Functions of a Matrix

The motivation is to study matrix-valued functions, which stems from the differential equations describing linear systems.

$$\dot{x} = Ax(t)$$

$$x(t) = e^{At}x(0)$$

The power series representation of any function is

$$f(s) = \sum_{i=0}^{\infty} lpha_i s^i$$

where $s \in \mathbb{C}$.

The power series representation of a matrix-valued function is

$$f(A) = \sum_{i=0}^{\infty} lpha_i A^i$$

where $A \in \mathbb{C}^{n \times n}$. This solution is another matrix as the same size as A.

The exponential function is defined for matrices as

$$e^t = \sum_{i=0}^{\infty} rac{t^i}{i!} \implies e^A = \sum_{i=0}^{\infty} rac{A^i}{i!}$$

By using Cayley-Hamilton Theorem, we can write A^i as a linear combination of $I, A, A^2, \cdots, A^{n-1}$.

$$e^A = c_0 I + c_1 A + c_2 A^2 + \dots + c_{n-1} A^{n-1}$$

where c_i are scalars.

Remark: One can use the minimal polynomial of a matrix to express the lth power of a matrix in terms of I,A,A^2,\cdots,A^{l-1} . l is the order of the minimal polynomial.

$$e^A = c_0 I + c_1 A + c_2 A^2 + \dots + c_{l-1} A^{l-1}$$

First Method

Let

$$f(s) = \sum_{i=0}^{\infty} lpha_i s^i$$

$$f(A) = \sum_{i=0}^{\infty} lpha_i A^i$$

Define p(s) and P(A) as follows

$$p(s) = c_0 + c_1 s + c_2 s^2 + \dots + c_{l-1} s^{l-1}$$

$$P(A) = c_0 I + c_1 A + c_2 A^2 + \dots + c_{l-1} A^{l-1}$$

Then we have the equality

$$f(A) = P(A)$$

where P(A) is a polynomial of A.

Case I: A is diagonalizable

Suppose

$$m(s) = (s - \lambda_1)(s - \lambda_2) \cdots (s - \lambda_{\sigma})$$

$$l=\sigma$$
 , $m_1=m_2=\cdots=m_\sigma=1$

$$f(A) = P(A) = c_0 I + c_1 A + c_2 A^2 + \dots + c_{l-1} A^{l-1}$$

$$Ae_i = \lambda_i e_i$$

Let e_i be the eigenvector of A corresponding to λ_i , multiply both sides by e_i .

$$\sum_{n=0}^{l-1} lpha_i A^n e_i = \sum_{n=0}^{l-1} c_n \lambda_i^n e_i$$

$$\sum_{n=0}^{l-1}lpha_i\lambda_i^ne_i=\sum_{n=0}^{l-1}c_n\lambda_i^ne_i$$

$$lpha_i \lambda_i^n = c_n \lambda_i^n$$

$$\alpha_i = c_n$$

$$f(A) = P(A) = \sum_{i=0}^{l-1} lpha_i A^i = \sum_{i=0}^{l-1} c_i A^i$$

$$f(\lambda_i) = P(\lambda_i)$$

Solution:

$$d(s) = (s-3)(s-1)$$

$$\lambda_1=3$$
, $\lambda_2=1$

$$m(s) = (s-3)(s-1)$$
, $l=2$

$$p(s) = c_0 + c_1 s$$
, and $P(A) = c_0 I + c_1 A$

$$Ae_1 = 3e_1$$
, $Ae_2 = e_2$

$$f(3)=p(3)$$

$$f(1) = p(1)$$

$$f(3) = e^3 = c_0 + 3c_1$$

$$f(1) = e = c_0 + c_1$$

$$c_1 = rac{e^3 - e}{2} \ c_0 = rac{3e - e^3}{2}$$

$$c_0 = \frac{3e-e^3}{2}$$

$$e^A = \frac{3e - e^3}{2}I + \frac{e^3 - e}{2}A$$

$$e^A=rac{3e-e^3}{2}egin{bmatrix}1&0\0&1\end{bmatrix}+rac{e^3-e}{2}egin{bmatrix}2&1\1&2\end{bmatrix}$$

Case II: A is not diagonalizable

Consider the following example. Let $A \in \mathbb{R}^3$ and $m(s) = (s - \lambda_1)^2 (s - \lambda_2)$.

$$J = egin{bmatrix} \lambda_1 & 1 & 0 \ 0 & \lambda_1 & 0 \ 0 & 0 & \lambda_2 \end{bmatrix} \ \sum m_i = 2 + 1 = 3 \ f(A) = P(A) = c_0 I + c_1 A + c_2 A^2 \ f(\lambda_1) = P(\lambda_1) & f(\lambda_2) = P(\lambda_2) \ \end{pmatrix}$$

These two equations are not enough to find c_0, c_1, c_2 .

Consider the matrix P that transforms A into its Jordan canonical form J.

We know that $P^{-1} = P^*$ and $P^*AP = J$, and P is in the form of $[e_1, f_1, e_2]$. Where e_1 and e_2 are the eigenvectors of A corresponding to λ_1 and λ_2 respectively. f_1 is the generalized eigenvector of A corresponding to λ_1 .

$$P = \begin{bmatrix} \vdots & \vdots & \vdots \\ e_1 & f_1 & e_2 \\ \vdots & \vdots & \vdots \end{bmatrix}$$

$$\begin{bmatrix} \vdots & \vdots & \vdots \\ e_1 & f_1 & e_2 \\ \vdots & \vdots & \vdots \end{bmatrix} \begin{bmatrix} \lambda_1 & 1 & 0 \\ 0 & \lambda_1 & 0 \\ 0 & 0 & \lambda_2 \end{bmatrix} = A \begin{bmatrix} \vdots & \vdots & \vdots \\ e_1 & f_1 & e_2 \\ \vdots & \vdots & \vdots \end{bmatrix}$$

$$Af_1 = \lambda_1 f_1 + e_1$$

$$A^2 f_1 = \lambda_1 A f_1 + A e_1$$

$$= \lambda_1^2 f_1 + \lambda_1 e_1 + \lambda_1 e_1 = \lambda_1^2 f_1 + 2\lambda_1 e_1$$

$$= \lambda_1^2 f_1 + \lambda_1 e_1 + \lambda_1 e_1 = \lambda_1^3 f_1 + 3\lambda_1^2 e_1$$

$$\vdots$$

$$A^k f_1 = \lambda_1^k f_1 + k \lambda_1^{k-1} e_1$$

Return to the equation f(A) = P(A).

$$\sum_{i=0}^{l-1}lpha_iA^i=\sum_{i=0}^{l-1}c_iA^i$$

Multiply both sides by f_1 from the right.

$$egin{split} \sum_{i=0}^{l-1}lpha_iA^if_1 &= \sum_{i=0}^{l-1}c_iA^if_1\ \sum_{i=0}^{l-1}lpha_i\lambda_1^if_1 + \sum_{i=0}^{l-1}lpha_ii\lambda_1^{i-1}e_1 &= \sum_{i=0}^{l-1}c_i\lambda_1^if_1 + \sum_{i=0}^{l-1}c_ii\lambda_1^{i-1}e_1\ &f(\lambda_1)f_1 + f'(\lambda_1)e_1 &= P(\lambda_1)f_1 + P'(\lambda_1)e_1\ &f(\lambda_1) &= P(\lambda_1)\ &f'(\lambda_1) &= P'(\lambda_1) \end{split}$$

Which is the additional equation we need to find c_0, c_1, c_2 .

General Case

Let $m(s)=(s-\lambda_1)^{m_1}(s-\lambda_2)^{m_2}\cdots(s-\lambda_\sigma)^{m_\sigma}$. We have the following set of equations.

$$f^{(t)}(\lambda_i) = P^{(t)}(\lambda_i)$$

where $t=0,1,2,\cdots,m_i-1$ and $i=1,2,\cdots,\sigma$. We have $\sum_{i=1}^{\sigma}m_i=l$ equations.

Solution:

 $m(s)=s^3(s-1)^2$ and the order of the total minimal polynomial is l=5.

$$p(s) = c_0 + c_1 s + c_2 s^2 + c_3 s^3 + c_4 s^4$$

$$p(A) = c_0 I + c_1 A + c_2 A^2 + c_3 A^3 + c_4 A^4$$

We need five equations to find c_0, c_1, c_2, c_3, c_4 .

Starting with

$$f(s) = \sin(\pi s)$$

$$f'(s) = \pi \cos(\pi s)$$

$$f''(s) = -\pi^2 \sin(\pi s)$$

Then

$$p(s) = c_0 + c_1 s + c_2 s^2 + c_3 s^3 + c_4 s^4$$

 $p'(s) = c_1 + 2c_2 s + 3c_3 s^2 + 4c_4 s^3$
 $p''(s) = 2c_2 + 6c_3 s + 12c_4 s^2$

For the first eigenvalue $\lambda_1=0$. We have $m_1=3$.

$$f(\lambda_1) = p(\lambda_1)$$

$$f'(\lambda_1) = p'(\lambda_1)$$

$$f''(\lambda_1) = p''(\lambda_1)$$

$$f(0) = p(0)$$

$$f'(0) = p'(0)$$

$$f''(0) = p''(0)$$

$$\sin(0) = 0 = c_0$$

$$\pi \cos(0) = \pi = c_1$$

$$-\pi^2 \sin(0) = 0 = 2c_2$$

For the second eigenvalue $\lambda_2 = 1$. We have $m_2 = 2$.

$$egin{aligned} egin{bmatrix} c_0 \ c_1 \ c_2 \ c_3 \ c_4 \end{bmatrix} &= egin{bmatrix} 0 \ \pi \ 0 \ -2\pi \ \pi \end{bmatrix} \ p(s) &= \pi s - 2\pi s^3 + \pi s^4 \ \sin{(\pi A)} &= \pi A - 2\pi A^3 + \pi A^4 \end{aligned}$$

Remark: f(A) does not exist when $f^{(t)}(\lambda_i)$ does not exist for some t and i.

#EE501 - Linear Systems Theory at METU