## vetor RSSI simulado

May 17, 2025

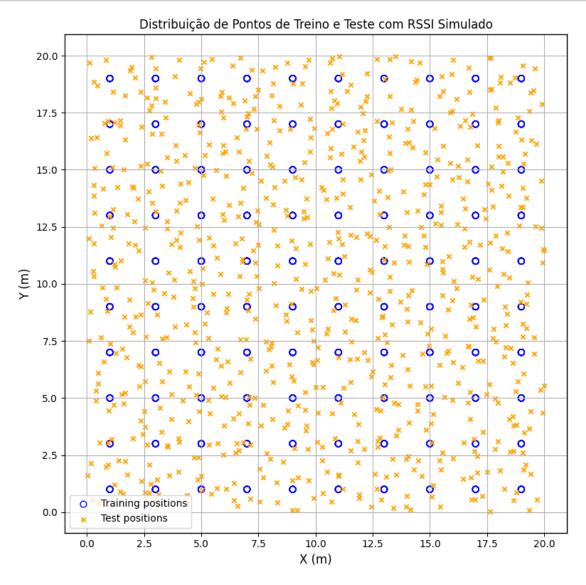
## 1 Simulação de Vetores RSSI com 10 APs em Área 20m x 20m

```
[19]: import numpy as np
    import pandas as pd
    import matplotlib.pyplot as plt
# 1. Parâmetros do ambiente
    area_size = 20
    grid step = 1
    n_aps = 10
    n_measurements = 10  # por ponto de treino
    frequency = 2.4e9 # Hz
    pt = 20 \# dBm
    p10 = 40 \# dB
    mu = 3.5
    sigma = 2
    d0 = 1 \# m
# 2. Posições fixas dos APs
    np.random.seed(42)
    ap_positions = np.random.uniform(0, area_size, size=(n_aps, 2))
# 3. Função para gerar RSSI
    # =========
    def simulate_rssi(point):
       rssi_values = []
       for ap in ap_positions:
          d = np.linalg.norm(point - ap)
          d = max(d, d0)
          path_loss = pl0 + 20 * np.log10(frequency) + 10 * mu * np.log10(d / d0)
          noise = np.random.normal(0, sigma)
          rssi = pt - path_loss + noise
```

```
rssi = max(rssi, -110)
  rssi_values.append(rssi)
return rssi_values
```

```
df_test["source"] = "test"
# 7. Unificar para uso no GAN
     # -----
     df_all = pd.concat([df_simulated, df_test], ignore_index=True)
# 8. Verificação
     print(f"Treino: {len(df_simulated)} vetores")
     print(f"Teste: {len(df_test)} vetores")
     print(f"Total no dataset final (df_all): {len(df_all)} vetores")
    Treino: 1000 vetores
    Teste: 800 vetores
    Total no dataset final (df_all): 1800 vetores
# 9. Salvar CSVs (opcional)
     # -----
     df_simulated.to_csv("/home/darkcover/Documentos/Gan/Data/df_simulated.csv",
      →index=False)
     df_test.to_csv("/home/darkcover/Documentos/Gan/Data/df_test.csv", index=False)
     df_all.to_csv("/home/darkcover/Documentos/Gan/Data/df_all.csv", index=False)
[51]: import matplotlib.pyplot as plt
     # Separar treino e teste com base na coluna "source"
     df_train_vis = df_all[df_all['source'] == 'real']
     df_test_vis = df_all[df_all['source'] == 'test']
     # Criar figura
     plt.figure(figsize=(8, 8))
     # Plotar pontos de treino (azul)
     plt.scatter(df_train_vis['X'], df_train_vis['Y'], marker='o', facecolors='none',
               edgecolors='blue', s=40, label='Training positions')
     # Plotar pontos de teste (vermelho)
     plt.scatter(df_test_vis['X'], df_test_vis['Y'],
               c='orange', marker='x', s=20, label='Test positions')
     # Configurações do gráfico
     plt.xlabel("X (m)")
     plt.ylabel("Y (m)")
     plt.title("Distribuição de Pontos de Treino e Teste com RSSI Simulado")
     plt.legend()
```

```
plt.grid(True)
plt.axis('equal')
plt.tight_layout()
plt.show()
```



```
[34]: import matplotlib.pyplot as plt
import matplotlib as mpl

# Estilo geral
mpl.rcParams.update({
    "font.size": 10,
    "axes.labelsize": 12,
```

```
"axes.titlesize": 12,
    "legend.fontsize": 10,
    "xtick.labelsize": 10,
    "ytick.labelsize": 10,
    "figure.dpi": 100,
    "axes.linewidth": 1
})
# Separar treino e teste
df_train_vis = df_all[df_all['source'] == 'real']
df test vis = df all[df all['source'] == 'test']
# Criar figura
plt.figure(figsize=(6.5, 6.5))
# Test positions (vermelho escuro)
plt.scatter(df_test_vis['X'], df_test_vis['Y'],
            c='darkred', marker='x', s=40, label='Test positions')
# Training positions (azul claro com contorno)
plt.scatter(df_train_vis['X'], df_train_vis['Y'],
            facecolors='lightblue', edgecolors='black',
            marker='o', s=50, label='Training positions')
# Configurações finais
plt.xlabel("X")
plt.ylabel("Y")
plt.grid(True, linestyle='--', linewidth=0.5, alpha=0.7)
plt.legend(loc='upper right', frameon=True)
plt.axis('equal')
plt.xlim(0, 20)
plt.ylim(0, 20)
# Remover título superior, adicionar título estilo legenda inferior
plt.tight_layout()
plt.subplots_adjust(bottom=0.12)
plt.figtext(0.5, 0.01, "FIGURE 3. The location of training and test positions ⊔
 ⇔on the simulated indoor environment.",
            wrap=True, horizontalalignment='center', fontsize=10)
plt.show()
```

Ignoring fixed x limits to fulfill fixed data aspect with adjustable data limits.

Ignoring fixed y limits to fulfill fixed data aspect with adjustable data limits.

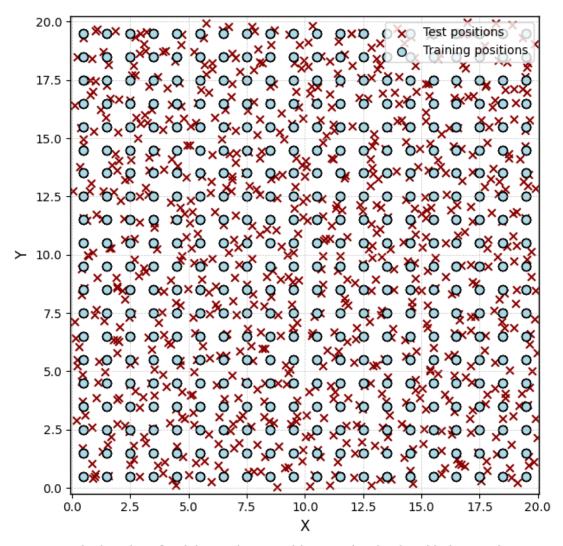


FIGURE 3. The location of training and test positions on the simulated indoor environment.