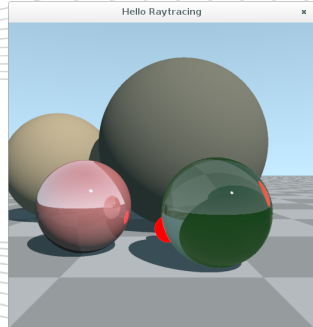
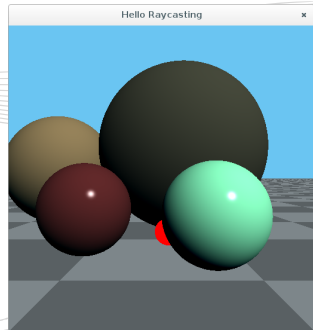


Ray-based graphics, and the rendering equation

Computer Graphics (DT3025)

Martin Magnusson
November 18, 2016



Last time

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 - Shadow mapping: noisy and blurry — unless we take good care to improve them — but better for complex geometry.
 - Tuning the bias for avoiding z-fighting.
 - Warping and partitioning for avoiding aliasing.
- (From now on, we'll deal with methods where we get proper shadows “for free”!)

Shadow volumes: how much geometry?

We have the following scene with 2 triangles and 2 omnidirectional point light sources. How many triangles have to be generated for computing the shadow volumes?



1 10

2 16

3 24



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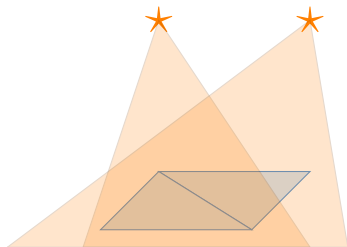
2 16

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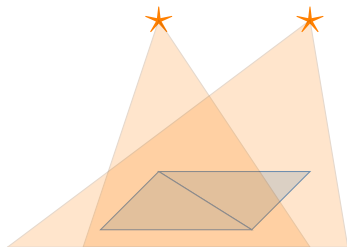
Shadow volumes: how many rendering passes?

We have the following scene with 2 triangles and 2 spot lights.
How many rendering passes are required for rendering this scene with *stencil-buffer shadow volumes*?



Shadow mapping: how many rendering passes?

We have the following scene with 2 triangles and 2 spot lights.
How many rendering passes are required for rendering this scene with *shadow mapping*?



Today

- Ray casting vs rasterisation
- The rendering equation!
- Ray tracing for shadows and transparency

Reading instructions

- Hughes et al:
 - 15.1–15.2.4, 15.4–15.4.1, 15.4.3
 - 7.8
 - 29

Rasterisation outline

```
1  for (each triangle)
2  {
3      for (each pixel)
4      {
5          if (triangle covers pixel)
6          {
7              update z-buffer
8              keep closest hit
9          }
10     }
11 }
```

■ (Remember Lecture 1.)

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- (Remember Lecture 1.)
- Rasterisation, AKA *projective rendering*.

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- (Remember Lecture 1.)
- Rasterisation, AKA *projective rendering*.
- Each object is *projected* to screen and *rasterised*.

Ray casting vs rasterisation

Rasterisation

```
for (each triangle)
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    for (each pixel)
    {
        if (triangle covers pixel)
        {
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        }
    }
}
```

Ray casting

```
for (each pixel)
{
    shoot a ray through pixel
    for (each object)
    {
        if (ray hits object)
        {
            keep closest hit
        }
    }
}
```

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- We just need to swap the for-loops!

Evolution of Lara Croft



kanasoku.info

Polygon counts

- Tom Raider I (1996): 230
- TombRaider III (1998): 300
- Angel of Darkness (2003): 4 400
- Legend (2006): 9 800
- Underworld (2008): 32 816

Speaking of Lara Croft, Schleiner (2001) is worth reading too.

Rasterisation pros and cons

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- Each pixel may need to be touched many times for complex scenes.
- Ray casting used to be hard to implement in hardware, but with general-purpose GPUs, we are getting there (Lab 4!)

00:23.06 - 00.844

1 00:21.686

2 00:01.38

3

PERFORMANCE BEST!

875

Rasterisation example

01:13.205

BEST
01:12.075

875

398

369



Drive Club, Evolution Studios

146 3
KM/H

Ray tracing example



Source: "Now with vitamin R"

Ray casting

```
1  for every pixel
2  {
3      cast ray from eye through pixel
4      for every object
5      {
6          check intersection point with ray
7          if closest
8              keep it
9      }
10
11 }
```

Ray casting

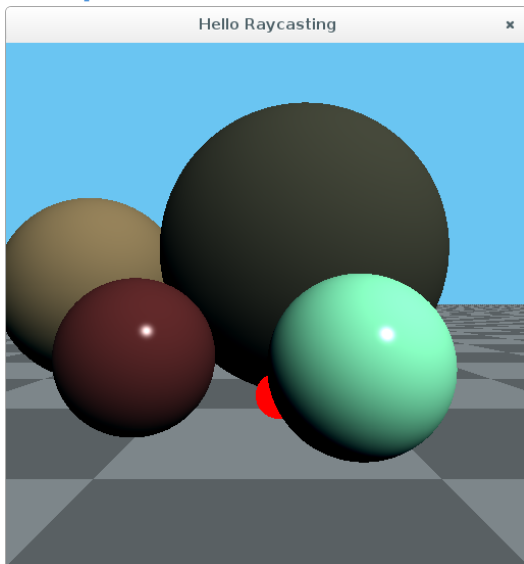
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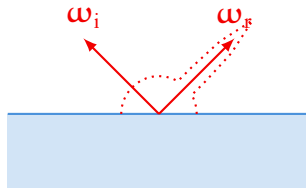
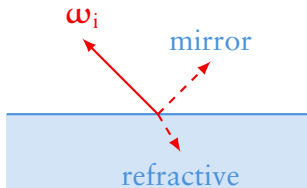
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- *How do we compute the colour?*
- With a BSDF, as part of *the rendering equation*.
- Different ways of approximating the rendering equation leads to different rendering methods.

Ray casting example

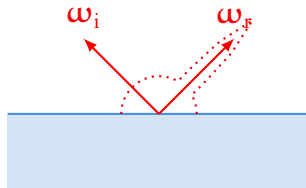
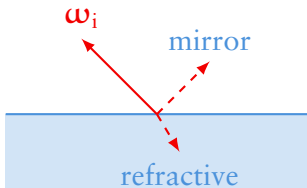


Two types of scattering



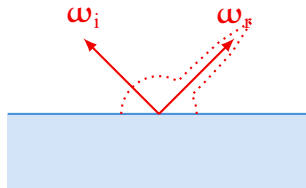
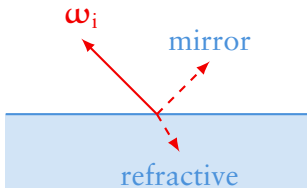
1 Mirror scattering

Two types of scattering



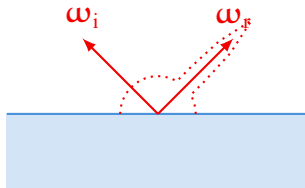
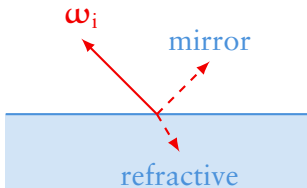
- 1 Mirror scattering
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Two types of scattering



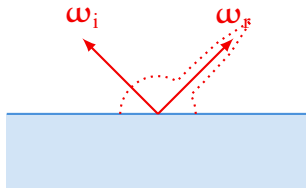
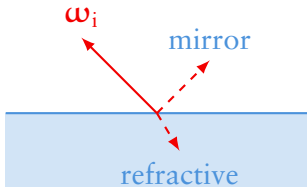
- 1 Mirror scattering
- 2 Snell-transmissive scattering (refraction)
- 3 Three! Three types of scattering!

Two types of scattering



- 1 Mirror scattering
- 2 Snell-transmissive scattering (refraction)
- 3 Everything else

Two types of scattering



- 1 Impulse scattering: either mirror or refractive (i.e. Snell-transmissive).
- 2 Everything else (integrals).

Two types of lights

- 1 Point lights (impulses in incoming light).

Two types of lights

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- 2 Everything else (area lights \implies integrals).

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- 1 Point lights (impulses in incoming light).
 - 2 Everything else (area lights \implies integrals).
- *Luminaire* = light source.

How to compute how light is distributed in the scene?

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L^e a function describing the *illumination*

- $L^e(P, \omega_o) =$ how much radiance is emitted from P in direction ω_o

R a ray-casting function

- $R(P, \omega) =$ the first point hit when going from P toward ω

The reflectance equation

$$L^{\text{ref}}(P, \omega_o) = \int_{\omega_i \in \mathbf{S}_+^2(P)} L(P, -\omega_i) f_r(P, \omega_i, \omega_o) (\omega_i \cdot \mathbf{n}_P) d\omega_i$$

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The radiance (light) reflected at P towards ω_o

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The radiance (light) reflected at P towards ω_o is computed by

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The radiance (light) reflected at P towards ω_o is computed by
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The radiance (light) reflected at P towards ω_o is computed by integrating (summing up) **over all incoming light directions ω_i above the surface at P**

The reflectance equation

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The radiance (light) reflected at P towards ω_o is computed by integrating (summing up) over all incoming light directions ω_i *above the surface* at P **the contribution from each direction being**

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The radiance (light) reflected at P towards ω_o is computed by integrating (summing up) over all incoming light directions ω_i *above the surface* at P the contribution from each direction being the incoming irradiance from $-\omega_i$

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The radiance (light) reflected at P towards ω_o is computed by integrating (summing up) over all incoming light directions ω_i *above the surface* at P the contribution from each direction being the incoming irradiance from $-\omega_i$ **times the BRDF for these particular directions**

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Impulses (point lights and mirror reflections) can't really be integrated like this, but let's pretend we can stuff them inside the integral too for now (just make a sum instead of an integral).

The rendering equation (take 1)

$$\begin{aligned}
 L(P, \omega_o) &= L^e(P, \omega_o) + L^{\text{ref}}(P, \omega_o) \\
 &= L^e(P, \omega_o) + \int_{\omega_i \in S_+^2(P)} L(P, -\omega_i) f_r(P, \omega_i, \omega_o) (\omega_i \cdot \mathbf{n}_P) d\omega_i
 \end{aligned}$$

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- This is an *integral equation* and is difficult to solve exactly.
- We can only hope to approximate the solution.

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- In other words, the light arriving at P from $-\omega_i$ is the same as the light that leaves from the closest surface point when looking to ω_i with direction $-\omega_i$.

The rendering equation (take 2)

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 - and the radiance from another point. (Just a recursive function.)

What about $R(P, \omega)$?

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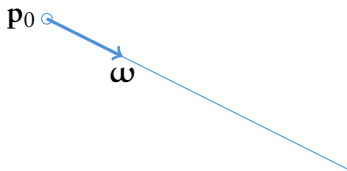
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- (... and that integral).
- For a ray with starting point P and direction ω , how to compute which surface point it hits first?

Intersection testing

- How to represent a ray?
- Given start point \mathbf{p}_0 and (normalised) direction $\boldsymbol{\omega}$,

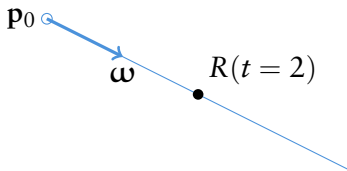
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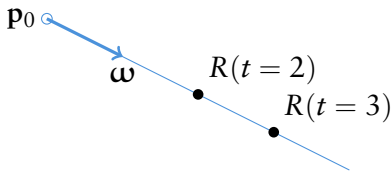
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- Infinite plane defined by point \mathbf{p}_0 in the plane and normal \mathbf{n} ,
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- Infinite plane defined by point \mathbf{p}_0 in the plane and normal \mathbf{n} ,
- or as the normal $\mathbf{n} = (a, b, c)$ and a distance d from the origin.
- Implicit plane equation

$$\begin{aligned}H(\mathbf{p}) &= ax + by + cz + d = 0 \\ &= \mathbf{n} \cdot \mathbf{p} + d = 0\end{aligned}$$



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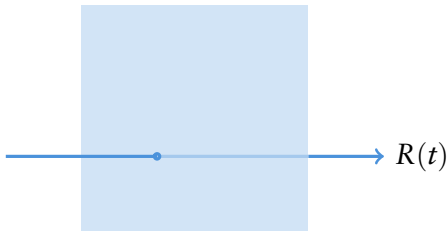
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- Now: how to check if ray intersects plane?

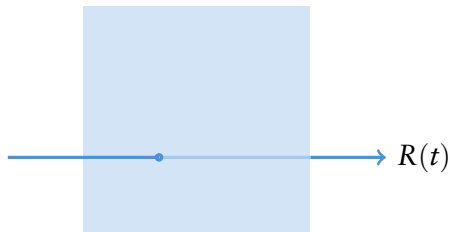
Ray-plane intersection

- Intersection iff both equations are satisfied.



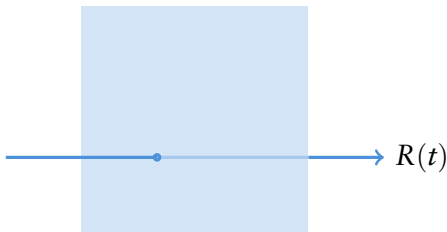
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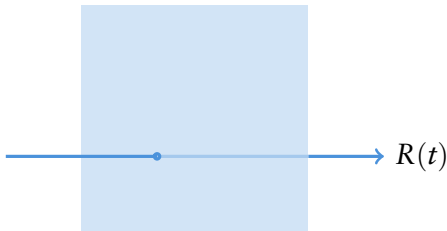
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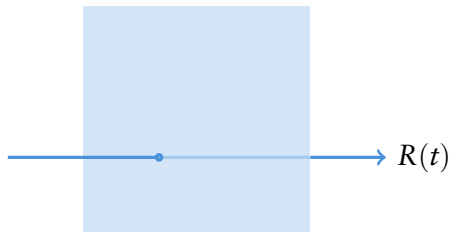
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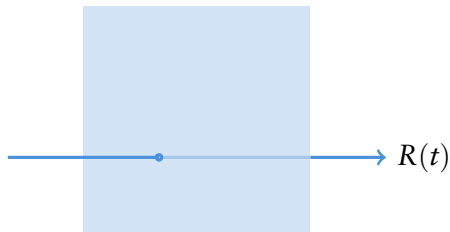
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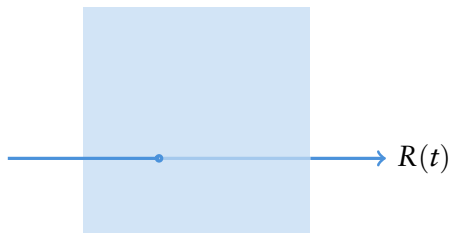


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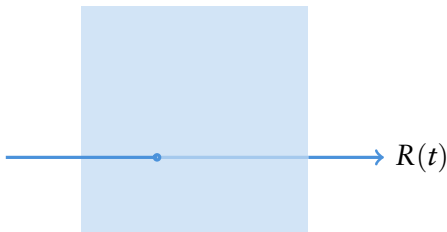
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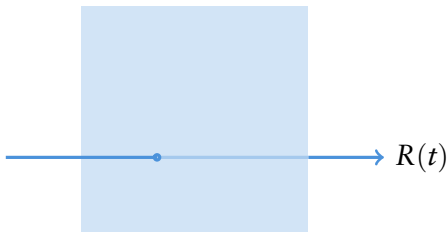
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voilà!

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- Check that t is not behind us:

$$R(t) > t_{\text{min}}.$$

What do we do after verifying t ?

- Finally, we also need to compute the normal at the point $R(t)$, for computing *lighting and secondary rays*.

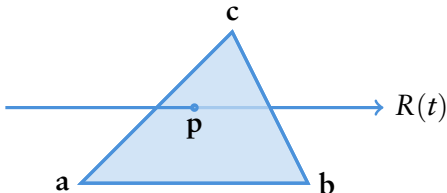
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- Finally, we also need to compute the normal at the point $R(t)$, for computing *lighting and secondary rays*.
- For plane, normal is constant for all points.

Ray-triangle intersection

Two options:

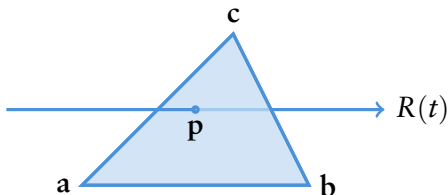
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Ray-triangle intersection

Two options:

- 1 First ray-plane intersection, then test if $R(t)$ is inside triangle (as with rasterisation).
- 2 Better: use barycentric coordinates.



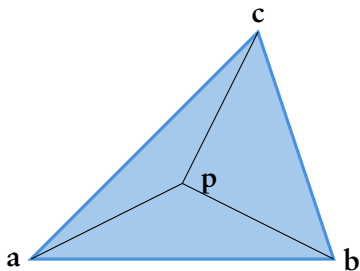
Triangle representation

■ Implicit triangle-patch equation

$$T(\alpha, \beta, \gamma) = \alpha \mathbf{a} + \beta \mathbf{b} + \gamma \mathbf{c}$$

$$\alpha + \beta + \gamma = 1$$

$$0 \leq \alpha, \beta, \gamma \leq 1$$



Just the same as when doing texture interpolation, etc.

Simplified triangle representation

- Since $\alpha + \beta + \gamma = 1$ we can use that $\alpha = 1 - \beta - \gamma$ and get rid of α .

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$$0 \leq \beta - \gamma \leq 1$$

Ray-triangle intersection

- So, does our ray intersect the triangle?

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- (Write out as three equations, for $\boldsymbol{\omega} = [\omega_x, \omega_y, \omega_z]$ and $\mathbf{p}_0 = [p_x, p_y, p_z]$.)

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- Solve

$$\begin{bmatrix} \omega_x & A_x - B_x & A_x - C_x \\ \omega_y & A_y - B_y & A_y - C_y \\ \omega_z & A_z - B_z & A_z - C_z \end{bmatrix} \begin{bmatrix} t \\ \beta \\ \gamma \end{bmatrix} = \begin{bmatrix} A_x - p_x \\ A_y - p_y \\ A_z - p_z \end{bmatrix}$$

Ray-triangle intersection

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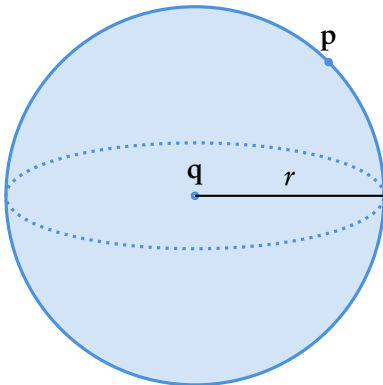
- Intersection if $\beta + \gamma < 1$ **and** $\beta, \gamma > 0$ **and** $t > 0$.

I think this version is conceptually simpler than the book's.

Sphere representation

- Implicit sphere equation:
- Sphere centred at \mathbf{q} with radius r . Point \mathbf{p} is on sphere iff

$$(\mathbf{p} - \mathbf{q}) \cdot (\mathbf{p} - \mathbf{q}) = r^2.$$



Ray-sphere intersection

- Insert explicit ray equation into implicit sphere equation and solve for t .

$$(\mathbf{p} - \mathbf{q}) \cdot (\mathbf{p} - \mathbf{q}) = r^2$$

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- Using $\mathbf{p} - \mathbf{q} \equiv \mathbf{v}$, this boils down to

$$(\mathbf{v} \cdot \mathbf{v} - r^2) + t(2\boldsymbol{\omega} \cdot \mathbf{v}) + t^2(\boldsymbol{\omega} \cdot \boldsymbol{\omega}) = 0$$

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- which is quadratic in t .

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 - One solution: ray *just* touches sphere.
 - Two solutions: ray pierces sphere. Choose **smallest positive** t .

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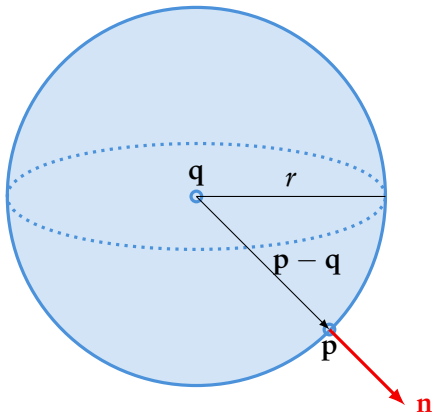
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- (Useful in Lab 4.)

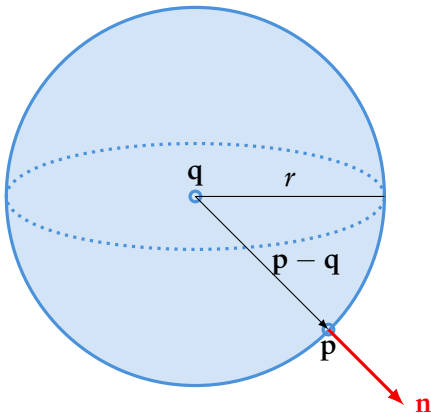
Sphere normal

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- ...and then we need the normal at \mathbf{p} too.
- $\mathbf{n} = \mathbf{p} - \mathbf{q} / \|\mathbf{p} - \mathbf{q}\|$



Light transport

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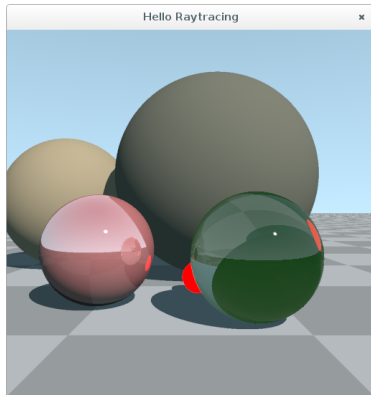
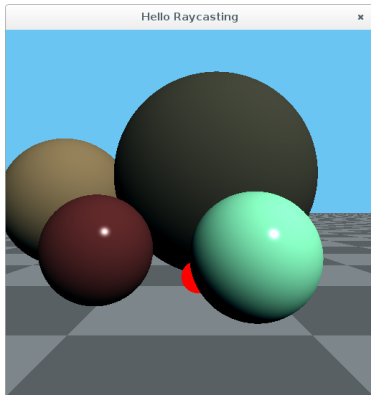
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Light transport

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- Sooner or later, light reaches eye.

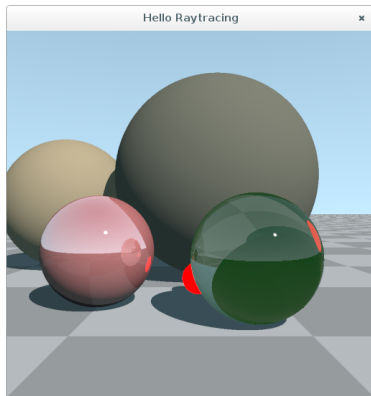
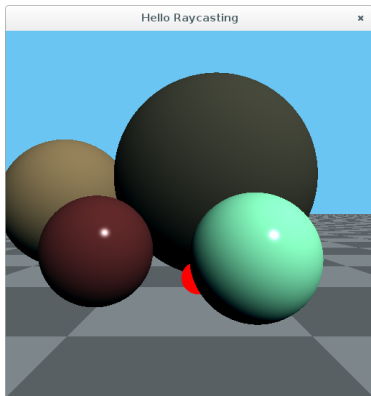
Ray casting vs ray tracing

- Ray casting: stop at first intersection.

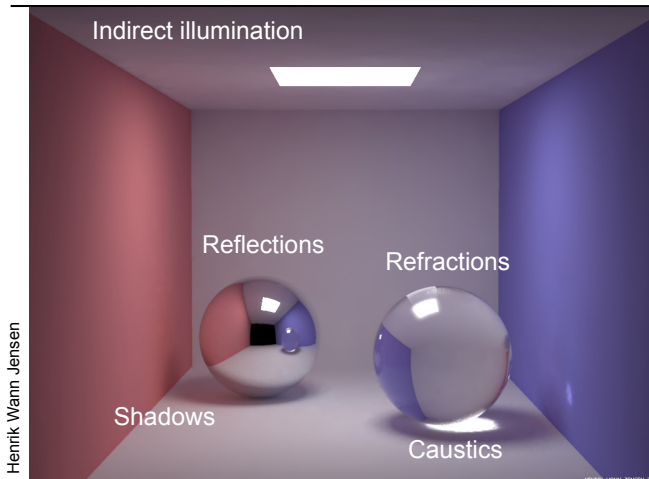


Ray casting vs ray tracing

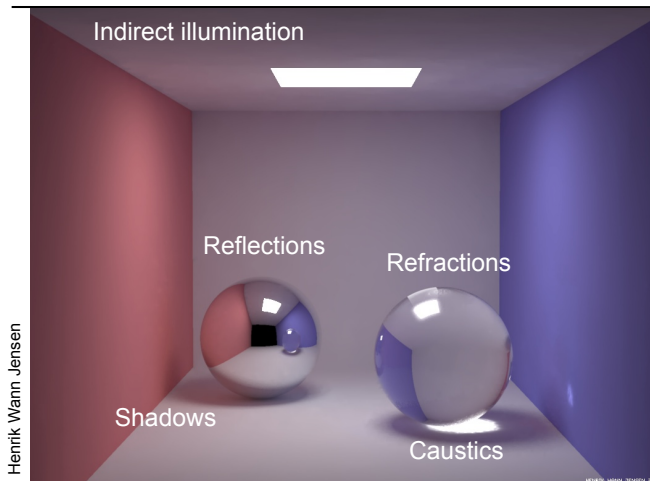
- Ray casting: stop at first intersection.
- Ray tracing: secondary rays for reflections, shadows, etc.



Physically based rendering



Physically based rendering



With ray tracing, we get (hard) shadows, reflections, refractions, but *not* indirect illumination and caustics.

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- Precision issues (z-fighting): start ray at $\mathbf{p} + \epsilon(\mathbf{q} - \mathbf{p})$ instead of \mathbf{p} .

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2  colour = 0;
3  for (all light sources)
4  {
5      colour += brdf(light_direction, view_direction, normal) * cosine;
6  }
7  mirror = reflect(view_direction, normal);
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- *We just took one more sample from the integral.*

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- In ray casting, we go backwards: EDL .

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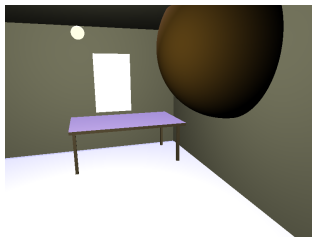
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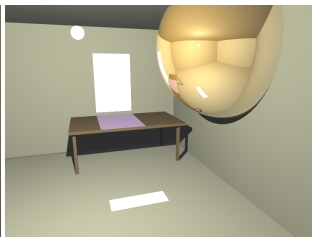
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A taxonomy of tracing

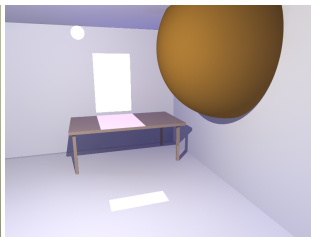
■ Ray casting $E(D|G)L$



Ray casting



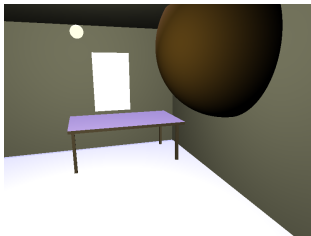
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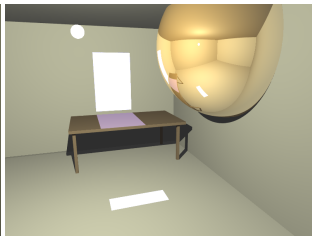
Radiosity

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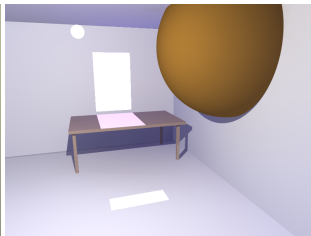
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Ray casting



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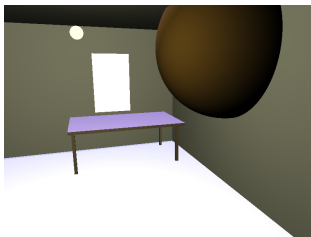


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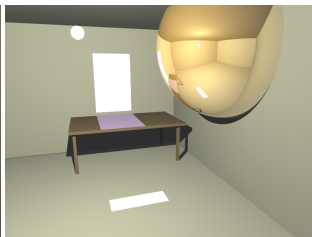
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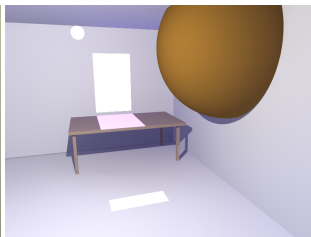
(lecture 8)



Ray casting



Ray tracing



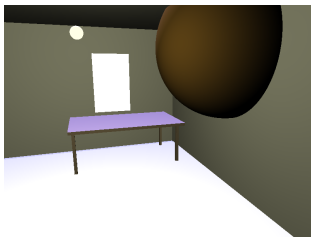
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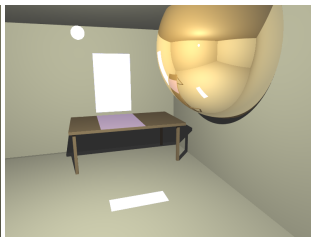
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(lecture 8)

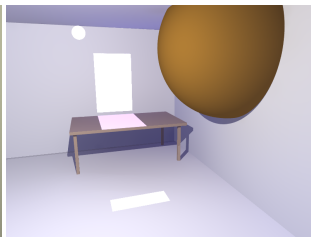
(lecture 8)



Ray casting



Ray tracing



Radiosity

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- Classification of light-transport paths to describe different types of rendering methods

Next lecture: more reflections, transmission, materials

Time and place

- Mon 21 Nov, 13.15–15.00
- T-141

Reading material

- We'll stick to Chapter 29, mostly.

References



Anne-Marie Schleiner (2001). “Does Lara Croft Wear Fake Polygons? Gender and Gender-Role Subversion in Computer Adventure Games”. In: *Leonardo* 34.3, pp. 221–226.