BBM402-Lecture 11: The Class NP

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Resources for the presentation: http://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-045j-automata-computability-and-complexity-spring-2011/Syllabus/https://courses.engr.illinois.edu/cs498374/lectures.html

Introduction

- P = { L | there is some polynomial-time deterministic Turing machine that decides L }
- NP = { L | there is some polynomial-time nondeterministic Turing machine that decides L }
- Alternatively, L ∈ NP if and only if (∃ V, a polynomial-time verifier) (∃ p, a polynomial) such that:

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x \in L \text{ iff } (\exists c, |c| \le p(|x|)) [V(x, c) accepts]
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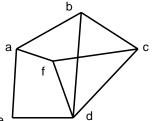
- To show that L ∈ NP, we need only exhibit a suitable verifier V and show that it works (which requires saying what the certificates are).
- $P \subset NP$, but it's not known whether P = NP.

Introduction

- P = { L | ∃ poly-time deterministic TM that decides L }
- NP = { L | ∃ poly-time nondeterministic TM that decides L }
- L \in NP if and only if (\exists V, poly-time verifier) (\exists p, poly) $x \in L$ iff (\exists c, $|c| \le p(|x|)$) [V(x, c) accepts]
- Some languages are in NP, but are not known to be in P (and are not known to not be in P):
 - SAT = { $< \phi > | \phi$ is a satisfiable Boolean formula }
 - 3COLOR = { < G > | G is an (undirected) graph whose vertices can be colored with ≤ 3 colors with no 2 adjacent vertices colored the same }
 - CLIQUE = { < G, k > | G is a graph with a k-clique }
 - VERTEX-COVER = { < G, k > | G is a graph having a vertex cover of size k }

CLIQUE

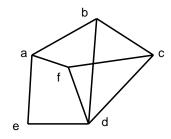
- CLIQUE = { < G, k > | G is a graph with a k-clique }
- k-clique: k vertices with edges between all pairs in the clique.
- In NP, not known to be in P, not known to not be in P.



- 3-cliques: { b, c, d }, { c, d, f }
- Cliques are easy to verify, but may be hard to find.

CLIQUE

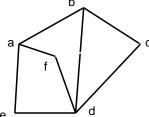
CLIQUE = { < G, k > | G is a graph with a k-clique }



- Input to the VC problem: < G, 3 >
- Certificate, to show that < G, 3 > ∈ CLIQUE, is { b, c, d } (or { c, d, f }).
- Polynomial-time verifier can check that { b, c, d } is a 3-clique.

VERTEX-COVER

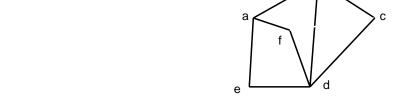
- VERTEX-COVER = { < G, k > | G is a graph with a vertex cover of size k }
- Vertex cover of G = (V, E): A subset C of V such that, for every edge (u,v) in E, either u ∈ C or v ∈ C.
 - A set of vertices that "covers" all the edges.
- In NP, not known to be in P, not known to not be in P.



- 3-vc: { a, b, d }
- Vertex covers are easy to verify, may be hard to find.

VERTEX-COVER

VERTEX-COVER = { < G, k > | G is a graph with a vertex cover of size k }



- Input to the VC problem: < G, 3 >
- Certificate, to show that < G, 3 > ∈ VC, is { a, b, d }.
- Polynomial-time verifier can check that { a, b, d } is a 3-vertex-cover.

HAMPATH Problem

HAMPATH =

- $\{ \langle G, s, t \rangle | G \text{ is a directed path with a Hamiltonian } s, t \text{path} \}$
 - There is an exponential brute force algorithm given in Thm 7.14 (Sipser).
 - Verifying the existence of a Hamiltonian path is much easier than determining its existence.

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Verifier: A verifier for a language A is an algorithm, where

$$A = \{w | V \text{ accepts } < w, c > \text{ for some string c}\}$$

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Polynomial time verifier: The running time of the verifier is measured by the length of w. Thus, a poly. time verifier runs in $O(w^k)$ (polynomial time in the length of w).

Certificate: A verifier uses additional information, represented by the symbol c. This information is called a *certificate*, or proof, of membership in A.

Why is HAMPATH in NP?

- NP is the class of languages that have polynomial time verifiers.
- The term NP comes from "nondeterministic polynomial time".

Decider for HAMPATH

N : "On input < G, s, t >, where G is a directed graph with nodes s and t:

- Write a list of m numbers p_1, \ldots, p_m , where m is the number of nodes in G. Each number in the list is nondeterministically selected between 1 and m.
- Check for repetitions in the list. If any are found, reject.
- **1** Check whether $s = p_1$ and $t = p_m$. If either fail, reject.
- For each $1 \le i \le m-1$, check whether (p_i, p_{i+1}) is an edge of G. If they are not, reject. Otherwise, all tests have been passed, so accept.

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- Write a list of m numbers p_1, \ldots, p_m , where m is the number of nodes in G. Each number in the list is nondeterministically selected between 1 and m.
- Check for repetitions in the list. If any are found, reject.
- **3** Check whether $s = p_1$ and $t = p_m$. If either fail, reject.
- For each $1 \le i \le m-1$, check whether (p_i, p_{i+1}) is an edge of G. If they are not, reject. Otherwise, all tests have been passed, so accept.

This algorithm runs in nondeterministic polynomial time:

- Stage 1: The nondeterministic selection runs in p.t.
- Stage 2, 3 and 4: p.t.

Theorem (Thm 7.20, Sipser)

A language is in NP "iff" (if and only if) it is decided by some nondeterministic polynomial time machine. ((1) language in NP $\implies \exists$ nondet. p. t. machine AND (2) Nondet. p.t. machine \implies language in NP)

To show (1): Let $A \in NP$. Show that A is decided by a poly. time NTM N.

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• Let V be the poly. time verifier for A that exists because $A \in NP$, assuming V runs in time $O(n^k)$.

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To show (2): Assume that A is decided by a poly. time NTM N. Construct a polynomial time verifier V for A. On input < w, c >, where w and c are strings:

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On input < w, c >, where w and c are strings:

• Simulate N on input w, treating each symbol of c as a description of the nondeterministic choice to make at each step,

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To show (2): Assume that A is decided by a poly. time NTM N. Construct a polynomial time verifier V for A.

On input $\langle w, c \rangle$, where w and c are strings:

- Simulate N on input w, treating each symbol of c as a description of the nondeterministic choice to make at each step,
- If this branch of N's computation accepts, accept, otherwise, reject.

Some Classical Optimization Problems

- Maximum Independent Set
- Maximum Clique
- Minimum Vertex Cover
- Traveling Salesman Problem
- Knapsack Problems
- Integer Linear Programming
- . . .

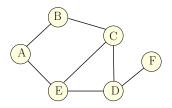
All of these optimization problems have a decision version which is an **NP** problem. And there are many, many other problems too.

4

Maximum Independent Set in a Graph

Definition

Given undirected graph G = (V, E) a subset of nodes $S \subseteq V$ is an independent set (also called a stable set) if for there are no edges between nodes in S. That is, if $u, v \in S$ then $(u, v) \not\in E$.

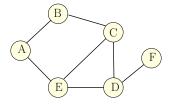


Some independent sets in graph above: $\{D\}, \{A, C\}, \{B, E, F\}$

Maximum Independent Set Problem

Input Graph G = (V, E)

Goal Find maximum sized independent set in G



MIS is an optimization problem. How do we cast it as a decision problem?

Decision version of Maximum Independent Set

Input Graph G = (V, E) and integer k written as G, k Question Is there an independent set in G of size at least k?

The answer to < G, k > is YES if G has an independent set of size at least k. Otherwise the answer is NO. Sometimes we say < G, k > is a YES instance or a NO instance.

The language associated with this decision problem is

 $L_{MIS} = \{ \langle G, k \rangle | G \text{ has an independent set of size } \geq k \}$

MIS is in NP

 $L_{MIS} = \{ \langle G, k \rangle | G \text{ has an independent set of size } \geq k \}$ A non-deterministic polynomial-time algorithm for L_{MIS} .

Input: a string $\langle G, k \rangle$ encoding graph G = (V, E) and integer k

- lacktriangle Non-deterministically guess a subset lacktriangle lacktr
- Verify (deterministically) that
 - S forms an independent set in G by checking that there is no edge in E between any pair of vertices in S
 - |S| > k.
- If S passes the above two tests output YES Else NO

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MIS is in NP

 $L_{MIS} = \{ \langle G, k \rangle | G \text{ has an independent set of size } \geq k \}$ A non-deterministic polynomial-time algorithm for L_{MIS} .

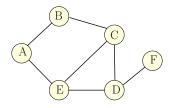
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 - string encoding S, < S > has length polynomial in length of input < G, k >
 - verification of guess is easily seen to be polynomial in length of
 S > and
 G, k >.

Minimum Vertex Cover

Definition

Given undirected graph G = (V, E) a subset of nodes $S \subseteq V$ is an vertex cover if every edge (u, v) has at least one of its end points in S. That is, every edge is covered by S.

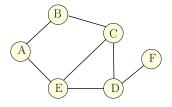


Examples of vertex covers in graph above:

Minimum Vertex Cover

Input Graph G = (V, E)

Goal Find minimum sized vertex cover in G



Decision version: given **G** and **k**, does **G** have a vertex cover of size at most **k**?

$$L_{VC} = \{ \langle G, k \rangle | G \text{ has a vertex cover size } \leq k \}$$

Minimum Vertex Cover is in NP

 $L_{VC} = \{ \langle G, k \rangle | G \text{ has a vertex cover size } \leq k \}$ A non-deterministic polynomial-time algorithm for L_{VC} .

Input: a string $\langle G, k \rangle$ encoding graph G = (V, E) and integer k

- lacktriangle Non-deterministically guess a subset lacktriangle lacktr
- Verify (deterministically) that
 - S forms a vertex cover in G by checking that for each edge $(u, v) \in E$ at least one of u, v is in S
 - |S| < k.
- If S passes the above two tests output YES Else NO

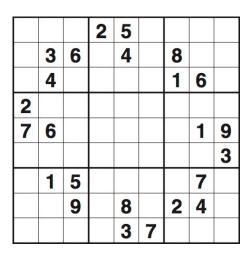
Minimum Vertex Cover is in NP

 $L_{VC} = \{ \langle G, k \rangle | G \text{ has a vertex cover size } \leq k \}$ A non-deterministic polynomial-time algorithm for L_{VC} .

Input: a string $\langle G, k \rangle$ encoding graph G = (V, E) and integer k

- **1** Non-deterministically guess a subset $S \subseteq V$ of vertices
- Verify (deterministically) that
 - S forms a vertex cover in G by checking that for each edge $(u, v) \in E$ at least one of u, v is in S
 - $|S| \leq k$
- If S passes the above two tests output YES Else NO Key points:
 - string encoding S, < S > has length polynomial in length of input < G, k >
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 S > and < G, k >.

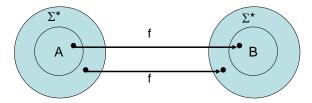
Sudoku



Given $\mathbf{n} \times \mathbf{n}$ sudoku puzzle, does it have a solution?

 Definition: A ⊆ Σ* is polynomial-time reducible to B ⊆ Σ*, A ≤_p B, provided there is a polynomial-time computable function f: Σ* → Σ* such that:

 $(\forall w)$ [$w \in A$ if and only if $f(x) \in B$]

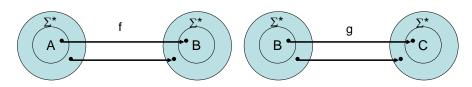


- Extends to different alphabets Σ_1 and Σ_2 .
- Same as mapping reducibility, ≤_m, but with a polynomial-time restriction.

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$$(\forall w) [w \in A \text{ if and only if } f(x) \in B]$$

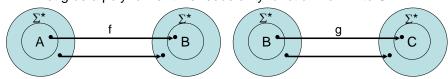
- Theorem: (Transitivity of ≤_p)
 If A ≤_p B and B ≤_p C then A ≤_p C.
- Proof:
 - Let f be a polynomial-time reducibility function from A to B.
 - Let g be a polynomial-time reducibility function from B to C.



• Definition: $A \leq_p B$, provided there is a polynomial-time computable function $f: \Sigma^* \to \Sigma^*$ such that:

$$(\forall w)$$
 [$w \in A$ if and only if $f(w) \in B$]

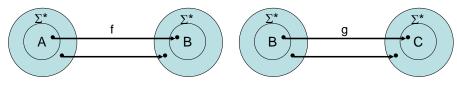
- Theorem: If $A \leq_p B$ and $B \leq_p C$ then $A \leq_p C$.
- Proof:
 - Let f be a polynomial-time reducibility function from A to B.
 - Let g be a polynomial-time reducibility function from B to C.



h(w)

- Define h(w) = g(f(w)).
- Then $w \in A$ if and only if $f(w) \in B$ if and only if $g(f(w)) \in C$.
- h is poly-time computable:

- Theorem: If $A \leq_p B$ and $B \leq_p C$ then $A \leq_p C$.
- Proof:
 - Let f be a polynomial-time reducibility function from A to B.
 - Let g be a polynomial-time reducibility function from B to C.



- Define h(w) = g(f(w)).
- h is poly-time computable:
 - |f(w)| is bounded by a polynomial in |w|.
 - Time to compute g(f(w)) is bounded by a polynomial in |f(w)|, and therefore by a polynomial in |w|.
 - Uses the fact that substituting one polynomial for the variable in another yields yet another polynomial.

• Definition: $A \leq_p B$, provided there is a polynomial-time computable function $f: \Sigma^* \to \Sigma^*$ such that:

$$(\forall w) [w \in A \text{ if and only if } f(x) \in B]$$

- Theorem: If $A \leq_{D} B$ and $B \in P$ then $A \in P$.
- Proof:
 - Let f be a polynomial-time reducibility function from A to B.
 - Let M be a polynomial-time decider for B.
 - To decide whether w ∈A:
 - Compute x = f(w).
 - Run M to decide whether x ∈ B, and accept / reject accordingly.
 - Polynomial time.
- Corollary: If A ≤_D B and A is not in P then B is not in P.
- Easiness propagates downward, hardness propagates upward.

- Can use ≤_p to relate the difficulty of two problems:
- Theorem: If A ≤_p B and B ≤_p A then either both A and B are in P or neither is.
- Also, for problems in NP:
- Theorem: If $A \leq_{D} B$ and $B \in NP$ then $A \in NP$.
- Proof:
 - Let f be a polynomial-time reducibility function from A to B.
 - Let M be a polynomial-time nondeterministic TM that decides B.
 - · Poly-bounded on all branches.
 - Accepts on at least one branch iff and only if input string is in B.
 - NTM M' to decide membership in A:
 - On input w:
 - Compute x = f(w); |x| is bounded by a polynomial in |w|.
 - Run M on x and accept/reject (on each branch) if M does.
 - Polynomial time-bounded NTM.

- Theorem: If $A \leq_{D} B$ and $B \in NP$ then $A \in NP$.
- · Proof:
 - Let f be a polynomial-time reducibility function from A to B.
 - Let M be a polynomial-time nondeterministic TM that decides B.
 - NTM M' to decide membership in A:
 - On input w:
 - Compute x = f(w); |x| is bounded by a polynomial in |w|.
 - Run M on x and accept/reject (on each branch) if M does.
 - Polynomial time-bounded NTM.
 - Decides membership in A:
 - M' has an accepting branch on input w iff M has an accepting branch on f(w), by definition of M', iff $f(w) \in B$, since M decides B, iff $w \in A$, since A $\leq_p B$ using f.
 - So M' is a poly-time NTM that decides A, A ∈ NP.

- Theorem: If $A \leq_{D} B$ and $B \in NP$ then $A \in NP$.
- Corollary: If A ≤_p B and A is not in NP, then B is not in NP.

- · A technical result (curiosity):
- Theorem: If A ∈ P and B is any nontrivial language (meaning not Ø, not Σ*), then A ≤_p B.
- Proof:
 - Suppose $A \in P$.
 - − Suppose B is a nontrivial language; pick $b_0 \in B$, $b_1 \in B^c$.
 - Define $f(w) = b_0$ if $w \in A$, b_1 if w is not in A.
 - f is polynomial-time computable; why?
 - Because A is polynomial time decidable.
 - Clearly $w \in A$ if and only if $f(w) \in B$.
 - So A \leq_{D} B.
- Trivial reduction: All the work is done by the decider for A, not by the reducibility and the decider for B.