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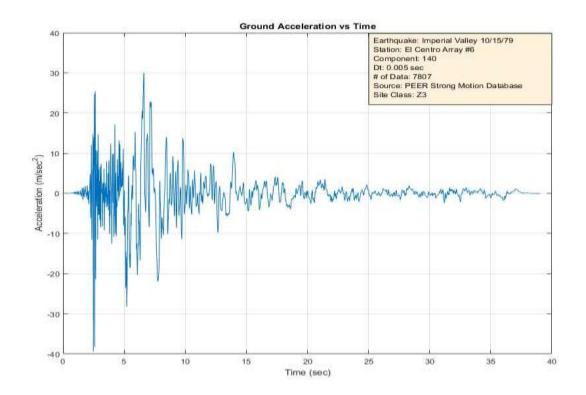
Introduction

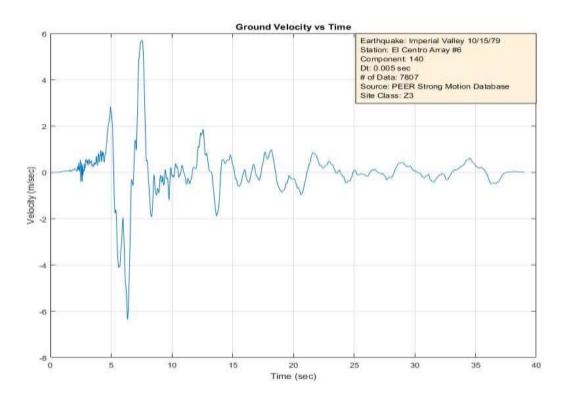
This report is prepared for the solutions of the assigned problems in the Homework 1. According to provided ground motion data E0140 earthquake has occurred on October 15th 1979, Imperial Valley. Earthquake site is underplayed with a Z3 type of soil. The station which acceleration data recorded is El Centro Array #6. Figure 1 shows extra information about the earthquake.

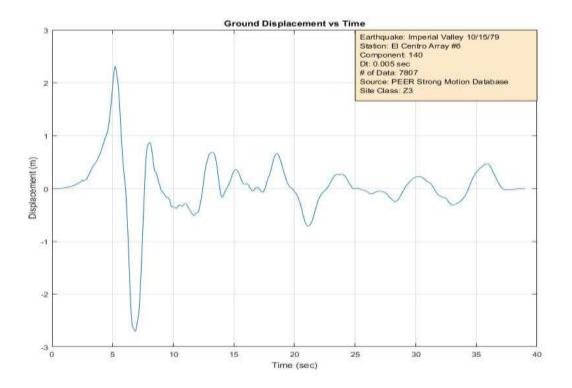


Figure 1: Earthquake Information

```
% This script is written for CE490 Introduction to Earthquake Engineering
close all
clc
time = 0:0.005:39.03; % Dt: 0.005 sec (given in the .txt file), and 7807
data point exist (7807-1)*0.05=39.03
acceleration recorded = dlmread('E06140.txt'); % importing the given
acceleration data file
u double dot = acceleration recorded*9.80665; % determining the ground
acceleration by multiplying g=9.80665
u dot = cumtrapz(time, u double dot); % velocity is obtained by taking
integral of the acceleration (cumulative trapezoidal integration method is
used)
u = cumtrapz(time, u dot); % displacement is obtained by taking integral of
the velocity (cumulative trapezoidal integration method is used)
figure(1)
plot(time, u double dot);
                                  % Acceleration vs Time graph is
plotted
title('Ground Acceleration vs Time')
xlabel('Time (sec)')
ylabel('Acceleration (m/sec^2)')
grid on
figure(2)
plot(time, u dot);
                                % Velocity vs Time graph is plotted
 title('Ground Velocity vs Time')
xlabel('Time (sec)')
ylabel('Velocity (m/sec)')
grid on
figure(3)
                          % Displacement vs Time graph is plotted
plot(time, u);
title('Ground Displacement vs Time')
xlabel('Time (sec)')
 ylabel('Displacement (m)')
 grid on
```





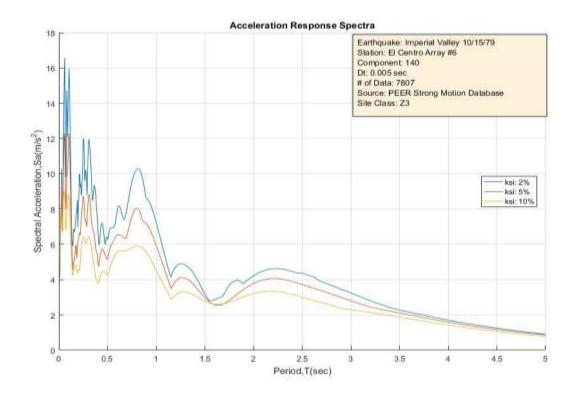


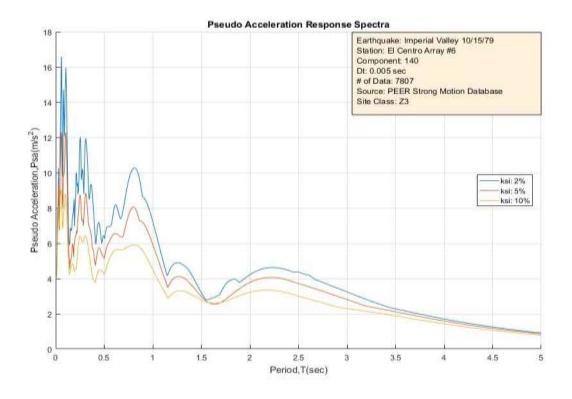
```
% This script is written for CE490 Introduction to Earthquake Engineering
clear
close all
clc
acceleration recorded = dlmread('E06140.txt'); % importing the given
acceleration data file
size = size(acceleration recorded);
                                % size of the imported data determined
by creating a matrix
n = size(1,1);
                                % nomber of data included in .txt file
is determined
delta t = 0.005;
                                % Dt: 0.005 sec (given in the .txt
file)
time = (n-1)*delta t;
ksi1 = [0.02; 0.05; 0.1];
                                  % a ksil matrix is created includes
asked ksi values
                                  % size is determined 5/0.005=1000
Sa = zeros(1000, 1);
```

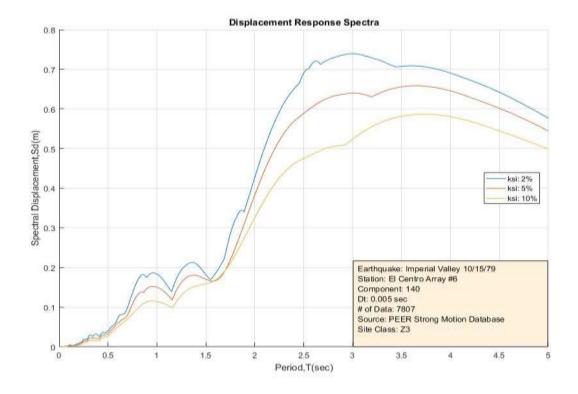
```
% size is determined 5/0.005=1000
Sa1 = zeros(1000, 1);
Sd = zeros(1000,1);
                                        % size is determined 5/0.005=1000
                                        % size is determined 5/0.005=1000
Sd1 = zeros(1000, 1);
PSa = zeros(1000,1);
                                        % size is determined 5/0.005=1000
for i = 1:3
   ksi = ksil(i,1);
                                        % asked ksi values are used from ksi1
matrix
   ii = 1;
   for T = 0:0.005:5
       mass = 1;
        omega n = 2*pi/T;
                                            % natural frequency is
calculated
                                             % stiffness is determined
        k = omega n*omega n*mass;
        c = 2*ksi*mass*omega n;
        u = 0;
        u dot = 0;
        for j = 1:n-1
            F 1 = -acceleration recorded(j,1)*mass;
            F 2 = -acceleration recorded(j+1,1)*mass;
            u double dot = (F 1-c*u dot-k*u)/mass;
            k1 = k+(2*c)/delta t+(4*mass)/(delta t*delta t);
            delta F = F 2-F 1+(4*mass/delta t+2*c)*u dot+2*mass*u double dot;
            delta u = delta F/k1;
            delta u dot = 2*delta u/delta t-2*u dot;
            delta u double dot = 4*delta u/(delta t^2)-4*u dot/delta t-
2*u double dot;
            u = u + delta u;
            u dot = u dot+delta u dot;
            u double dot = u double dot+delta u double dot;
            Sal(j,1) = u*omega n^2;
            Sd1(j,1) = u;
        end
```

```
Sa(ii,1) = max(abs(Sa1));
    Sd(ii,1) = max(abs(Sd1));
    PSa(ii,1) = (omega n^2)*Sd(ii,1);
        ii = ii+1;
end
figure(1)
hold on
  plot(0:0.005:5,Sa)
  title ('Acceleration Response Spectra')
  xlabel('Period, T(sec)')
  ylabel('Spectral Acceleration, Sa(m/s^2)')
  legend('ksi: 2%','ksi: 5%','ksi: 10%','Location','east')
  grid on
figure(2)
 hold on
    plot(0.00:0.005:5,Sd)
    title('Displacement Response Spectra')
    xlabel('Period,T(sec)')
    ylabel('Spectral Displacement, Sd(m)')
    legend('ksi: 2%','ksi: 5%','ksi: 10%','Location','east')
    grid on
figure(3)
 hold on
    plot(0.00:0.005:5, PSa)
    title('Pseudo Acceleration Response Spectra')
    xlabel('Period,T(sec)')
    ylabel('Pseudo Acceleration, Psa(m/s^2)')
    legend('ksi: 2%','ksi: 5%','ksi: 10%','Location','east')
   grid on
```

end



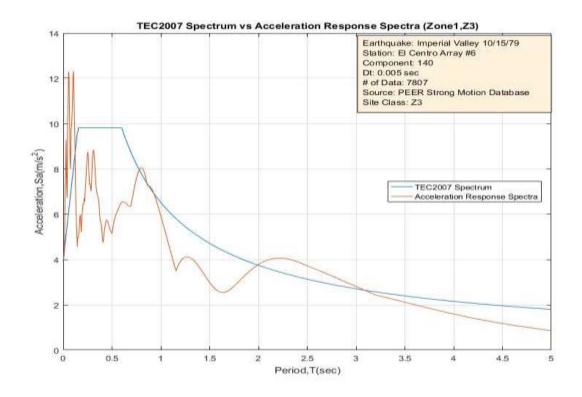




```
% This script is written for CE490 Introduction to Earthquake Engineering
clear
close all
clc
acceleration_recorded = dlmread('E06140.txt'); % importing the given
acceleration data file
size = size(acceleration recorded);
                              % size of the imported data determined
by creating a matrix
n = size(1,1);
                               % nomber of data included in .txt file
is determined
                               \mbox{\%} Dt: 0.005 sec (given in the .txt
delta t = 0.005;
file)
time = (n-1)*delta t;
```

```
ksi1 = [0.02; 0.05; 0.1];
                                        % a ksil matrix is created includes
asked ksi values
                                         % size is determined 5/0.005=1000
Sa = zeros(1000, 1);
                                         % size is determined 5/0.005=1000
Sa1 = zeros(1000, 1);
                                         % size is determined 5/0.005=1000
Sd = zeros(1000,1);
Sd1 = zeros(1000, 1);
                                         % size is determined 5/0.005=1000
PSa = zeros(1000, 1);
                                         % size is determined 5/0.005=1000
Ta = 0.15;
                                           % for Z3 soil type Ta
Tb = 0.60;
                                           % for Z3 soil type Tb
A0 = 0.40;
                                           % for zone 1
I = 1;
                                           % building importance factor
g = 9.80656;
                                           % gravity
tec data = zeros(1000,1);
i = 1;
for T = 0:0.005:5
    if T < Ta
       S = 1+1.5*(T/Ta);
                                                          % spectrum
coefficient
    elseif Ta < T && T < Tb
        S = 2.5;
    elseif Tb < T</pre>
        S = 2.5*(Tb/T)^0.8;
    tec_data(i,1)=S;
    i = i+1;
end
A = (A0*I)*tec data;
Sae = A*q;
plot(0:0.005:5, Sae)
ii=1:
   for T = 0:0.005:5
        ksi = 0.05;
                                                   % specified in the question
        mass = 1;
                                                   % unit mass
        omega_n = 2*pi/T;
                                                   % natural frequency
        k = omega n*omega n*mass;
        c = 2*ksi*mass*omega n;
        u = 0;
                                                    % displacement
                                                    % velocity
        u dot = 0;
```

```
for j = 1:n-1
            F 1 = -acceleration recorded(j,1)*mass;
            F 2 = -acceleration recorded(j+1,1)*mass;
            u double dot = (F 1-c*u dot-k*u)/mass;
            k1 = k+(2*c)/delta t+(4*mass)/(delta t*delta t);
            delta F = F 2-F 1+(4*mass/delta t+2*c)*u dot+2*mass*u double dot;
            delta u = delta F/k1;
            delta u dot = 2*delta u/delta t-2*u dot;
            delta u double dot = 4*delta u/(delta t^2)-4*u dot/delta t-
2*u double dot;
            u = u+delta_u;
            u dot = u dot+delta u dot;
            u double dot = u double dot+delta u double dot;
            Sal(j,1) = u*omega n^2;
            Sd1(j,1) = u;
        end
        Sa(ii,1) = max(abs(Sa1));
        Sd(ii,1) = max(abs(Sd1));
        PSa(ii,1) = omega n*omega n*Sd(ii,1);
            ii = ii+1;
    end
 hold on
      plot(0:0.005:5,Sa)
      title('TEC2007 Spectrum vs Acceleration Response Spectra (Zone1, Z3)')
      xlabel('Period,T(sec)')
      ylabel('Acceleration, Sa(m/s^2)')
      legend('TEC2007 Spectrum','Acceleration Response
Spectra', 'Location', 'east')
      grid on
```



In the second part of the homework, Acceleration Response, Pseudo Acceleration Response and Displacement Response Spectra with respect to Period curves are obtained for three different damping ratios. By looking those curves, it can be said that effect of the damping ratio is significantly high for smaller periods as compared to the higher periods. Moreover, spectral parameters decrease as the damping ratio increases. In the case of smaller periods, small changes in the damping ratio result in significant changes at the behavior of the structural system. Having different damping ratios does not affect the spectral parameters seriously for the situation of relatively higher periods.

In the third part of the homework, TEC design response spectrum and Acceleration Response Spectra are compared. Since design response spectrum is mean and smoother version of a larger spectra, there are differences between TEC Spectrum and Acceleration Response Spectra. However, when all the data is considered and checked for the input values Acceleration Response Spectra is similar to the TEC Spectrum and gives reasonable results.