fase3 2

May 18, 2025

```
[1]: import numpy as np
  import pandas as pd
  import matplotlib.pyplot as plt
  from sklearn.model_selection import train_test_split
  from tensorflow.keras.models import Sequential
  from tensorflow.keras.layers import Dense
  from tensorflow.keras.optimizers import Adam
```

2025-05-18 20:33:40.130223: I external/local_xla/xla/tsl/cuda/cudart_stub.cc:32] Could not find cuda drivers on your machine, GPU will not be used.

2025-05-18 20:33:40.233613: I external/local_xla/xla/tsl/cuda/cudart_stub.cc:32] Could not find cuda drivers on your machine, GPU will not be used.

2025-05-18 20:33:40.316685: E

external/local_xla/xla/stream_executor/cuda/cuda_fft.cc:467] Unable to register cuFFT factory: Attempting to register factory for plugin cuFFT when one has already been registered

WARNING: All log messages before absl::InitializeLog() is called are written to STDERR

E0000 00:00:1747614820.389666 66064 cuda_dnn.cc:8579] Unable to register cuDNN factory: Attempting to register factory for plugin cuDNN when one has already been registered

E0000 00:00:1747614820.411612 66064 cuda_blas.cc:1407] Unable to register cuBLAS factory: Attempting to register factory for plugin cuBLAS when one has already been registered

W0000 00:00:1747614820.571882 66064 computation_placer.cc:177] computation placer already registered. Please check linkage and avoid linking the same target more than once.

W0000 00:00:1747614820.571921 66064 computation_placer.cc:177] computation placer already registered. Please check linkage and avoid linking the same target more than once.

W0000 00:00:1747614820.571926 66064 computation_placer.cc:177] computation placer already registered. Please check linkage and avoid linking the same target more than once.

W0000 00:00:1747614820.571929 66064 computation_placer.cc:177] computation placer already registered. Please check linkage and avoid linking the same target more than once.

2025-05-18 20:33:40.614977: I tensorflow/core/platform/cpu_feature_guard.cc:210] This TensorFlow binary is optimized to use available CPU instructions in

performance-critical operations.

To enable the following instructions: AVX2 FMA, in other operations, rebuild TensorFlow with the appropriate compiler flags.

/home/darkcover/.cache/pypoetry/virtualenvs/gan-oPyfrVEv-py3.12/lib/python3.12/site-packages/keras/src/layers/core/dense.py:87:
UserWarning: Do not pass an `input_shape`/`input_dim` argument to a layer. When using Sequential models, prefer using an `Input(shape)` object as the first layer in the model instead.

```
super().__init__(activity_regularizer=activity_regularizer, **kwargs)
2025-05-18 20:33:50.035518: E
external/local_xla/xla/stream_executor/cuda/cuda_platform.cc:51] failed call to
cuInit: INTERNAL: CUDA error: Failed call to cuInit: UNKNOWN ERROR (303)
```

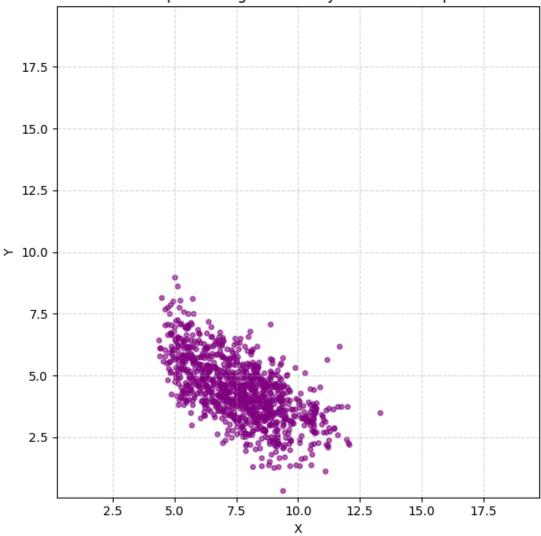
[3]: <keras.src.callbacks.history.History at 0x76326e8ba180>

```
# 4. Reproduzir Figura 4
    sample_1000 = df_generated.iloc[:1000]
    plt.figure(figsize=(6.5, 6.5))
    plt.scatter(sample_1000['X'], sample_1000['Y'],
              c='purple', alpha=0.6, s=15, label='Pseudo-labeled positions')
    plt.xlabel("X")
    plt.ylabel("Y")
    plt.title("FIGURE 4. 1000 positions generated by the GAN with pseudo labels.")
    plt.grid(True, linestyle='--', alpha=0.5)
    plt.axis('equal')
    plt.xlim(0, 20)
    plt.ylim(0, 20)
    plt.tight_layout()
    plt.show()
```

Ignoring fixed y limits to fulfill fixed data aspect with adjustable data limits.

Ignoring fixed x limits to fulfill fixed data aspect with adjustable data limits.





```
plt.xlim(0, 20)
plt.ylim(0, 20)
plt.tight_layout()
plt.show()
```

Ignoring fixed y limits to fulfill fixed data aspect with adjustable data limits.

Ignoring fixed ${\bf x}$ limits to fulfill fixed data aspect with adjustable data limits.

17.5 15.0 12.5 > 10.0 7.5 5.0 2.5 -

```
FIGURE 4. 1000 positions generated by the GAN with pseudo labels.
```

5.0

7.5

10.0

Х

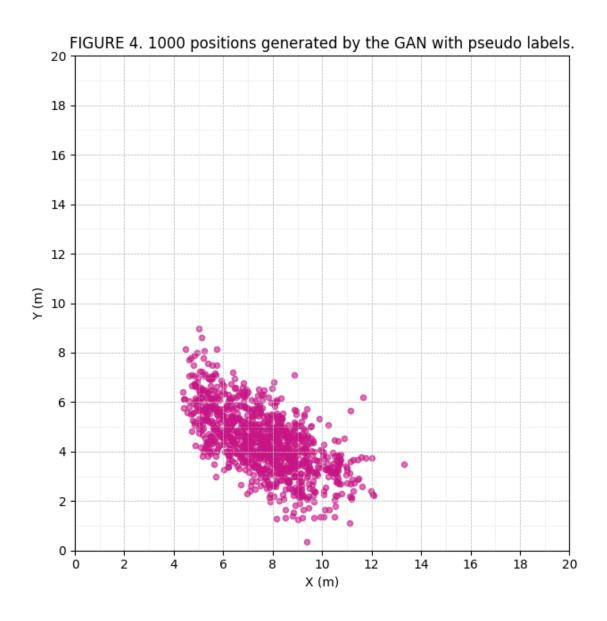
12.5

15.0

17.5

2.5

```
sample_1000 = df_generated.iloc[:1000]
plt.figure(figsize=(6.5, 6.5))
# Dispersão simples dos pseudo-rótulos
plt.scatter(sample_1000['X'], sample_1000['Y'],
            c='mediumvioletred', s=20, alpha=0.6)
# Desenhar fundo quadriculado
for x in range(0, 21):
    plt.axvline(x, color='lightgray', linestyle=':', linewidth=0.5)
for y in range(0, 21):
    plt.axhline(y, color='lightgray', linestyle=':', linewidth=0.5)
# Estilo compatível com o artigo
plt.xlabel("X (m)")
plt.ylabel("Y (m)")
plt.title("FIGURE 4. 1000 positions generated by the GAN with pseudo labels.")
plt.xlim(0, 20)
plt.ylim(0, 20)
plt.xticks(np.arange(0, 21, 2))
plt.yticks(np.arange(0, 21, 2))
plt.grid(True, linestyle='--', linewidth=0.5)
plt.gca().set_aspect('equal', adjustable='box')
plt.tight_layout()
plt.show()
```



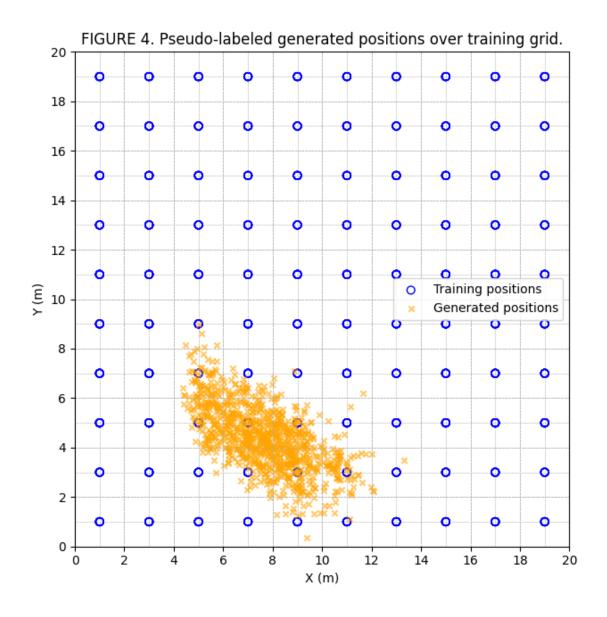
```
[13]: import matplotlib.pyplot as plt
import numpy as np

# Carregar os dados reais de treino (centralizados)
df_train = pd.read_csv("/home/darkcover/Documentos/Gan/Data/df_simulated.csv")
sample_1000 = df_generated.iloc[:1000]

# Criar gráfico
plt.figure(figsize=(6.5, 6.5))

# Treinamento: círculos vazados azuis
```

```
plt.scatter(df_train['X'], df_train['Y'],
            facecolors='none', edgecolors='blue', s=40, label='Training_
 ⇔positions')
# Gerados: preenchidos em roxo
plt.scatter(sample 1000['X'], sample 1000['Y'],
            c='orange', marker='x', s=20, alpha=0.6, label='Generated_
 ⇔positions')
# Sublinhas tracejadas de 1 em 1 metro (por cima dos pontos)
for x in np.arange(0, 21, 1):
    plt.axvline(x, color='gray', linestyle=':', linewidth=0.5, zorder=0)
for y in np.arange(0, 21, 1):
    plt.axhline(y, color='gray', linestyle=':', linewidth=0.5, zorder=0)
# Configurações visuais
plt.xlabel("X (m)")
plt.ylabel("Y (m)")
plt.title("FIGURE 4. Pseudo-labeled generated positions over training grid.")
plt.xticks(np.arange(0, 21, 2))
plt.yticks(np.arange(0, 21, 2))
plt.xlim(0, 20)
plt.ylim(0, 20)
plt.grid(True, linestyle='--', linewidth=0.5)
plt.gca().set_aspect('equal', adjustable='box')
plt.legend()
plt.tight_layout()
plt.show()
```



```
[14]: import matplotlib.pyplot as plt
import numpy as np

# Carregar os dados reais de treino (centralizados)
df_train = pd.read_csv("/home/darkcover/Documentos/Gan/Data/df_simulated.csv")
sample_1000 = df_generated

# Criar gráfico
plt.figure(figsize=(6.5, 6.5))

# Treinamento: círculos vazados azuis
```

```
plt.scatter(df_train['X'], df_train['Y'],
            facecolors='none', edgecolors='blue', s=40, label='Training_
 ⇔positions')
# Gerados: preenchidos em roxo
plt.scatter(sample 1000['X'], sample 1000['Y'],
            c='orange', marker='x', s=20, alpha=0.6, label='Generated_
 ⇔positions')
# Sublinhas tracejadas de 1 em 1 metro (por cima dos pontos)
for x in np.arange(0, 21, 1):
    plt.axvline(x, color='gray', linestyle=':', linewidth=0.5, zorder=0)
for y in np.arange(0, 21, 1):
    plt.axhline(y, color='gray', linestyle=':', linewidth=0.5, zorder=0)
# Configurações visuais
plt.xlabel("X (m)")
plt.ylabel("Y (m)")
plt.title("FIGURE 4. Pseudo-labeled generated positions over training grid.")
plt.xticks(np.arange(0, 21, 2))
plt.yticks(np.arange(0, 21, 2))
plt.xlim(0, 20)
plt.ylim(0, 20)
plt.grid(True, linestyle='--', linewidth=0.5)
plt.gca().set_aspect('equal', adjustable='box')
plt.legend()
plt.tight_layout()
plt.show()
```

