

## fase3\_2

May 21, 2025

```
[33]: import numpy as np
import pandas as pd
from sklearn.model_selection import train_test_split
import tensorflow as tf
from tensorflow.keras.models import Model, load_model
from tensorflow.keras.layers import Dense, Input
from tensorflow.keras.optimizers import Adam
import matplotlib.pyplot as plt
```

```
[34]: # =====
# 1. Carregar dados reais e gerados
# =====
df_all = pd.read_csv("/home/darkcover/Documentos/Gan/Data/df_all.csv")
df_generated = pd.read_csv("/home/darkcover/Documentos/Gan/Data/df_generated.
    ↪CSV")

df_real = df_all[df_all["source"] == "real"].copy()
X_real = df_real.iloc[:, :10].values.astype(np.float32)
y_real = df_real[["X", "Y"]].values.astype(np.float32)
```

```
[35]: # =====
# 2. Treinar rede DNN para pseudo-rotulação
# (2 camadas: 30 e 20 neurônios, 250 epochs, batch_size=100)
# =====
n_features = X_real.shape[1]
inp = Input(shape=(n_features,))
x = Dense(30, activation='relu')(inp)
x = Dense(20, activation='relu')(x)
out = Dense(2, activation='linear')(x) # Saida linear para as coordenadas X e Y
model_dnn = Model(inputs=inp, outputs=out, name="PseudoLabelModel")

model_dnn.compile(optimizer=Adam(learning_rate=0.01), loss='mse')
X_train, X_val, y_train, y_val = train_test_split(X_real, y_real, test_size=0.
    ↪2, random_state=42)

model_dnn.fit(X_train, y_train, validation_data=(X_val, y_val), epochs=250,
    ↪batch_size=100, verbose=1)
```

```
# Salvar o modelo
model_dnn.save("/home/darkcover/Documentos/Gan/Models/pseudo_label_model.keras")
```

Epoch 1/250

8/8                    2s 38ms/step - loss:  
1918.4399 - val\_loss: 123.3480

Epoch 2/250

8/8                    0s 13ms/step - loss:  
91.9337 - val\_loss: 71.7335

Epoch 3/250

8/8                    0s 13ms/step - loss:  
63.3985 - val\_loss: 44.2677

Epoch 4/250

8/8                    0s 14ms/step - loss:  
48.3444 - val\_loss: 33.4482

Epoch 5/250

8/8                    0s 13ms/step - loss:  
33.9562 - val\_loss: 29.2731

Epoch 6/250

8/8                    0s 13ms/step - loss:  
28.1700 - val\_loss: 23.6993

Epoch 7/250

8/8                    0s 13ms/step - loss:  
22.5565 - val\_loss: 19.9321

Epoch 8/250

8/8                    0s 14ms/step - loss:  
18.1816 - val\_loss: 17.7275

Epoch 9/250

8/8                    0s 14ms/step - loss:  
17.7881 - val\_loss: 16.2061

Epoch 10/250

8/8                    0s 13ms/step - loss:  
16.6534 - val\_loss: 14.8085

Epoch 11/250

8/8                    0s 13ms/step - loss:  
14.8596 - val\_loss: 13.8147

Epoch 12/250

8/8                    0s 13ms/step - loss:  
13.3045 - val\_loss: 11.8507

Epoch 13/250

8/8                    0s 13ms/step - loss:  
11.6568 - val\_loss: 10.4727

Epoch 14/250

8/8                    0s 13ms/step - loss:  
9.7378 - val\_loss: 9.2843

Epoch 15/250

8/8                    0s 13ms/step - loss:

8.5150 - val\_loss: 7.8157  
Epoch 16/250  
8/8 0s 13ms/step - loss:  
7.2352 - val\_loss: 6.6290  
Epoch 17/250  
8/8 0s 13ms/step - loss:  
6.2295 - val\_loss: 5.9885  
Epoch 18/250  
8/8 0s 13ms/step - loss:  
5.7207 - val\_loss: 5.1383  
Epoch 19/250  
8/8 0s 13ms/step - loss:  
4.9185 - val\_loss: 4.9630  
Epoch 20/250  
8/8 0s 13ms/step - loss:  
4.7254 - val\_loss: 5.2709  
Epoch 21/250  
8/8 0s 13ms/step - loss:  
4.7733 - val\_loss: 5.1562  
Epoch 22/250  
8/8 0s 13ms/step - loss:  
4.9529 - val\_loss: 5.3197  
Epoch 23/250  
8/8 0s 13ms/step - loss:  
4.9335 - val\_loss: 5.1622  
Epoch 24/250  
8/8 0s 13ms/step - loss:  
4.3694 - val\_loss: 4.5321  
Epoch 25/250  
8/8 0s 14ms/step - loss:  
4.2866 - val\_loss: 4.8205  
Epoch 26/250  
8/8 0s 19ms/step - loss:  
4.3365 - val\_loss: 4.5162  
Epoch 27/250  
8/8 0s 16ms/step - loss:  
4.3279 - val\_loss: 4.4671  
Epoch 28/250  
8/8 0s 19ms/step - loss:  
3.9940 - val\_loss: 4.4875  
Epoch 29/250  
8/8 0s 16ms/step - loss:  
4.1959 - val\_loss: 4.4012  
Epoch 30/250  
8/8 0s 15ms/step - loss:  
4.1950 - val\_loss: 4.2256  
Epoch 31/250  
8/8 0s 15ms/step - loss:

4.1101 - val\_loss: 4.2619  
Epoch 32/250  
8/8 0s 16ms/step - loss:  
3.9472 - val\_loss: 4.7233  
Epoch 33/250  
8/8 0s 17ms/step - loss:  
3.8310 - val\_loss: 4.1380  
Epoch 34/250  
8/8 0s 17ms/step - loss:  
3.9136 - val\_loss: 4.0744  
Epoch 35/250  
8/8 0s 15ms/step - loss:  
4.0219 - val\_loss: 4.1986  
Epoch 36/250  
8/8 0s 15ms/step - loss:  
3.4935 - val\_loss: 4.0508  
Epoch 37/250  
8/8 0s 13ms/step - loss:  
3.7200 - val\_loss: 4.0263  
Epoch 38/250  
8/8 0s 14ms/step - loss:  
3.7237 - val\_loss: 3.9542  
Epoch 39/250  
8/8 0s 17ms/step - loss:  
4.2211 - val\_loss: 4.8645  
Epoch 40/250  
8/8 0s 16ms/step - loss:  
4.1602 - val\_loss: 5.0247  
Epoch 41/250  
8/8 0s 14ms/step - loss:  
4.3937 - val\_loss: 5.0287  
Epoch 42/250  
8/8 0s 15ms/step - loss:  
4.1487 - val\_loss: 4.1744  
Epoch 43/250  
8/8 0s 28ms/step - loss:  
3.5144 - val\_loss: 4.1166  
Epoch 44/250  
8/8 0s 19ms/step - loss:  
4.2125 - val\_loss: 5.2371  
Epoch 45/250  
8/8 0s 13ms/step - loss:  
4.4151 - val\_loss: 3.8922  
Epoch 46/250  
8/8 0s 14ms/step - loss:  
3.6710 - val\_loss: 3.7805  
Epoch 47/250  
8/8 0s 13ms/step - loss:

3.9533 - val\_loss: 3.8797  
Epoch 48/250  
8/8 0s 13ms/step - loss:  
3.5574 - val\_loss: 3.9474  
Epoch 49/250  
8/8 0s 13ms/step - loss:  
3.7332 - val\_loss: 4.0632  
Epoch 50/250  
8/8 0s 13ms/step - loss:  
3.7063 - val\_loss: 4.7731  
Epoch 51/250  
8/8 0s 13ms/step - loss:  
3.8886 - val\_loss: 3.9884  
Epoch 52/250  
8/8 0s 13ms/step - loss:  
3.4109 - val\_loss: 3.7116  
Epoch 53/250  
8/8 0s 13ms/step - loss:  
3.4204 - val\_loss: 3.7883  
Epoch 54/250  
8/8 0s 14ms/step - loss:  
3.3371 - val\_loss: 3.9241  
Epoch 55/250  
8/8 0s 13ms/step - loss:  
3.5332 - val\_loss: 3.9396  
Epoch 56/250  
8/8 0s 14ms/step - loss:  
3.6738 - val\_loss: 3.7927  
Epoch 57/250  
8/8 0s 15ms/step - loss:  
3.7892 - val\_loss: 3.8183  
Epoch 58/250  
8/8 0s 16ms/step - loss:  
4.0052 - val\_loss: 4.3349  
Epoch 59/250  
8/8 0s 16ms/step - loss:  
3.4092 - val\_loss: 3.7952  
Epoch 60/250  
8/8 0s 15ms/step - loss:  
3.4528 - val\_loss: 3.7430  
Epoch 61/250  
8/8 0s 27ms/step - loss:  
3.2570 - val\_loss: 3.9642  
Epoch 62/250  
8/8 0s 14ms/step - loss:  
3.3435 - val\_loss: 3.8988  
Epoch 63/250  
8/8 0s 16ms/step - loss:

3.2473 - val\_loss: 3.9612  
Epoch 64/250  
8/8 0s 15ms/step - loss:  
3.6429 - val\_loss: 3.8029  
Epoch 65/250  
8/8 0s 13ms/step - loss:  
3.2844 - val\_loss: 3.6122  
Epoch 66/250  
8/8 0s 13ms/step - loss:  
3.2897 - val\_loss: 3.7547  
Epoch 67/250  
8/8 0s 13ms/step - loss:  
3.3917 - val\_loss: 4.2650  
Epoch 68/250  
8/8 0s 16ms/step - loss:  
3.4222 - val\_loss: 4.0333  
Epoch 69/250  
8/8 0s 17ms/step - loss:  
3.5339 - val\_loss: 3.8665  
Epoch 70/250  
8/8 0s 15ms/step - loss:  
3.2375 - val\_loss: 3.5190  
Epoch 71/250  
8/8 0s 14ms/step - loss:  
3.1870 - val\_loss: 3.6121  
Epoch 72/250  
8/8 0s 14ms/step - loss:  
3.3674 - val\_loss: 3.7019  
Epoch 73/250  
8/8 0s 14ms/step - loss:  
3.2982 - val\_loss: 3.7362  
Epoch 74/250  
8/8 0s 13ms/step - loss:  
3.3845 - val\_loss: 4.4913  
Epoch 75/250  
8/8 0s 19ms/step - loss:  
3.5884 - val\_loss: 3.9656  
Epoch 76/250  
8/8 0s 17ms/step - loss:  
3.5034 - val\_loss: 3.7725  
Epoch 77/250  
8/8 0s 14ms/step - loss:  
3.3811 - val\_loss: 3.8900  
Epoch 78/250  
8/8 0s 13ms/step - loss:  
3.3924 - val\_loss: 3.8306  
Epoch 79/250  
8/8 0s 16ms/step - loss:

3.3399 - val\_loss: 3.7815  
Epoch 80/250  
8/8 0s 18ms/step - loss:  
3.1395 - val\_loss: 3.7856  
Epoch 81/250  
8/8 0s 17ms/step - loss:  
3.7090 - val\_loss: 3.6853  
Epoch 82/250  
8/8 0s 17ms/step - loss:  
3.0607 - val\_loss: 3.6571  
Epoch 83/250  
8/8 0s 17ms/step - loss:  
3.3859 - val\_loss: 3.8379  
Epoch 84/250  
8/8 0s 16ms/step - loss:  
3.1451 - val\_loss: 3.5412  
Epoch 85/250  
8/8 0s 14ms/step - loss:  
3.2023 - val\_loss: 3.6028  
Epoch 86/250  
8/8 0s 13ms/step - loss:  
3.3016 - val\_loss: 3.8572  
Epoch 87/250  
8/8 0s 13ms/step - loss:  
3.5570 - val\_loss: 3.5096  
Epoch 88/250  
8/8 0s 14ms/step - loss:  
3.2471 - val\_loss: 3.5162  
Epoch 89/250  
8/8 0s 18ms/step - loss:  
3.0058 - val\_loss: 3.9020  
Epoch 90/250  
8/8 0s 20ms/step - loss:  
3.0403 - val\_loss: 3.9628  
Epoch 91/250  
8/8 0s 18ms/step - loss:  
3.0173 - val\_loss: 3.3913  
Epoch 92/250  
8/8 0s 14ms/step - loss:  
3.3396 - val\_loss: 3.8356  
Epoch 93/250  
8/8 0s 14ms/step - loss:  
3.3955 - val\_loss: 4.0431  
Epoch 94/250  
8/8 0s 16ms/step - loss:  
3.2940 - val\_loss: 3.5857  
Epoch 95/250  
8/8 0s 16ms/step - loss:

3.5791 - val\_loss: 4.3708  
Epoch 96/250  
8/8 0s 13ms/step - loss:  
3.4592 - val\_loss: 3.9275  
Epoch 97/250  
8/8 0s 15ms/step - loss:  
3.0427 - val\_loss: 3.5305  
Epoch 98/250  
8/8 0s 21ms/step - loss:  
3.0898 - val\_loss: 3.4564  
Epoch 99/250  
8/8 0s 19ms/step - loss:  
3.0763 - val\_loss: 4.0141  
Epoch 100/250  
8/8 0s 15ms/step - loss:  
3.5653 - val\_loss: 3.7900  
Epoch 101/250  
8/8 0s 16ms/step - loss:  
3.2799 - val\_loss: 3.6945  
Epoch 102/250  
8/8 0s 14ms/step - loss:  
3.5751 - val\_loss: 3.3681  
Epoch 103/250  
8/8 0s 14ms/step - loss:  
3.3871 - val\_loss: 3.4569  
Epoch 104/250  
8/8 0s 16ms/step - loss:  
3.0218 - val\_loss: 3.5148  
Epoch 105/250  
8/8 0s 16ms/step - loss:  
3.0626 - val\_loss: 3.7389  
Epoch 106/250  
8/8 0s 39ms/step - loss:  
3.1320 - val\_loss: 3.2999  
Epoch 107/250  
8/8 0s 17ms/step - loss:  
3.0195 - val\_loss: 3.8026  
Epoch 108/250  
8/8 0s 14ms/step - loss:  
3.2995 - val\_loss: 3.4903  
Epoch 109/250  
8/8 0s 17ms/step - loss:  
2.9554 - val\_loss: 3.3274  
Epoch 110/250  
8/8 0s 16ms/step - loss:  
2.9474 - val\_loss: 3.2734  
Epoch 111/250  
8/8 0s 14ms/step - loss:



2.8492 - val\_loss: 3.4922  
Epoch 112/250  
8/8 0s 15ms/step - loss:  
3.1676 - val\_loss: 3.4310  
Epoch 113/250  
8/8 0s 16ms/step - loss:  
2.9392 - val\_loss: 3.4707  
Epoch 114/250  
8/8 0s 13ms/step - loss:  
3.0215 - val\_loss: 3.6275  
Epoch 115/250  
8/8 0s 13ms/step - loss:  
3.0582 - val\_loss: 3.4924  
Epoch 116/250  
8/8 0s 13ms/step - loss:  
3.1304 - val\_loss: 3.3033  
Epoch 117/250  
8/8 0s 13ms/step - loss:  
2.9306 - val\_loss: 3.2812  
Epoch 118/250  
8/8 0s 13ms/step - loss:  
2.9623 - val\_loss: 3.6463  
Epoch 119/250  
8/8 0s 12ms/step - loss:  
2.9771 - val\_loss: 3.2923  
Epoch 120/250  
8/8 0s 13ms/step - loss:  
3.1767 - val\_loss: 3.9721  
Epoch 121/250  
8/8 0s 12ms/step - loss:  
3.3571 - val\_loss: 3.2481  
Epoch 122/250  
8/8 0s 13ms/step - loss:  
2.9300 - val\_loss: 3.2632  
Epoch 123/250  
8/8 0s 13ms/step - loss:  
3.3300 - val\_loss: 3.3451  
Epoch 124/250  
8/8 0s 13ms/step - loss:  
2.8625 - val\_loss: 3.6540  
Epoch 125/250  
8/8 0s 13ms/step - loss:  
3.3044 - val\_loss: 3.3976  
Epoch 126/250  
8/8 0s 12ms/step - loss:  
3.6335 - val\_loss: 3.4135  
Epoch 127/250  
8/8 0s 13ms/step - loss:

3.2759 - val\_loss: 3.3847  
Epoch 128/250  
8/8 0s 17ms/step - loss:  
3.3028 - val\_loss: 3.3820  
Epoch 129/250  
8/8 0s 14ms/step - loss:  
3.0881 - val\_loss: 3.2860  
Epoch 130/250  
8/8 0s 15ms/step - loss:  
3.1732 - val\_loss: 3.6789  
Epoch 131/250  
8/8 0s 13ms/step - loss:  
3.0261 - val\_loss: 3.4222  
Epoch 132/250  
8/8 0s 13ms/step - loss:  
3.0202 - val\_loss: 3.1877  
Epoch 133/250  
8/8 0s 13ms/step - loss:  
2.8390 - val\_loss: 3.4471  
Epoch 134/250  
8/8 0s 14ms/step - loss:  
3.3808 - val\_loss: 3.8040  
Epoch 135/250  
8/8 0s 18ms/step - loss:  
3.5450 - val\_loss: 4.1029  
Epoch 136/250  
8/8 0s 16ms/step - loss:  
3.3996 - val\_loss: 3.5228  
Epoch 137/250  
8/8 0s 14ms/step - loss:  
3.0014 - val\_loss: 4.1702  
Epoch 138/250  
8/8 0s 15ms/step - loss:  
3.3622 - val\_loss: 4.2507  
Epoch 139/250  
8/8 0s 13ms/step - loss:  
3.5239 - val\_loss: 4.0857  
Epoch 140/250  
8/8 0s 13ms/step - loss:  
3.3365 - val\_loss: 4.0007  
Epoch 141/250  
8/8 0s 13ms/step - loss:  
3.6556 - val\_loss: 4.3725  
Epoch 142/250  
8/8 0s 13ms/step - loss:  
3.4249 - val\_loss: 3.4605  
Epoch 143/250  
8/8 0s 13ms/step - loss:

3.3095 - val\_loss: 3.6842  
Epoch 144/250  
8/8 0s 15ms/step - loss:  
3.5377 - val\_loss: 4.0976  
Epoch 145/250  
8/8 0s 13ms/step - loss:  
3.3792 - val\_loss: 3.5307  
Epoch 146/250  
8/8 0s 21ms/step - loss:  
3.2307 - val\_loss: 3.3244  
Epoch 147/250  
8/8 0s 15ms/step - loss:  
3.0717 - val\_loss: 3.1948  
Epoch 148/250  
8/8 0s 19ms/step - loss:  
2.8372 - val\_loss: 3.1924  
Epoch 149/250  
8/8 0s 17ms/step - loss:  
2.9449 - val\_loss: 3.4436  
Epoch 150/250  
8/8 0s 16ms/step - loss:  
3.1724 - val\_loss: 3.2725  
Epoch 151/250  
8/8 0s 16ms/step - loss:  
2.9288 - val\_loss: 3.3891  
Epoch 152/250  
8/8 0s 17ms/step - loss:  
3.1180 - val\_loss: 3.2663  
Epoch 153/250  
8/8 0s 16ms/step - loss:  
3.0802 - val\_loss: 3.0891  
Epoch 154/250  
8/8 0s 15ms/step - loss:  
3.1676 - val\_loss: 3.3667  
Epoch 155/250  
8/8 0s 14ms/step - loss:  
2.8837 - val\_loss: 3.4482  
Epoch 156/250  
8/8 0s 15ms/step - loss:  
2.7958 - val\_loss: 2.9868  
Epoch 157/250  
8/8 0s 13ms/step - loss:  
2.8710 - val\_loss: 3.0894  
Epoch 158/250  
8/8 0s 13ms/step - loss:  
2.8029 - val\_loss: 3.2512  
Epoch 159/250  
8/8 0s 13ms/step - loss:

2.8113 - val\_loss: 2.9710  
Epoch 160/250  
8/8 0s 13ms/step - loss:  
2.5236 - val\_loss: 3.0272  
Epoch 161/250  
8/8 0s 14ms/step - loss:  
2.8521 - val\_loss: 3.2415  
Epoch 162/250  
8/8 0s 13ms/step - loss:  
2.8121 - val\_loss: 2.9064  
Epoch 163/250  
8/8 0s 13ms/step - loss:  
2.6733 - val\_loss: 2.8839  
Epoch 164/250  
8/8 0s 13ms/step - loss:  
2.9209 - val\_loss: 3.3569  
Epoch 165/250  
8/8 0s 13ms/step - loss:  
2.9056 - val\_loss: 2.8741  
Epoch 166/250  
8/8 0s 15ms/step - loss:  
2.5774 - val\_loss: 2.9144  
Epoch 167/250  
8/8 0s 14ms/step - loss:  
2.6709 - val\_loss: 3.0261  
Epoch 168/250  
8/8 0s 13ms/step - loss:  
2.8163 - val\_loss: 2.9801  
Epoch 169/250  
8/8 0s 13ms/step - loss:  
2.6176 - val\_loss: 2.8335  
Epoch 170/250  
8/8 0s 17ms/step - loss:  
2.7054 - val\_loss: 3.0623  
Epoch 171/250  
8/8 0s 15ms/step - loss:  
3.0994 - val\_loss: 3.1713  
Epoch 172/250  
8/8 0s 14ms/step - loss:  
2.9912 - val\_loss: 3.1087  
Epoch 173/250  
8/8 0s 16ms/step - loss:  
2.7611 - val\_loss: 2.8760  
Epoch 174/250  
8/8 0s 18ms/step - loss:  
2.9130 - val\_loss: 3.0043  
Epoch 175/250  
8/8 0s 16ms/step - loss:

2.5414 - val\_loss: 2.9790  
Epoch 176/250  
8/8 0s 15ms/step - loss:  
2.5630 - val\_loss: 2.8930  
Epoch 177/250  
8/8 0s 14ms/step - loss:  
2.4459 - val\_loss: 2.8482  
Epoch 178/250  
8/8 0s 13ms/step - loss:  
2.7471 - val\_loss: 2.8158  
Epoch 179/250  
8/8 0s 13ms/step - loss:  
2.6262 - val\_loss: 2.9421  
Epoch 180/250  
8/8 0s 14ms/step - loss:  
2.7541 - val\_loss: 3.1860  
Epoch 181/250  
8/8 0s 13ms/step - loss:  
2.8702 - val\_loss: 3.2193  
Epoch 182/250  
8/8 0s 13ms/step - loss:  
3.0620 - val\_loss: 2.8906  
Epoch 183/250  
8/8 0s 13ms/step - loss:  
2.6153 - val\_loss: 3.0230  
Epoch 184/250  
8/8 0s 22ms/step - loss:  
2.9780 - val\_loss: 2.8207  
Epoch 185/250  
8/8 0s 18ms/step - loss:  
2.6279 - val\_loss: 3.1171  
Epoch 186/250  
8/8 0s 13ms/step - loss:  
2.8123 - val\_loss: 2.7742  
Epoch 187/250  
8/8 0s 13ms/step - loss:  
2.5581 - val\_loss: 2.9438  
Epoch 188/250  
8/8 0s 13ms/step - loss:  
2.6428 - val\_loss: 3.0153  
Epoch 189/250  
8/8 0s 13ms/step - loss:  
2.6929 - val\_loss: 2.7569  
Epoch 190/250  
8/8 0s 13ms/step - loss:  
2.6233 - val\_loss: 2.9072  
Epoch 191/250  
8/8 0s 13ms/step - loss:

2.6010 - val\_loss: 3.0313  
Epoch 192/250  
8/8 0s 13ms/step - loss:  
2.9142 - val\_loss: 2.6704  
Epoch 193/250  
8/8 0s 12ms/step - loss:  
2.6024 - val\_loss: 2.9002  
Epoch 194/250  
8/8 0s 13ms/step - loss:  
2.8371 - val\_loss: 3.1703  
Epoch 195/250  
8/8 0s 15ms/step - loss:  
2.5916 - val\_loss: 2.8851  
Epoch 196/250  
8/8 0s 13ms/step - loss:  
2.5158 - val\_loss: 2.8282  
Epoch 197/250  
8/8 0s 13ms/step - loss:  
2.4862 - val\_loss: 2.6464  
Epoch 198/250  
8/8 0s 13ms/step - loss:  
2.5178 - val\_loss: 2.7205  
Epoch 199/250  
8/8 0s 13ms/step - loss:  
2.6780 - val\_loss: 2.6854  
Epoch 200/250  
8/8 0s 13ms/step - loss:  
2.7847 - val\_loss: 2.7456  
Epoch 201/250  
8/8 0s 14ms/step - loss:  
2.6973 - val\_loss: 3.0340  
Epoch 202/250  
8/8 0s 13ms/step - loss:  
2.6448 - val\_loss: 3.3541  
Epoch 203/250  
8/8 0s 13ms/step - loss:  
2.9174 - val\_loss: 2.6517  
Epoch 204/250  
8/8 0s 18ms/step - loss:  
2.5360 - val\_loss: 2.8544  
Epoch 205/250  
8/8 0s 17ms/step - loss:  
2.5844 - val\_loss: 2.7052  
Epoch 206/250  
8/8 0s 18ms/step - loss:  
2.4476 - val\_loss: 2.6490  
Epoch 207/250  
8/8 0s 18ms/step - loss:

2.5809 - val\_loss: 2.9596  
Epoch 208/250  
8/8 0s 17ms/step - loss:  
2.5066 - val\_loss: 2.9539  
Epoch 209/250  
8/8 0s 19ms/step - loss:  
2.7879 - val\_loss: 2.7316  
Epoch 210/250  
8/8 0s 16ms/step - loss:  
2.4063 - val\_loss: 2.7973  
Epoch 211/250  
8/8 0s 13ms/step - loss:  
2.5988 - val\_loss: 2.6656  
Epoch 212/250  
8/8 0s 13ms/step - loss:  
2.3476 - val\_loss: 2.6060  
Epoch 213/250  
8/8 0s 13ms/step - loss:  
2.5817 - val\_loss: 2.5777  
Epoch 214/250  
8/8 0s 17ms/step - loss:  
2.4121 - val\_loss: 2.6798  
Epoch 215/250  
8/8 0s 22ms/step - loss:  
2.4011 - val\_loss: 2.6544  
Epoch 216/250  
8/8 0s 16ms/step - loss:  
2.3469 - val\_loss: 2.6284  
Epoch 217/250  
8/8 0s 13ms/step - loss:  
2.1841 - val\_loss: 2.7264  
Epoch 218/250  
8/8 0s 13ms/step - loss:  
2.3985 - val\_loss: 2.5384  
Epoch 219/250  
8/8 0s 13ms/step - loss:  
2.2590 - val\_loss: 2.5911  
Epoch 220/250  
8/8 0s 13ms/step - loss:  
2.6058 - val\_loss: 2.5409  
Epoch 221/250  
8/8 0s 13ms/step - loss:  
2.5033 - val\_loss: 2.6867  
Epoch 222/250  
8/8 0s 13ms/step - loss:  
2.4019 - val\_loss: 2.8562  
Epoch 223/250  
8/8 0s 13ms/step - loss:

2.5830 - val\_loss: 2.6484  
Epoch 224/250  
8/8 0s 13ms/step - loss:  
2.4115 - val\_loss: 2.5228  
Epoch 225/250  
8/8 0s 13ms/step - loss:  
2.3907 - val\_loss: 2.8402  
Epoch 226/250  
8/8 0s 13ms/step - loss:  
2.4103 - val\_loss: 2.8649  
Epoch 227/250  
8/8 0s 13ms/step - loss:  
2.4914 - val\_loss: 2.6461  
Epoch 228/250  
8/8 0s 13ms/step - loss:  
2.5274 - val\_loss: 2.5128  
Epoch 229/250  
8/8 0s 13ms/step - loss:  
2.3912 - val\_loss: 3.0698  
Epoch 230/250  
8/8 0s 13ms/step - loss:  
2.6779 - val\_loss: 2.6600  
Epoch 231/250  
8/8 0s 13ms/step - loss:  
2.4622 - val\_loss: 2.7183  
Epoch 232/250  
8/8 0s 13ms/step - loss:  
2.7125 - val\_loss: 3.2702  
Epoch 233/250  
8/8 0s 13ms/step - loss:  
2.5869 - val\_loss: 2.5520  
Epoch 234/250  
8/8 0s 12ms/step - loss:  
2.3138 - val\_loss: 2.7724  
Epoch 235/250  
8/8 0s 13ms/step - loss:  
2.3066 - val\_loss: 2.6678  
Epoch 236/250  
8/8 0s 13ms/step - loss:  
2.3575 - val\_loss: 2.9221  
Epoch 237/250  
8/8 0s 13ms/step - loss:  
2.6503 - val\_loss: 2.5473  
Epoch 238/250  
8/8 0s 13ms/step - loss:  
2.3392 - val\_loss: 2.5012  
Epoch 239/250  
8/8 0s 13ms/step - loss:



```

2.4223 - val_loss: 2.5203
Epoch 240/250
8/8          0s 13ms/step - loss:
2.2452 - val_loss: 2.5098
Epoch 241/250
8/8          0s 13ms/step - loss:
2.2928 - val_loss: 2.6741
Epoch 242/250
8/8          0s 13ms/step - loss:
2.2902 - val_loss: 2.4388
Epoch 243/250
8/8          0s 14ms/step - loss:
2.4358 - val_loss: 2.6542
Epoch 244/250
8/8          0s 24ms/step - loss:
2.3562 - val_loss: 2.8325
Epoch 245/250
8/8          0s 21ms/step - loss:
2.5471 - val_loss: 2.5571
Epoch 246/250
8/8          0s 13ms/step - loss:
2.4250 - val_loss: 2.4898
Epoch 247/250
8/8          0s 13ms/step - loss:
2.2759 - val_loss: 2.4635
Epoch 248/250
8/8          0s 13ms/step - loss:
2.2975 - val_loss: 2.5253
Epoch 249/250
8/8          0s 13ms/step - loss:
2.2699 - val_loss: 2.4112
Epoch 250/250
8/8          0s 13ms/step - loss:
2.4405 - val_loss: 2.5085

```

```

[36]: # =====
# 3. Predição de pseudo-rotulos nos vetores sinteticos
#   (X, Y) para os dados gerados
# =====
X_gen = df_generated.iloc[:, :10].values.astype(np.float32)
pseudo = model_dnn.predict(X_gen, verbose=1)
df_generated[['X', 'Y']] = pseudo

```

```

1250/1250          2s 1ms/step

```

```

[37]: # =====
# 4. Avaliar realismo via Discriminador (critério 2)
#   (Modelo DNN com 2 camadas: 30 e 20 neurônios, 250 epochs, batch_size=100)

```

```
# =====
# Carregar o modelo do discriminador
discriminator = load_model("/home/darkcover/Documents/Gan/Models/
↳Modelsdiscriminator.keras")
d_score = discriminator.predict(X_gen, verbose=1)
df_generated['D_score'] = d_score.flatten()

# 4.1. Salvar df_generated com coordenadas e D_score para uso na Fase 4
df_generated.to_csv("/home/darkcover/Documents/Gan/Data/
↳df_generated_with_coords.csv", index=False)
print(">>> df_generated_with_coords.csv gravado com X, Y e D_score")
```

```
1250/1250          2s 1ms/step
>>> df_generated_with_coords.csv gravado com X, Y e D_score
```

```
[38]: # =====
# 5. Dividir ambiente em zonas de  $4m^2$  ( $2x2m$ ) e selecionar 1000 amostras
#      (X, Y) para cada zona
# =====
L, W = 20, 20
zone_size = 2
nx, ny = int(L / zone_size), int(W / zone_size)
num_zones = nx * ny
ms = 1000
nj = ms // num_zones

# Calcular rotulos de zona
df_generated['zone_x'] = np.minimum((df_generated['X'] // zone_size).
↳astype(int), nx - 1)
df_generated['zone_y'] = np.minimum((df_generated['Y'] // zone_size).
↳astype(int), ny - 1)
df_generated['zone_id'] = df_generated['zone_x'] + nx * df_generated['zone_y']

# Selecionar top-nj por zona segundo D_score
selected_blocks, zone_logs = [], []
for zone, group in df_generated.groupby('zone_id'):
    topk = group.nlargest(nj, 'D_score')
    selected_blocks.append(topk)
    zone_logs.append((zone, len(group), topk['D_score'].mean()))

df_selected = pd.concat(selected_blocks, ignore_index=True)
df_selected.to_csv("/home/darkcover/Documents/Gan/Data/df_selected_synthetic.
↳csv", index=False)
```

```
[39]: # =====
# 6. Logs e Visualizações
# =====
```

```

print("Total sintéticas selecionadas:", len(df_selected))
for zid, total, avg in zone_logs:
    print(f"Zona {zid:03d}: {total} geradas, D_score médio selecionadas {avg:.
↵3f}")

L, W      = 20, 20
zone_size = 2.0

fig, ax = plt.subplots(figsize=(6,6))
# Pontos reais: círculos vazados
ax.scatter(df_real['X'], df_real['Y'],
           facecolors='lightblue', edgecolors='blue',
           s=40, label='Real')

# Pontos sintéticos: xis laranja
ax.scatter(df_selected['X'], df_selected['Y'],
           marker='x', c='#FF6600',
           s=30, label='Sintéticas Selecionadas')

# Desenha grid fino tracejado a cada 1 m
for coord in np.arange(0, L+1, 1):
    ax.axvline(coord, linestyle=':', linewidth=0.5, color='gray', zorder=0)
    ax.axhline(coord, linestyle=':', linewidth=0.5, color='gray', zorder=0)

# Delimitações das zonas (a cada 2 m)
for coord in np.arange(0, L+zone_size, zone_size):
    ax.axvline(coord, linestyle='--', linewidth=1, color='gray', zorder=0)
    ax.axhline(coord, linestyle='--', linewidth=1, color='gray', zorder=0)

ax.set_xlim(0, L)
ax.set_ylim(0, W)
ax.set_aspect('equal', 'box')
ax.set_xticks(np.arange(0, L+1, 2))
ax.set_yticks(np.arange(0, W+1, 2))
ax.set_xlabel("X (m)", fontsize=12)
ax.set_ylabel("Y (m)", fontsize=12)
ax.legend(frameon=False, loc='upper right', fontsize=10)
ax.set_title("Cobertura Espacial - Real vs. Sintéticas Selecionadas", pad=12)

plt.tight_layout()
plt.show()

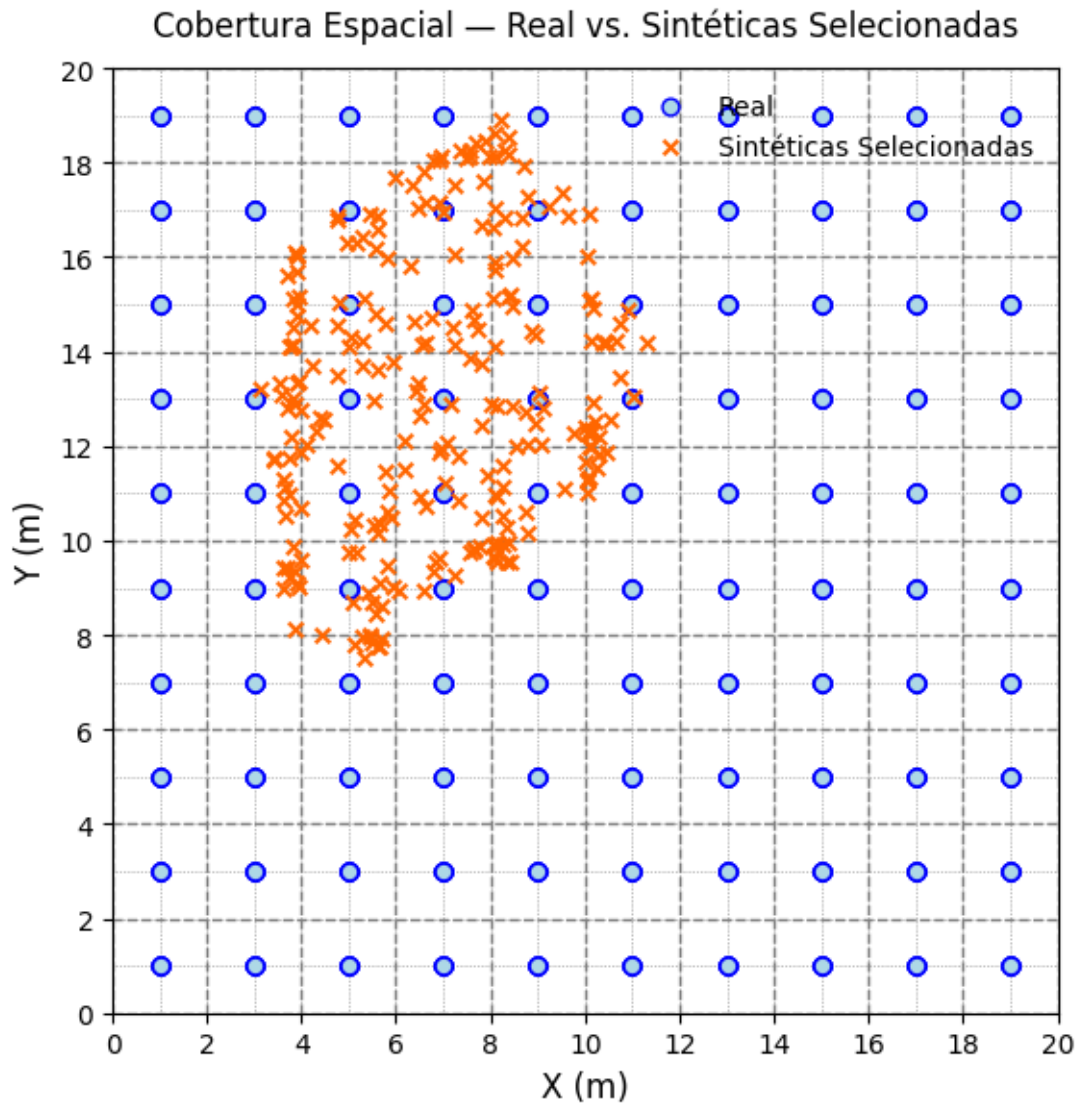
```

```

Total sintéticas selecionadas: 251
Zona 032: 116 geradas, D_score médio selecionadas 1.000
Zona 041: 90 geradas, D_score médio selecionadas 1.000
Zona 042: 2338 geradas, D_score médio selecionadas 1.000
Zona 043: 5467 geradas, D_score médio selecionadas 1.000
Zona 044: 415 geradas, D_score médio selecionadas 1.000

```

Zona 051: 279 geradas, D\_score médio selecionadas 1.000  
Zona 052: 3993 geradas, D\_score médio selecionadas 1.000  
Zona 053: 6294 geradas, D\_score médio selecionadas 1.000  
Zona 054: 4382 geradas, D\_score médio selecionadas 1.000  
Zona 055: 66 geradas, D\_score médio selecionadas 1.000  
Zona 061: 215 geradas, D\_score médio selecionadas 1.000  
Zona 062: 3721 geradas, D\_score médio selecionadas 1.000  
Zona 063: 4515 geradas, D\_score médio selecionadas 1.000  
Zona 064: 1370 geradas, D\_score médio selecionadas 1.000  
Zona 065: 165 geradas, D\_score médio selecionadas 1.000  
Zona 071: 88 geradas, D\_score médio selecionadas 1.000  
Zona 072: 2159 geradas, D\_score médio selecionadas 1.000  
Zona 073: 2201 geradas, D\_score médio selecionadas 1.000  
Zona 074: 445 geradas, D\_score médio selecionadas 1.000  
Zona 075: 11 geradas, D\_score médio selecionadas 1.000  
Zona 081: 3 geradas, D\_score médio selecionadas 1.000  
Zona 082: 810 geradas, D\_score médio selecionadas 1.000  
Zona 083: 742 geradas, D\_score médio selecionadas 1.000  
Zona 084: 82 geradas, D\_score médio selecionadas 1.000  
Zona 085: 2 geradas, D\_score médio selecionadas 1.000  
Zona 093: 25 geradas, D\_score médio selecionadas 1.000  
Zona 094: 6 geradas, D\_score médio selecionadas 1.000



```
[40]: L, W      = 20, 20
      zone_size = 2.0

      fig, ax = plt.subplots(figsize=(6,6))
      # Pontos reais: círculos vazados
      ax.scatter(df_real['X'], df_real['Y'],
                 facecolors='lightblue', edgecolors='blue',
                 s=40, label='Real')

      # Pontos sintéticos: xis laranja
      ax.scatter(df_generated['X'], df_generated['Y'],
                 marker='x', c='#FF6600',
```

```

        s=30, label='Sintéticas Seleccionadas')

# Desenha grid fino tracejado a cada 1 m
for coord in np.arange(0, L+1, 1):
    ax.axvline(coord, linestyle=':', linewidth=0.5, color='gray', zorder=0)
    ax.axhline(coord, linestyle=':', linewidth=0.5, color='gray', zorder=0)

# Delimitações das zonas (a cada 2 m)
for coord in np.arange(0, L+zone_size, zone_size):
    ax.axvline(coord, linestyle='--', linewidth=1, color='gray', zorder=0)
    ax.axhline(coord, linestyle='--', linewidth=1, color='gray', zorder=0)

ax.set_xlim(0, L)
ax.set_ylim(0, W)
ax.set_aspect('equal', 'box')
ax.set_xticks(np.arange(0, L+1, 2))
ax.set_yticks(np.arange(0, W+1, 2))
ax.set_xlabel("X (m)", fontsize=12)
ax.set_ylabel("Y (m)", fontsize=12)
ax.legend(frameon=False, loc='upper right', fontsize=10)
ax.set_title("Cobertura Espacial - Real vs. Sintéticas Seleccionadas", pad=12)

plt.tight_layout()
plt.show()

```

