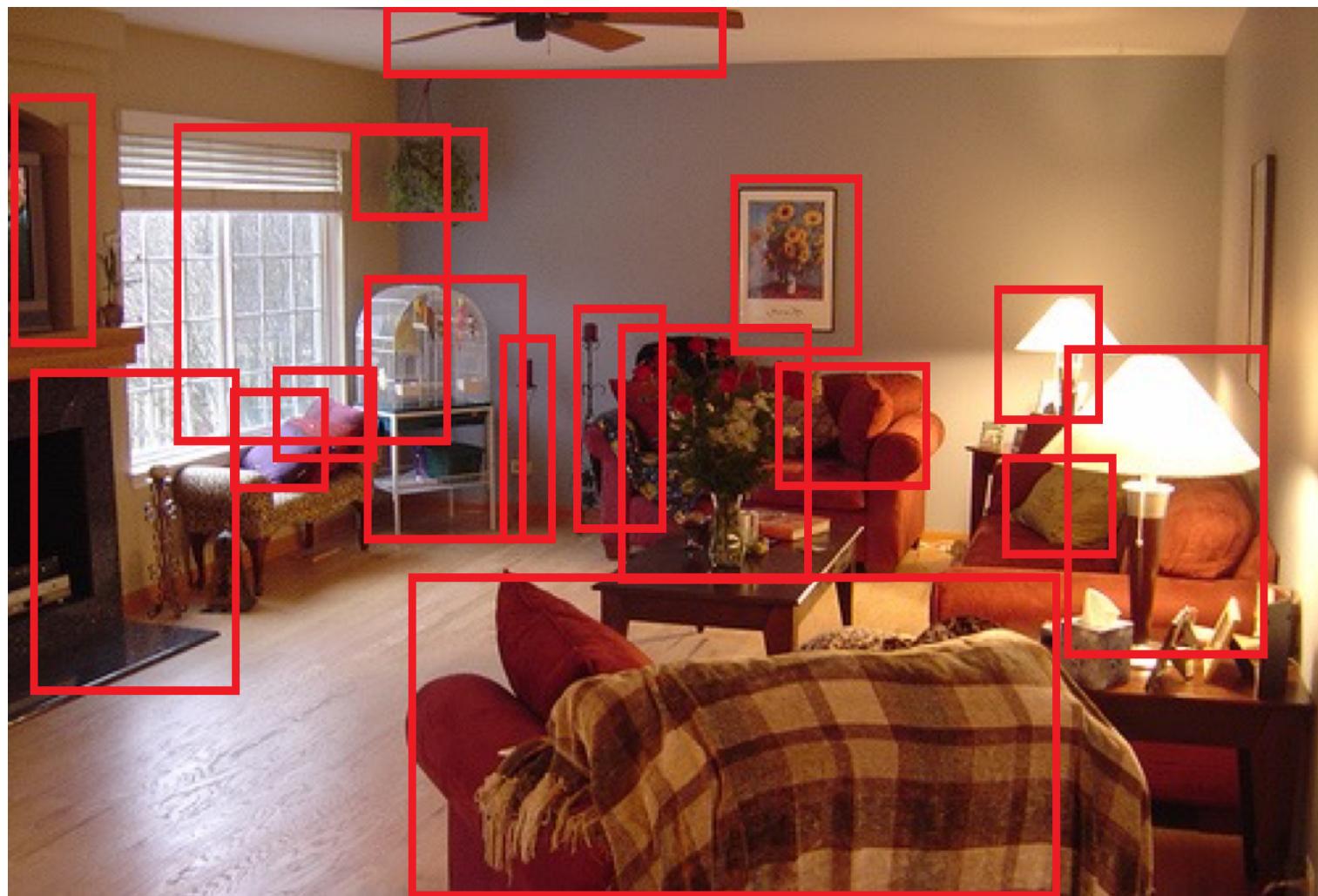
Thought Experiment



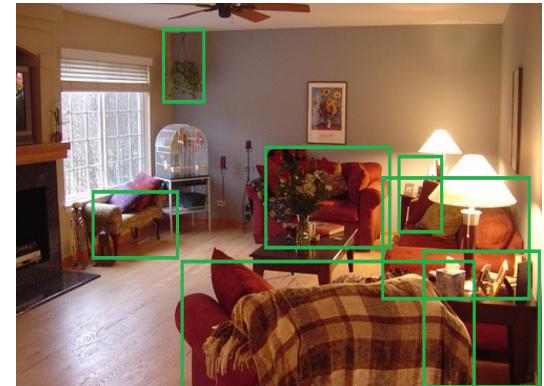
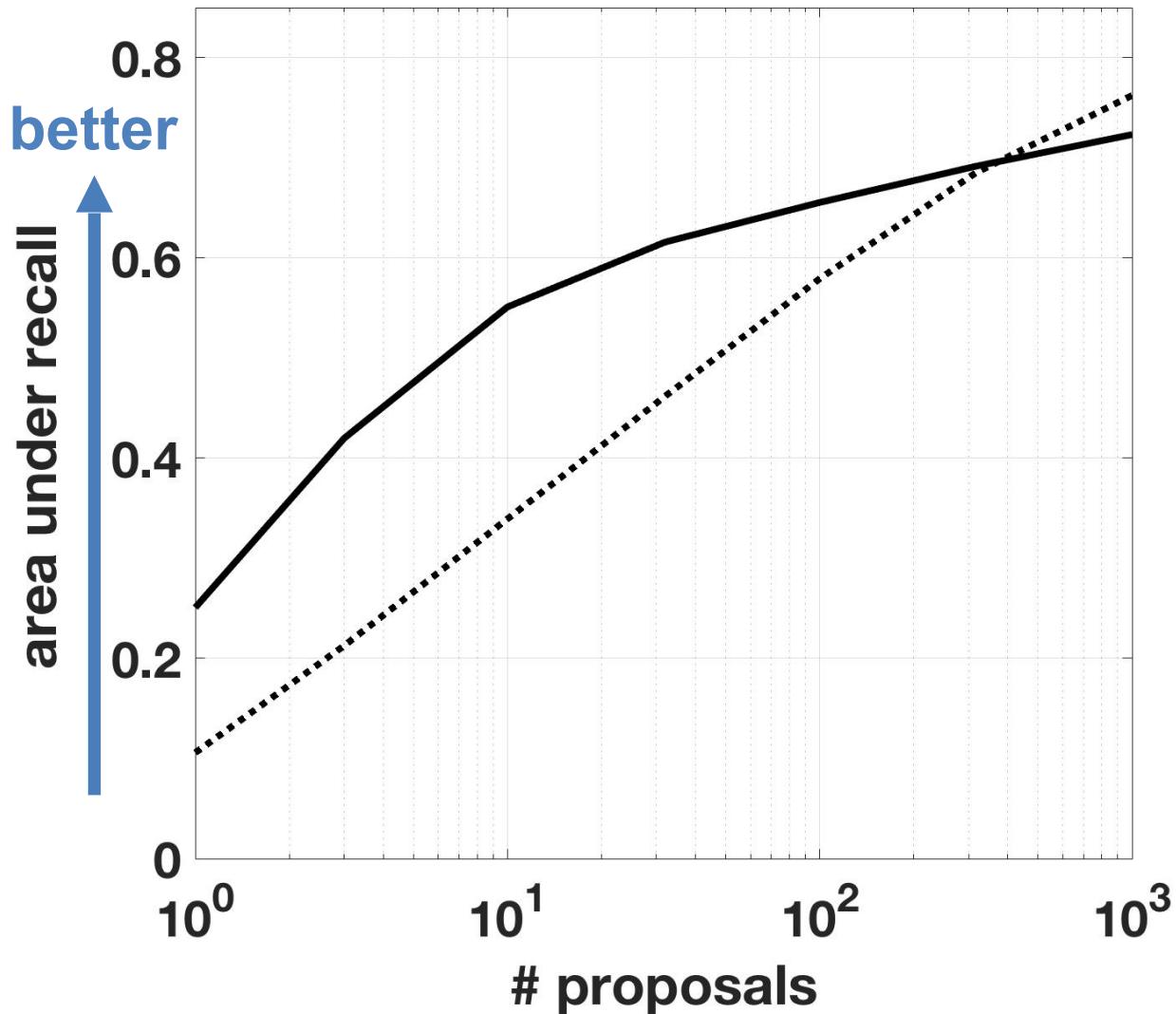
Thought Experiment: Proposal Method 1



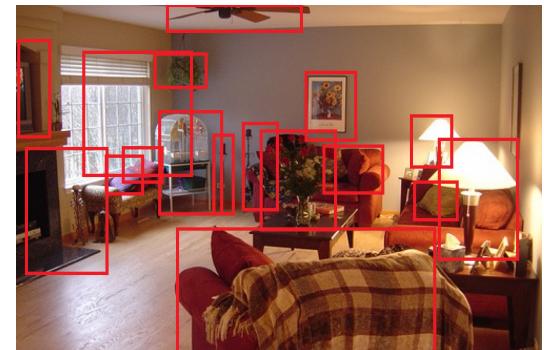
Thought Experiment: Proposal Method 2



Which is better?

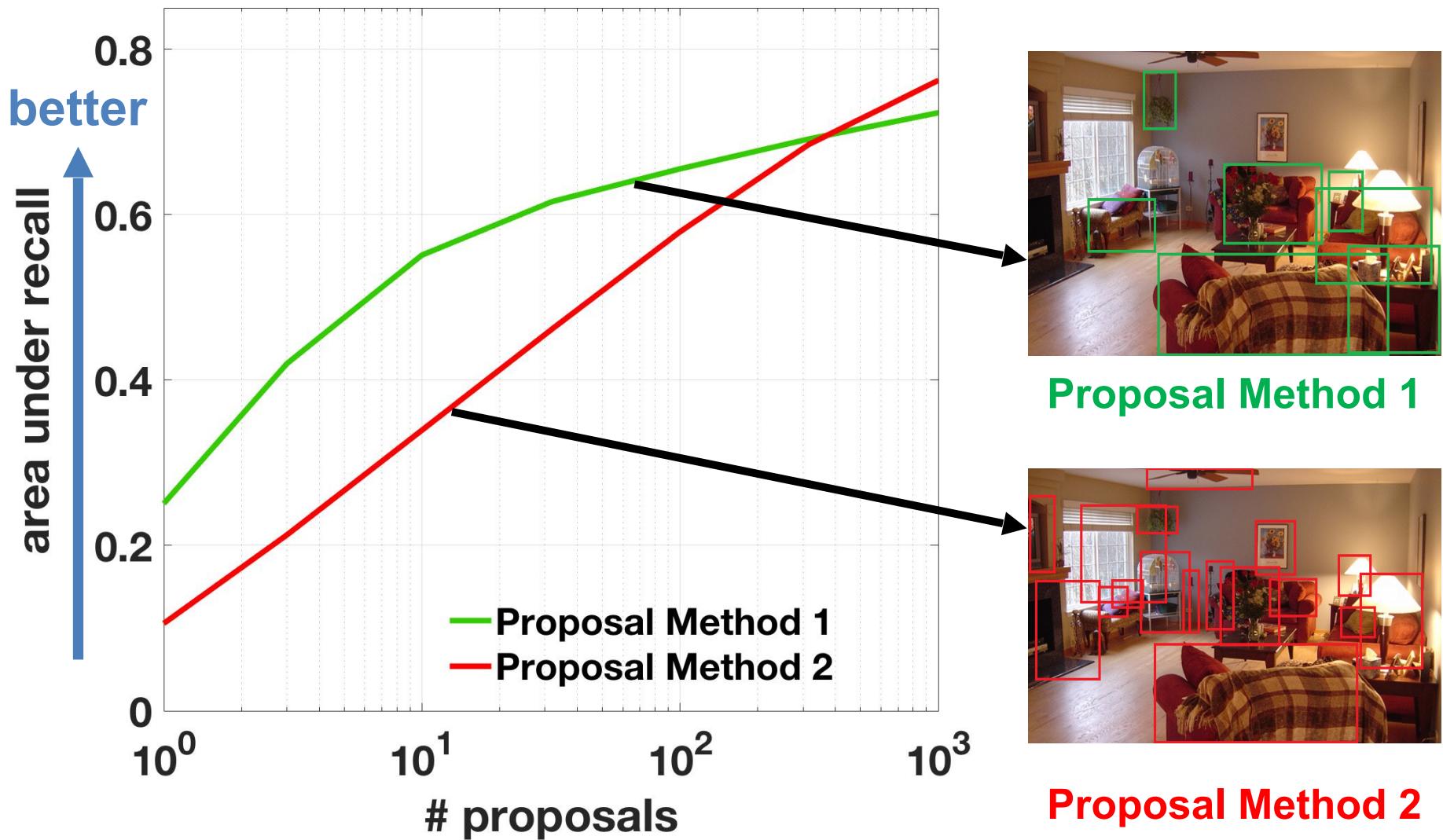


Proposal Method 1

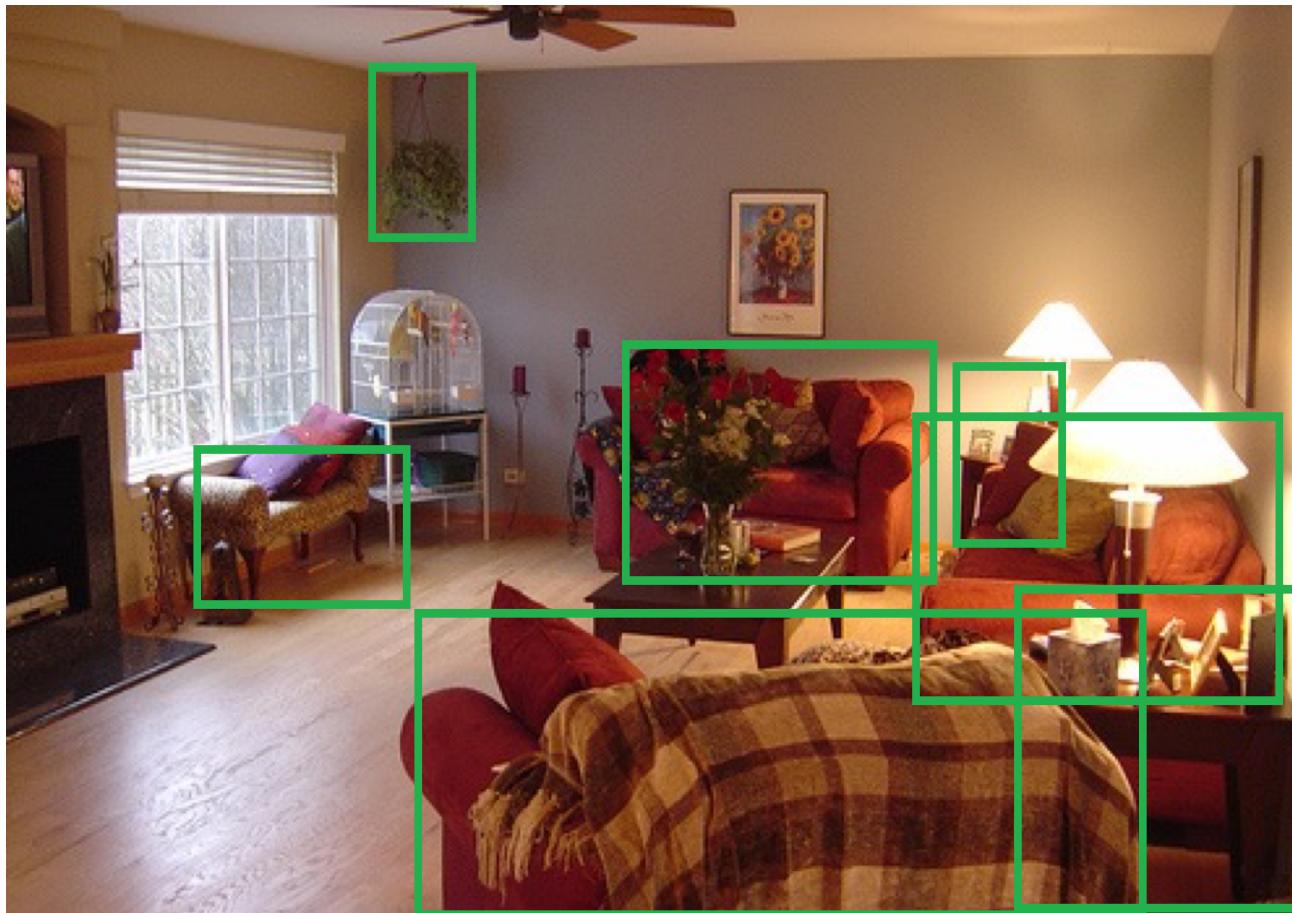


Proposal Method 2

Think Again!

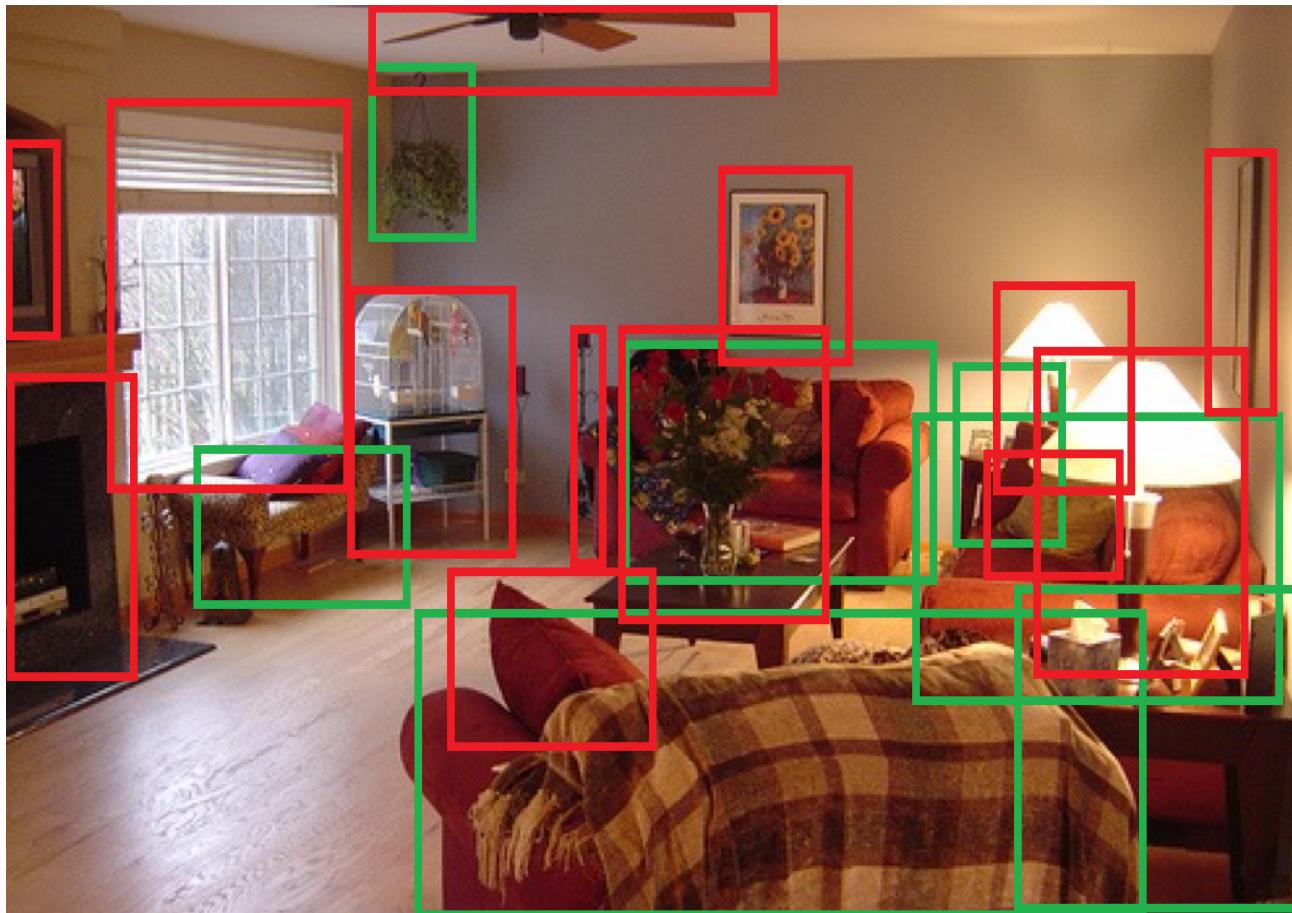


What the ground-truth contains



- Table
- Sofa
- Potted Plant

What the ground-truth is missing



- Table
- Sofa
- Potted Plant
- Picture Frame
- Lamp
- Fireplace
- Window
- Cushion
- Fan

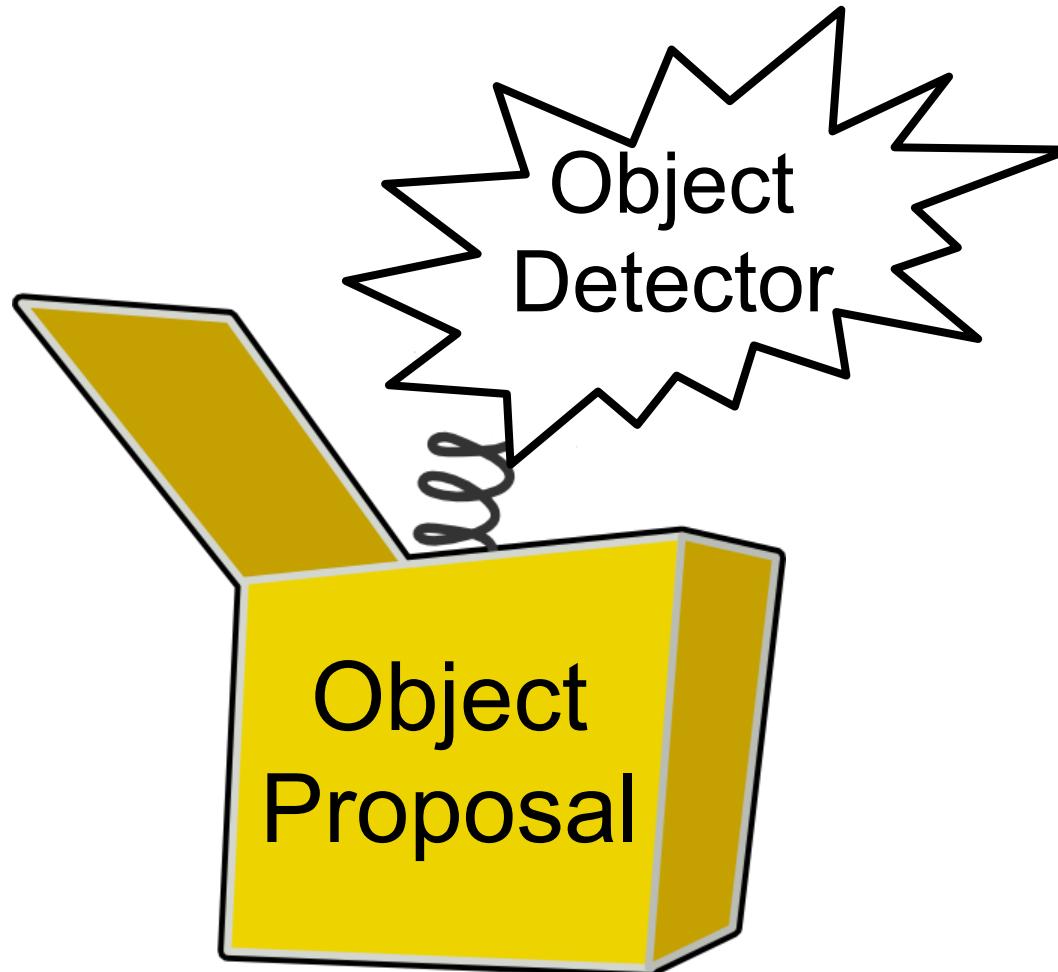
How to game the protocol?

Detector Masquerading as Proposals (DMP)



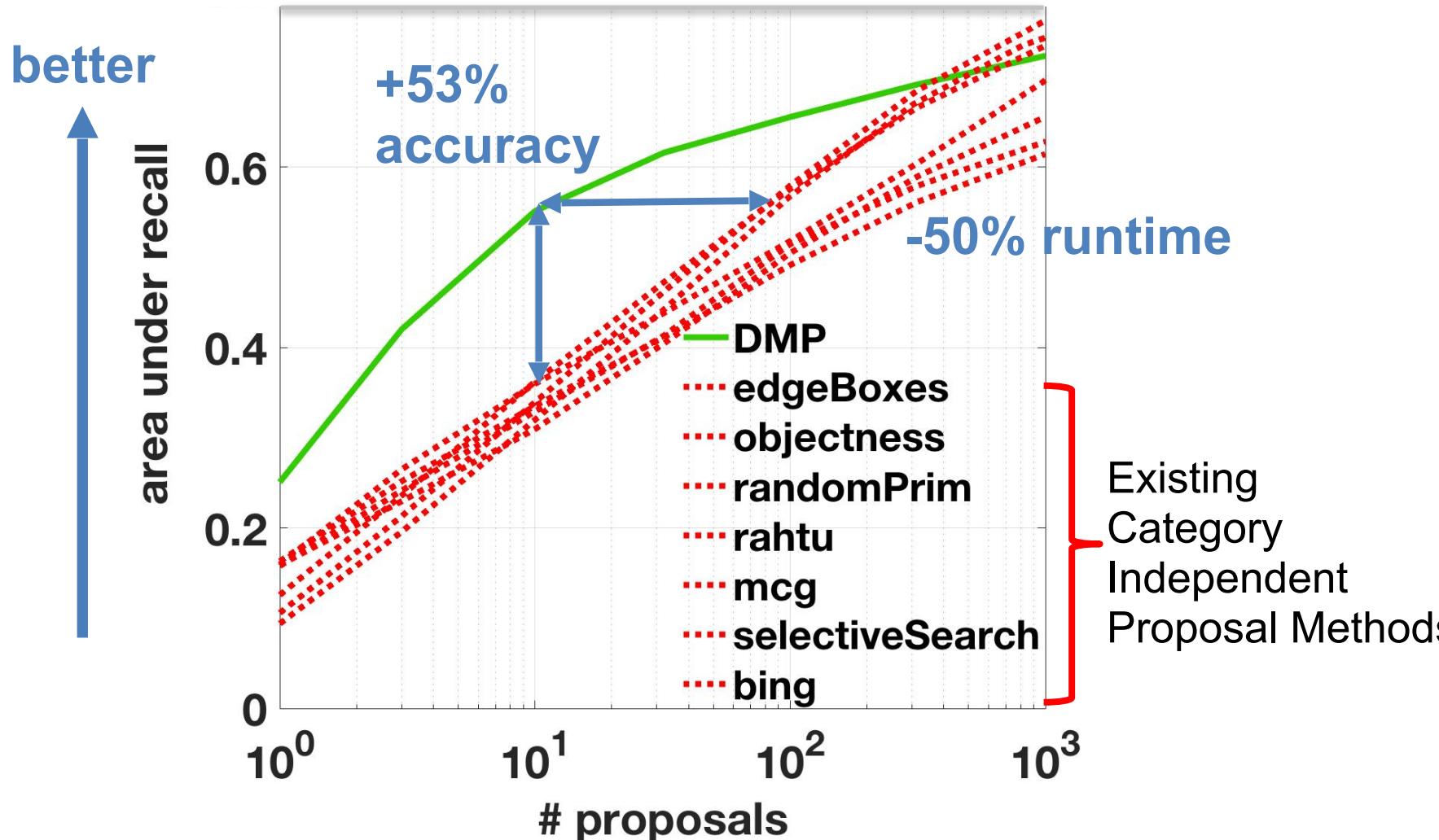
How to game the protocol?

Detector Masquerading as Proposals (DMP)



How to game the protocol?

Detector Masquerading as Proposals (DMP)

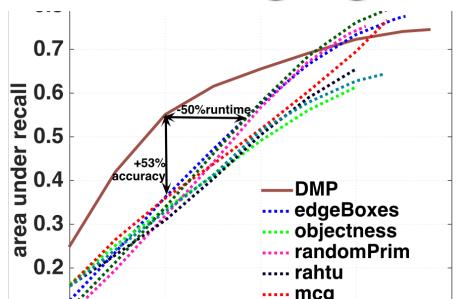


4. A Thought Experiment: How to Game the Evaluation Protocol

Let us conduct a thought experiment to demonstrate that the object proposal evaluation protocol can be ‘gamed’.

Imagine yourself reviewing a paper claiming to introduce a new object proposal method – called DMP.

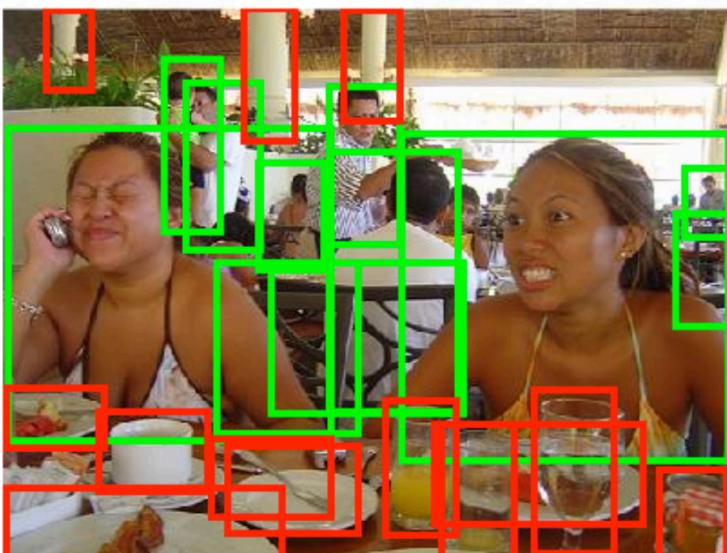
Before we divulge the details of DMP, consider the performance of DMP shown in Fig. 3 on the PASCAL VOC 2010 dataset, under the AUC-vs.-#proposals metric.



So what is our proposed state-of-art technique DMP?
It is a mixture-of-experts model, consisting of 20 experts, where each expert is a deep feature (fc7)-based [61] objectness detector. At this point, you, the savvy reader, are probably already beginning to guess what we did.

Contributions

- Alleviating the ‘game-ability’ by:
 - Evaluation on fully annotated dataset
 - Cross dataset evaluation on densely annotated datasets
 - Measuring bias capacity



Cloud-CV / [object-proposals](#)

Watch 32 ⭐ Star 103 Fork 74

Repository containing wrapper to obtain various object proposals easily

242 commits 3 branches 0 releases 9 contributors

Branch: master New pull request Find file Clone or download

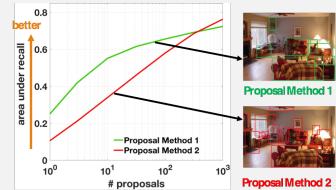
abshkdz committed on GitHub Merge pull request #36 from abshkdz/lpo ... Latest commit 597a895 on Feb 16

File	Description	Time
demo_img	Adding demo script	3 years ago
dependencies	Adds vlfeat MEX compiled binaries; Being used by `rantalankilaSegments`	2 years ago
edgeBoxes	Removes compiled MEX binaries from git	2 years ago
endres/proposals	Removes compiled MEX binaries from git	2 years ago
evaluation-metrics	Update evaluateABO.m	2 years ago
gop_1.3	Fixes namespace issues for `Proposal` and `Oversegmentation` (LPO & GOP)	2 years ago
jsonlab_1.0beta	Adding JSON decoding/encoding library	3 years ago

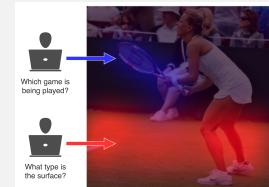
PASCAL-Context Instance
Annotations

Outline

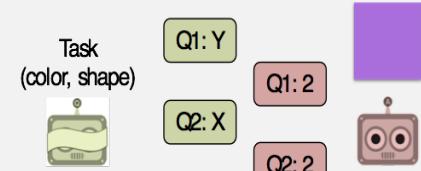
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Rant about Vision vs NLP reviewing!



Human Attention in VQA: Do Humans & Deep Networks Look at the Same Regions?

[EMNLP '16]



Abhishek Das*



Harsh Agrawal*



Larry Zitnick



Devi Parikh



Dhruv Batra

Visual questions target different image regions

Which game is being played?

What type is the surface?



Image from MS-COCO [Lin et al., 2014]

Visual questions target different image regions

Which game is being played?



What type is the surface?

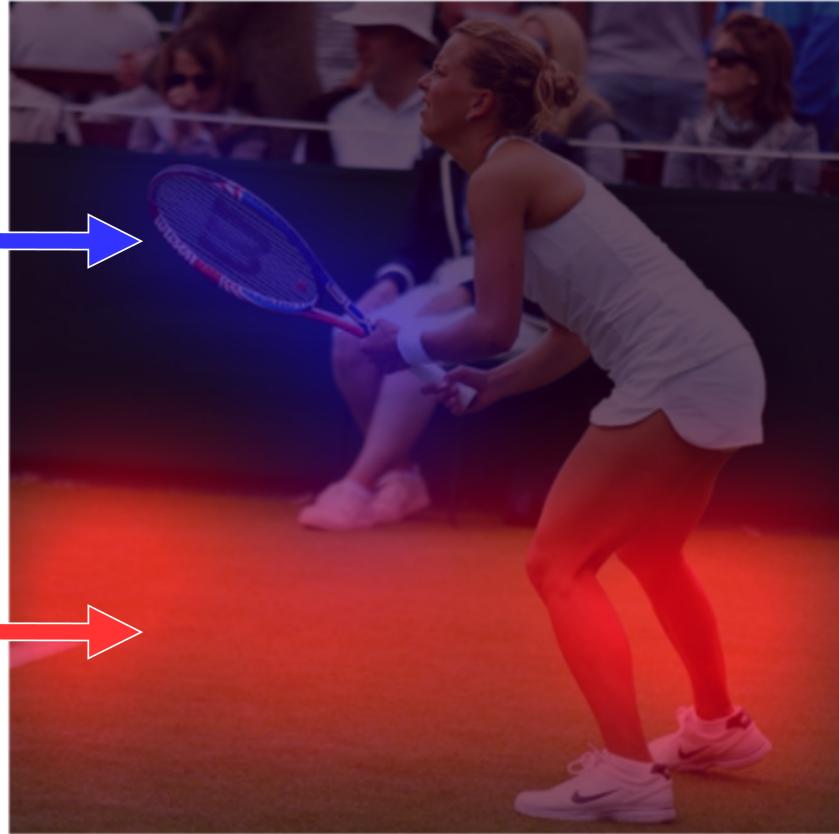
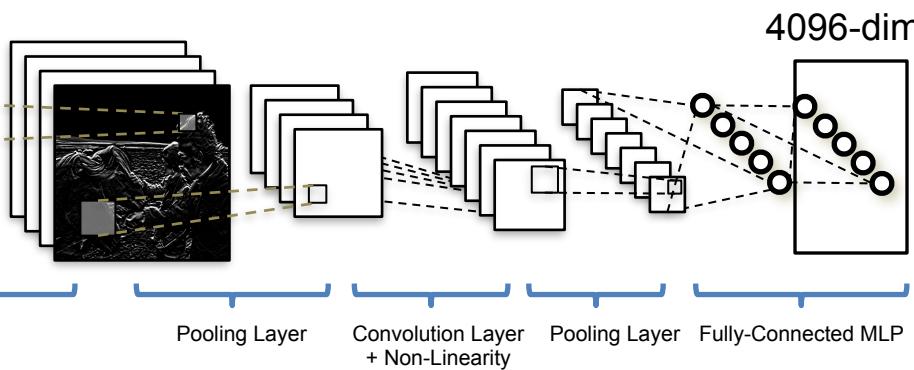


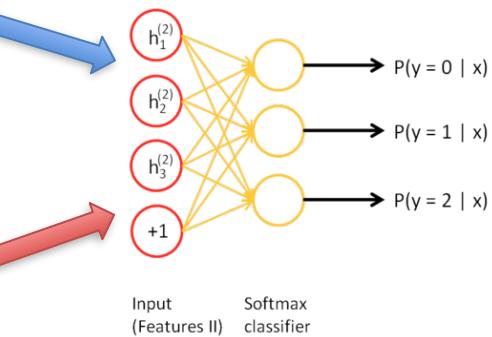
Image from MS-COCO [Lin et al., 2014]

2-Channel VQA Model

Image Embedding (VGGNet)

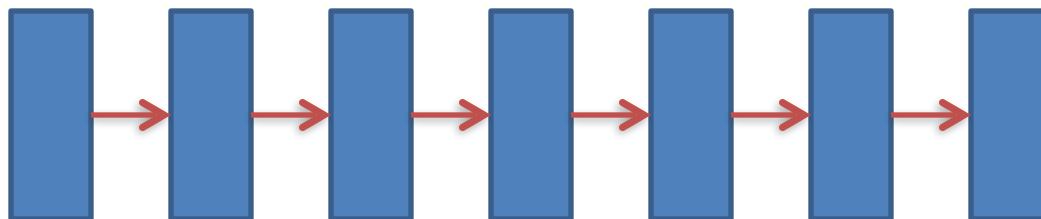


Neural Network
Softmax
over top K answers



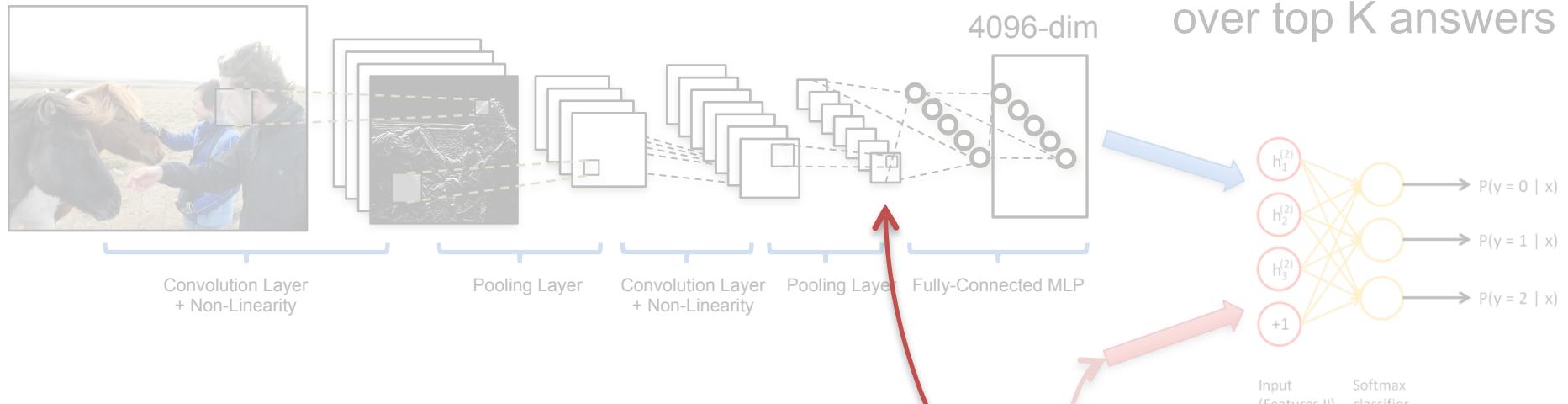
Question Embedding (LSTM)

“How many horses are in this image?”



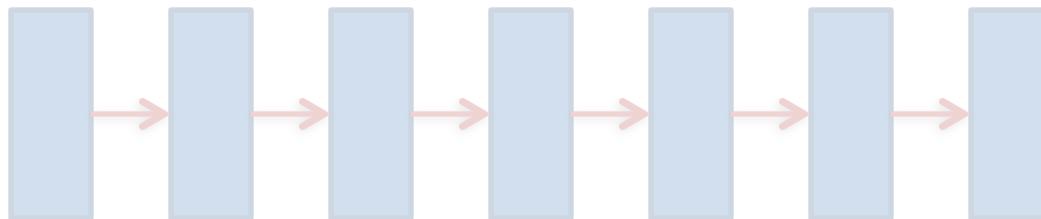
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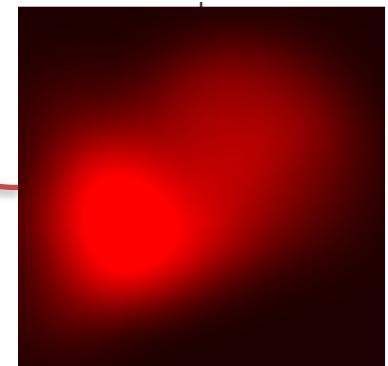


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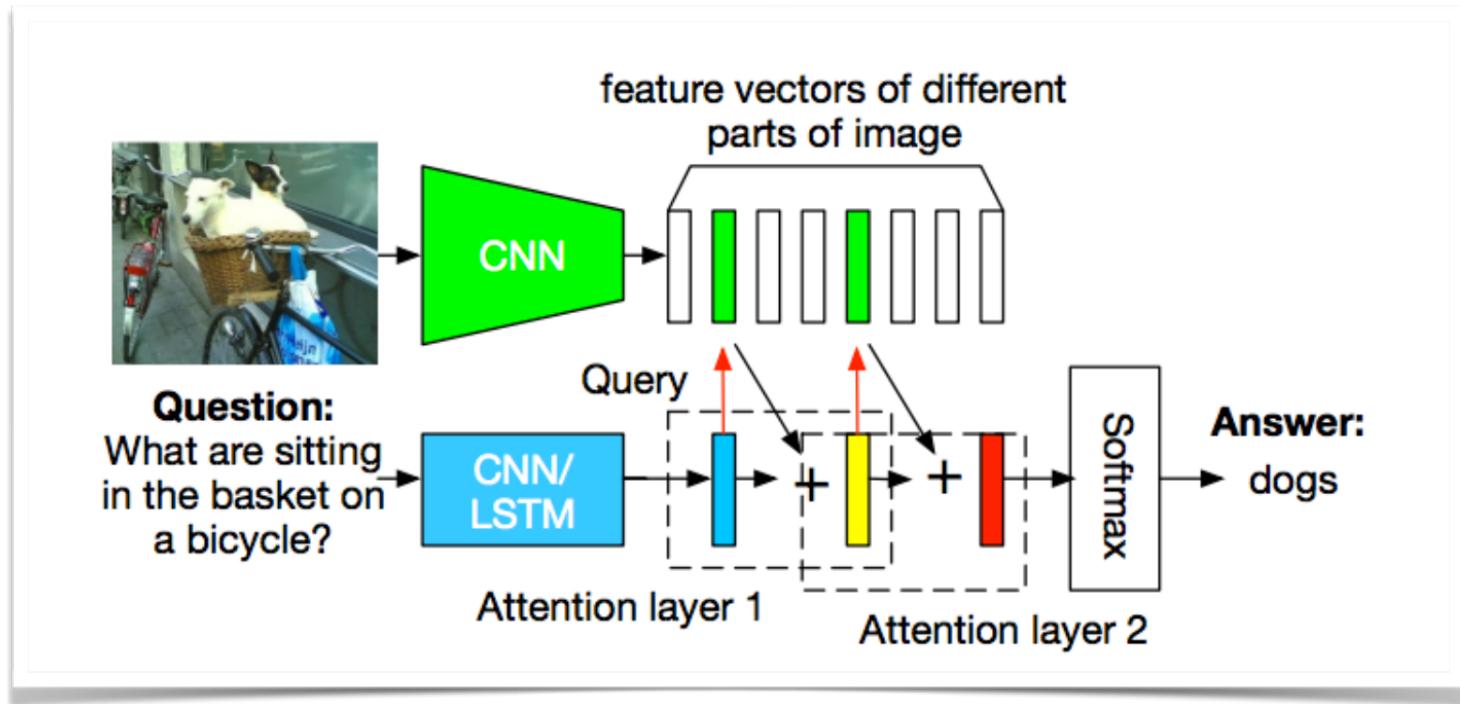
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Attention Map

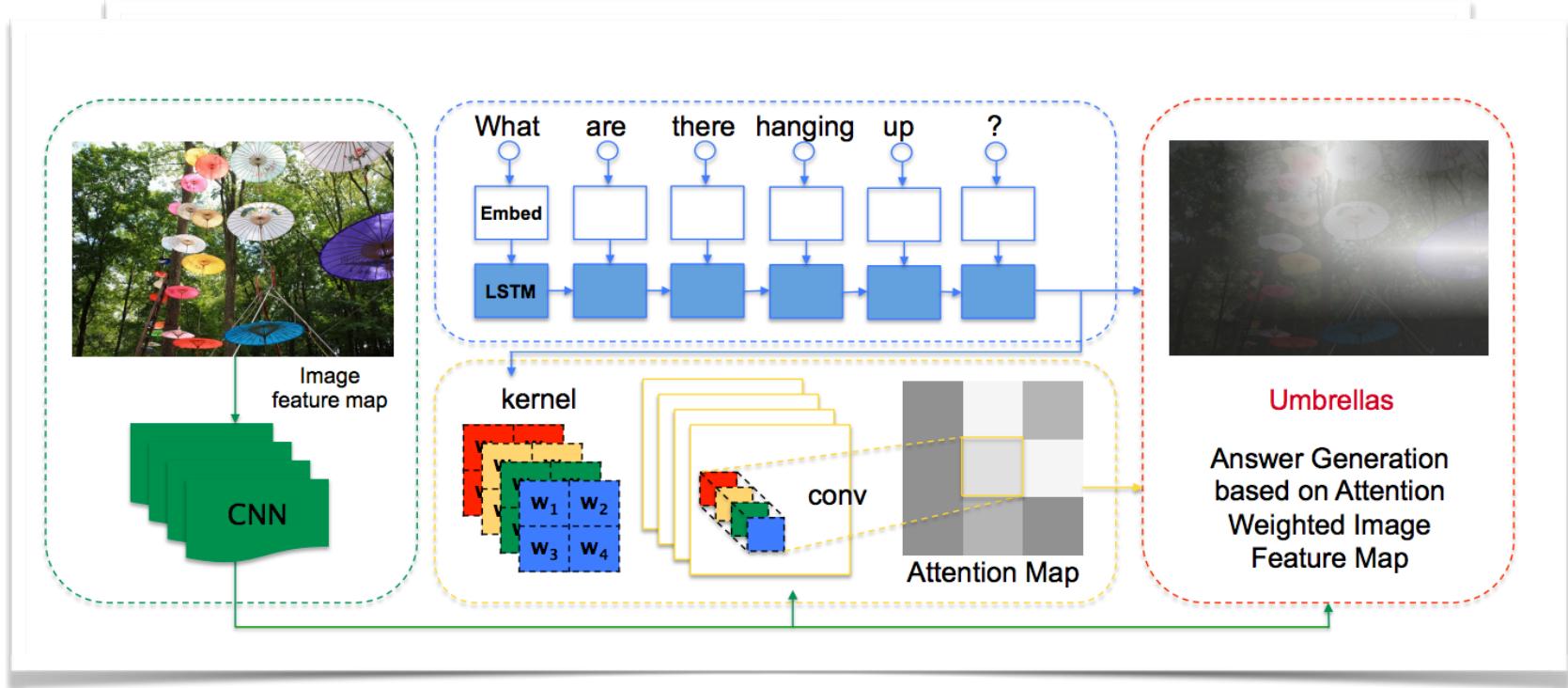


Attention-based VQA models



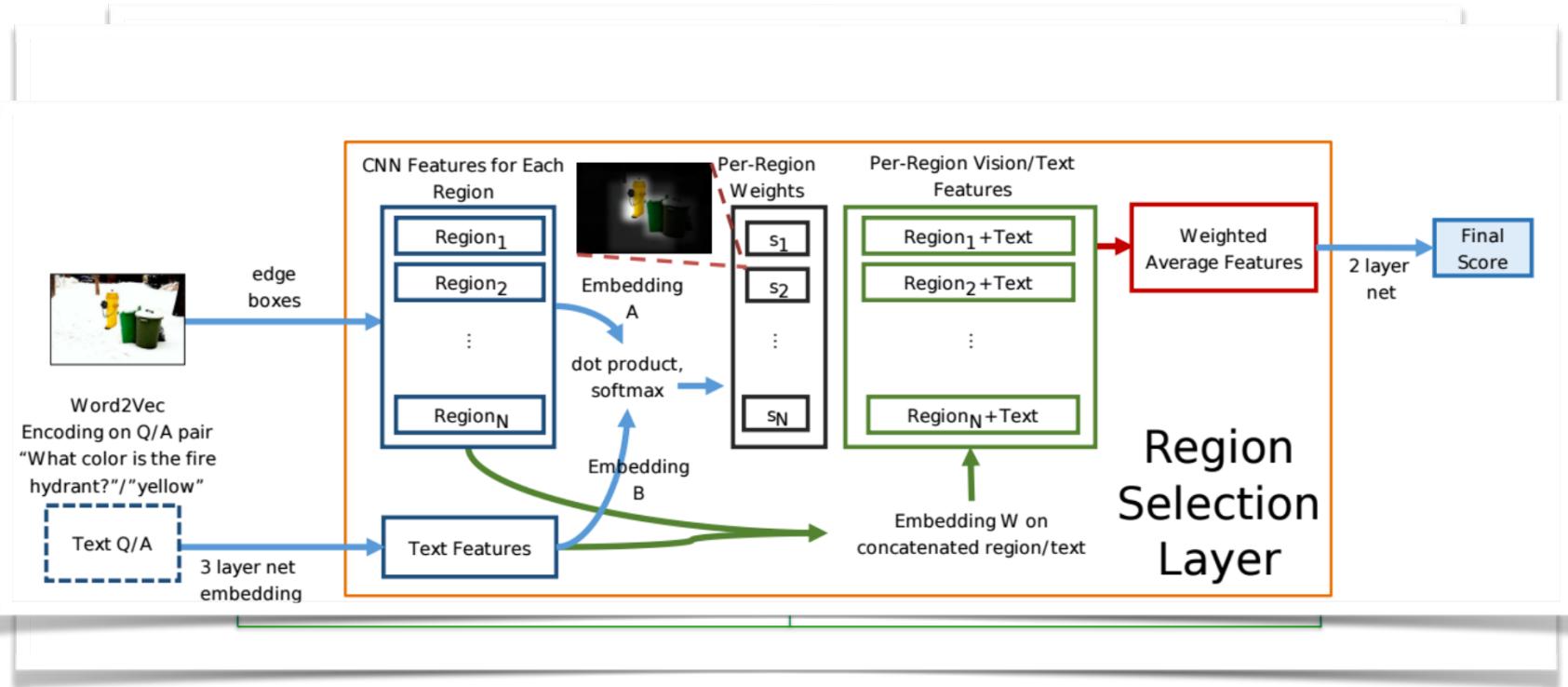
[Yang et al., CVPR16]

Attention-based VQA models



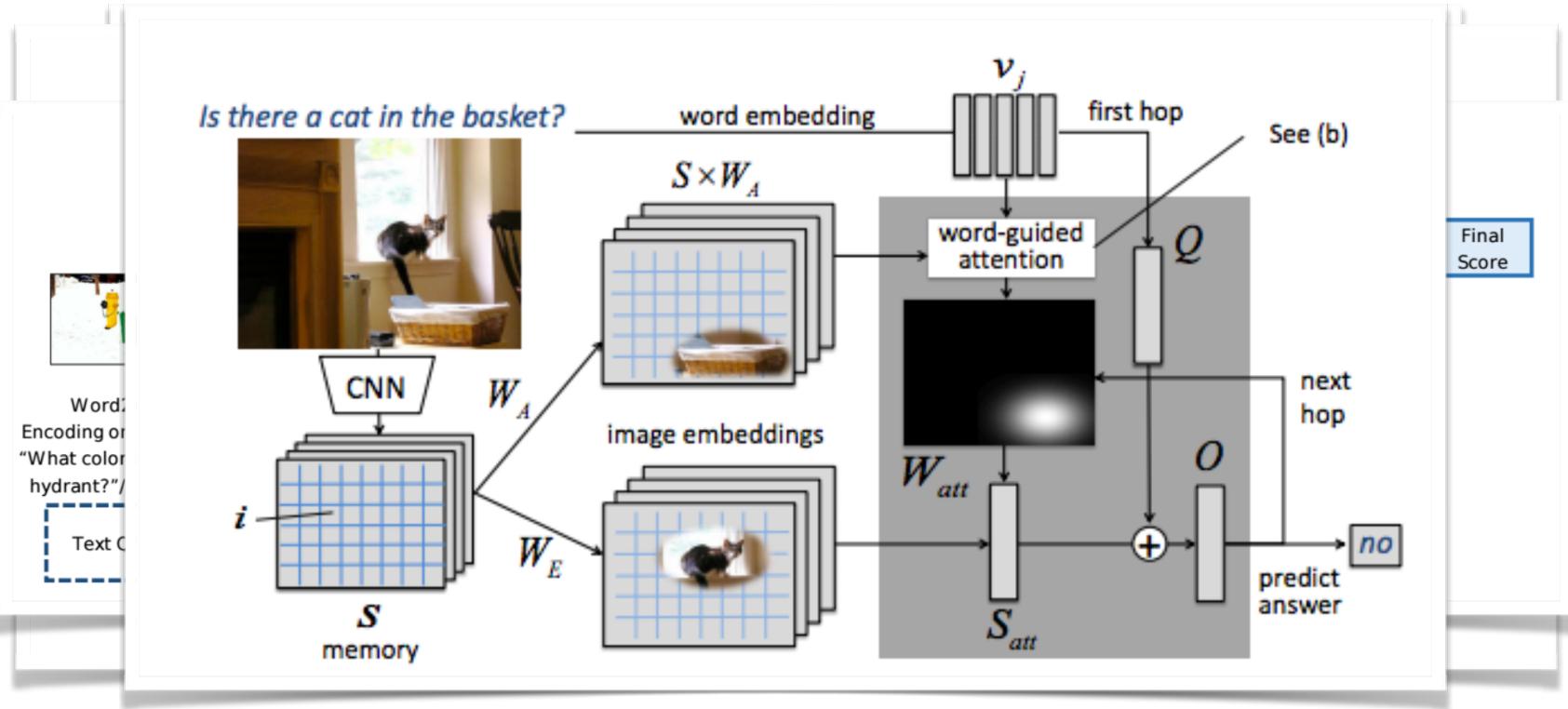
[Chen et al., 2015]

Attention-based VQA models



[Shih et al., CVPR16]

Attention-based VQA models



[Xu et al., 2015]

Attention-based VQA models



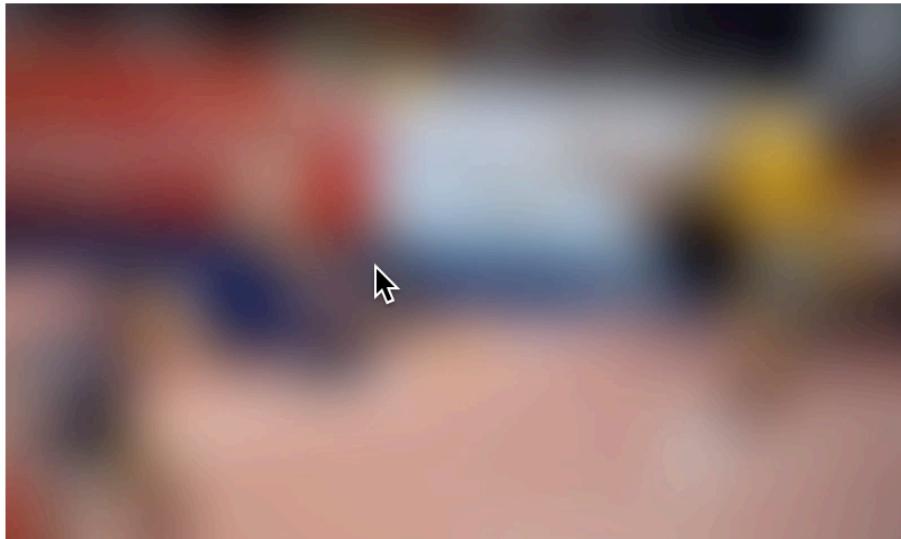
[Yang et al., CVPR16]

- Few qualitative examples
- Nothing to compare with
- No ‘gold standard’

Where do humans choose to look to answer visual questions?

VQA-HAT (Human ATtention)

Question: How many players are visible in the image?

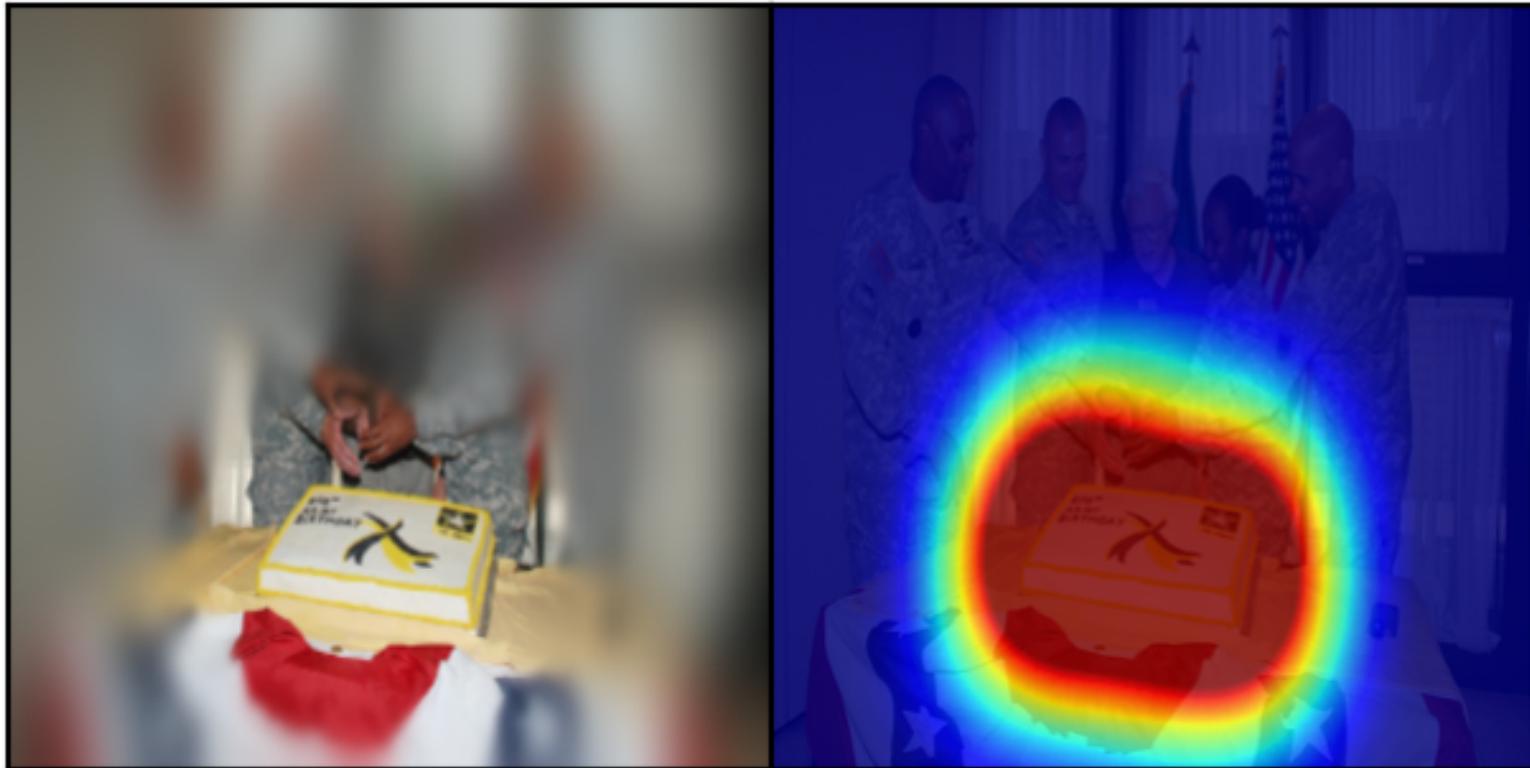


BLUR IMAGE

Answer:

3

VQA-HAT (Human ATtention)



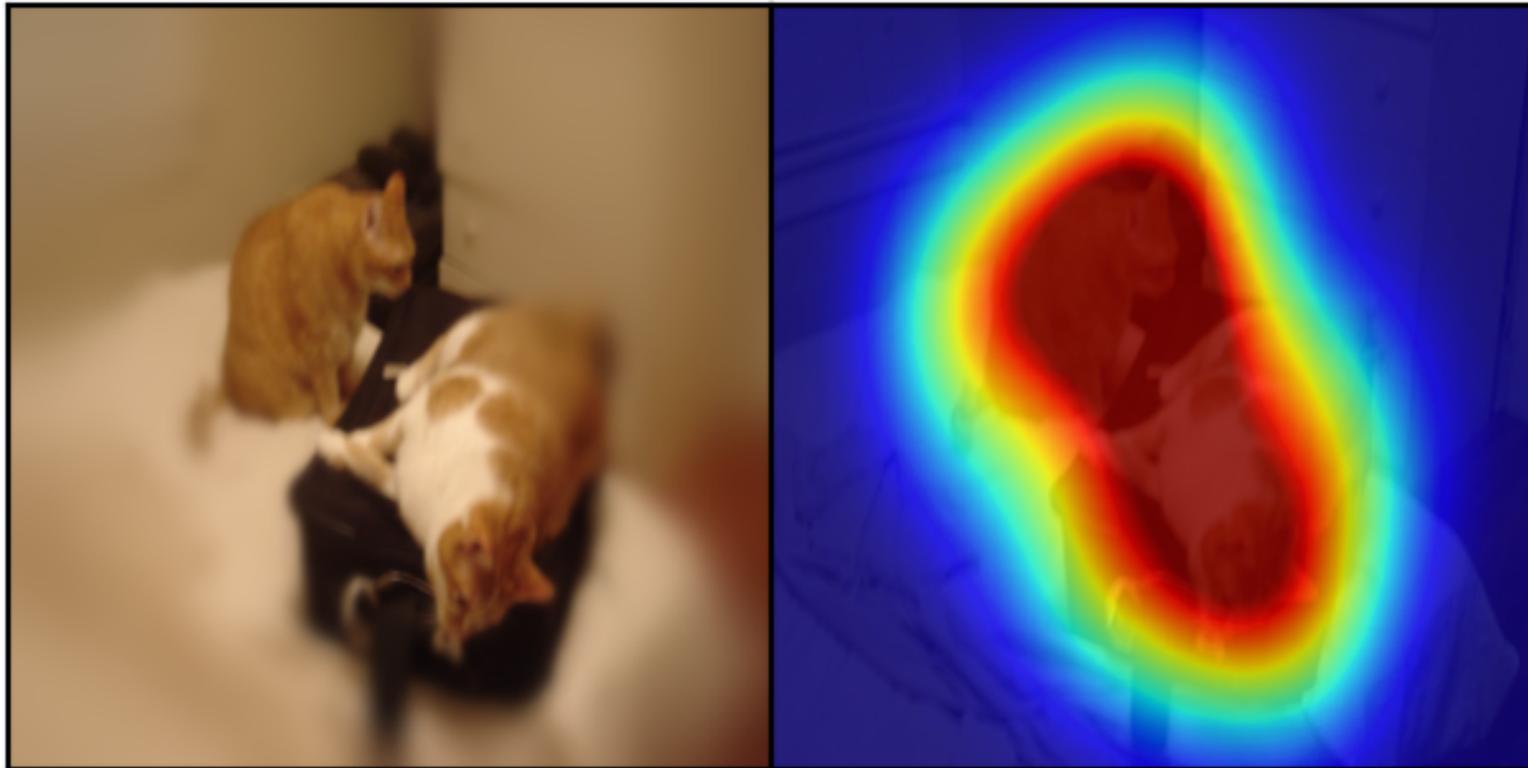
What food is on the table? Cake

VQA-HAT (Human ATtention)



What animal is she riding? Horse

VQA-HAT (Human ATtention)



What number of cats are laying on the bed? 2

VQA-HAT (Human ATtention)

- Attention maps for VQA dataset [Antol et al., ICCV15]
- 58k training I-Q pairs
- 1.4k validation I-Q pairs (3 maps per question)

VQA-HAT (Human ATtention)

Is it sunny? Is it storming outside? Is there a plane in this photo? Are there trees in the background?

What is the color of the train on the left? What is next to the house?

What arm does the man wear his watch on? Is the surfer wearing shoes?

Is it possible for the player on the left to catch the ball that is visible in front of him?

How many lanes are in the road? Is there a rug on the floor? Are they both wearing shoes?

Is that a kite flying? What is on top of the traffic light pole?

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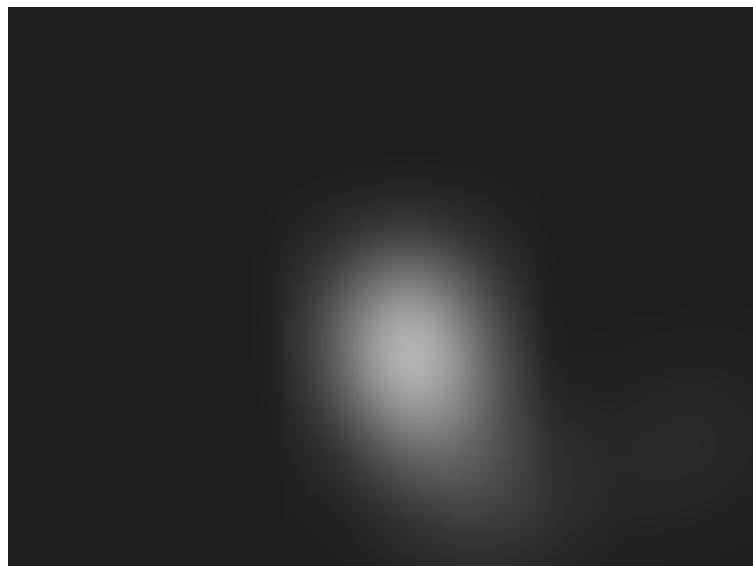
Do deep neural networks ‘look at’
the same regions as humans?

Evaluating attention maps

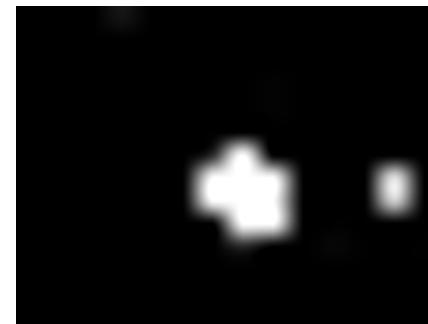
- Metric: Rank correlation

Evaluating attention maps

- Metric: Rank correlation



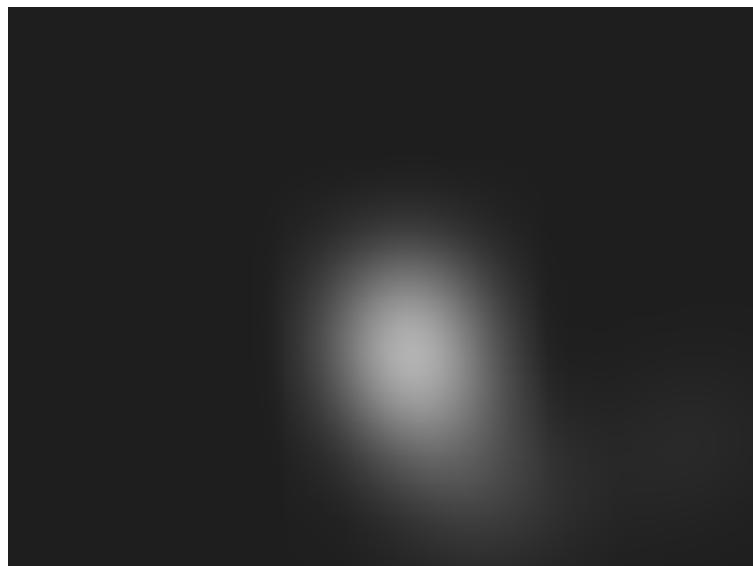
Attention map 1



Attention map 2

Evaluating attention maps

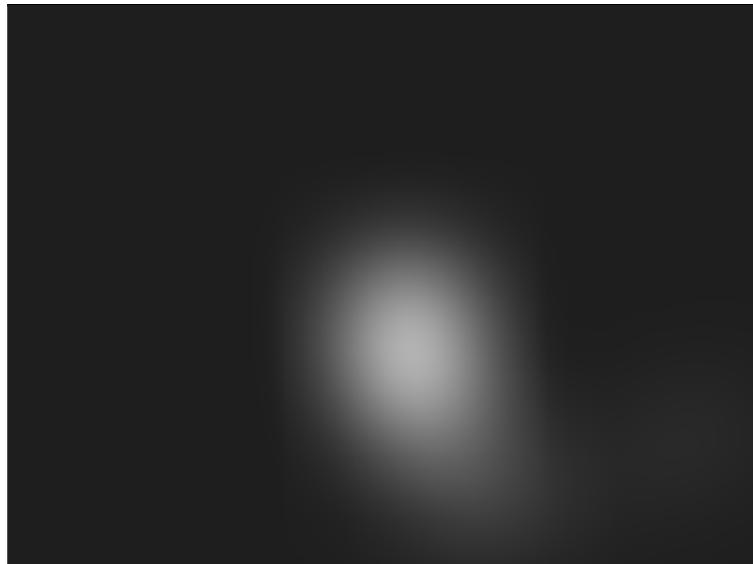
- Metric: Rank correlation



Scale to same size

Evaluating attention maps

- Metric: Rank correlation



Compute pixel intensities

Evaluating attention maps

- Metric: Rank correlation

5	5	5
5	200	400
5	250	320

0	0	0
0	240	270
0	340	0

Rank the pixel intensities

Evaluating attention maps

- Metric: Rank correlation

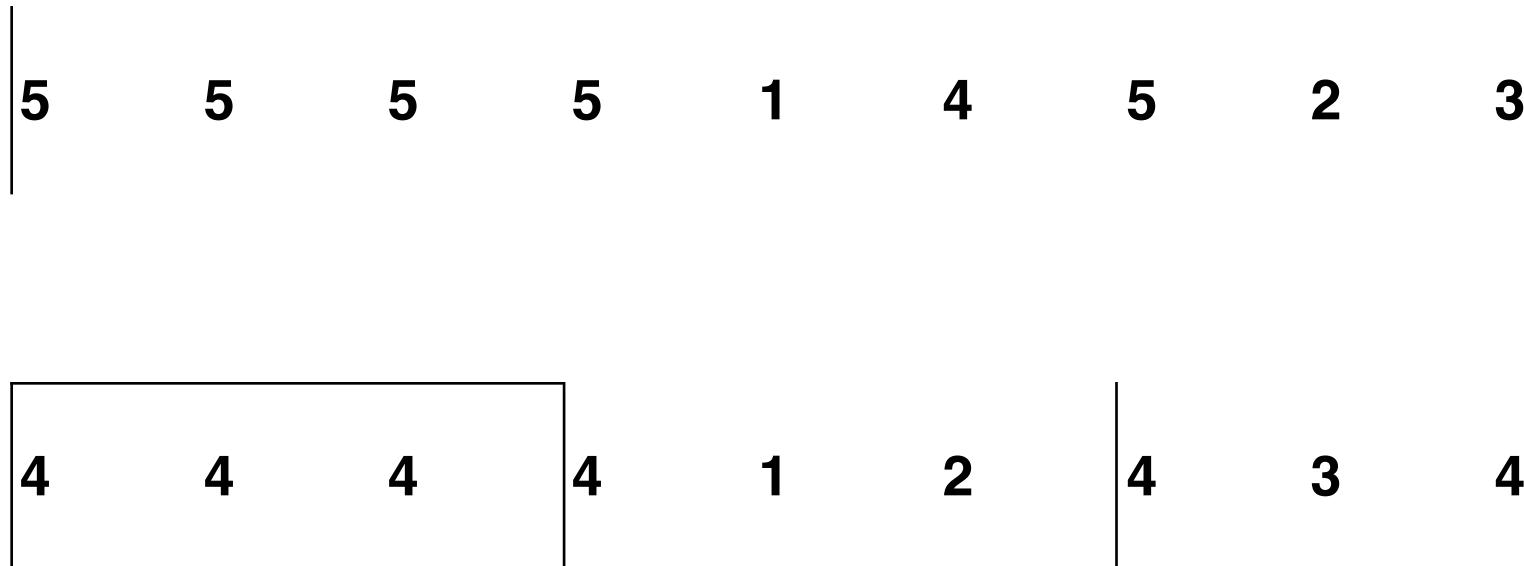
5	5	5	5	5	5	1
5	1	4				
4	2	4	3	4	1	

4	5	4	2	4	3	3	4	3
4	1	2						
4	3	3	4	4	4	4	4	4

Flatten them into vectors

Evaluating attention maps

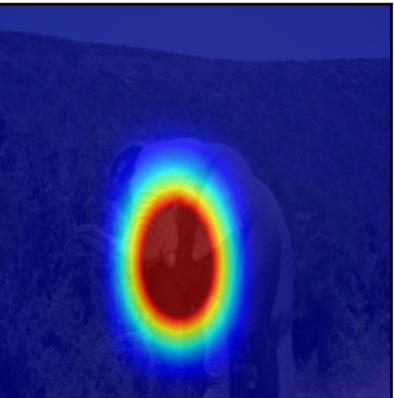
- Metric: Rank correlation



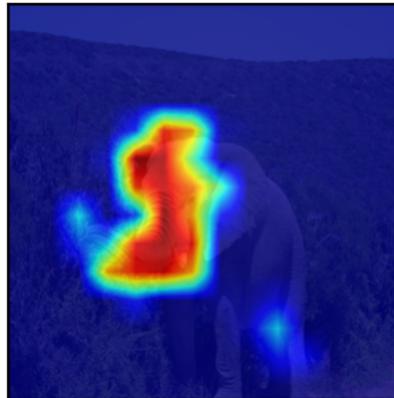
Compute correlation between the ranked lists



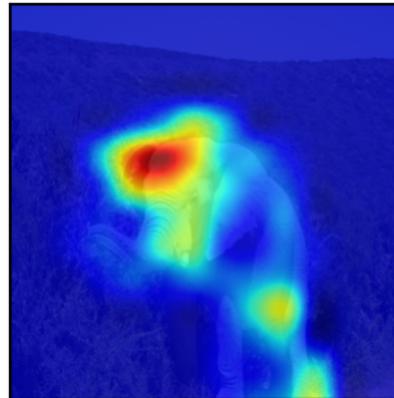
What color is the elephant tusk? white



Human Attention



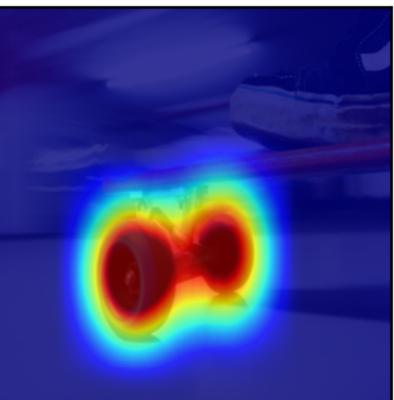
SAN-2 (Yang et al.)
Correlation: 0.529



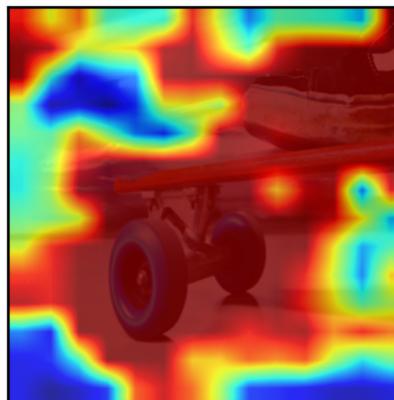
HieCoAtt-Q (Lu et al.)
Correlation: 0.655



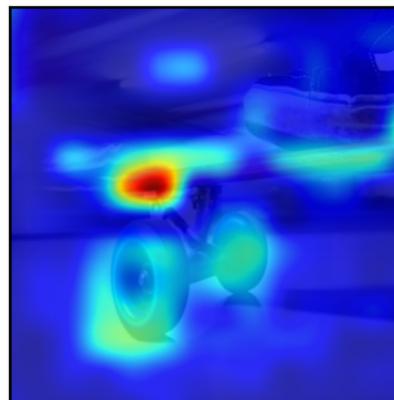
How many wheels are shown? 2



Human Attention



SAN-2 (Yang et al.)
Correlation: 0.390



HieCoAtt-Q (Lu et al.)
Correlation: 0.581



What color is the parking meter? blue



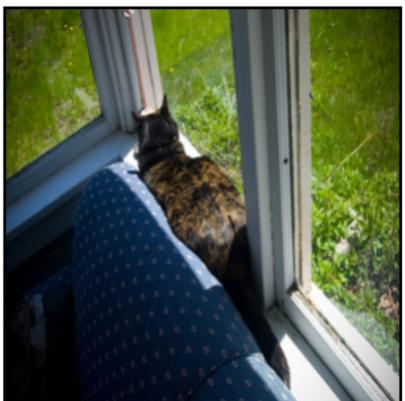
Human Attention



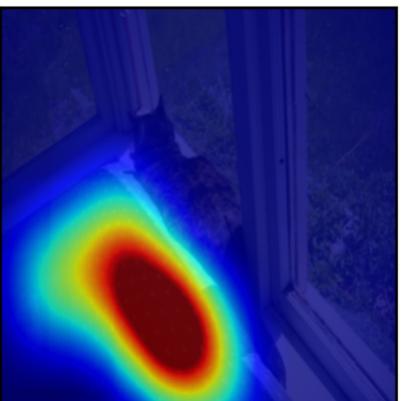
SAN-2 (Yang et al.)
Correlation: 0.149



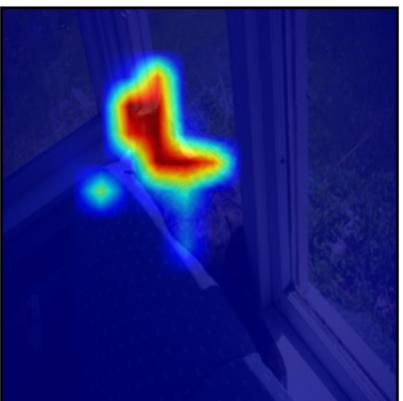
HieCoAtt-Q (Lu et al.)
Correlation: 0.244



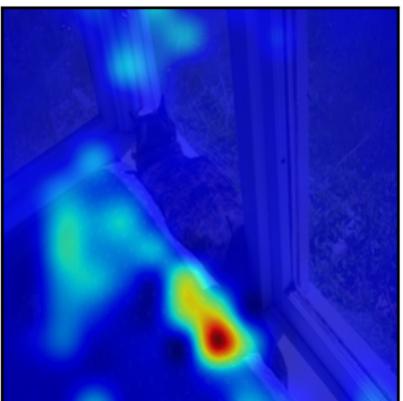
What color is the couch? blue



Human Attention



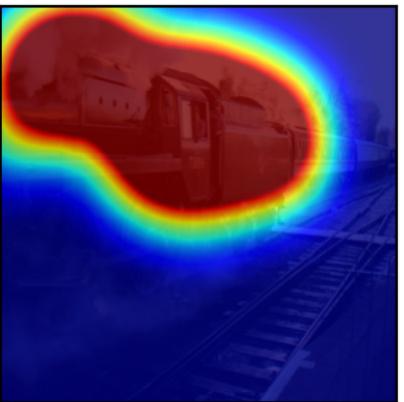
SAN-2 (Yang et al.)
Correlation: 0.519



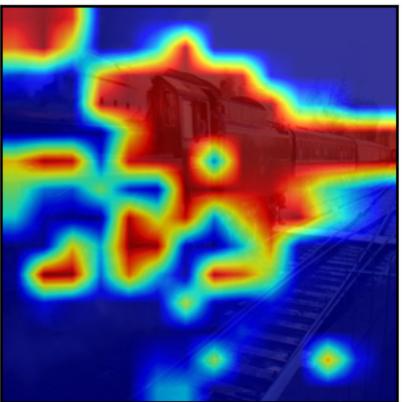
HieCoAtt-Q (Lu et al.)
Correlation: 0.538



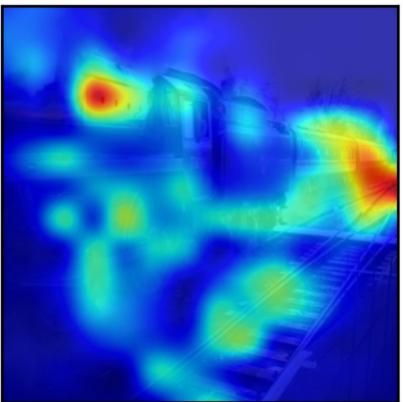
What kind of engine is this? steam



Human Attention



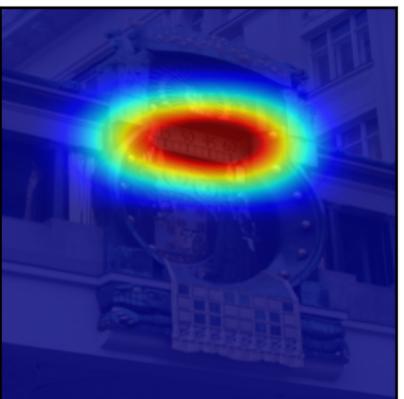
SAN-2 (Yang et al.)
Correlation: 0.468



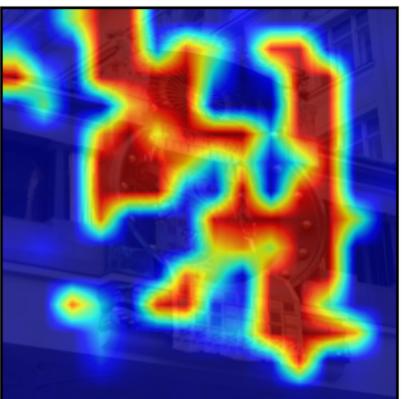
HieCoAtt-Q (Lu et al.)
Correlation: 0.456



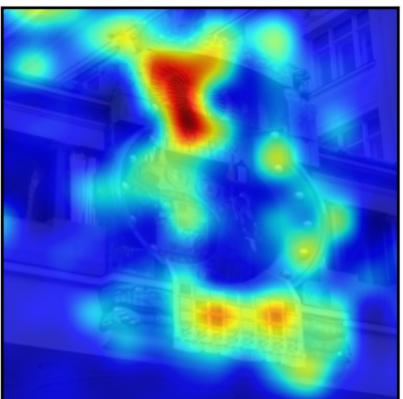
What is the highest number shown? 60



Human Attention



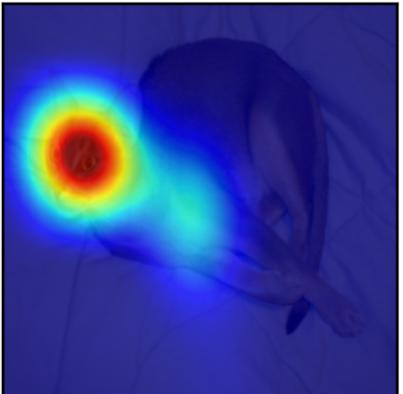
SAN-2 (Yang et al.)
Correlation: 0.460



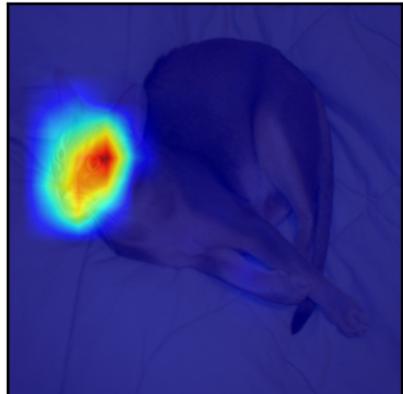
HieCoAtt-Q (Lu et al.)
Correlation: 0.359



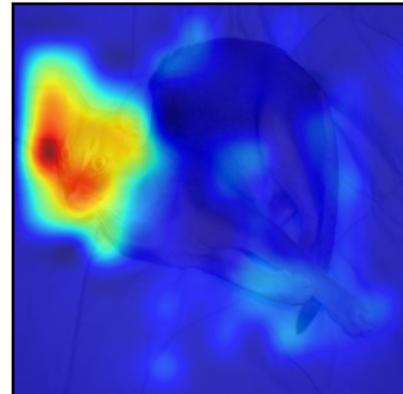
What color are the animal's eyes? green



Human Attention



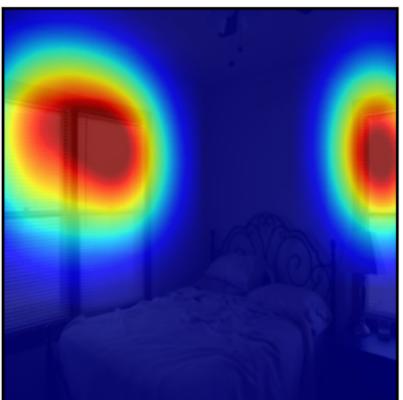
SAN-2 (Yang et al.)
Correlation: 0.573



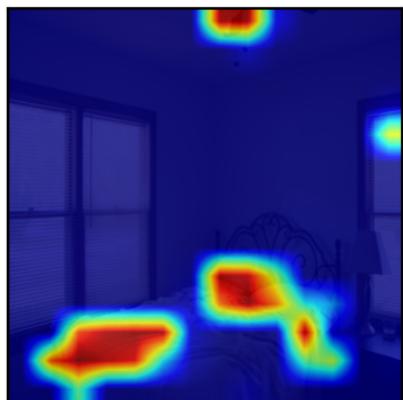
HieCoAtt-Q (Lu et al.)
Correlation: 0.527



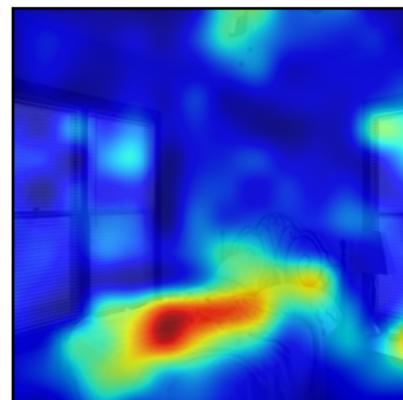
What is covering the windows? blinds



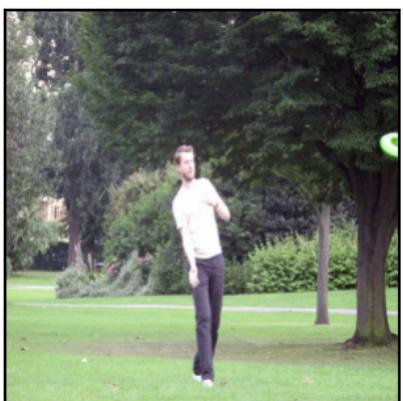
Human Attention



SAN-2 (Yang et al.)
Correlation: -0.495



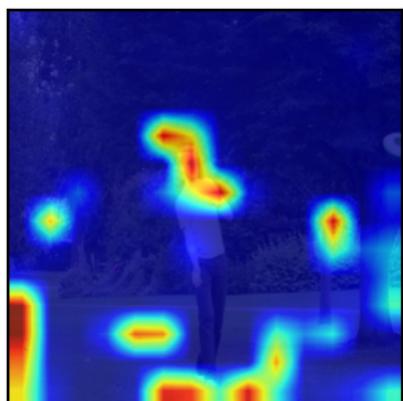
HieCoAtt-Q (Lu et al.)
Correlation: -0.440



What is the man doing? playing frisbee



Human Attention



SAN-2 (Yang et al.)
Correlation: -0.060



HieCoAtt-Q (Lu et al.)
Correlation: 0.238

Evaluating attention maps

VQA Model

Mean Rank-Correlation

Human	0.62
-------	------

Evaluating attention maps

VQA Model	Mean Rank-Correlation
Human	0.62
Implicit Attention: Occlusion	0.07
Implicit Attention: Guided Backprop [Springenberg et al., ICLR15]	0.12

Evaluating attention maps

VQA Model	Mean Rank-Correlation
Human	0.62
Implicit Attention: Occlusion	0.07
Implicit Attention: Guided Backprop [Springenberg et al., ICLR15]	0.12
Explicit Attention: SAN-2 [Yang et al., CVPR16]	0.25
Explicit Attention: HieCoAtt [Lu et al., 2016]	0.26

Evaluating attention maps

Task-specific

VQA Model	Mean Rank-Correlation
Human	0.62
Implicit Attention: Occlusion	0.07
Implicit Attention: Guided Backprop [Springenberg et al., ICLR15]	0.12
Explicit Attention: SAN-2 [Yang et al., CVPR16]	0.25
Explicit Attention: HieCoAtt [Lu et al., 2016]	0.26
Task-independent Saliency [Judd et al., ICCV09]	0.50

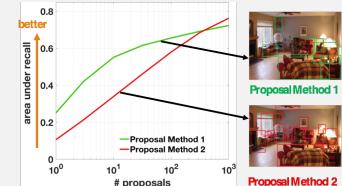
Evaluating attention maps

Task-specific

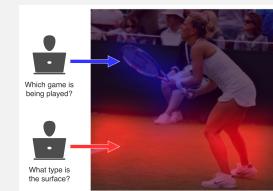
VQA Model	Mean Rank-Correlation complete set	without center bias
Human	0.62	0.73
Implicit Attention: Occlusion	0.07	0.02
Implicit Attention: Guided Backprop [Springenberg et al., ICLR15]	0.12	-0.03
Explicit Attention: SAN-2 [Yang et al., CVPR16]	0.25	0.06
Explicit Attention: HieCoAtt [Lu et al., 2016]	0.26	0.12
Task-independent Saliency [Judd et al., ICCV09]	0.50	-0.07

Outline

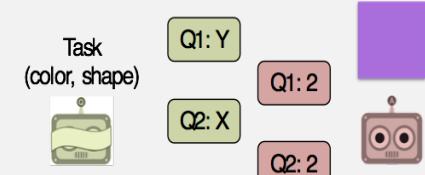
Object-Proposal Evaluation
Protocol is ‘Gameable’ [CVPR ‘16]



Human Attention in VQA:
Do Humans and Deep Networks
Look at the Same Regions? [EMNLP ‘16]



Natural Language Does Not Emerge
‘Naturally’ in Multi-Agent Dialog [EMNLP ‘17]



Rant about Vision vs NLP reviewing!



Learning Cooperative Visual Dialog Agents with Deep Reinforcement Learning

[ICCV '17]



Abhishek Das*
(Georgia Tech)



Satwik Kottur*
(CMU)



José Moura
(CMU)



Stefan Lee
(Virginia Tech)



Dhruv Batra
(Georgia Tech / FAIR)

Visual Dialog: Task

- Given
 - Image I
 - History of human dialog $(Q_1, A_1), (Q_2, A_2), \dots, (Q_{t-1}, A_{t-1})$
 - Follow-up Question Q_t
- Task
 - Produce free-form natural language answer A_t

Visual Dialog



Q: How many people on wheelchairs?

A: Two.

Q : What gender are the people in the wheelchairs?

A : One is female, one is male.

Q : Which one is holding the racket?

A : The female.

Q : Is the other one holding anything?

A : He is not.

Problems

- No goal
 - Why are we talking?
- Agent not in control
 - Artificially injected at every round into a human conversation
 - Can't *steer* the conversation
 - Doesn't get to see its errors during training
- Can't learn the *meaning* of responses
 - Many equivalent responses that should be treated equally, but aren't!
 - Is log-likelihood of human response really a good metric?

Image Guessing Game

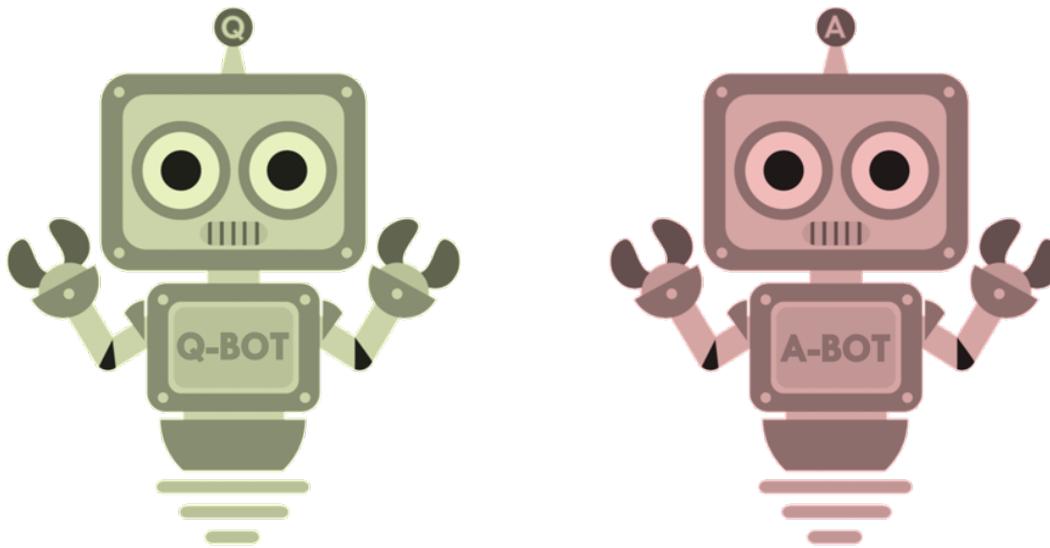
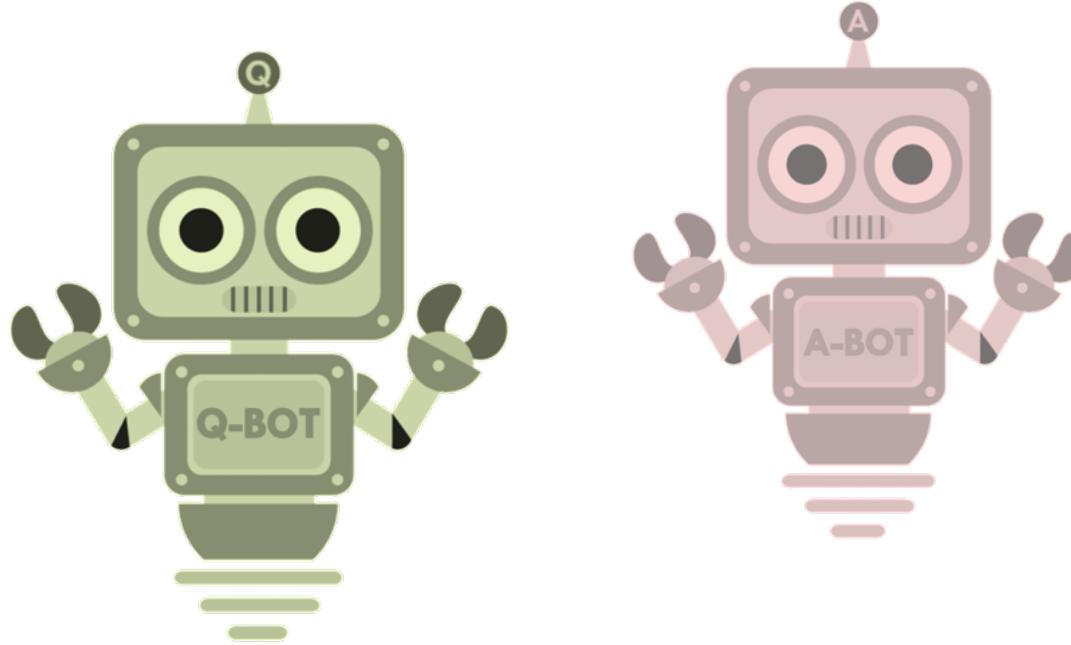
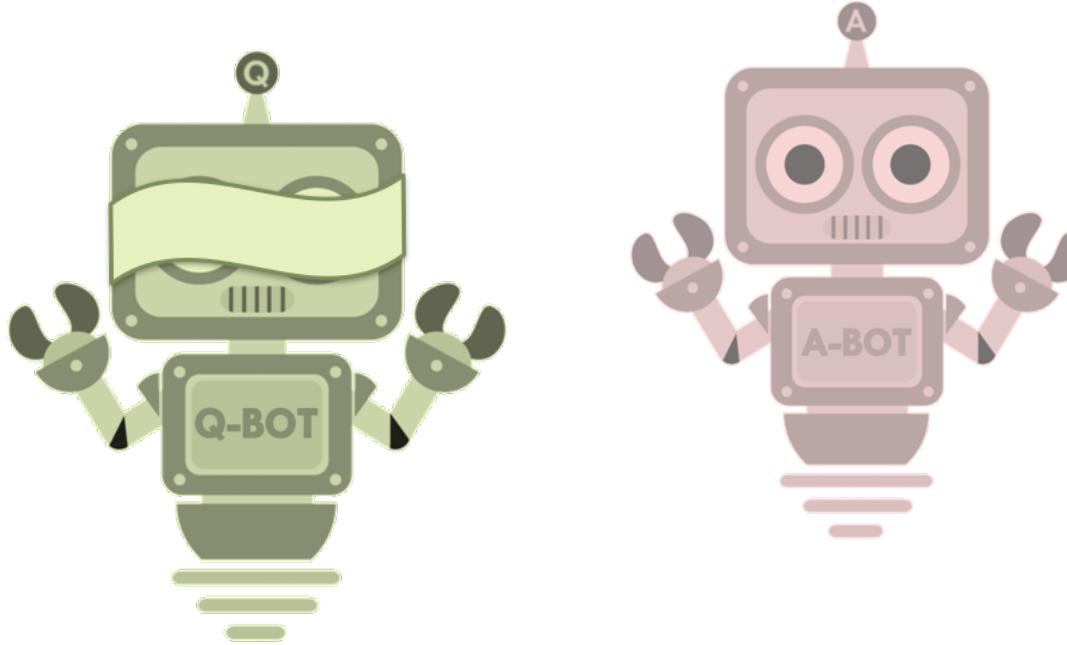


Image Guessing Game



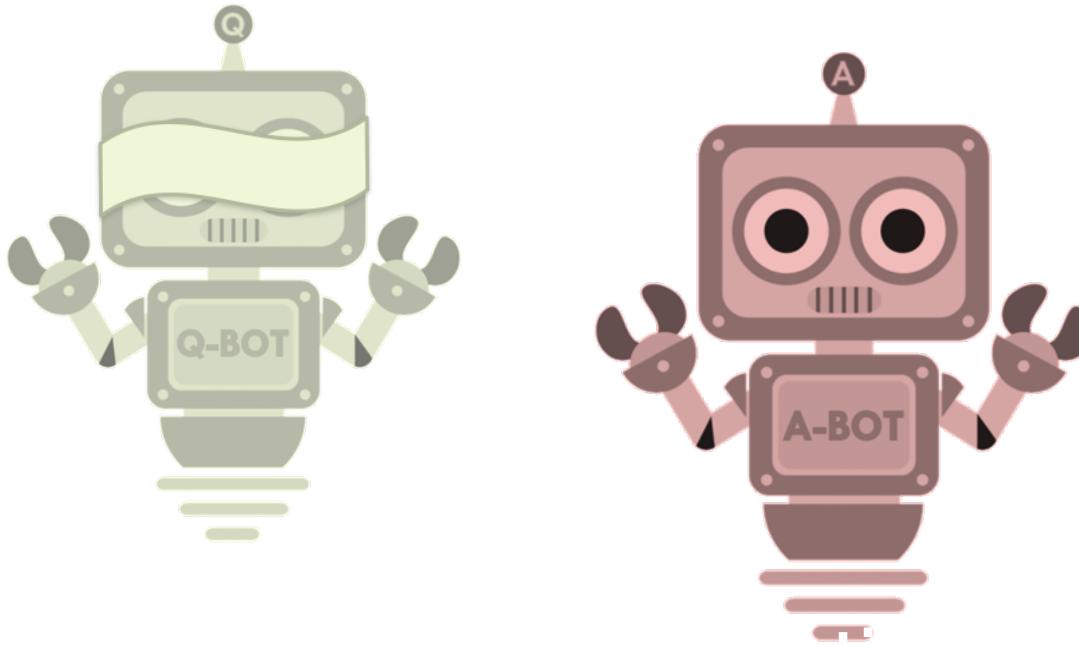
Q-Bot asks questions

Image Guessing Game



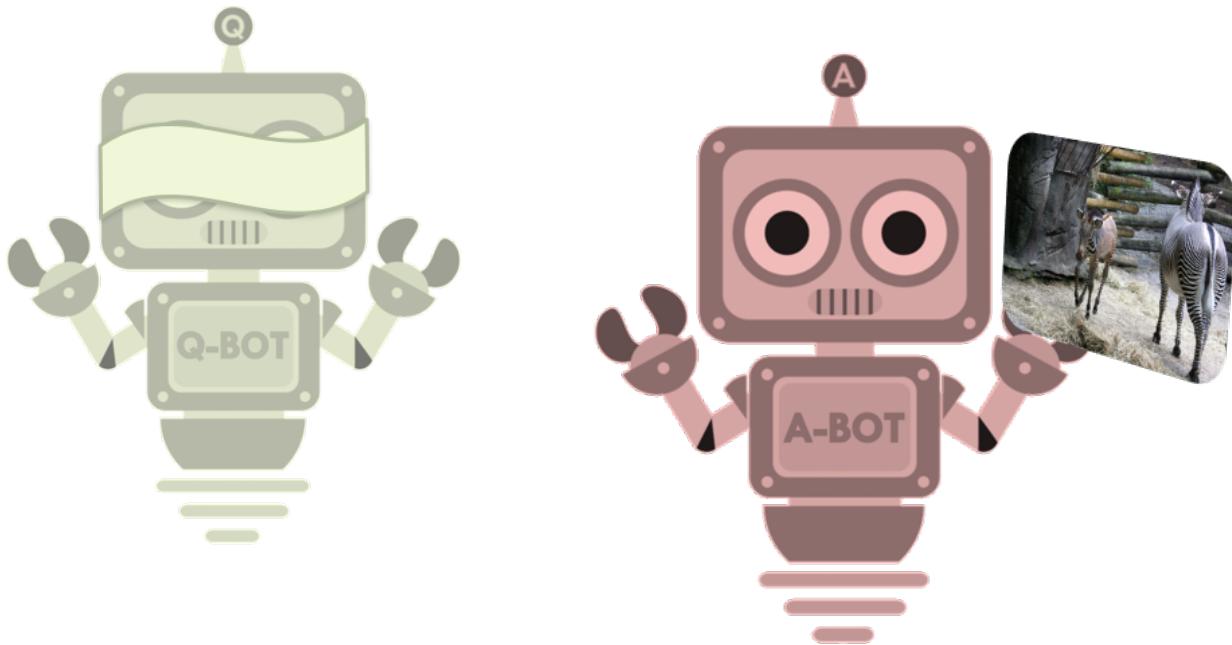
Q-Bot is blindfolded

Image Guessing Game



A-Bot answers questions

Image Guessing Game



A-Bot sees an image

Image Guessing Game

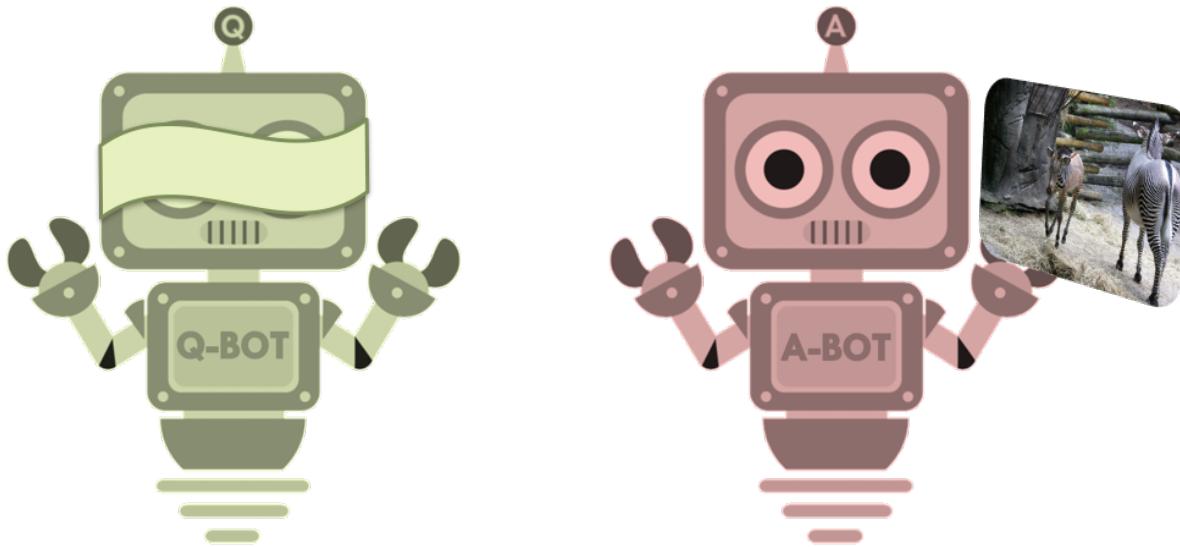
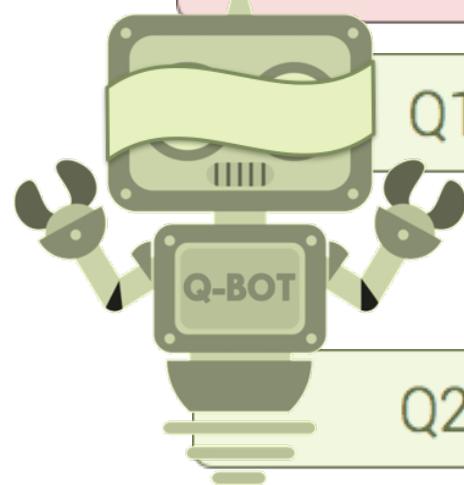
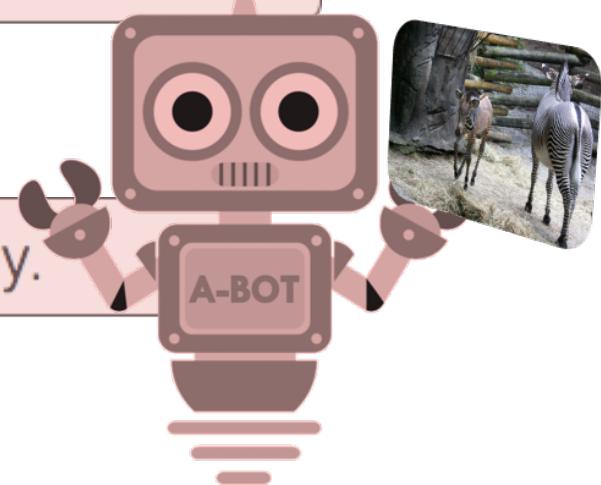


Image Guessing Game

Q Two zebra are walking around their pen at the zoo. A



Q1: Any people in the shot?



A1: No, there aren't any.

Q2: Any other animal?

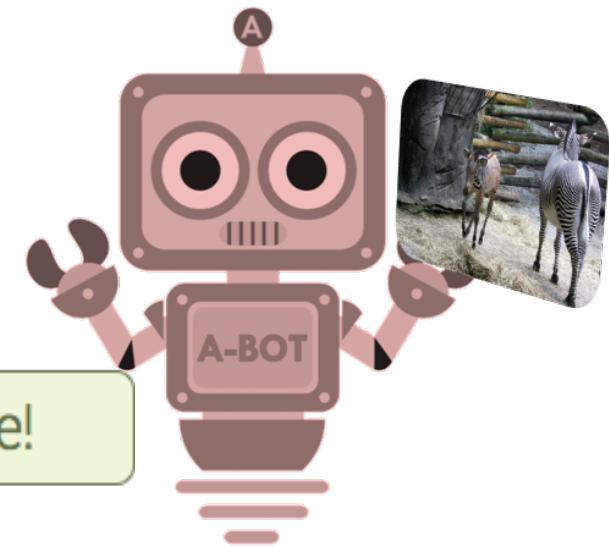
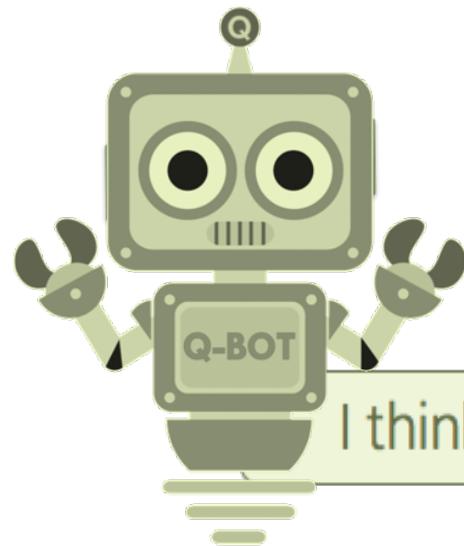
A2: No, just zebras.

Q3: Are they facing each other?

A3: They aren't.

Image Guessing Game

A3: They aren't.



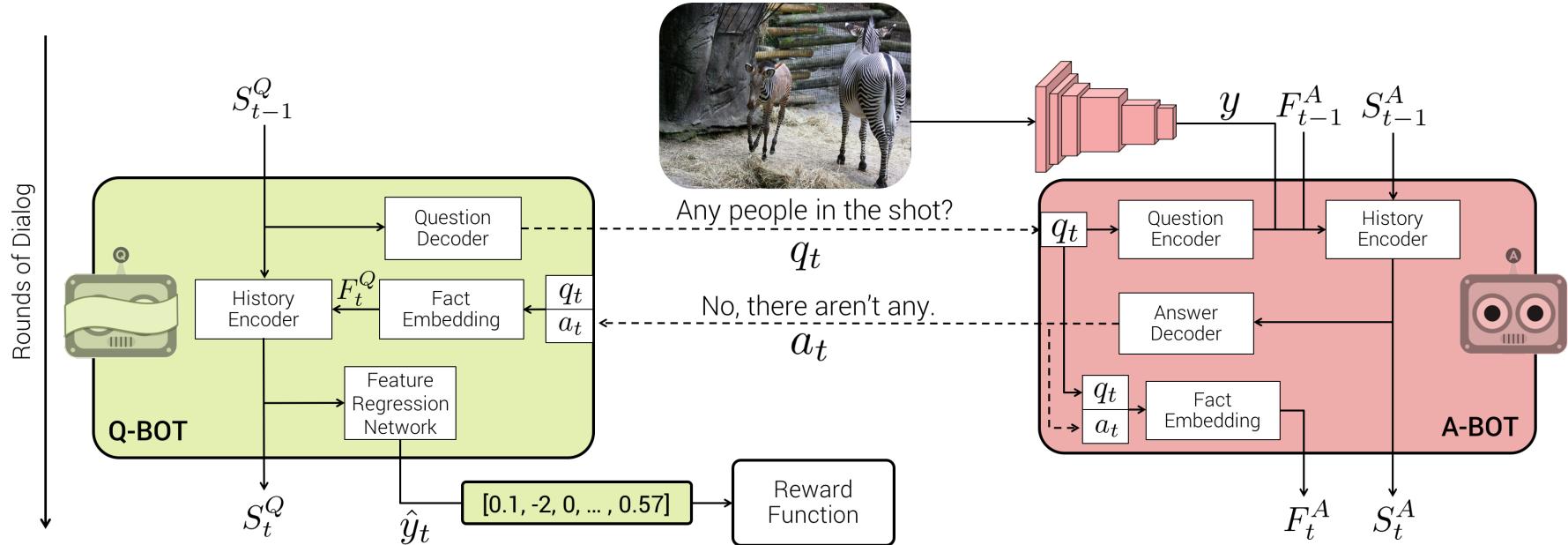
Policy Networks

Q-Bot

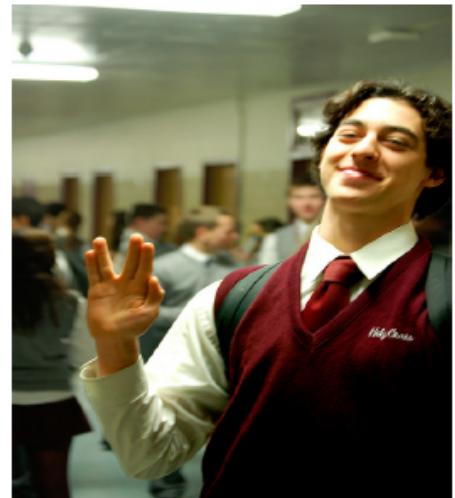
$$\pi_Q(q_t | S_{t-1}^Q)$$

A-Bot

$$\pi_A(a_t | S_{t-1}^A)$$



Turing Test



How old is this man?
Does he have short hair or long hair?
What color is his hair?
Is he wearing glasses?
Does he have facial hair?
How is he dressed?
Is he larger man or is he skinny?
Is this picture taken outside?
Can you tell if it's daytime?
Can you tell what room he is standing in?

He looks like late teens
Medium Brown
No
No
He's white dress shirt with red tie ... school uniform
He's skinny
Inside
I'm not sure
He's in hallway

A man making the live long and prosper sign from star trek.

Where is man located?
What is man wearing?
Are there any other people in picture?
What color is table?
Is there anything else on table?
What are other people doing?
Are there any windows?
What color are walls?
What time of day do you think it is?
What is man wearing?

Looks like classroom of some sort
Black t shirt and jeans
Yes, quite few people in background
Picture is black and white, but it's wood table
Not that I can see
They are standing in front of him, but I don't ...
Not that I can see
I can't see walls
I can't tell
Black t shirt and jeans



How old is man?
 What is he wearing?
 What color is his shirt?
 what color are his pants?
 what color is his shirt?
 What color are his shoes?
 What color are his shoes?

I can't see his face, I don't know
 shorts and t shirt
 white
 black
 blue
 Black
 Black
 Black
 Black
 Black

What color is skateboard?
 Is he wearing helmet?
 Is he wearing knee pads?
 Is it day or night?
 Is it sunny?
 Can you see any other people?
 Is it day or night?
 Is it sunny?
 What color is skateboard?
 Is he wearing helmet?

It is hard to tell but I think it's black
 Yes
 No, no knee pads
 It is daytime
 It is bright out, but I see no shadows, so I can not
 There are 2 other people in background
 It is daytime
 Yes, it is sunny
 It is hard to tell but I think it's black
 Yes, he is wearing helmet

SL Agents

RL Agents

Natural Language Does Not Emerge 'Naturally' in Multi-Agent Dialog

[EMNLP '17]



Satwik Kottur*
(CMU)



José Moura
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Stefan Lee
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Dhruv Batra
(Georgia Tech / FAIR)

Toy World

- Sanity check

- Simple, synthetic world
 - Instances - (shape, color, style)
 - Total of 4^3 (64) instances

shape	color	style
triangle		 filled
square		 dashed
circle		 dotted
star		 solid

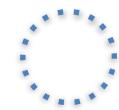
- Example instances:



(triangle, purple, filled)



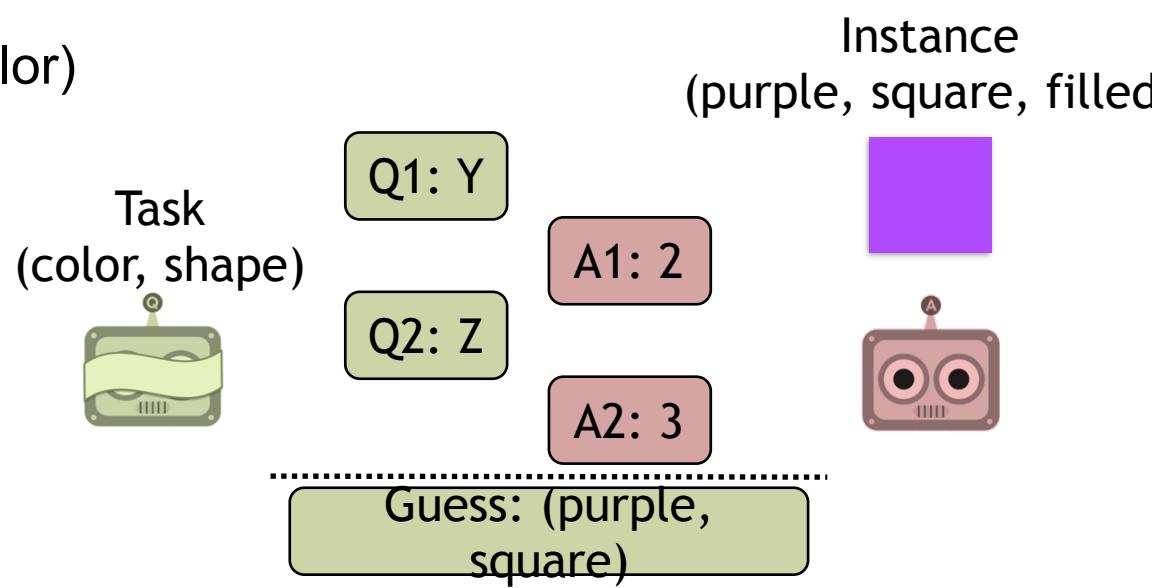
(square, blue, solid)



(circle, blue, dotted)

Task & Talk

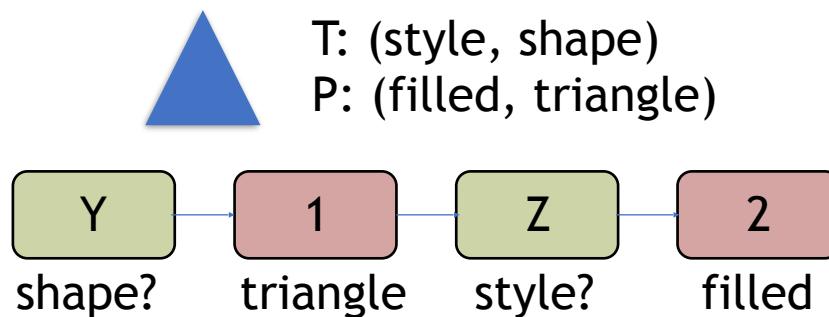
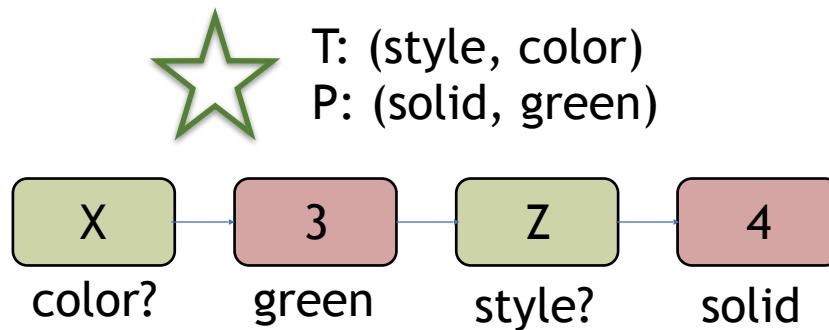
- Task (G)
 - Inquire pair of attributes
 - (color, shape), (shape, color)
- Talk
 - Single token per round
 - Two rounds
- Q-bot guesses a pair
 - Reward : +1 / -1
 - Prediction order matters!



Get reward!



Emergence of Grounded Dialog



Emergence of Grounded Dialog

- Compositional grounding
 - Predict dialog for unseen instances

Attributes				Task	q_1, q_2
V_A	X	Y	Z		
1	<i>blue</i>	<i>triangle</i>	<i>dotted</i>	(<i>color, shape</i>)	Y, X
2	<i>purple</i>	<i>square</i>	<i>filled</i>	(<i>shape, color</i>)	
3	<i>green</i>	<i>circle</i>	<i>dashed</i>	(<i>shape, style</i>)	Y, Z
4	<i>red</i>	<i>start</i>	<i>solid</i>	(<i>color, style</i>)	Z, X
				(<i>style, color</i>)	X, Z

(a) A-BOT

(b) Q-BOT



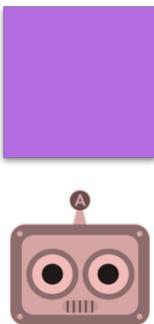
Task (color, shape)

Q1: Y

Q2: X

Q1: 2

Q2: 2



A. Over-complete vocabulary

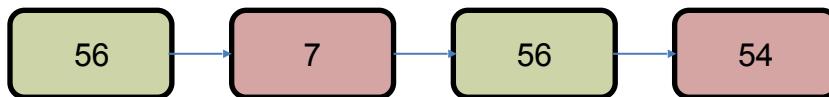
- $|V_Q|, |V_A| > 64$ (#instances)
 - More capacity than needed
 - Enough for A-bot to convey entire instance in a single round
- Observations:
 - ABot learns a mapping between instance and (pairs) of V_A

A. Over-complete vocabulary



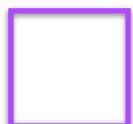
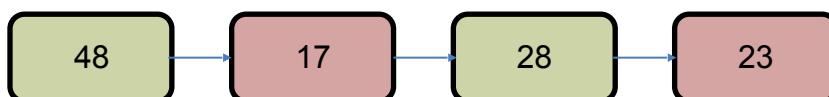
T: (style, color)

P: (solid, blue)



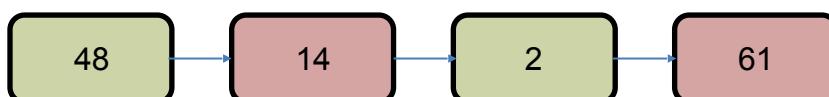
T: (style, color)

P: (green, solid)



T: (color, style)

P: (purple, solid)

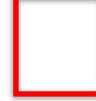
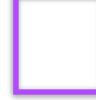


- Learn mapping from instance to pairs of V_A
- Two rounds unnecessary
- Q-bot immaterial
- Lewis Signaling Game
- No compositionality
- Poor generalization: 25.6%
- Let's limit capacity!

B. Attribute vocabulary

- $|V_Q| = 3$

- Matches #attributes
 - (style, shape, color)

shape	color	style
triangle		 filled
square		 dashed
circle		 dotted
star		 solid

- $|V_A| = 12$

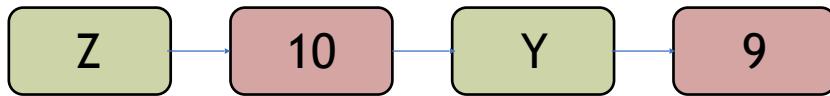
- Matches #attribute values
 - 3 attributes x 4 values / attribute

- Can they learn individual concept grounding ?

B. Attribute vocabulary



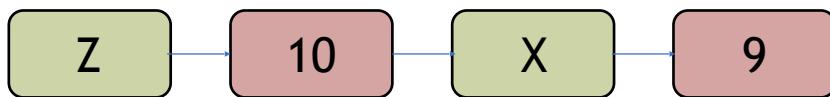
T: (style, color)
P: (solid, green)



{style,
color}?



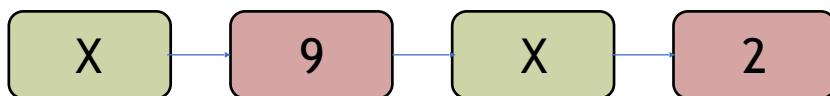
T: (color, style)
P: (green, solid)



{style,
color}?



T: (shape, style)
P: (triangle, filled)



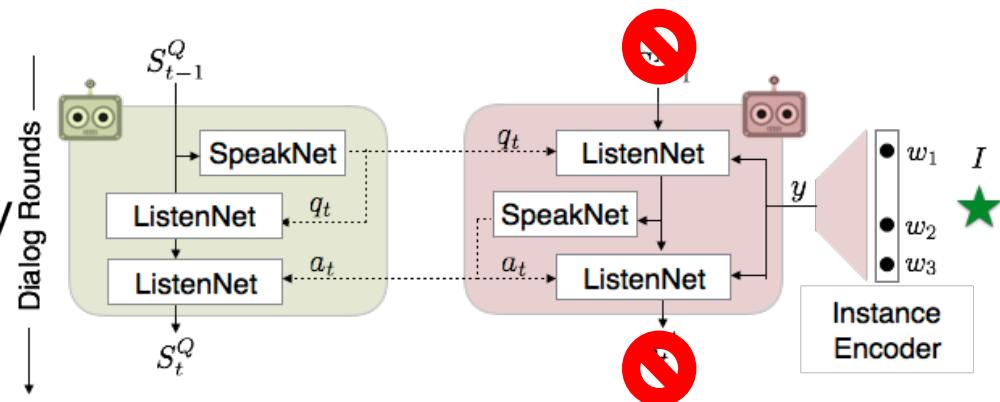
{style,
shape}?

- $|V_Q| = 3, |V_A| = 12$
- Q-bot conveys task in first round
- Non-compositional
- Inconsistent A-bot grounding
- Poor generalization : 38.5%

C. Minimal vocabulary

- $|V_Q| = 3, |V_A| = 4$
 - Minimum
 - Q-bot : tasks across two rounds
 - A-bot : values across two rounds

- Remove A-bot memory
 - A-bot cannot leverage history
 - Consistent groundings

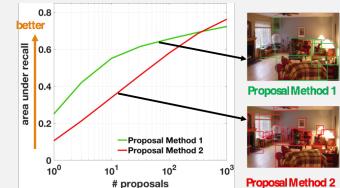


Summary of findings

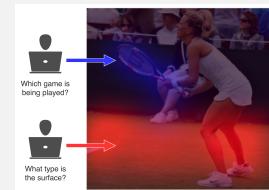
Setting	Vocabulary	Memory		Generalization	Characteristics	
	Q-bot	A-bot				
A. Over-complete	64	64	Yes	Yes	25.6 %	<ul style="list-style-type: none"> • Non-compositional • Q-bot insignificant • Inconsistent A-bot • Poor generalization
B. Attribute	3	12	Yes	Yes	38.5 %	<ul style="list-style-type: none"> • Non-compositional • Q-bot uses one task • Inconsistent A-bot • Poor generalization
C. Minimal	3	4	Yes	No	74.4 %	<ul style="list-style-type: none"> • Compositional • Q-bot uses both tasks • Consistent A-bot • Good generalization

Outline

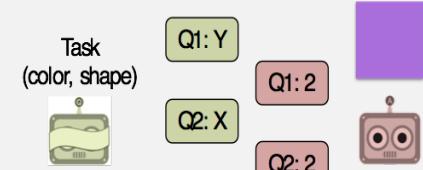
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Protocol is ‘Gameable’ [CVPR ‘16]



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‘Naturally’ in Multi-Agent Dialog [EMNLP ‘17]



Rant about Vision vs NLP reviewing!



Object-Proposal Evaluation Protocol is ‘Gameable’

[CVPR ‘16]



Neelima Chavali*



Harsh Agrawal*



Aroma Mahendru*



Dhruv Batra

Rejected from ICCV 2015

- Weak Reject, Weak Reject, Strong Reject
- R1: Strengths:
 - *The authors convincingly show that object proposal generation is indeed "gameable".*
 - *The paper warns for dataset biases, which is an important issue.*
 - *The authors introduce an improved version of the fully annotated Pascal Context dataset [41] by providing instance-level annotations.*
 - *The paper is well written.*
 - *The authors release software which allows comparison of object proposal methods.*
 - *The main object proposal methods are compared.*
 - *Three different datasets are used with quite a variety of different object classes.*

Rejected from ICCV 2015

- Weak Reject, Weak Reject, Strong Reject
- R1: Weaknesses:
 - *I do not find many new insights in the paper. To my knowledge, methods on generating object proposals have always stressed the importance of being able to find any object, even though because of lack of datasets they were only evaluated on Pascal VOC. It is indeed true that one could learn class-specific classifiers to get better results on creating object proposals, but this is not very surprising and I think that such a method would not survive a good review process.*

Rejected from ICCV 2015

- Weak Reject, Weak Reject, Strong Reject
- R1: Weaknesses:
 - *The authors posit that there are two interpretations of object proposal: "category-independent object proposals" and "detection proposals", whereas the latter is to improve object detection only for the target classes in the dataset. However, I have never seen a work on object proposals which uses the second interpretation because this is just a fundamentally wrong interpretation*

Rejected from ICCV 2015

- Consistent theme
 - *Hence I feel that this paper does not bring enough new insights to the community to **warrant publication at a top-tier conference like ICCV**.*
 - *The use of the Pascal dataset as a base for the experiments is in the reviewer's opinion **not enough in an current ICCV paper**.*
 - *All in all, the reviewer finds that the only contribution of the paper is an experiment to make researchers aware of the potential per-class bias of the current evaluations, which the reviewer thinks is **not enough for an ICCV paper**.*

CVPR Reviewers



From reviewers with love: Not on my watch!



How to write a good CVPR submission



Bill Freeman
MIT CSAIL
Nov. 6, 2014

From an AC's point of view

- The types of papers in your pile:
 - About 1/3 are obvious rejects
 - In the whole set, maybe 1 is a really nice paper
 - well-written, great results, good idea.
 - The rest are borderline, and these fall into two camps..

Two types of “borderline” papers

- The Cockroach
 - You try, but you can't find a way to kill this paper. While there's nothing too exciting about it, it's pretty well written, the reviews are ok, the results show an incremental improvement. Yet another kind of boring CVPR paper.



Two types of “borderline” papers

- The Puppy with 6 toes
 - A delightful paper, but with some easy-to-point-to flaw. This flaw may not be important, but it makes it easy to kill the paper, and sometimes you have to reject that paper, even though it's so fresh and wonderful.



Short Papers!

emnlp2017



SIGDAT, the Association for Computational Linguistics special interest group on linguistic data and corpus-based approaches to NLP, invites you to participate in EMNLP 2017.

Long papers

EMNLP 2017 long paper submissions must describe substantial, original, completed and unpublished work. Wherever appropriate, concrete evaluation and analysis should be included. Each submission will be reviewed by at least three program committee members. Each long paper submission consists of a paper of up to eight (8) pages of content, plus unlimited pages for references; final versions of long papers will be given one additional page (up to nine pages with unlimited pages for references) so that reviewers' comments can be taken into account.

Short papers

EMNLP 2017 also solicits short papers. Short paper submissions must describe original and unpublished work. While a short paper is not a shortened long paper, the characteristics of short papers include a small, focused contribution; work in progress; a negative result; an opinion piece; an interesting application nugget. Each short paper submission consists of up to four (4) pages of content, plus unlimited pages for references; final versions of short papers will be given one additional page (up to five pages in the proceedings and unlimited pages for references) so that reviewers' comments can be taken into account. Each short paper submission will be reviewed by at least three program committee members.

Concluding thoughts

- Definitive conclusive negative results are hard
- Publishing such negative results is even harder!
- It seems to be particularly hard at Vision venues
- Please please please please please please
try accepting the puppy with 6 toes!



Machine Learning & Perception Group



Dhruv Batra
Assistant Professor

Postdoc
Stefan Lee



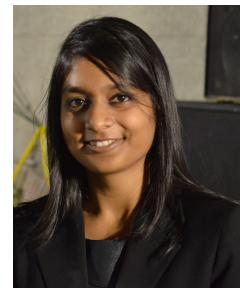
(C) Dhruv Batra

PhD

Qing Sun



Aishwarya Agrawal



Yash Goyal



Michael Cogswell



Abhishek Das



Ashwin Kalyan



Aroma Mahendru



Akrit Mohapatra



MS

Interns

Deshraj Yadav



Tejas Khot



Viraj Prabhu



Thanks!