

Pratyush Kar

CONTACT INFORMATION	140, Madan Lal Block Asian Games Village New Delhi, India - 110049	Phone: (+91) 9868826888 E-mail: pratyush.kar@gmail.com Website: https://p-kar.github.io/
EDUCATION	BITS Pilani , Rajasthan, India B.E. (Hons.), Computer Science <ul style="list-style-type: none">GPA (10 point): 9.31Major GPA: 9.82 The Mother's International School , New Delhi, India Central Board of Secondary Education (CBSE) <ul style="list-style-type: none">10th GPA (10 point): 9.812th Percentage: 94.6%	Aug, 2013 – Present 2001 – 2013
PROFESSIONAL EXPERIENCE	Qualcomm India Pvt. Ltd. , Hyderabad, India <i>Software Engineering Intern</i> Developed a parser and command sequencer (in C++ and Python) for running commands present in the log files to simulate a voice call in ADSP test framework on the Hexagon Simulator. Indian Institute of Remote Sensing (IIRS) , Dehradun, India <i>Summer Research Intern</i> Developing a data mining plugin for QGIS (Dr. Sameer Saran) <ul style="list-style-type: none">Designed an open source plugin (in Python) for QGIS to run data mining (like Decision Trees, AdaBoost, and Random Forest) algorithms on multi-band raster datasets. Detecting Gradual Change in Noisy Time Series Data (Dr. Shefali Agarwal) <ul style="list-style-type: none">Implemented algorithms for detecting intervals of gradual change in time series vegetation data using persistent delta approach (Chamber et. al).	Summer, 2016 Summer, 2015
ACADEMIC PROJECTS	Workload characterisation in cloud data centers (Prof. Sundar B.) <i>Undergraduate Thesis</i> <ul style="list-style-type: none">Developed approaches based on user behavior modeling for the prediction of future workloads on the Google cluster dataset.Implemented models based on Support Vector Regression (SVR) for prediction of future CPU and memory usage. Autonomous humanoid robot: AcYut (Prof. B.K. Rout) <ul style="list-style-type: none">Developed a fully autonomous soccer-playing humanoid robot funded by Dept. of Electronics and Information Technology (DeitY, Govt. of India).Implemented algorithms based on Monte Carlo Localization (MCL) for efficient localization using field line detection.Designed the behavior control framework of AcYut 7 (using Extensible Agent Behavior Specification Language, XABSL).Participated and stood 6th in RoboCup 2015 (only team from India) held in Hefei, China.Demonstrated AcYut at India-HU workshop for Sensing and Robotics (HiSENS 2015).	Fall, 2016 – Present Oct, 2013 – Present

	<p>Content based image retrieval for Shekhawati paintings (Prof. Sundar B.) Spring, 2016</p> <ul style="list-style-type: none"> • Implemented graph-based image segmentation algorithms for identifying important objects in the paintings. • Designed image classification algorithms using HOG features and SVM for automatic annotation of the input images. <p>Hand gesture recognition (Prof. Navneet Goyal) Fall, 2015</p> <ul style="list-style-type: none"> • Implemented classification of multivariate time series gesture data using two-dimensional singular value decomposition (2d-SVD) (Weng et. al). • Implemented a real-time hand gesture recognition software using the webcam in MATLAB. <p>Multi-robot exploration using TurtleBots (Prof. Sudeept Mohan) Jan – Dec, 2015</p> <ul style="list-style-type: none"> • Designed planning and task allocation algorithms based on Constrained Delaunay Triangulation and tested them on the TurtleBot platform (in ROS).
PUBLICATIONS	<p>Pratyush Kar, Archit Jain, B.K. Rout. Effective localization of humanoid with fish-eye lens using field line detection. IEEE Asia-Pacific Conference on Intelligent Robot Systems (ACIRS 2016) held in Tokyo, Japan.</p> <p>Kaustubh Nawade, V. Aditya, Pratyush Kar, Anirudh Bhutani, Nishant Bansal, Anant Anurag, Shreyas P. Dixit. Autonomous humanoid robot AcYut. Extended abstract accepted at the Developing Countries Forum of the IEEE International Conference on Robotics and Automation (ICRA 2015) held in Seattle, USA.</p> <p>B.K. Rout, Kaustubh Nawade, V. Aditya, Pratyush Kar, Anirudh Bhutani. Team AcYut – Team Description Paper 2015. RoboCup 2015 Symposium held in Hefei, China.</p> <p>Pratyush Kar, Sameer Saran. SpatialDM: An open source data mining plugin for QGIS. Journal of Geomatics, Vol. 9 No. 2, pp. 141-145, 2015.</p>
TEACHING EXPERIENCE	<p>BITS Pilani, Rajasthan, India</p> <p><i>Teaching Assistant</i> Spring, 2016</p> <p>Co-taught an undergraduate course to over 200 students. Shared responsibility for labs, programming assignments, and grades.</p> <ul style="list-style-type: none"> • CS F211 Data Structures and Algorithms
HONORS AND AWARDS	<p>Recipient of the BITS Pilani merit scholarship. Awarded to the top 2% students each semester for exceptional academic performance.</p> <p>Recipient of Kishore Vaigyanik Protsahan Yojana (KVPY) scholarship, awarded by the Department of Science and Technology (Govt. of India), 2013.</p>
COMPUTER SKILLS	<ul style="list-style-type: none"> • Softwares: MATLAB, IBM SPSS Modeler, Oracle SQL Developer, Git • Languages: C, C++, Python, Java, SQL, Prolog, \LaTeX • Libraries: OpenCV, LibSVM, cvBlob, XABSL, QT • Operating Systems: Unix/Linux, macOS, Windows
EXTRA CURRICULARS	<p>Photography</p> <ul style="list-style-type: none"> • Completed a diploma course on DSLR photography under Mr. Nitin Rai.
LANGUAGES	<p>English (fluent), Hindi (native).</p>