

# Democratizing LEO Satellite Network Measurement

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## ABSTRACT

Low Earth Orbit (LEO) satellite networks are quickly gaining traction with promises of impressively low latency, high bandwidth, and global reach. However, the research community knows relatively little about their operation and performance in practice. The obscurity is largely due to the high barrier of entry for measuring LEO networks, which requires deploying specialized hardware or recruiting large numbers of satellite Internet customers. In this paper, we introduce LEO HitchHiking, a new methodology that democratizes global visibility into LEO satellite networks. HitchHiking builds on the observation that Internet exposed services that use LEO Internet can reveal satellite network architecture and performance, without needing physical hardware. We evaluate HitchHiking against ground truth measurements and prior methods, showing that it provides more coverage, speed, and accuracy. With HitchHiking, we complete the largest study to date of Starlink network latency, measuring over 1,600 users across 13 countries. We uncover unexpected patterns in latency that surface how LEO routing is more complex than previously understood. Finally, we conclude with recommendations for future research on LEO networks.

## 1 INTRODUCTION

Low Earth Orbit (LEO) satellite networks promise to decrease latency and increase Internet coverage beyond the means of terrestrial Internet. Used by at least 1.5 million people as of May 2023 [65], LEO networks have proven immensely useful in war zones [26], natural disaster areas [16], underprivileged schools [19], and remote research labs [28]. To improve Internet access for those that rely on LEO networks, researchers have already begun to propose improvements to its security [46], routing [39, 68], and latency [35].

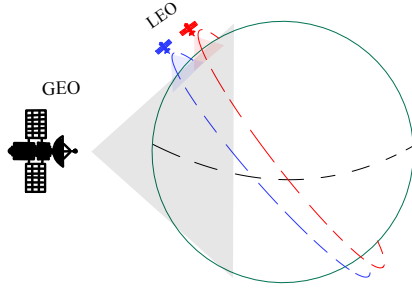
Unfortunately, researchers today face a barrier when understanding how LEO networks operate in practice: to collect real data, one must acquire expensive specialized hardware, or recruit hardware-equipped volunteers, in order to communicate with satellites. Consequently, the community’s understanding of LEO networks relies on either a severely limited set of vantage points (e.g., satellite dishes) [4, 50, 52, 55] or unvalidated theoretical models [35, 39, 46, 51, 68]. If researchers plan to help design and protect LEO networks, it behooves

us to lower the barrier to acquiring real data, such that we have an accurate understanding of how the worldwide LEO network ecosystem works in practice.

In this paper we introduce HitchHiking, a methodology to actively measure LEO satellite network characteristics at scale. HitchHiking builds on the key insight that probing publicly exposed devices on LEO satellite networks can reveal characteristics of the underlying satellite network. Crucially, the HitchHiking methodology requires no specialized hardware or painstaking recruitment, lowering the barrier to collect real data from LEO networks worldwide. HitchHiking works in three steps (1) find measurable endpoints that use LEO satellites for Internet connectivity, (2) identify where in the network path LEO satellites are used, and (3) measure (i.e., “hitchhike”) the satellite link.

We use HitchHiking to conduct the largest LEO satellite network measurement to date—measuring the latency of over 1,600 LEO satellite customers across 13 countries—of Starlink [25], the largest LEO satellite network. We show HitchHiking collects nearly identical latency data to ground truth as measured using a physical Starlink dish. We then use HitchHiking’s measurement of users across farms, boats, and remote locations, to surface the three primary ways in which Starlink’s network does not operate as prior work assumed. First, sustained peaks of latency are not correlated with the location of the satellite, nor caused by the switching of satellites. Second, customer latency is bounded by the availability of a nearby Point of Presence (POP). Third, the use of inter-satellite links significantly increases routing paths and latency.

Overall, for researchers conducting general Internet-wide measurement, our work illustrates the value of having a diverse perspective to understand the unique routing and latency artifacts that LEO networks introduce to the Internet. For researchers interested in studying LEO networks, HitchHiking provides accessibility to those desiring experiment flexibility and coverage when collecting real data. We are releasing the HitchHiking pipeline for measuring Starlink latency and the data HitchHiking collects under the Apache 2.0 license, in order to further lower the barrier for future LEO research.



**Figure 1: LEO vs GEO Satellites**—LEO satellites closer distance provides lower latency at the cost of less coverage and no longer being in geostationary orbit.

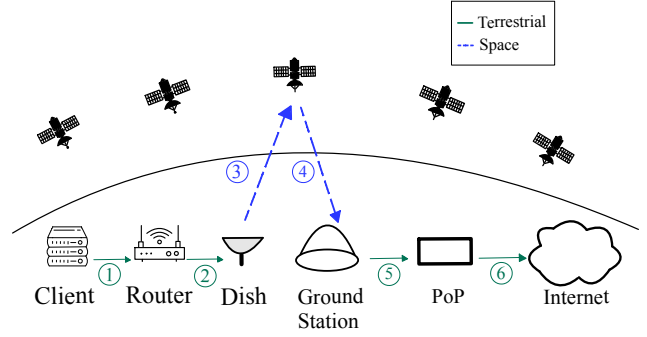
## 2 BACKGROUND

Satellite Internet has existed for over 20 years [1]. However, early Internet-providing satellites were large, expensive, and geostationary (i.e., fixed with respect to a position on the Earth). Geosynchronous equatorial orbit (GEO) satellites orbit at 36,000 km from earth. While this long distance brings wide coverage, it comes at the expense of latency. Even today, the minimum round trip time (RTT) for a packet to route through a GEO satellite is 240 ms, physically bounded by the speed of light. In response to lower latency requirements—and cheaper satellite technology—a new class of satellite networks emerged: Low Earth Orbit (LEO) satellite networks.

LEO satellite networks are comprised of hundreds to thousands of satellites that orbit 300 km to 2,000 km from Earth. LEO satellites’ closer distance provides significantly lower latency ( $\approx 10$  ms RTT), at the cost of reduced coverage and a non-geostationary orbit (Figure 1). The non-geostationary orbit and closer distance causes LEO satellites to travel at tens of thousands of kilometers per hour, orbiting the earth every 90 minutes. LEO satellite mobility is unique relative to other mobile networks (e.g., cellular, drones), because distances are longer and velocities are higher. Further, the core infrastructure of the network is mobile but theoretically predictable.

The most popular [5, 25, 69] LEO architectures often follow a “bent pipe” routing scheme (Figure 2). Packet routing works as follows:

- (1) A client sends a packet to its router
- (2) The router forwards the packet to a physical dish
- (3) The dish sends the packet via radio to a passing satellite
- (4) The satellite relays the packet to a ground station
- (5) The ground station forwards the packet to the provider’s Point of Presence (POP), which is often located at an Internet Exchange Point and plays the equivalent role of a home gateway in mobile networks [54]
- (6) The packet is routed from the POP onto the Internet



**Figure 2: LEO Satellite Network Routing (Egress)**—When a LEO client sends a packet to the public Internet, the packet is sent to a satellite using a dish, and is received by a ground station before forwarding to a POP.

Some newer satellites are equipped with Inter-Satellite Links (ISLs), which allow satellites to relay packets to each other in space until a ground station is in view. ISL deployment provides coverage to clients in extreme remote locations (e.g., in oceans) that are in view of a satellite (e.g., within 600 miles), but not a ground station. ISLs send packets at the speed of light by using lasers in space, thereby surpassing the performance of optical fiber [40].

As of 2020, Starlink [25] is the only consumer-targeted LEO satellite network. Starlink operates satellites with and without ISL capabilities, but does not publicly reveal where or when ISLs are used. Other operational LEO satellites that target businesses include Oneweb [5], a network that caters to enterprises that are located near the earth’s poles (e.g., fishing companies in Alaska). Amazon’s Project Kuiper [23] and Telesat [31] are expected to deploy LEO satellites for consumer-targeted Internet in the future.

## 3 RELATED WORK

Three primary methods have been introduced for studying LEO satellite networks: (1) Deploying specialized hardware (i.e., a dish) to connect to satellite Internet, capturing real data but providing little coverage; (2) Recruiting others with existing hardware, providing greater coverage at the cost of increased labor; or (3) theoretical models, providing the most coverage but no real data. However these methods face an inherent trade-off between collecting real data, coverage of vantage points, and labor.

**Deploying Physical Hardware.** To measure LEO satellite networks, researchers often invest in and travel with specialized hardware (i.e., a satellite dish). Michel et al. [55] deploy a satellite dish in Belgium to collect data about a single user’s perceived Starlink latency. Ma et al. [52] travel with four dishes around Canada to study Starlink latency across remote locations under different loads. Wang et al [69] deploy

a constellation of satellites—Tiansuan Constellation—to act as an open research platform in space.

Relying on physical hardware presents a financial and coverage barrier to researchers: hardware costs as much as \$500 [6] while monthly subscriptions cost upwards of \$100. To achieve world-wide coverage of LEO-accessible locations, one must travel with their hardware. Furthermore, the majority of the world’s population does not reside in a geographic location that qualifies for LEO satellite Internet subscriptions [27].

**Recruiting Existing Hardware.** To collect data on LEO networks with a wider coverage of users and geographic locations, researchers often recruit existing LEO customers. Kassem et al. [50] build browser extensions and recruit 18 Starlink users world-wide to study browser performance under Starlink connectivity. RIPE Atlas [4] has sent hardware (i.e., probes) to over 58 Starlink users across 13 countries, which can be used to run a variety of prescribed measurements.

Recruiting participants and maintaining data collection mechanisms (e.g., building extensions, sending hardware) creates a labor-consuming bottleneck for researchers and produces only limited geographic coverage. Further, relying solely on existing data collecting mechanisms often does not provide the data researchers need. For example, RIPE Atlas measurements can only be conducted at minimum intervals of 60 seconds, which is too coarse to detect significant network fluctuations (Section 6.1.2).

**Theoretical Models.** Consequently, one of the most popular methodologies to study LEO satellite networks is to rely on physics-based theoretical models, which simulate LEO Internet performance across any location, satellite orbiting pattern, and congestion level. The most popular LEO simulators include Hypatia [51], Starlink.sx [60], and SatelliteMap.space [20]. The flexibility of these tools—and theoretical physics in general—allowed researchers to simulate how LEO networks are affected by different congestion control algorithms [51], DDoS attacks [46], route variability [39, 68], ISL deployment [35], etc. However, the accuracy of simulations has never been verified. Notably, our work shows that simulations are non-trivial to configure and do not always accurately model the architecture, user-perceived latency, and the satellite–ground station selection process of the deployed LEO satellite networks (Section 6.1.2).

**Measuring Links.** We apply a decades-old observation—network characteristics between two arbitrary Internet points can be measured—to a new domain: LEO satellites. For example, in 1993 and 2006, Traceroute [53] and Paris-Traceroute [34] showed how to illuminate routers along an arbitrary network path. In 1999, Downey et al. introduced PathChar, a methodology for estimating latency and bandwidth between two arbitrary router hops [41]. The same year Savage introduced

Sting [63], a system for calculating packet loss rates across asymmetric routes. Notably, LEO satellite routing introduces a new source of non-deterministic delay (i.e., moving satellites) that existing tools primarily attribute to (stationary) router queuing-delay. Throughout our work, we illustrate the new challenges and implications that LEO satellites surface when measuring network characteristics.

**Inter-Satellite Links.** Prior work has perceived ISL’s minimal latency as an opportunity to decrease latency and provide more direct routing paths [36–38], and has assumed Starlink does the same [51, 56]. Proposed LEO attacks [46] and routing recommendations [39, 68] also assumed ISLs correlate with low latency and direct routing. However, we will show that prior work has overlooked a stark reality: while ISLs likely do minimize user to ground station routing, they significantly increase the total routing path. Thus, customers who rely on ISLs may experience some of the highest latency and most indirect routing paths.

## 4 LEO HITCHHIKING OVERVIEW

In this section, we present an overview of LEO HitchHiking, a general methodology to measure LEO satellite network characteristics at scale. HitchHiking builds on the key insight that probing publicly exposed satellite-routed devices can reveal the underlying satellite network architecture and performance characteristics. In contrast to previously used “inside-out” methodologies (i.e., connecting a measurement instrument to a satellite dish), which require physical access to privileged vantage points, the “outside-in” HitchHiking methodology requires no specialized hardware or painstaking recruitment. HitchHiking can measure wherever satellite clients are already located across the globe.

Broadly, HitchHiking consists of three steps: (1) identifying publicly accessible endpoints (e.g., servers, routers) that transit LEO satellites for connectivity; (2) isolating where in the network path LEO satellites are used; and finally (3) crafting an experiment to measure a desired characteristic (e.g., latency or availability) of the satellite link. In this section, we describe the general methodology. Then, in Section 5, we describe an implementation of HitchHiking specific to the Starlink LEO network and how it can be used to measure LEO latency.

### 4.1 Finding Satellite-Routed Endpoints

In the first step, HitchHiking needs to identify publicly reachable endpoints that transit a LEO satellite link and are, ideally, geographically distributed. To that end, HitchHiking must first identify networks (e.g., autonomous systems or IP blocks) that house LEO-routed services. Today, there exists only one commercial LEO network that sells to individual consumers: SpaceX-Starlink. However, within coming years,

AWS Kuiper, Telesat and OneWeb, are also expected to deploy consumer-oriented satellite services.

Once network(s) are identified, HitchHiking must find all Internet-exposed services that are hosted on the network. Notably, a service hosted within the address space of a LEO network does not immediately mean it transits a satellite link. For instance, LEO-network backbone equipment that routes traffic between a ground station and a POP, while within the LEO network’s IP address space, does not necessarily traverse a satellite link. Additionally, performance enhancement proxies (PEPs) are common in satellite routing as they decrease latency and increase reliability of networks by relying on proxies [59], caches [67], or back-up non-LEO networks [17]. While helpful to customers, PEPs add confounding factors to measuring LEO links. Thus, HitchHiking must filter for services that are likely using a LEO-satellite for routing.

## 4.2 Isolating Satellite Links

In the second step, after filtering for end-points that rely on LEO satellites, HitchHiking must identify satellite-based network hops. HitchHiking requires that enough of the routing path be visible to an external scanner, such that enough terrestrial routing artifact can be removed to make meaningful inferences. At a minimum, HitchHiking must (1) identify the hop before a satellite path is taken (i.e., hop 16 from Figure 3), and (2) identify the hop after the satellite path is taken (i.e., hop 18 from Figure 3).

## 4.3 Conducting An Experiment

In the third step, having identified the (ideally, globally distributed) satellite links in LEO satellite networks, HitchHiking can then be used to run measurement experiments. Notably, once the satellite link in the routing path is identified, many existing strategies for measuring characteristics of networking links (e.g., [41, 63]) can be applied.

For example, to measure LEO satellite outages due to a customer’s location or obstruction (e.g., a seagull lands on a dish), a researcher might do the following for all exposed LEO services in the same geographic area: (1) send a ping to the router before the satellite link (“terrestrial-hop” router); (2) send a ping to the customer IP after the satellite link (“exposed-service” router); (3) label potential outages as when exposed-service router pings are dropped, but terrestrial-hop router pings are not dropped, for an extended amount of time; and (4) compare outages with neighboring exposed services, to determine if the outages are network-wide or customer-specific.

As another example, to measure LEO satellite bandwidth, a researcher might estimate bandwidth using the pathchar [41] approach, where packets of increasing size sent to both the

hop before and after the satellite link can be used to estimate the satellite link’s bandwidth without flooding the link. In this paper, we focus on measuring latency in the Starlink network.

## 4.4 Ethical Considerations

HitchHiking relies on Internet-exposed services to measure LEO satellite links. HitchHiking is not the first to use the presence and exposed devices to measure Internet behavior. For example, researchers have measured the impact of natural disasters [44] and tracked software patching behavior [43].

However, much like at the onset of Internet-wide scanning, we need to establish guardrails for the use of exposed satellite-based services for performing experiments. For example, LEO satellite links often operate at lower capacity than terrestrial links [56]. It is imperative that HitchHiking experiments do not degrade the quality of service for users by, for example, flooding LEO satellite links. We recommend researchers send the minimum number of packets needed to collect statistics about a LEO link, and avoid using tools that overload bandwidth (e.g., iperf [47]).

## 5 HITCHHIKING STARLINK TO MEASURE LATENCY

In this section, we present an implementation of HitchHiking to measure the latency of the only commercially available consumer-targeted LEO network—Starlink. Tracking network latency is particularly interesting in the LEO satellite setting, as LEO satellite mobility is expected to induce uniquely predictable and dynamic changes in routing path [51]. We measure latency by continually sending TTL limited pings on hitchhiked LEO links and collecting their round trip time. For the measurements in this paper, we follow the best practices outlined by Durumeric et al. [44], including configuring the scanner’s IP to re-direct to an informative page that easily allows end-users to opt out of scans. We receive no requests to opt out.

Every 24 hours, we run an automated HitchHiking pipeline to measure latency with the following steps:

**1. Collect Exposed Services** To find measurable LEO-hosted Starlink services, we collect IPv4 and IPv6 exposed services in the Starlink network (AS 14593) using Censys [42], a public Internet device search engine. We note that researchers could also perform their own scans using tools like ZMap [44], Masscan [48], and LZr [49].

**2. Filter for Customer Endpoints.** To measure only services that are likely using a LEO-satellite for routing, we filter for services that belong to customer endpoints. To measure Starlink customer services, we include only IP addresses whose DNS PTR record follow the Starlink customer format: `customer.[location].pop.starlinkisp.net`. There exist

thousands of customer-exposed services in Starlink. For example, on May 10, 2023,<sup>1</sup> we identify a total 4,521 exposed services across 2,051 unique IPs (hosts), 857 unique ports, and 47 application layer protocols in the Starlink network. After filtering for customer endpoints, 1,790 unique IPs remain.

**3. Exclude PEPs.** We filter for performance enhancement by automatically filtering IPs hosting a TLS certificate that belong to the most popular PEP within the Starlink network: Peplink, a PEP that combines 5G connectivity with Starlink. Filtering for Peplink removes 9% of all services (1,629 IPs remain). We manually analyze other TLS certificates and exposed services and do not find other identifiable PEPs.

**4. Geolocate Services.** To obtain an approximate geographic location of a Starlink service, we (1) query the PTR record (e.g., `customer.atlagax1.pop.starlinkisp.net`) associated with each host IP, (2) use the geographic location specified in the domain name (e.g., `atlagax`) to map [62] the host to a geographic location (e.g., Atlanta, Georgia). The geographic location corresponds to the customer’s assigned POP, which is near the user. We manually validate that Starlink is present in IXPs at those locations using PeeringDB [2].

**5. Identify Last Visible Pre-Satellite Hop.** We measure the satellite link using an “outside-in” perspective. In Figure 3, we show the output of running a traceroute<sup>2</sup> from Stanford to an exposed Starlink service located in San Diego that we control. The outside-in traceroute identifies the second-to-last hop (Hop 16) as the occurring right before the satellite link. Note, the hop immediately before the exposed service (Hop 17) is not visible. In Appendix B.1, we use an internal network perspective to show that there is negligible RTT difference between the routers responsible for Hop 16 and 17.

**6. Identify First Visible Post-Satellite Hop.** The last responsive hop in the traceroute is typically the first, and only, visible post-satellite hop. Notably, while the link between the last visible pre-satellite hop and the first visible post-satellite hop includes the satellite link, it also includes the terrestrial pathway between the POP and the ground station. In Section 6, we show how our measurement technique filters much of the terrestrial routing outside of Starlink’s network.

**7. Measure Path Latency.** We measure path latency for 5 minutes sending two ICMP pings every second with the following additional configuration: (1) with a TTL equal to the terrestrial-hop-router-hop number and (2) with a TTL equal to the exposed-service hop number. In Appendix B and Appendix C, we discuss how sending TTL-specific pings increases coverage by an order of magnitude compared to TCP, UDP, and non-TTL specific pings.

<sup>1</sup>All experiments in this section use data collected on May 10, 2023.

<sup>2</sup>We experiment with many different traceroute tools in Appendix B.

**8. Isolate Satellite Link Latency.** We subtract the terrestrial-hop router RTT from the exposed-service router RTT, to measure the satellite link and minimize terrestrial artifacts.

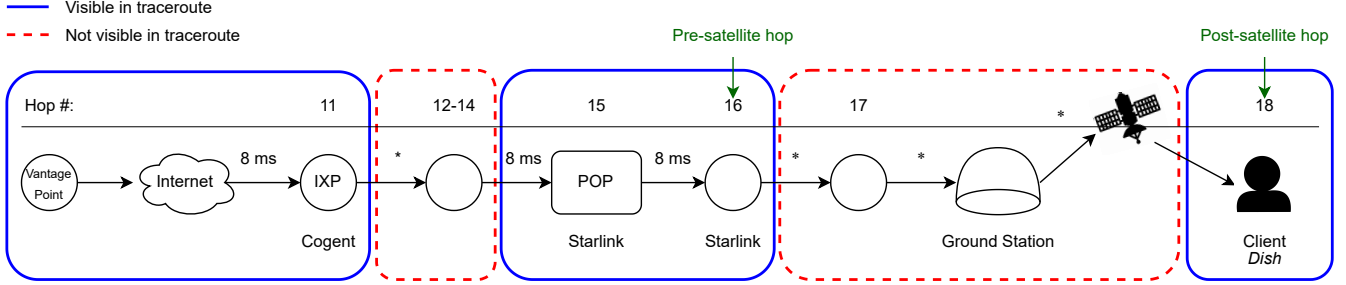
**9. Filter for Non-LEO Satellite Artifacts.** We apply a smoothing filter with a window size of 15 seconds (the time-step with which Starlink dishes stay connected to a satellite, before determining whether to switch connections [12]) to our timeseries of collected measurements, to eliminate short-lived artifacts (Section 6.1). Additionally, HitchHiking’s might not always identify the immediate hop after the satellite path, as it will likely occur within an exposed service’s local network (i.e., if the service’s router transparently forwards packets). Fortunately, routers (one of the most popular hosts of exposed services) must be physically connected to a satellite dish using Ethernet [29], thereby additionally minimizing potential Wi-Fi artifact. At least one-third of customer-exposed Starlink services belong to a vendor that produces routers and firewall appliances, with the two most popular being Fortinet and Sonicwall.

**10. Validating Incomplete Visibility** While HitchHiking lowers the barrier for identifying LEO satellite routing in the wild, it does not have complete visibility of all satellite routing. When measuring Starlink, HitchHiking cannot identify exactly what routing occurs between the POP and the client, does not know how many satellites, which satellites, and which ground stations packets are routed through. To understand if the incomplete visibility is still sufficient, in the next section, we validate HitchHiking with physical equipment. Critically, we find that HitchHiking’s lack of visibility is not a limitation of HitchHiking; even Starlink customers with physical equipment have near identical visibility into Starlink’s routing. In spite of this incomplete visibility, in Section 7, we demonstrate how HitchHiking’s global perspective helps build informed inferences that illuminate previously undisclosed routing patterns.

Overall, the HitchHiking pipeline is designed to be quickly adaptable to new users and geographic locations. Since LEO network architecture changes nearly everyday due to new satellite launches [64], satellite falls [18], the integration of inter-satellite lasers [45], new ground stations [66], etc, adaptability is crucial. The HitchHiking pipeline, which is open sourced under the Apache 2.0 licence, along with the data it collects, can be found at [https://github.com/stanford-esrg/LEO\\_HitchHiking](https://github.com/stanford-esrg/LEO_HitchHiking).

## 6 EVALUATION

In this section, we evaluate the accuracy, run-time, and coverage of HitchHiking on the Starlink network. First, we show that HitchHiking accurately measures satellite link latency relative to ground truth, capturing 100% of all sustained latency spikes. Second, we compare HitchHiking’s accuracy



**Figure 3: Truncated “Outside-In” Traceroute From Public Server to Starlink Dish**—The LEO link is traversed between the last hop and the second-to-last responsive hop, as indicated by the single spike in latency.

and run-time with the leading LEO-network simulator and show that, while a simulator requires 1 hour to model 30 seconds of latency predictions, HitchHiking requires only 30 seconds of measurement time (i.e., is 120 times faster) and is also up to 80% more accurate. Third, we demonstrate HitchHiking’s expansive coverage of LEO satellite links, which spans 13 countries and contains 28 times more measurable links than other methods.

We first show that HitchHiking collects nearly identical latency data to ground truth as measured using a physical Starlink dish. We compare HitchHiking measurements across three axes: (1) How close is the HitchHiking reported RTT to ground truth? (2) How often does HitchHiking capture the correct RTT spikes (i.e., true positive rate)? (3) How often does HitchHiking capture incorrect RTT spikes (i.e., false positive rate)? Further, we compare, relative to ground truth, the accuracy and runtime (when applicable) of the two most popular alternatives to studying LEO network latency without deploying satellite equipment: Hypatia [51] (the only available programmable theoretical simulation of LEO networks) and RIPE Atlas [4] (one of the largest community Internet measurement platforms).

## 6.1 Comparison with Ground Truth

To obtain ground truth about a client’s LEO network latency, we deploy our own residential generation 2.0 Starlink<sup>3</sup> dish in San Diego. To make our LEO link “hitchhikeable,” we (1) turn on router ping by bypassing the Starlink router with our own Asus RT-N66U router (Starlink generation 2.0 routers do not allow for port forwarding or respond to ICMP probes), and (2) configure our router to advertise the Starlink-provided public IPv6 address.

We also collect Starlink provided metrics from our dish, including the reported “POP ping latency,” packet drop, and estimated bandwidth usage every second. The POP ping

latency is the ground truth RTT of a ping from our dish to the assigned POP. The POP ping latency is the most granular provided metric of LEO latency; it includes terrestrial latency to and from the ground station. Starlink metrics do not reveal which ground station or satellite the dish is connected to [13]. However, we use a novel side-channel in our Starlink dish, the obstruction map, that in real time records the location of a successful satellite connection. Thus, to track satellite connections in real-time, we reboot our dish and save the obstruction map every second.

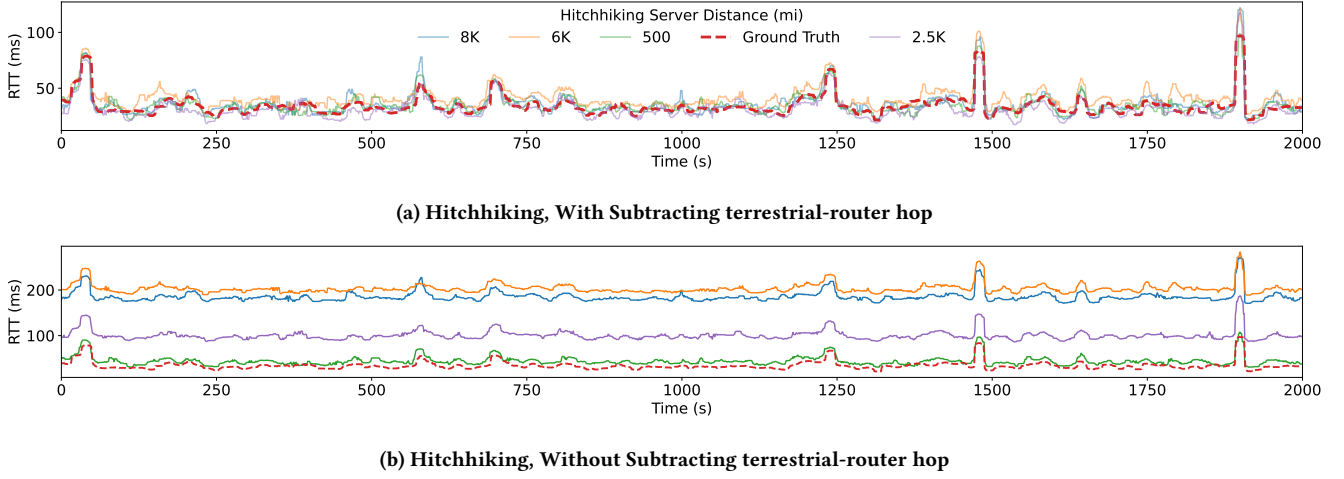
**6.1.1 HitchHiking.** We compare HitchHiking measured latency to ground truth. To evaluate HitchHiking under different distances from San Diego, we run HitchHiking from four geographic locations: Australia, Brazil, California (US), and Virginia (US). Each location is 500–8,000 miles away from our dish. All HitchHiking pipelines run at the same time on May 12, 2023. We note the presence of clear skies and no physical obstructions, and thus minimal interference during our experiment.

**Evaluation.** Across all HitchHiking vantage points, HitchHiking captures latency statistics that are close to the ground truth: 96% of reported RTT times are within one standard deviation (10 ms), and 50% of RTT times are within 3 ms of the ground truth (i.e., the dish’s pop ping latency). We illustrate the output of HitchHiking relative to the ground truth in Figure 4a and the output of HitchHiking without removing terrestrial artifact—to better depict the captured RTT patterns across HitchHiking locations—in Figure 4b. HitchHiking captures 100% of all sustained RTT spikes, which we define as latencies over two standard deviations away from the median that last at least 15 seconds (i.e., the Starlink minimum amount of time dishes stay connected to the same satellite [12]). We describe likely causes for RTT spikes (e.g., ISL usage) in Section 7.

HitchHiking observes only one false-positive RTT spikes across our cumulative 10,000 second measurement period. All but one HitchHiking geographic location have a 0% false

<sup>3</sup>Starlink is the only commercially available LEO-provider that sells to individuals, and therefore the only network that easily provides ground truth.



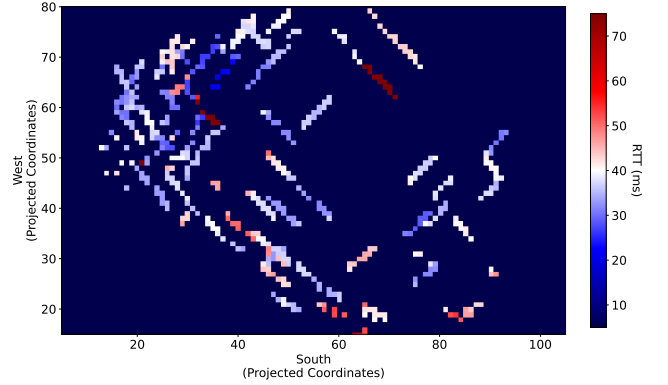


**Figure 4: Comparing Hitchhiking With GroundTruth**—HitchHiking from different servers world-wide is always able to detect long-lasting spikes in latency.

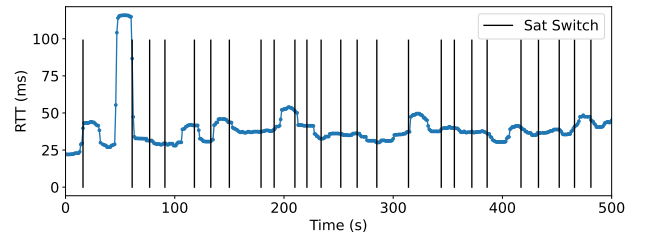
positive rate for capturing RTT spikes. When HitchHiking is deployed 6,000 miles from our ground-truth dish, it returns one false positive RTT peak near second 1800. We attribute the false positive to a less stable terrestrial-router hop; while other terrestrial-router hops never deviate more than 1 ms from the average, the 6,000 miles terrestrial-router hop jitters up to 10 ms in latency near second 1800. Thus, although terrestrial-router RTT is subtracted from the final hop, jitter can propagate. To decrease the false positive rate of finding sustained latency spikes, in Section 7, we filter for all endpoints whose second-to-last hop experiences no more than 1 ms deviation of RTT.

Sustained spikes in RTT are not correlated with satellite location or satellite switches. In Figure 5a, we present the obstruction map overlayed with the corresponding ground truth RTT. There exists no clear correlation between sustained latency and the satellite locations relative to the dish: sustained anomalous RTTs, colored in red, occur throughout all satellite locations. In Figure 5b, we vertically mark every satellite change, which we detected when the dish connects to a satellite that is not neighboring the prior connection’s location. Within the first 500 seconds of measurement, we see that the first sustained RTT peak occurs while still connected to the same satellite. Across the entire measurement period, 2/5 sustained RTT spikes occur while still connected to the same satellite. For standard RTT spikes (i.e., spikes over one—but not two—standard deviations above the median), 5% occur while still connected to the same satellites. Thus, satellites switches are not the cause behind latency spikes.

RTT spikes are also unlikely due to congestion. The ground truth metrics report no packet drop or drop in bandwidth



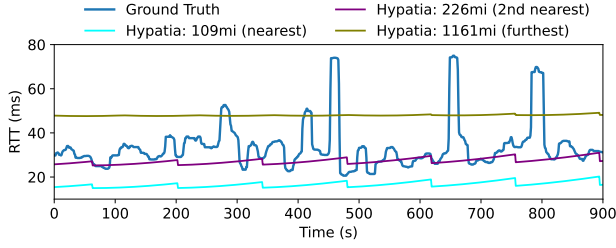
**(a) Sustained Latency Spikes are Not Correlated With Satellite Location**—The satellite obstruction map is an image projection of the satellites the dish connects to when facing the sky. The left of the dish faces west. We overlay the user RTT while connected to each satellite’s location.



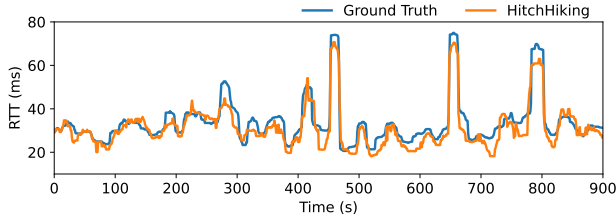
**(b) Sustained Latency Spikes are Not Always Satellite Changes**—Satellite switches are computed using the obstruction map above.

**Figure 5: Satellite Location Relative to Latency**—Sustained increased latency is not due to satellite location or satellite changes.

during sustained or standard latency spikes. Furthermore, we find that spikes occur in multiples of 15 second—aligning



(a) Simulation Predictions



(b) HitchHiking

**Figure 6: HitchHiking Comparison With Prior Work**— Simulations do not capture the dynamics of real-world Starlink RTTs.

with Starlink’s reported satellite reconfiguration period [12]—further making any cause of latency that is independent of Starlink routing (e.g., brief congestion caused by a nearby user) unlikely. In Section 7, we use HitchHiking’s global perspective to infer that sustained latency spikes are likely due to routing path changes exacerbated by ISLs.

**6.1.2 Hypatia.** Hypatia is a LEO simulator that takes as input the geographic location of ground stations and satellite constellation parameters (e.g., number of satellites, their altitude, inclination, etc.), and returns the predicted RTT packet latency between two ground stations (GS) A and B. We show that HitchHiking is faster and more accurate than Hypatia at estimating LEO latency.

**Methodology.** To model Starlink latency, we configure Hypatia with the Starlink constellation parameters published by the FCC [24]. To model client latency to a POP, we run multiple simulations where GS A is the location of our dish (Section 6.1) and GS B is a GS within the set of all GS that are reachable using one satellite hop from the dish. To account for additional terrestrial latency between the ground station and POP, we add the latency that a packet would incur traveling at 2/3rds the speed of light (i.e., estimated optical fiber latency [40]) between the ground station and POP.

We use Hypatia’s default satellite selection algorithms: Hypatia connects the client with a satellite that minimizes

the RTT between the client and ground station. In Appendix D, we present the results of configuring Hypatia using a theoretical worst case satellite selection algorithm and find that it does not significantly change the quality of Hypatia’s predictions. We compare Hypatia results with our ground truth dish and a HitchHiking deployment located 500 miles away from the dish.

**Evaluation.** While HitchHiking accurately estimates LEO satellite latency relative to ground truth, Hypatia is difficult to parameterize such that its output matches ground truth. In Figure 6a, we illustrate the output of Hypatia when using the best-case satellite selection algorithm, and a subset of nearby groundstations (the nearest, second nearest, and furthest). No matter the ground station, Hypatia never predicts that a client experiences sustained RTT spikes, unlike HitchHiking (Figure 6b). In Section 7.2, we find that RTT peaks are likely due to dynamic ISL routing patterns, which Hypatia is unaware of. Notably, configuring Hypatia to use the second nearest ground station produces a latency prediction that on average is only 7.6 ms in error relative to the ground truth. Nevertheless, HitchHiking RTTs are on average 1.8 times more accurate than Hypatia.

Hypatia’s inability to model real-world LEO links is not necessarily a deficiency of Hypatia, but rather a limitation of applying theoretical models to predict latencies about a network that reveals little about its operation. Starlink does not reveal its internal fiber paths between ground stations and POPs, terrestrial routing decisions, satellite selection or ISL routing algorithms, or congestion patterns. In order to approximate latency, the only ground truth information Hypatia has access to is satellite and ground station location.

HitchHiking is also an order of magnitude faster than Hypatia. While collecting a 30 second sample of LEO network latency consumes 30 seconds of HitchHiking (assuming an exposed service has already been found), simulating 30 seconds of RTT between just two ground stations consumes 1 hour of wall-clock time on a 12 core machine with 58 GB of RAM. A 6 hour Hypatia simulation executes in 41 hours. Thus, HitchHiking is up to 120 faster at estimating LEO latency than simulations.

Nevertheless, Hypatia’s theoretical minimum calculations can help illustrate which ground stations a dish is connected to. Given that 20% of ground truth RTT fall below the second-nearest ground station best-case RTTs, Starlink must be connected to the nearest ground station at least 20% of the time. However, using Hypatia alone, it is unclear whether other increases in RTT latency is due to connecting to a different ground station, or congestion.

**6.1.3 RIPE Atlas.** RIPE Atlas—one of the most comprehensive community-driven Internet measurement platforms—provides substantially less coverage and granular statistics



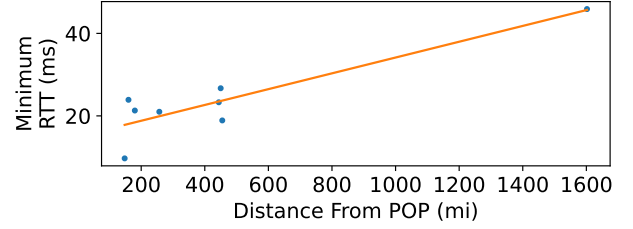
DNS	POP	# Distinct IPs	
Subdomain	Location	Hitch-Hiking	RIPE Atlas
sttlwax1	Seattle, Washington	243	7
atlagax1	Atlanta, Georgia	210	4
dllstxx1	Dallas, Texas	186	1
chcoilx1	Chicago, Illinois	182	6
lsancax1	Los Angeles, California	173	2
sydyaus1	Sydney, Australia	148	4
nwyynyx1	New York City, New York	144	6
frntdeu1	Frankfurt, Germany	124	13
dnvrcox1	Denver, Colorado	87	7
lndngbr1	Heathrow, England	56	6
mdrdesp1	Madrid, Spain	20	0
sntoch1	Santiago, Chile	19	1
acklnzl1	Auckland, New Zealand	11	0
lgosnga1	Lagos, Nigeria	6	0
bgtacol1	Bogata, Columbia	5	0
limaper1	Lima, Peru	3	0
prthaus1	Perth, Australia	3	1
qrtomex1	Mexico City, Mexico	3	0
splobra1	San Paulo, Brazil	3	0
tkyojpn1	Tokyo, Japan	3	0
Total		1,629	58

**Table 1: Geographic Coverage of Exposed Services**—Starlink exposed services are geographically wide-spread, providing LEO-Voyager an ample amount of measurable LEO links.

than HitchHiking. Unfortunately, the nearest RIPE Atlas dish that is assigned our POP is located over 300 miles away (i.e., uses a different set of ground stations). Furthermore, RIPE Atlas limits measurements to occur no more frequently than every 60 seconds, making it difficult to capture sustained RTT spikes that often change every 15 seconds.

## 6.2 HitchHiking Coverage

HitchHiking provides the most comprehensive coverage of LEO networks today. Fortuitously for HitchHiking, LEO network customers expose services across the world. On May 10, 2023, we use HitchHiking to measure all (publicly exposed) LEO links in the Starlink network (Section 5). In Table 1, we list the POP locations of Starlink customers that expose services, as well as the POP locations of all RIPE Atlas Starlink Probes. HitchHiking has 28 times more exposed services than RIPE Atlas, whose services use POPs across only five countries. HitchHiking finds exposed Starlink services are assigned to POPs that reside across 20 cities and 13 countries. While a majority (59%) of HitchHiking found services use POPs in the US, there exists a long-tail of other locations including Australia (7%), Germany (6%), and England (3%).



**Figure 7: Latency vs POP Distance**—Customers located further from their assigned POP experience higher minimum RTT times.

## 7 WORLDWIDE LATENCIES IN THE WILD

In this section, we perform the most geographically-diverse data-driven analysis of LEO satellite latency to date. Our global perspective illuminates that real world deployment of a global LEO network is more complex than previously understood. While prior work attributed differences in customer latency to localized effects such as satellite location or congestion, we infer customer latency is correlated with a customer’s distance to POP and unexpected ground station selection. Additionally, our investigation surfaces an overlooked reality by prior work: while ISLs likely do minimize user to ground station routing, they significantly increase the routing path between the ground station to POP.

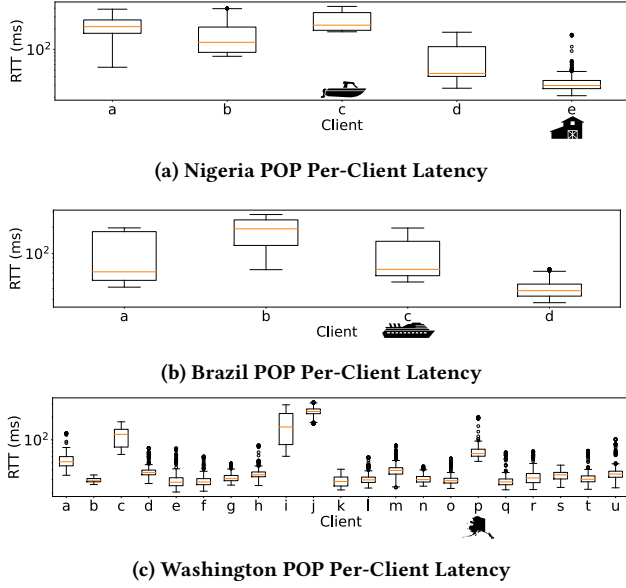
We use the HitchHiking methodology (Section 5) to collect Starlink latency data on May 18, 2023. Additionally, we use HitchHiking to scan the IP addresses of all Starlink RIPE Atlas probes, which provide ground truth about customer location; we mention when RIPE Atlas probes are used in our analysis. We filter the initial 1.6K exposed customer Starlink IPs for jittery pre-satellite hops, leaving 989 IPs that host exposed services.

### 7.1 POP Distance

In this section, we investigate how a customer’s distance to POP correlates with their expected latency. We find that even with Starlink’s vast network topology, remote customers can experience latency increases by over three fold compared to other customers assigned to the same POP.

In Figure 7, we plot the HitchHiking-measured latency and distances of the RIPE Atlas probes with their respective POPs. The further a Starlink customer is from their POP, the greater their minimum RTT. In the worst case, a customer from the US Virgin Islands is assigned to their nearest POP, in Atlanta, Georgia, located roughly 1600 miles away. They experience a minimum RTT nearly twice as large compared to customers that are closer to their own POP.

Minimum RTT can be used to approximate customer location when no ground truth is available (i.e., when measuring non-RIPE Atlas exposed services). For example, in Figure 8a,



**Figure 8: Client Latencies (Log Scale)**— Due to a variety of factors (distance from POP, ISL usage), clients assigned to the same POP experience latencies that differ by an order of magnitude.

minimum RTT indicates that customer e must be located much closer to the Nigerian POP than customer c. Indeed, customer c is on a yacht near Seychelles (they host a TLS certificate registered to the name of a unique sportfisher yacht, which MarineTraffic.com shows to be near Seychelles [3]) while customer e is in the Nigerian Palm-Oil farm (i.e., the customer hosts a TLS certificate that fingerprints to a Nigerian Palm-Oil farm). Additionally, in Figure 8c, we find that Customer p, whose minimum RTT is nearly 3 times larger than average minimum RTT, is thousands of miles away from their assigned nearest Seattle POP (customer p’s exposed email server belongs to Vuntut Gwitchin First Nation, a cultural site, which is located thousands of miles away Seattle near the northern border of Canada).

Notably, no matter a customer’s distance to their POP, all our Starlink traceroutes show that packets are *always* tunneled to/from the customers assigned POP before traversing the public Internet<sup>4</sup>, thereby causing unavoidable latency. Tunneling customers through a home gateway across all connections is not unique to Starlink, but rather also common in mobile networks [54].

<sup>4</sup>Packets are always first routed through the customer’s assigned Starlink POP once they enter the Starlink network. We conduct Section 6.1’s experiment in reverse (contact the geographically distributed servers from our dish), and find that when sending packets from a Starlink dish, packets are always routed through the customers assigned POP before leaving the Starlink network.

## 7.2 Routing Changes

We next investigate how routing changes between a client, groundstation, and POP correlate with latency. We find that customers physically located within ground station coverage likely experience routing changes solicited by ISL technology, surfacing surprising correlations with spikes in latency.

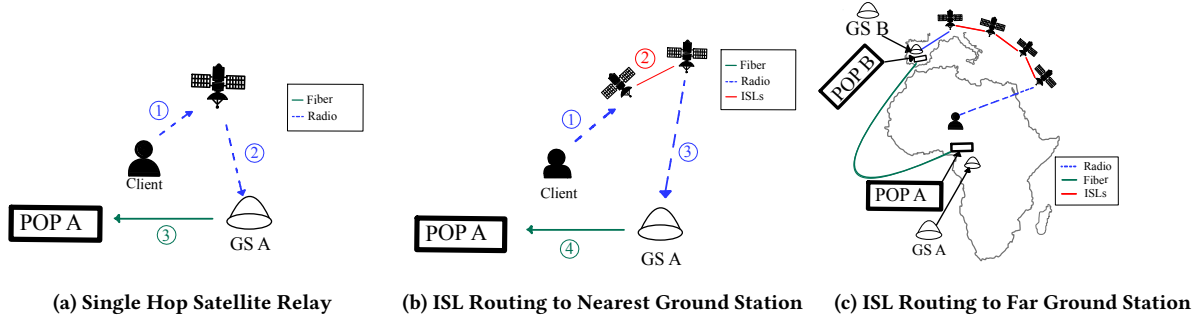
To deduce routing causes of latency, we take advantage of HitchHiking’s ability to measure customer latency nearly anywhere in the world and choose to study a POP that minimizes the most variables in packet routing: the Nigerian POP. The Nigerian POP has the least number<sup>5</sup> of ground stations (2) a negligible distance (80 miles) apart, within a one-hop satellite distance. We study a customer that we confirm is physically near their assigned Nigerian POP: the Palm-Oil customer (Section 7.1). Notably, without HitchHiking, one would have to solicit volunteers in Nigeria (of which currently there are none in RIPE Atlas) or travel with the dish to Nigeria.

In the simplest case of routing, the Palm-Oil customer will connect to one of the two Nigerian ground stations nearby, using a one satellite “relay” hop (Figure 9a). After connecting to any ground station, the packet is always *terrestrially* routed to the POP, as revealed by Starlink [10, 15]<sup>6</sup>.

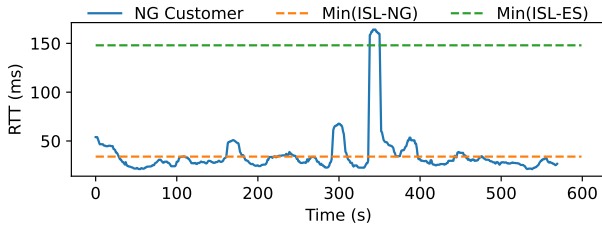
To deduce how often relay routing occurs, we first plot the customer’s RTT over time in Figure 10. Second, we plot Hypatia’s calculated minimum RTT when using non-relay routing (i.e., two satellites with ISLs) to the Nigerian ground station (“Min(ISL-NG)”). Over 70% of customer RTTs fall below Min(ISL-NG), indicating that in the majority of cases the customer falls below the theoretical minimum latency of using two satellites to route to the nearest ground station, and therefore must be using single-hop relay routed to the nearest ground station. However, one-third of the time, RTTs increase between 2–5 fold the median for a sustained 15 seconds. We record no packet drop during the RTT increases and, as shown in Section 6.1.1, know that a sustained latency increase is not due to a satellite switch. Thus, we infer that neither a single satellite’s location nor congestion is to blame.

<sup>5</sup>We rely on public crowd sourcing to collect country-specific SpaceX requests for ground stations (e.g., published by the United States FCC [24], the Chilean telecommunications ministry [9], the French Electronic Communications Authority [8], etc ) to map the ground station topology of Starlink’s network. Given Starlink’s large fanbase who enjoy tracking ground station locations [58, 60] we assume that our ground station location knowledge is complete. Even if our knowledge was incomplete, sustained latency spikes that increase RTT by nearly an order of magnitude (e.g., second 350 in Figure 10), could not be explained by connecting to nearby ground stations within one hop).

<sup>6</sup>In Section 5 we confirm that packets are routed terrestrially for as long as possible before reaching the satellite path. In Appendix B, we confirm that no matter the public Internet destination, packets leave their assigned (nearest) pop and continue the route terrestrially.



**Figure 9: Routing Options**— Paths from a client to its POP can vary in satellite hops and length.



**Figure 10: ISL Impact On Latency Spikes**—Customer e located in Nigeria experiences spikes in latency that coincide with the expected latency of different ISL routing methods. We describe the different ISL routing methods in Section 7.2.

Rather, we hypothesize that Starlink is connecting customers with ground stations that are further away, in part due to load balancing. Indeed, Starlink customer service reveals to a customer inquiring about their sustained spikes in latency that “The change in latency you are noticing is due to a combination of ground stations/routing as the packets travel through our network, in combination with changes we are making to launch and reposition our satellites” [61]. Starlink additionally reveals that users “obtain service through multiple satellites and gateways (ground stations), automatic traffic rerouting is essentially built into the system” [14]. Furthermore, “SpaceX requires that every location it serves be covered by at least three gateways at all times...every satellite will have multiple gateway sites in view with which it can communicate” [11].

Thus, it not improbable that, on occasion, the Palm-Oil customer is routed to an alternative nearest ground station not in Nigeria—but in Lepe Spain, over 2,000 miles away. Notably, when routed to Spanish ground station, customer traffic must then *terrestrially* traverse to a POP [10, 15]. Given that all customers traverse through their assigned POP (Section 7.1), the Palm-Oil customer’s terrestrial route from the example Spanish ground station, which we depict in Figure 9c, would span over 8,000KM.

While it may seem that always routing through a customer’s assigned POP, even when a closer POP is available, is uniquely inefficient, routing through an assigned gateway is a wide-spread practice in IP Packet Exchange Networks (IPX) during international roaming. Mandalari et al [54] show that in IPXs, significant latency increases occur due to the strict requirement of packets routing through the customer’s home gateway, no matter the packet destination, so that cellular carriers can easily monitor data usage, perform content filtering, etc. While Starlink customers are often stationary, the satellites (and their routing path) are not, causing routing patterns similar to international roaming. Coincidentally, the majority (70%) of Starlink traceroutes leak MultiProtocol Label Switching, a protocol heavily used by IPXs to route between gateways [54].

The Nigerian-POP Palm-Oil customer sustained latency spikes correlate with the expected latency of traversing longer routing paths. For example, the outlier latency (162 ms) near second 350 could be the sum of the following footnoted equation<sup>7</sup>, which calculates the minimum amount RTT of a Nigerian POP customer routing through the alternative nearest ground station not in Nigeria. The sustained latency spikes near seconds 175 and 300 are likely due to ISLs routing back to the Nigerian ground station, as depicted in Figure 9b. While the sustained peaks are above the theoretical minimum latency, when accounting for potential additional latency due to bad satellite selection<sup>8</sup> (12ms) and an indirect ISL routing

<sup>7</sup>A Nigerian POP customer routed through Spain would experience the following latency, where  $c$  is the speed of light:

$$\begin{aligned}
 & (\text{Sat. RTT}) + (\text{ISL RTT NG to ES}) + (\text{Terr. RTT ES to NG}) \\
 &= (\text{direct dist to sat}) + (\text{direct dist. NG to ES}) + (\text{fiber dist. from ES to NG}) \\
 &= (\text{Hypatia calculated}) + (\text{distance} * \text{ISL speed}) + (\text{distance} * \text{fiber speed}) \\
 &= (11 \text{ ms}) * 2 + (8K \text{ Km} * c) * 2 + (9K \text{ Km} * (2/3 * c)) * 2 \\
 &= (11 \text{ ms} * 2) + (18 \text{ ms} * 2) + (45 \text{ ms} * 2) = 148 \text{ ms}.
 \end{aligned}$$

<sup>8</sup>We compute worst case RTT using the methodology in Appendix 12.

path<sup>9</sup> (13 ms), the total RTT is within 5 ms of the second highest sustained peak at second 300.

We find that customers who must fully rely on ISLs experience latency that is substantially worse than the expected latency of direct ISL routing. For example, the Seychelles-yacht customer thousands of miles away from Nigeria (Section 7.1) is surrounded by no ground stations, and therefore must solely rely on ISLs to route to its assigned Nigerian-POP. The Seychelles yacht’s experiences a minimum RTT of 181 ms (6 times worse than Palm-Oil-Farm Customer’s minimum RTT) indicating that it is theoretically improbable that ISLs are using a direct path to reach the ground station nearest to the Nigerian POP (i.e., a direct speed of light path from Seychelles to the Nigerian POP would take an RTT of 40 ms, and no more than 80 ms to account for potential “zig-zag” paths between satellites [51]). Rather, the Seychelles yacht is also likely routed to a further ground station and suffers the additional latency of a terrestrial path back to the customer POP. Making matters worse, the Seychelles yacht is likely frequently re-routed: during 42% of our measurement period, the yacht’s RTT is 150 ms over its minimum RTT.

Sustained latency spikes are widespread; across all geographic locations, the majority (81%) of customers experience at least one sustained latency spike within 5 minutes. In the next section, we find other instances of customers who rely on ISLs that experience the most consistent and impactful sustained RTT peaks.

### 7.3 Geographic Patterns

Latency across POPs significantly vary due to their assigned types of customers (e.g., maritime, stationary) and distances of customers (e.g., extremely remote). We plot the distribution of customer RTTs across all 989 customers and POP locations in Figure 11. Average RTTs vary by over 500%: from 28 ms (Mexico)–149 ms (Nigeria). Standard deviation of RTTs also vary by an order of magnitude: from 4 ms (Mexico)–109 ms (Nigeria). While customers with different RTTs are commonplace across all POPs (Figure 8a–Figure 8c), we describe how certain geographies are more or less likely to attract unique customer patterns:

**Nigeria.** Nigeria contains the only POP for the entire continent of Africa, which causes African marine traffic (e.g., Seychelles yacht in Figure 8a) to be routed through the Nigeria POP. Since marine traffic must rely on ISLs, which correlate with high average RTTs (Section 7.2), it is no surprise that Nigeria customers experience the worst RTTs.

<sup>9</sup>Starlink’s first shell contains 22 satellites per orbit, creating a roughly 2,000 KM distance between satellites. If using an extra satellite to ISL route through, that would create additional RTT of  $2 \times 2,000\text{KM} \times \text{speed of light}$  (13 ms).

**Brazil.** Brazil-POP customers experience the second largest average RTT (104 ms) and standard deviation of RTT (27 ms). While Brazil has at least 10 ground stations, its coastal location also attracts marine traffic that relies on ISLs, which correlate with substantially increased latency. For example, customer Oceanica Sub VII (identified using an exposed SNMP firewall name) who is off the coast of Fortaleza Brazil [21] at the time of our experiment is 2,400 km away from its POP—a 14 ms RTT if using a direct ISL path—but experiences an average RTT of 96 ms (Figure 8b), indicating indirect routing is in use. Consistent with other marine traffic, Oceanica Sub VII continually experiences sustained latency spikes, lasting for 16% of our measurement period.

**Georgia, US.** Georgia-POP customers experience the highest average (58 ms) and standard deviation (21 ms) of latency across the US. Ground truth location from RIPE atlas probes indicate that on average, a Georgia-POP customer is 1,000 miles away, partly due to customers located in the US Virgin Islands being assigned the Georgia POP. Thus, customers’ often long distance to the Georgia-POP increases the lower bound of the latency that the majority of customers experience.

**Other POPs.** Peru, Australia, and New Zealand experience the shortest RTT times, on average under 30 ms. All three locations surrounded by at least six groundstations that are reachable by a single satellite-hop. We do not identify any maritime customers assigned to those POPs.

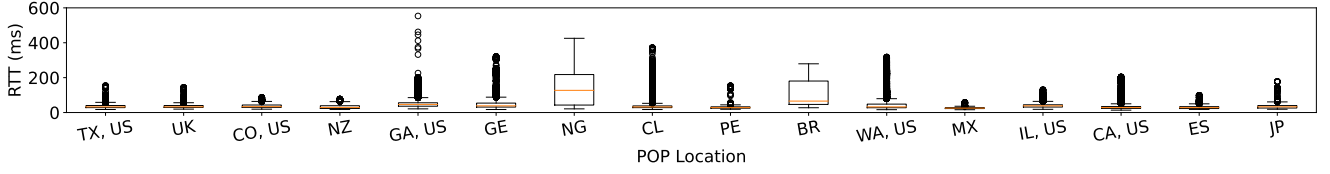
### 7.4 Summary

HitchHiking’s global perspective shows how Starlink’s complex network architecture impacts customer latency across many facets. First, we find that depending upon a customer’s distance to their POP, minimum latency grows over three-fold. Second, routing changes to different ground stations likely cause sustained latency spikes that increase RTT by near an order of magnitude. Third, reliance on ISLs (e.g., customers on boats) correlates with increases in RTT and sustained latency increases. Notably, the diversity of customers and routing infrastructure causes large variances in RTT across POPs worldwide, underlining the value of the global and diverse perspective provided by HitchHiking.

## 8 LIMITATIONS AND FUTURE WORK

HitchHiking does not replace existing methodologies, but rather serves as a low-barrier methodology that provides data about LEO links worldwide. We see many possible directions to integrate HitchHiking into future LEO research:

**Measuring Other LEO Networks.** While Starlink is the only LEO satellite network that sells to individuals, other LEO networks (e.g., AWS Kuiper, Telesat, etc) are expected



**Figure 11: Latency Across All Starlink POPs** —Customer latency varies dramatically depending upon their geographic location. Nigerian-POP customers experience the highest average RTT.

to provide new services in the coming years. With different networking architectures, including differently-arranged satellite constellations, these networks will likely exhibit both similar and different behaviors to Starlink. HitchHiking can be applied to measure other LEO networks once customers begin to expose services. HitchHiking collected data can illuminate the similarities and differences of LEO network performance across different architectures in practice.

**Measuring LEO Networks Over Time.** As Starlink continues to add more customers, ground stations, POPs, satellite orbits and routing policies, HitchHiking can be used to compare how the architecture changes network measurements over time. For example, how does adding more users in a single location affect congestion, bandwidth and latency? Do different routing policies fundamentally change customer network quality of experience? We are open sourcing HitchHiking daily-collected data, giving researchers immediate access to answer temporal questions.

**Data-Driven Simulations.** While simulations allow for a wider flexibility of experiments than measurements, simulation accuracy is constrained by a plethora of unknowns about how real LEO networks operate. Future work should look into (1) training predictive models with HitchHiking collected data to better simulate real-world networking conditions world wide, (2) creating “replay” models with HitchHiking data that can test the performance of new algorithms (e.g., congestion control) using real data from the past.

**Geo-location for LEO Exposed Services.** Current methods for Geolocating exposed LEO services assume that the service is nearby the POP. While RIPE Atlas Starlink probes show that this is nearly always the case, a user’s nearest POP could be a thousands of miles away (Section 7.1). Future work should develop automated methods to identify granular locations for exposed services.

## 9 CONCLUSION

In this work we introduced HitchHiking, a methodology for measuring LEO satellite networks at scale. HitchHiking builds on the observation that Internet exposed services

that use LEO-based Internet access can reveal both satellite network architecture and performance, without needing physical hardware. HitchHiking is accurate, fast, and provides an order of magnitude more coverage than alternative solutions. Using our new global perspective, we study near 1,000 Starlink customers across farms, boats, and remote regions, to understand user latency.

Our investigation surfaces that contrary to prior assumptions, sustained peaks of latency are not always correlated with either the location of the satellite, or switching of satellites. Additionally, we highlight that ISL routing patterns create the widest variance of latency. While ISLs were advertised as a low latency solution for more direct routing [51, 57], they significantly increase the routing path between the ground station to POP, at the benefit of increasing connectivity (e.g., to ships).

Connectivity at the cost of latency is not unique to Starlink; mobile networks face the same trade-off when providing international roaming under different regulatory bodies [54]. By increasing connectivity through ISL deployment, Starlink customers now occasionally experience RTTs that are closer to GEO latency patterns. As LEO networks continue to increase connectivity, we hope the community uses HitchHiking to understand their real-world deployment when continuing to help design and protect the LEO ecosystem.



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Hop	Router IP	RTT (ms)	Network
1	2605:59c8:3049:fa00::1	1	Dish (LAN)
2	2605:59c8:3000:f27f::1	39	Starlink
3	2620:134:b0fe:251::114	38	Starlink
4	2620:134:b0ff::378	38	Starlink
5	2620:134:b0ff::368	38	Starlink
6	2620:107:4008:d03::1	38	Cogent

**Table 2: Truncated Traceroute From Dish to Public Server—** The LEO link is traversed between the first and second hop, as indicated by the single spike in latency.

## A ETHICS

Our work does not involve human subjects and therefore, according to our institution’s IRB policies, does not require IRB approval. Nevertheless, we agree with and support the mission of minimizing harm when measuring LEO links, and thoroughly discuss the measures we take in both Section 4.4 and Section 5.

## B MAPPING THE STARLINK NETWORK WITH TRACEROUTE

To map Starlink, we first experiment with different tools and protocols, to determine which illicit the most network information. We experiment with running ICMP, UDP, and TCP traceroutes across the following tools, which differ in the manner they construct and send packets: dublin-traceroute [7], paris-traceroute [33], tcp-traceroute [30], mtr (with the mpls flag) [32], and TNT. When scanning all Starlink customer endpoints (Section 5) from Stanford, 60.3% are reachable across all tools using ICMP, 17.2% are reachable using UDP, and 24.6% using TCP. The number of routing hops within the Starlink network nearly always (96% of the time) does not change depending upon the tool or protocol used.

After performing all variations of traceroute, we find three noteworthy network characteristics of Starlink: (1) Starlink routes TCP and UDP packets through a changing set of IP addresses before reaching the endpoint, while keeping a consistent routing path for ICMP packets. While 98.3% of tcp-traceroutes result in a second-to-last hop set of at least two IP addresses, 100% of ICMP paris-traceroutes result in a second-to-last hop set of just one IP address. (2) Starlink’s consistent routing path traverses the customer’s POP across 100% of traceroutes, no matter from/to where the server and client are. (3) Starlink uses MPLS routing before reaching the end-host. Consequently, a subset of routing is not visible to any traceroute tool. TNT, a tool used to uncover routing behind MPLS does not find any new networking paths within Starlink. While mtr reveals the last label assigned to a packet

at the end of an MPLS tunnel, we do not identify any useful patterns.

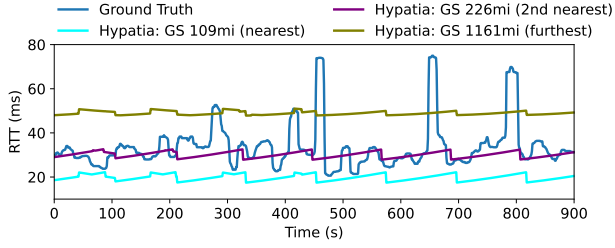
### B.1 Mapping Starlink’s Routing

To obtain ground truth on Starlink’s internal network operation, we purchase a Starlink generation 2 router and dish [22], and deploy it in San Diego. To identify where internal satellite routing occurs, we conduct egress ICMP paris-traceroutes from our dish to a diverse set of end-points, including at least 3 LEO satellite endpoints (Section 6.2) in every available country, all the geographically-distributed DNS root servers, and geographically distributed AWS servers (described in Section 6). Across all egress traceroutes, once a packet leaves our dish’s local area network (LAN), there is a spike in the round trip time (e.g., 39ms in Table 2). All subsequent Starlink (ASN 14593) hops incur negligibly different round-trip-times, suggesting that the first hop encompasses at least the entire satellite link (i.e., dish to satellite to ground-station). We further validate in Section 6 that the satellite link is within the first hop.

While the first visible non-LAN hop includes the satellite link, it likely also includes the terrestrial pathway between the groundstation and POP. Starlink addresses that are one hop away from a different autonomous system (e.g., hop 5 in Table 2) likely belong to equipment located in Internet Exchange Points (i.e., Starlink PoPs), as they are (1) often (68.2% of the resolvable hostnames) preceded by an IP address a hostname suffix that indicates an IXP presence (e.g., any2ix.coresite.com, ch3.unitedix.net) (2) nearly always (87.6%) experience less than 1ms RTT difference between the preceded router. All Starlink IP addresses between the POP hop and the client incur negligible additional latency, indicating that they are likely not a ground station, which, in our experiment, is built at least 100 miles away from the POP. Thus, with physical equipment and today’s networking tools, Starlink’s satellite link will include terrestrial latencies between the groundstation and POP. We further evaluate the groundstation impact in Section 6.1.2.

## C HITCHHIKING IMPLEMENTATION DETAILS CONTINUED

We define a ttl ping as an ICMP paris-traceroute with the first hop and max-ttl set to the same hop number. To ping the terrestrial router we set both the first hop and the max-ttl to the terrestrial-hop-router-hop number (i.e., the second-to-last visible hop in the paris-traceroute). To ping the exposed service router we set both the first hop and the max-ttl to the exposed-service-hop-router-hop number (i.e., the last hop in the paris-traceroute). We opt to use ttl pings over regular pings due to the lack of coverage regular pings provide for terrestrial routers. We find that 99.2% of regular pings to



**Figure 12: Worst Case Hypatia Predictions**— Simulations do not capture the dynamics of real-world Starlink RTTs.

terrestrial-hop-router-hops never respond. In contrast, 0% of ttl pings to terrestrial routers resulted in complete packet loss.

To use ttl pings, we rely on the assumption that the terrestrial-hop-router-hop number and the exposed-service-hop-router-hop number and the IP addresses they map to are stable. We validate the assumption by running 100 paris-traceroutes, one second apart, to each exposed service. We find that the vast majority of the exposed-service-hop-router-hop numbers (96.1%) and terrestrial-hop-router-hop numbers (99.9%)

are consistent across the ICMP paris-traceroutes to the same exposed service. Additionally, we find that IP addresses for the same hop numbers do not change across ICMP paris-traceroutes.

## D HYPATIA WORST CASE SATELLITE SELECTION PREDICTIONS

We modify Hypatia’s source code such that, when simulating routing patterns, it chooses the worst-case option for satellite routing (i.e., it connects the client with satellite that maximizes its round trip time to the ground station). We additionally configure Hypatia to reflect the azimuth properties of a Starlink dish. Since a Starlink dish cannot connect to satellites behind itself [29], and points itself at an azimuth of -22 N, we configure Hypatia to choose satellites for the dish that are between an azimuth lower than  $180 - 22 = 158$  or greater than  $360 - 22 = 338$ . The ground station is not configured with an azimuth cut-off, as their antennas can connect to satellites across all 360 degrees. In Figure 12, we illustrate the worst case predictions between the client and a subset of ground stations. Unfortunately, even worst case predictions do not capture Starlink’s RTT dynamics.