

3.3.2

a) $M = (\{p, q\}, \Sigma, \nu, \Delta, p, \{q\})$

$$\Delta = \{ ((p, e, e), (q, s)), ((q, e, s), (q, e)), ((q, e, s), (q, ss)), ((q, e, s), (q, [s])), ((q, e, s), (q, (s))), ((q, (, (, (q, e)), ((q,),), (q, e)), ((q, [, [), (q, e)), ((q,],]), (q, e)) \}$$

$$\Sigma = \{ (, [,] \}$$

$$\nu = \{ s, (, [,] \}$$

b) $M = (\{s, f, g\}, \{a, b\}, \{a\}, \Delta, s, \{f, g\})$

$$\Delta = \{ ((s, a, e), (s, a)), ((s, e, e), (f, e)), ((f, b, a), (f, e)), ((f, b, a), (g, e)), ((g, b, e), (f, e)) \}$$

c) $M = (\underbrace{\{q_1, q_2, q_3, q_4\}}_{\Sigma}, \underbrace{\{a, b\}}_{\Sigma}, \underbrace{\{a, b, c\}}_{\Sigma}, \Delta, q_1, \{q_4\})$

$$\Delta = \{ ((q_1, e, e), (q_2, e)), ((q_2, a, e), (q_2, a)), ((q_2, b, e), (q_2, b)), ((q_2, a, e), (q_3, e)), ((q_2, b, e), (q_3, e)), ((q_2, e, e), (q_3, e)) \}$$

$(q_3, a, a), (q_3, e)$,
 $(q_3, b, b), (q_3, e)$,
 $((q_3, e, c), (q_4, e))$

d) $M = (\{S\}, \{a, b\}, \{A, B\}, \Delta, S, \{S\})$

$\Delta = \{((S, b, e), (S, B)), ((S, b, A), (S, e)),$
 $((S, a, B), (S, e)), ((S, a, e), (S, AA)), ((S, a, A), (S, A))\}$

3.4.1:

$M = (\{p, q\}, \{c\}, \{s, t\}, \Delta, p, \{q\})$

$\Delta = \{((p, e, e), (q, s)), ((q, e, s), (q, e)),$
 $((q, e, s), (q, ss)), ((q, e, s), (q, (s))),$
 $((q, c, c), (q, e)), ((q,) ,), (q, e))\}$

• $(c)(c)$ given input.

$(p, (c)(c), e) \vdash (q, (c)(c), s) \vdash (q, (c)(c), (s))$
 $\vdash (q, (c)(c), s) \vdash (q, (c)(c), ss) \vdash (q, (c)(c), (s)s)$
 $\vdash (q, (c)(c), s)s) \vdash (q, (c)(c),)s) \vdash (q, (c)(c), s)$
 $\vdash (q, (c), sq) \vdash (q, (c), (s)s) \vdash (q, (c), s)s)$
 $\vdash (q, (c),)s) \vdash (q, (c), s) \vdash (q, (c),) \vdash (q, e)$