

COMP2521 25T2

Graphs (IV)

Directed and Weighted Graphs

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directed graphs
weighted graphs

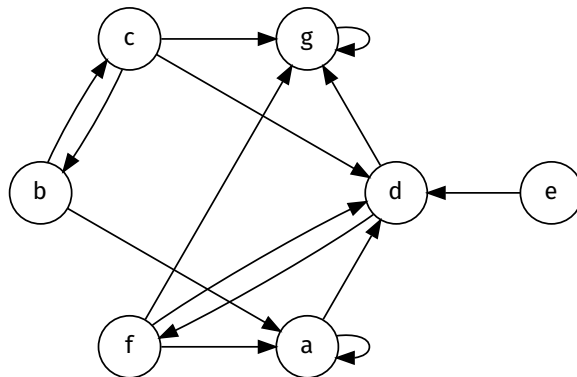
In graphs representing real-world scenarios, edges are often **directional** and may have a sense of **cost**.

Thus, we need to consider **directed** and **weighted** graphs.

Some applications require us to consider
directional edges: $v \rightarrow w \neq w \rightarrow v$
e.g., 'follow' on Twitter, one-way streets, etc.

In a **directed graph** or **digraph**:
edges have direction.

Each edge (v, w) has a **source** v and a **destination** w .



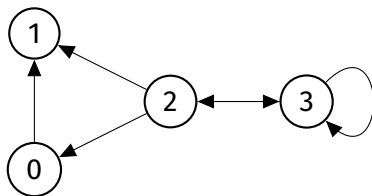
application	vertex is...	edge is...
WWW	web page	hyperlink
chess	board state	legal move
scheduling	task	precedence
program	function	function call
journals	article	citation
make	target	dependency

in-degree $\deg^-(v)$ or $\text{in}(v)$

the number of incoming edges to a vertex

out-degree $\deg^+(v)$ or $\text{out}(v)$

the number of outgoing edges from a vertex

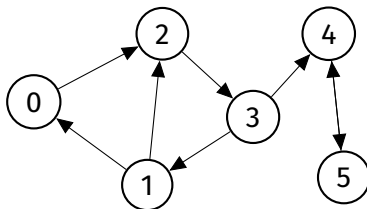


$\text{in}(0) = 1$	$\text{out}(0) = 1$
$\text{in}(1) = 2$	$\text{out}(1) = 0$
$\text{in}(2) = 1$	$\text{out}(2) = 3$
$\text{in}(3) = 2$	$\text{out}(3) = 2$

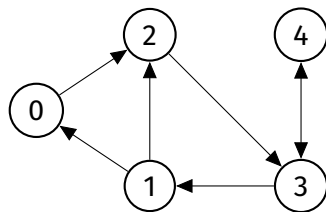
A **directed path** is
a sequence of vertices where
each vertex has an outgoing edge to
the next vertex in the sequence

If there is a directed path from v to w ,
then we say that w is **reachable** from v

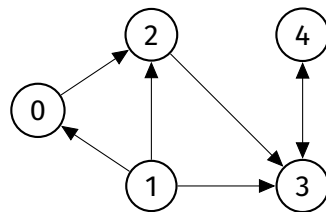
A **directed cycle** is
a directed path where
the first and last vertices are the same
e.g., 0-2-3-1-0, 1-2-3-1



A digraph is **strongly connected** if there is a directed path from every vertex to every other vertex



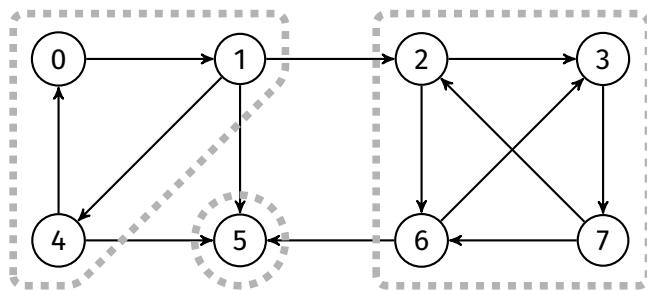
strongly connected



not strongly connected

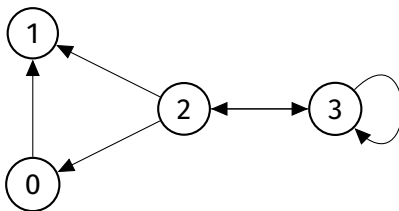
A **strongly-connected component** is a maximally strongly-connected subgraph.

A digraph that is not strongly connected has two or more strongly-connected components.



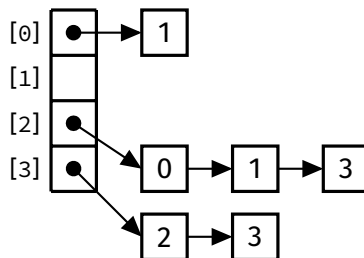
Same representations as for undirected graphs:

- Adjacency matrix
- Adjacency list
- Array of edges



[0]	●	→	0	1	0	0
[1]	●	→	0	0	0	0
[2]	●	→	1	1	0	1
[3]	●	→	0	0	1	1

Adjacency matrix



Adjacency list

0	1
2	0
2	1
2	3
3	2
3	3

Array of edges

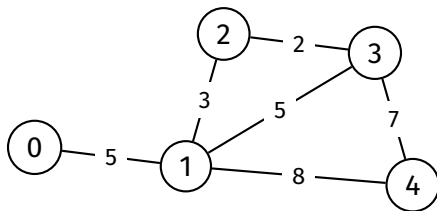
	Adjacency Matrix	Adjacency List	Array of Edges
Space usage	$O(V^2)$	$O(V + E)$	$O(E)$
Insert edge	$O(1)$	$O(\deg(v))$	$O(E)$
Remove edge	$O(1)$	$O(\deg(v))$	$O(E)$
Contains edge	$O(1)$	$O(\deg(v))$	$O(\log(E))$

Real digraphs tend to be sparse (large V , small average $\deg(v)$),
so we use $\deg(v)$ to denote the degree of the source vertex v .

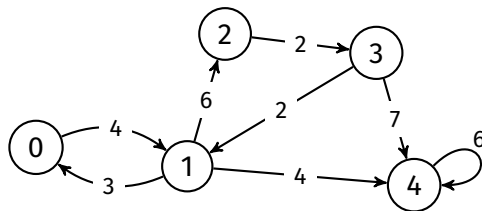
Weighted Graphs

Some applications require us to consider a **cost** or **weight** assigned to a relation between two nodes.

In a **weighted graph**, each edge (s, t, w) has a weight w .

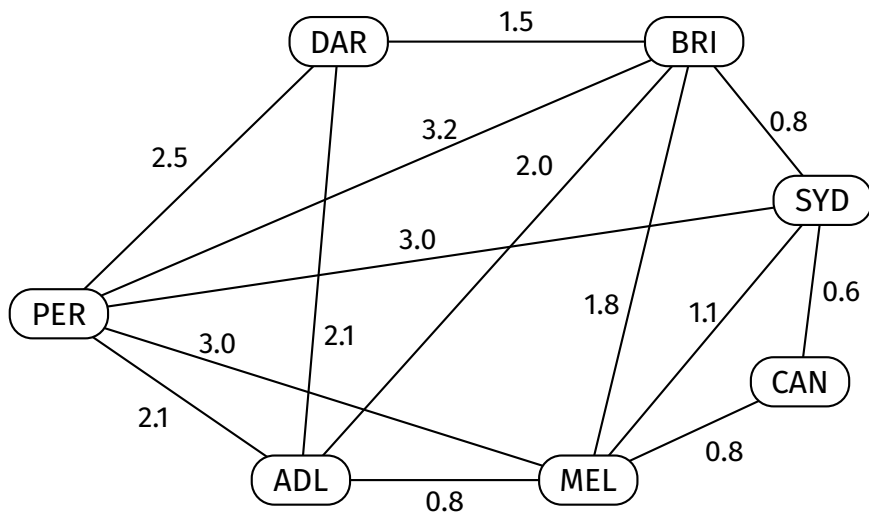


Weighted Graph



Directed Weighted Graph

Example: Major airline routes in Australia



Adjacency matrix:

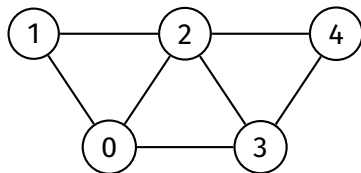
- store *weight* in each cell, not just true/false
- need a value to signify “no edge”

Adjacency list:

- add weight to each list node

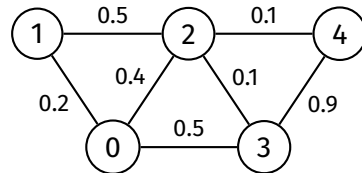
Array of edges:

- add weight to each edge



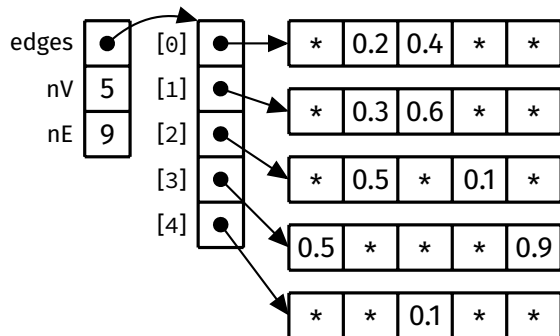
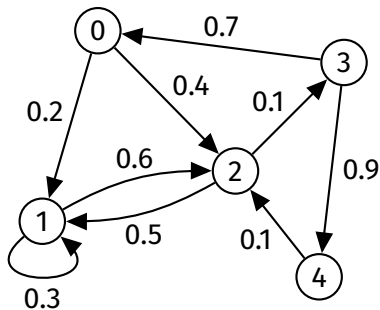
$$\begin{bmatrix} 0 & 1 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 \end{bmatrix}$$

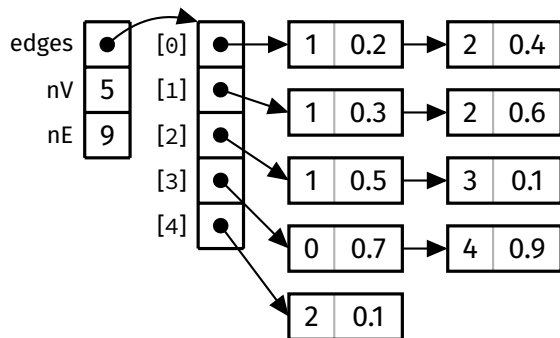
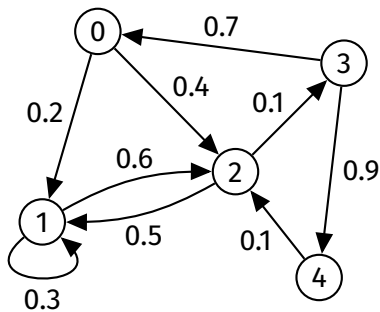
undirected, unweighted

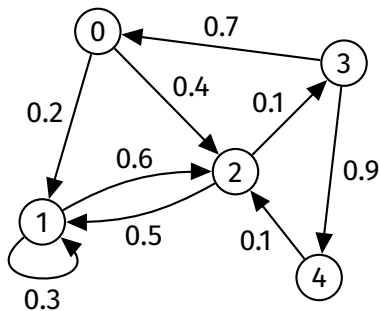


$$\begin{bmatrix} - & 0.2 & 0.4 & 0.5 & - \\ 0.2 & - & 0.5 & - & - \\ 0.4 & 0.5 & - & 0.1 & 0.1 \\ 0.5 & - & 0.1 & - & 0.9 \\ - & - & 0.1 & 0.9 & - \end{bmatrix}$$

undirected, **weighted**







edges	●	→		
nV	5	0	1	0.2
nE	9	0	2	0.4
maxE	...	1	1	0.3
		1	2	0.6
		2	1	0.5
		2	3	0.1
		3	0	0.7
		3	4	0.9
		4	2	0.1