Oliver Zhang

Interdisciplinary engineer skilled in design and problem solving. Seeking opportunities where I can use my skills to improve the world. http://www.andrew.cmu.edu/user/ozz/

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Graduation May 2019

OPA: 3.63/4.0

EDUCATION:

Carnegie Mellon University Pittsburgh PA

Bachelor of Science in Mechanical Engineering and Robotics

Engineering Courses: Statics, Thermodynamics, Fluid Mechanics, Stress Analysis

Notable Projects:

- Programmed in MATLAB an autonomous robot with two wheels and caster, encoders and LIDAR. Implemented state estimation, feedback/feedforward control, visual goal acquisition, trajectory planning
- Designed and built crane using aluminum strips. Successfully lifted 1 lb weight more than 2 inches.
- Developed OCR program that can execute printed/written Python, demonstrated project in class showcase.
- Designed and built mousetrap car to perform S-shaped course, 2nd fastest in class of 100+ students.

WORK EXPERIENCE:

Autel Robotics Pittsburgh, PA

Summer 2017

Project Engineer Intern

- Worked in a group of three to design tracking and gesture recognition systems on a quadcopter.
- Developed and tested program using MATLAB and used C/C++ cross compilation for embedded execution.

Supplemental Instruction (SI) Pittsburgh, PA

Spring 2017 – Present

SI Leader

• Designed and lead collaborative learning sessions for students in Thermodynamics I.

PERSONAL PROJECTS

Ouadcopter Project

2016 – Present

Team leader

- Develop indoor autonomous quadcopter to participate in International Aerial Robotics Competition
- Utilize ROS, cameras, LIDAR, and SLAM to implement autonomous navigation and target detection
- Apply CAD in Solidworks to laser cut, print, machine hardware such as landing gears, sensor mounts.

Amphibious Rescue Craft Project

Summer 2016 – Spring 2017

Team member

- Designed prototype amphibious vehicle for remote beach rescue. Funded by SURG and SHRG programs.
- Implemented control using Arduino, XBee, Python. Manufactured parts using Solidworks, 3D Printing, CNC

Multipurpose Mobile Manipulator (MMM) Project

Summer 2016 – Spring 2017

Team Leader

- Guide and teach teams of students to create parody films involving the MMM as the lead actor.
- Designed an animator interface and android controller for easy control of the MMM.
- Programmed behavior in Unity3D, Arduino. Engineered attachments, mounts. Edited footage with Adobe CS

Space Game Development Project

Spring 2016 – Spring 2017

Lead Developer

- Develop 3D voxel spaceship game with procedurally generated planets and sandbox ship building
- Implement controls, game logic, animations in Unity 3D. Design models in Blender.

ACTIVITIES:

CMU Robotics Club Officers Board Pittsburgh, PA

Spring 2017 – Present

Training Officer

Designed and lead sessions to train members on engineering principles and resources at the Robotics Club.

Habitat For Humanity trips to Philippines and Cambodia

Spring 2013, 2014

Volunteer and Officer

Volunteered to construct shelter for people without homes, officer of club responsible for trip logistics.

SKILLS: C#, Python, Java, C/C++, MATLAB, Unity3D, ROS, Solidworks, Mastercam, Adobe CS, Fluent Mandarin. **INTERESTS:** Watching films, video gaming, reading, cooking, practicing karate.