

RULES

1. This is the **version 3.1**. In case there are any corrections for the solutions of Exercise 3, we will post an updated version on our website. You can follow the changes in the exercises by the **Version History** section

Version History

v3.0 Solutions of Exercise 3 are released.

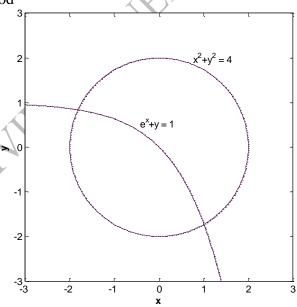
v3.1 In the solution of question 1 typing mistake " $\Delta x_k = -J^{-1} * x_k$ " was changed to its true form " $\Delta x_k = -J^{-1} * F$ ", results in the table is still same and true.

1.

$$x^2 + y^2 = 4$$

Solve this system using

a. graphical method





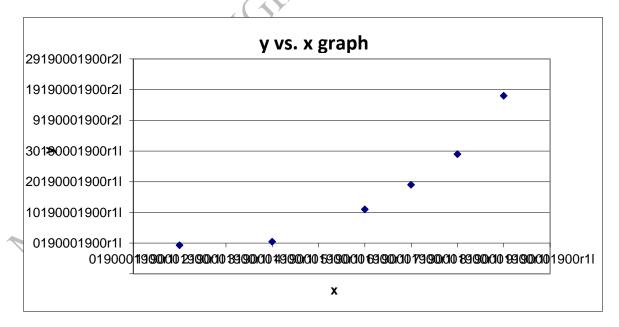
CE305Numerical Methods for Civil Engineers Solutions of Exercise v3.0

b. Newton-Jacobi method using $x_0 = 1$ and $y_0 = -1.7$, and error tolerance with respect to maximum norm as 10^{-4} .

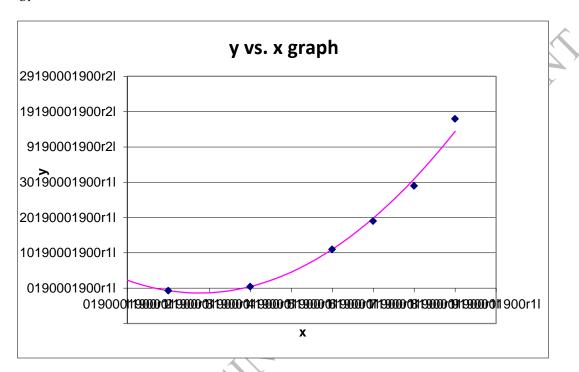
Iteration #	$\mathbf{x}_{\mathbf{k}}$	f(x _k)		J	J.	1	$\Delta \mathbf{x}_{\mathbf{k}} = -\mathbf{J}^{-1} * \mathbf{F}$	X _{k+1}	€ _{max}
	1.0000000	-0.1100000	2.0000000	-3.4000000	0.0889509	0.3024330	0.0042556	1.0042556	
1	-1.7000000	0.0182818	2.7182818	1.0000000	-0.2417936	0.1779018	-0.0298497	1.7298497	2.98E-02
	1.0042556	0.0009091	2.0085111	-3.4596993	0.0873129	0.3020765	-0.0000868	1.0041687	
2	-1.7298497	0.0000246	2.7298743	1.0000000	-0.2383534	0.1753690	0.0002124	- 1.7296373	2.12E-04
_	1.0041687	0.0000001	2.0083375	-3.4592746	0.0873294	0.3020962	0.0000000	1.0041687	
3	-1.7296373	0.0000000	2.7296373	1.0000000	-0.2383775	0.1753868	0.0000000	- 1.7296373	1.07E-08

2.

a.



b.

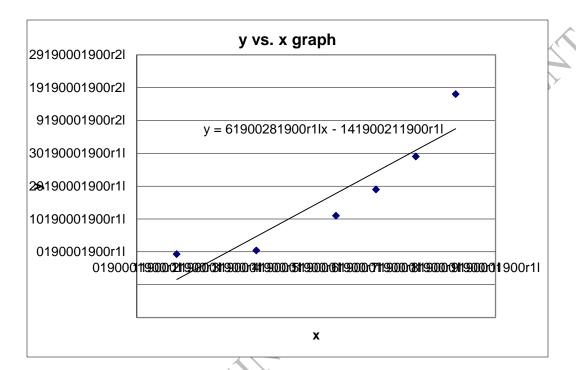


c.

X	у	y'	err %
1	-0,7	-0,7	0
6	19	19,8	4,0404
8	48	44,45	7,9865

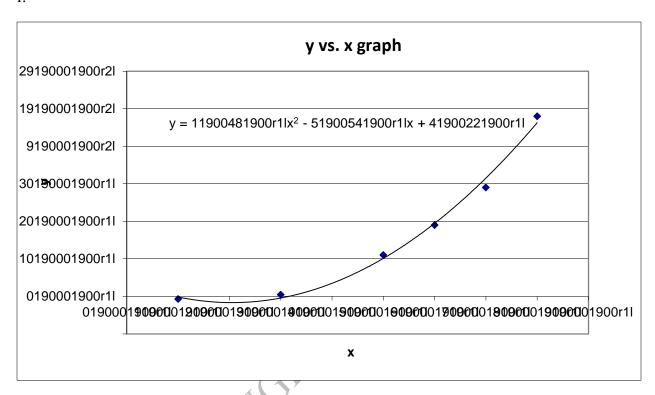
X	y'
3,6	2,628
9	60,3

e.



X	у	y'	diff	RMS
1,	-0,7	-8,425	7,725	
3	0,45	4,685	-4,235	
5	11	17,795	-6,795 -5,35	6,672406
6	19	24,35	-5,35	0,072400
7	29	30,905	-1,905	
8	48	37,46	10,54	

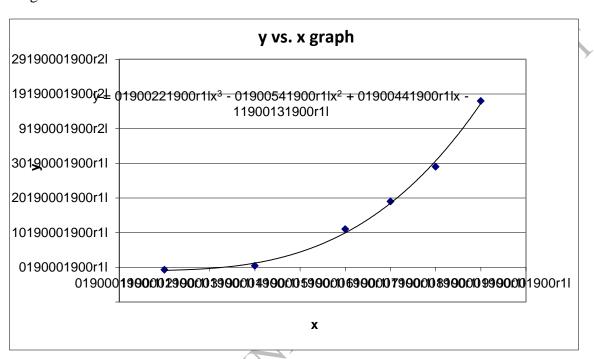
f.



Х	у	y'	diff	RMS
1	-0,7	-0,167	-0,533	
3	0,45	-0,453	0,903	
5	11	10,101	0,899	1,37641
6	19	19,443	-0,443	1,37041
7	29	31,495	-2,495	
8	48	46,257	1,743	

x	у	y'
3,6	-0,7	1,575
9	0,45	63,729

g.



x	у	y'	diff	RMS
1	-0,7	-0,8881	0,1881	
3	0,45	1,2161	-0,7661	
5	11	9,9483	1,0517	0,95043
6	19	18,4919	0,5081	0,93043
7	29	30,7229	-1,7229	
8	48	47,3181	0,6819	

x	у	y'
3,6	-0,7	2,893465
9	0,45	68,9543

h. Cubic estimation worked better than the others and gave the smallest RMS error because of the nature of function.

i. Quadratic regression function works better than the Lagrange polynomial as the whole data points were considered while applying quadratic regression. However for Lagrange polynomial only the three data points given were used to plot the graph.

