

CE 353 FORMULA SHEET

<p align="center">Braking and Stopping Sight Distance</p> $F_{b\max} = F_{bf\max} + F_{br\max}$ $BFR_{f\max} = \frac{F_{bf\max}}{F_{br\max}} = \frac{l_r + h(\mu + f_{rl})}{l_f - h(\mu + f_{rl})}$ $F_{bf\max} = \mu W_f = \frac{\mu W}{L} [l_r + h(\mu + f_{rl})]$ $F_{br\max} = \mu W_r = \frac{\mu W}{L} [l_f - h(\mu + f_{rl})]$ $F_{b\max} = \mu W = m \cdot a_{\max} \quad ; \quad \mu = \frac{a_{\max}}{g}$ $F_b = \eta_b \cdot \mu \cdot W = m \cdot a \quad ; \quad \eta_b = \frac{g_{\max}}{\mu}$ $f_{rl} = 0.01 \left(1 + \frac{V}{44.73} \right)$ $d_b = \frac{\gamma_b (V_1^2 - V_2^2)}{2g(\eta_b \mu + f_{rl} \pm G)} \quad d_b = \frac{V_1^2 - V_2^2}{2g(\eta_b \mu \pm G)}$ $d_s = \frac{\gamma_b V_1^2}{2g(\eta_b \mu + f_{rl} \pm G)} \quad d_s = \frac{V_1^2}{2g(\eta_b \mu \pm G)}$ $d_b = \frac{V_1^2 - V_2^2}{2g(0.35 \pm G)} \quad d_s = \frac{V_1^2}{2g(0.35 \pm G)}$ $d_r = V_l \times t_r \quad S_s = V_d t_r + \frac{V_d^2}{2g(0.35 \pm G)}$ $S_s = 0.278 V_d t_r + \frac{V_d^2}{254(0.35 \pm G)}$	$K = 2R \sin(\Delta/2) \quad \beta_i = l_i D$ $l_i = R \beta_i^{rad} \quad l_i = R \frac{\beta_i^o \pi}{180}$ <p align="center">Setting out circular curves</p> $k_i = 2R \sin(\beta_i/2) \text{ or } k_i = 2R \sin(l_i D/2)$ $d_i = \sum_i l_i \frac{D}{2} \quad y_i = R \sin\left(\sum_i l_i D\right)$ $x_i = R \left[1 - \cos\left(D \sum_i l_i\right) \right]$	<p>2) $L_m < S_s$</p> $M_s = M_m + \left(\frac{S_s - L_m}{2} \right) \sin \frac{\Delta}{2}$ $M_m = R_m \left(1 - \cos \frac{\Delta}{2} \right)$ $Max(S_s) = L_m + \frac{2(M_s - M_m)}{\sin(\Delta/2)}$ <p>For passing sight distance;</p> <p>1) $L_m \geq S_p$</p> $M_s = R_m \left(1 - \cos \frac{S_p}{2R_m} \right)$
<p align="center">Passing Sight Distance</p> $d_1 = 0.278 t_1 \left(V - m + \frac{at_1}{2} \right)$ $d_4 = 2/3 d_2 \quad S_p = d_1 + d_2 + d_3 + d_4$	<p align="center">Superelevation</p> $e + f_s = \frac{V^2}{gR} \quad ; \quad e + f_s = \frac{V^2}{127R}$ $e = \frac{0.00443V^2}{R} \quad ; \quad L_s = \frac{V^3}{RC}$ $L_s = \frac{e_{\max} D}{S_r} \quad L_s = \frac{e_{\max} w}{S_r}$ $L_s = \frac{0.0354V^3}{R} \quad L_s = \frac{e_{\max} (n_1 w)}{S_r} b_w$ $L_t = \frac{e_o}{e_{\max}} L_s$	<p>2) $L_m < S_p$</p> $M_s = M_m + \left(\frac{S_p - L_m}{2} \right) \sin \frac{\Delta}{2}$ $Max(S_p) = L_m + \frac{2(M_s - M_m)}{\sin(\Delta/2)}$
<p align="center">Circular curves</p> $D^{rad} = \frac{1}{R} \quad D^o = \frac{180}{\pi R}$ $L = R \Delta^{rad} ; \quad L = R \frac{\Delta^o \pi}{180} \quad T = R \tan\left(\frac{\Delta}{2}\right)$ $E = T \tan\left(\frac{\Delta}{4}\right) \text{ or } E = R \left[\frac{1}{\cos(\Delta/2)} - 1 \right]$ $M = R (1 - \cos(\Delta/2))$	<p align="center">Compound Curves</p> $t_1 = R_1 \tan \frac{\Delta_1}{2} \quad t_2 = R_2 \tan \frac{\Delta_2}{2}$ $T_1 = R_1 \tan \frac{\Delta_1}{2} + \frac{(t_1 + t_2) \sin \Delta_2}{\sin \Delta}$ $T_2 = R_2 \tan \frac{\Delta_2}{2} + \frac{(t_1 + t_2) \sin \Delta_1}{\sin \Delta}$ <p align="center">Sight Distance on Horizontal Curve</p> $\Delta_s^{rad} = \frac{S_s}{R_m}$ <p>1) $L_m \geq S_s$</p> $M_s = R_m \left(1 - \cos \frac{S_s}{2R_m} \right)$ $Max(S_s) = 2R_m \cos^{-1} \left(\frac{R_m - M_s}{R_m} \right)$	

<p>Parabolic Vertical Curves</p> $y = \frac{G_2 - G_1}{200L}x^2 + \frac{G_1}{100}x + Elv. PVC$ $Y = \frac{A}{200L}x^2$ $Y_m = \frac{AL}{800}, Y_f = \frac{AL}{200}, L = K * A$ $A = G_1 - G_2 , X_{h,l} = \frac{L}{A} * G_1 = K * G_1 $	<p>Earthwork</p> $A = \frac{1}{2} \sum_{i=1}^n [y_i (x_{i-1} - x_{i+1})] \cup$ $A = \frac{1}{2} \sum_{i=1}^n [y_i (x_{i+1} - x_{i-1})] \cup$ $V = \frac{A_1 + A_2}{2} d$ $l_c = \frac{A_c}{A_c + A_f} d, l_f = \frac{A_f}{A_c + A_f} d$	<p>Level of Service</p> $FFS = S_{FM} + 0.0125 \frac{V_f}{f_{HV}}$ $f_{HV} = \frac{1}{1 + P_T(E_T - 1) + P_R(E_R - 1)}$ $v_p = \frac{V}{PHF * x_f * x_{f_{HV}}}, PHF = \frac{V}{V_{15 \times 4}}$ $ATS = FFS - 0.0125 v_p - f_{np},$ $PTSF = BPTSF + f_{d/np}$ $BPTSF = 100(1 - e^{-0.000879 v_p})$
<p>Crest Type Vertical Curves</p> <p><u>For stopping sight distance;</u></p> $1) S_s < L \quad L_{min} = \frac{A * S_s^2}{658} \quad K = \frac{S_s^2}{658}$ $2) S_s > L \quad L_{min} = 2 * S_s - \frac{658}{A}$ <p><u>For passing sight distance;</u></p> $1) S_p < L \quad L_{min} = \frac{A * S_p^2}{864} \quad K = \frac{S_p^2}{864}$ $2) S_p > L \quad L_{min} = 2 * S_p - \frac{864}{A}$	<p>Traffic Flow Models</p> $K = \frac{DHV}{AADT} \quad DDHV = K * D * AADT$ $q = \frac{n}{t} \quad t = \sum_{i=1}^n h_i,$ $q = \frac{n}{\sum_{i=1}^n h_i}, q = \frac{1}{\bar{h}}$ $\bar{h} = \sum_{i=1}^n \frac{h_i}{n}, \quad \bar{u}_t = \frac{\sum_{i=1}^n u_i}{n}$ $\bar{u}_s = \frac{l}{\bar{t}} \quad \bar{t} = \sum_{i=1}^n \frac{t_i}{n}$ $\bar{u}_s = \frac{1}{\frac{1}{n} \sum_{i=1}^n \frac{1}{\left(\frac{l}{t_i}\right)}}$ $k = \frac{n}{l}, \quad l = \sum_{i=1}^n S_i,$ $k = \frac{n}{\sum_{i=1}^n S_i}$ $k = \frac{1}{\bar{s}}, \quad \bar{s} = \frac{\sum_{i=1}^n S_i}{n},$ $u = u_f \left(1 - \frac{k}{k_j}\right)$ $q = u * k \quad q_{cap} = \frac{u_f * k_j}{4}$ $q = u_f \left(k - \frac{k^2}{k_j}\right) = k_j \left(u - \frac{u^2}{u_f}\right)$ $k = k_j \left(1 - \frac{u}{u_f}\right)$	<p>Traffic Signalization</p> $S = \frac{3600}{h},$ $t_L = t_{sl} + t_{cl} = t_1 + t_2 + AR$ $t_{sl} = t_1 \quad t_{cl} = t_2 + AR$ $I = Y + AR \quad C = \sum_{i=1}^n G_i + nI$ $g = G + Y + AR - t_L$ $r = R + t_L - AR;$ $t_L = t_1 + t_2 + AR$ $r = R + t_1 + t_2$ $r = C - g$ $cap_i = S_i \frac{g_i}{C},$ $L = \sum_{i=1}^n (t_L)_{ci} \quad Y_C = \sum \left(\frac{v}{s}\right)_{ci},$ $C_{opt} = \frac{1.5xL + 5}{1 - Y_C}$ $g_i = \left(\frac{v}{s}\right)_{ci} \left(\frac{C - L}{Y_C}\right)$
<p>Sag Type Vertical Curve</p> $1) S_s < L$ $L_{min} = \frac{A * S_s^2}{120 + 3.5 S_s}$ $K = \frac{S_s^2}{120 + 3.5 S_s}$ $2) S_s > L$ $L_{min} = 2 * S_s - \frac{120 + 3.5 S_s}{A}$ <p>For passenger comfort; $L = \frac{AV_d^2}{395}$</p> <p>Underpass sight distance for Sag Vertical Curve</p> $1) S_s < L \quad L = \frac{A * S_s^2}{800(H_c - 1.5)}$ $2) S_s > L \quad L = 2 * S_s - \frac{800(H_c - 1.5)}{A}$		