

A correlated and positive model for Bayesian image deconvolution

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Abstract

- Construction of a positive and correlated field by noise filtering.
- Application to a truncated Gaussian and a low-pass filter.
- Independent Metropolis-Hastings sampler to retrieve parameters.

Keywords

Positivity, Correlation, Filtering, Metropolis-Hastings, High resolution

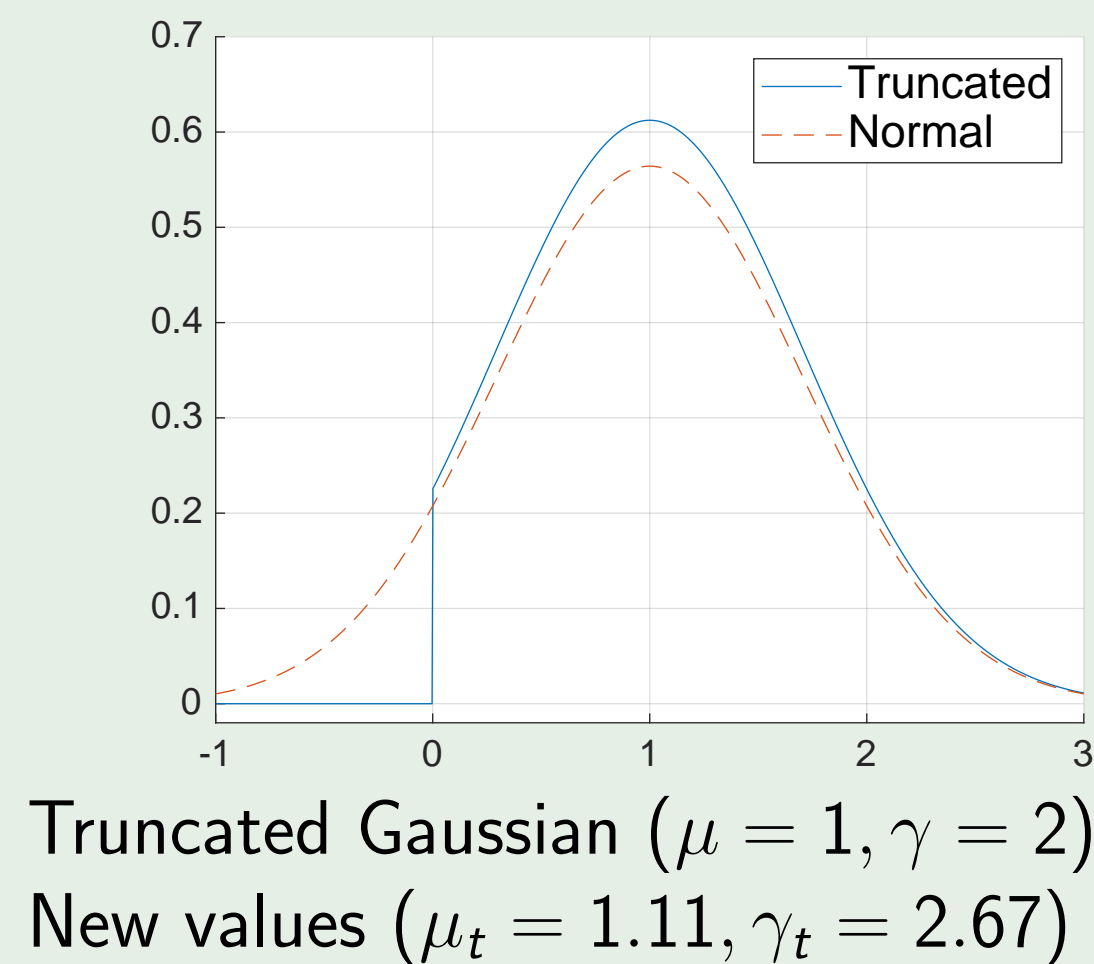
Positive field

U is a field with iid components according to a positive-support law

$$\mathbb{1}_+(u) = \prod_{p=0}^{P-1} \mathbb{1}_{[0,+\infty]}(u_p) = \mathbb{1}_{\mathbb{R}_+^P}(u)$$

Law for the components of U

- Uniform on $[u_m, u_M]$ with $u_m \geq 0$
 - + straightforward expression
 - bounded by u_M
- Truncated Gaussian on $0 \rightsquigarrow$ chosen
- Gamma
- Levy with $\mu = 0$
 - + law stability after filtering
 - undefined moments



Filtering

A_η has positive coefficients

- preserves positivity
- adds correlation on the field U

$$x = A_\eta u$$

A_η controls the first and second order

A_η represents a 2D convolution

- Mean : $\mathbb{E}[X] = \mu_t \sum_{n_h, n_v} a_\eta(n_h, n_v)$
- Cov : $C_X(n_h, n_v) = \gamma_t^{-1} a_\eta * a'_\eta(n_h, n_v)$
- PSD : $S_X(\nu_h, \nu_v) = \gamma_t^{-1} |\hat{a}_\eta(\nu_h, \nu_v)|^2$
- $a_\eta(n_h, n_v)$ the impulse resp.
- $\hat{a}_\eta(\nu_h, \nu_v)$ the frequency resp.

A_η has usefull properties

- Circulant Block-Toeplitz with Circulant Blocks (CBTCB)
- Diagonalisable in the Fourier domain
 - F is the matrix of the discretised 2D Fourier transform
 - Λ_η is the discretised frequency response of the filtering

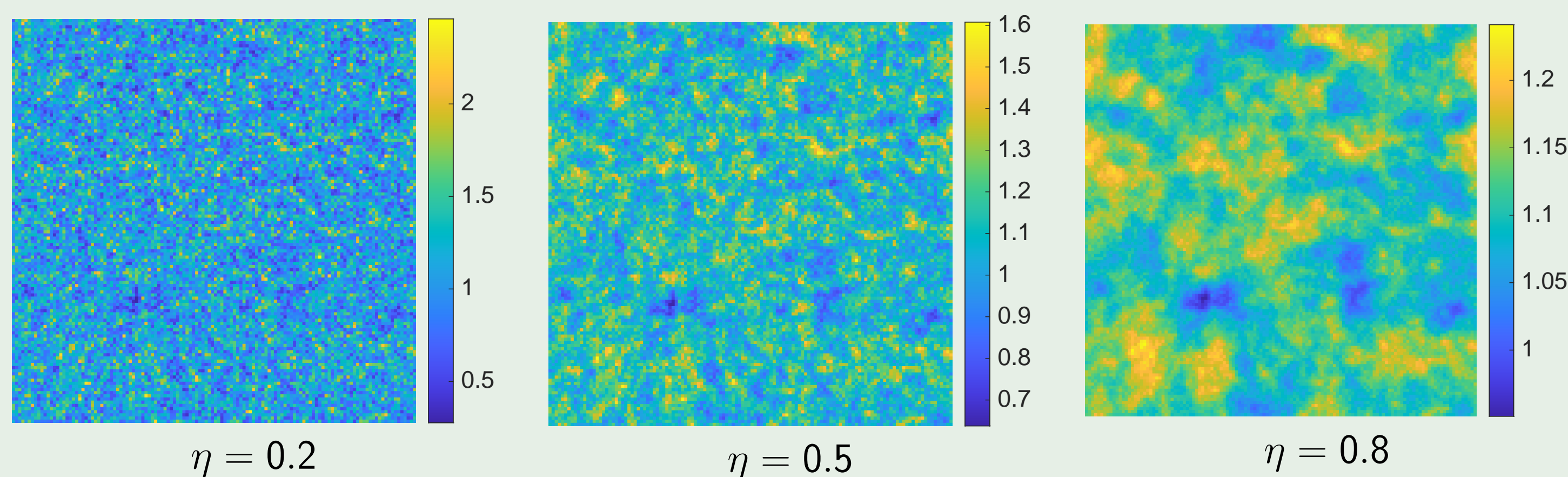
$$\Lambda_\eta = F A_\eta F^\dagger = \text{diag}[\lambda_\eta(p), p = 0 \dots (P-1)]$$

$$F x = \hat{x} = \Lambda_\eta \hat{u} = \Lambda_\eta F u$$

with $\lambda_\eta(p) = \hat{a}_\eta(n_h/N, n_v/N)$ the discretised frequency response.

Example of images

$$S_X(\nu_h, \nu_v) = \gamma_t^{-1} \times (1 - \eta)^2 \left[1 + \eta^2 - 2\eta \cos \left(2\pi \sqrt{\nu_h^2 + \nu_v^2} \right) \right]^{-1}$$



Change of variables

Filtering corresponds to a multivariate change of variables.

$$\begin{aligned} f_X(x) &= |\det A_\eta|^{-1} f_U(A_\eta^{-1}x) \mathbb{1}_+(A_\eta^{-1}x) \\ &= |\det \Lambda_\eta|^{-1} f_U(F^\dagger \Lambda_\eta^{-1} \hat{x}) \mathbb{1}_+(F^\dagger \Lambda_\eta^{-1} \hat{x}) \end{aligned}$$

Filtered truncated Gaussian case

$$\begin{aligned} f_{X|\Theta}(x|\theta) &= |\det A_\eta|^{-1} K^P \exp \left(-\frac{\gamma}{2} \|A_\eta^{-1}x - \mu \mathbb{1}\|^2 \right) \mathbb{1}_+(A_\eta^{-1}x) \\ &= |\det \Lambda_\eta|^{-1} K^P \exp \left(-\frac{\gamma}{2} \sum_{p=0}^{P-1} \left| \frac{\hat{x}_p}{\lambda_\eta(p)} - \mu \hat{\mathbb{1}}_p \right|^2 \right) \mathbb{1}_+(F^\dagger \Lambda_\eta^{-1} \hat{x}) \end{aligned}$$

- $\theta = [\mu, \gamma, \eta]$ the parameter vector
- K the partition function of U

$$K = \sqrt{\frac{\gamma}{2\pi}} \times \frac{2}{1 + \text{erf}(\sqrt{\frac{\gamma}{2}}\mu)}$$

- μ the mean before the truncation of U
- γ the precision (inverse variance) before the truncation of U

Estimation of parameters

Given a direct observation of X , we aim to estimate $\theta = [\mu, \gamma, \eta]$

$$\pi_{\Theta|X}(\theta|x) = \frac{f_{X|\Theta}(x|\theta) \pi_{\Theta}(\theta)}{\int_{\Theta} f_{X,\Theta}(x, \theta) d\theta}$$

- $\pi_{\Theta|X}$ the posterior describing our problem
- $f_{X|\Theta}$ the likelihood (filtered and truncated Gaussian)
- π_{Θ} the prior knowledge about the parameters
- $\int_{\Theta} f_{X,\Theta}(x, \theta) d\theta$ the normalising constant

Uniform and independent priors are considered for θ .

Independent Metropolis-Hastings

Sampling $\pi_{\Theta|X}$ using a Metropolis-Hastings does not require $\int_{\Theta} f_{X,\Theta}(x, \theta) d\theta$.

$$\pi_{\Theta|X}(\theta|x) \propto f_{X|\Theta}(x|\theta) \pi_{\Theta}(\theta)$$

By using prior distribution as the proposed law, only the (log-)posterior is needed.

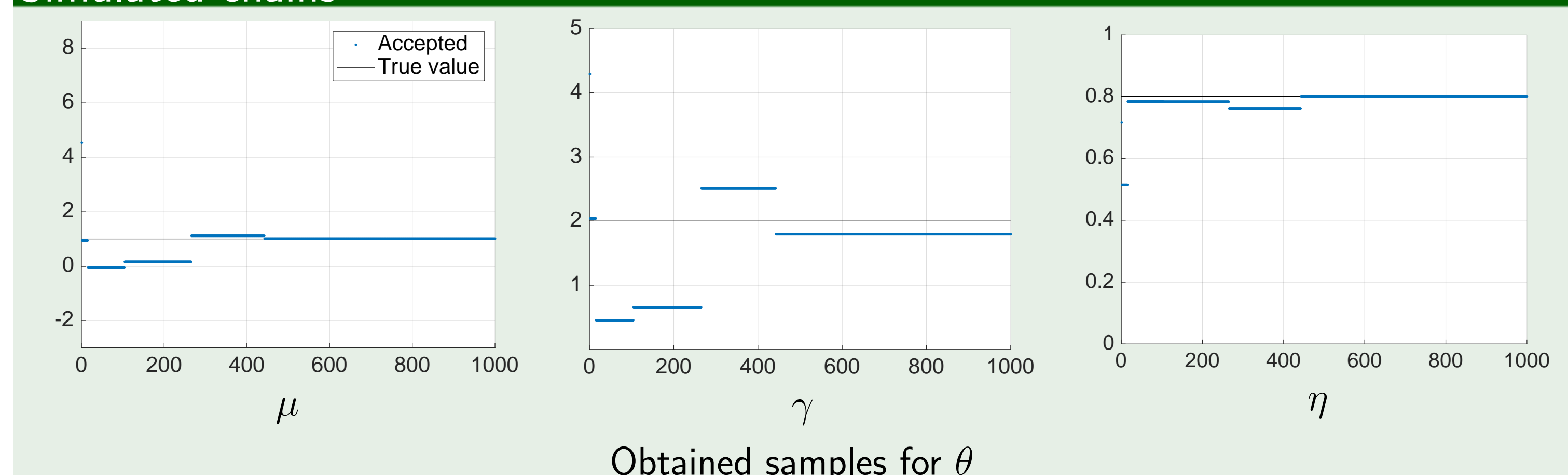
$$\begin{aligned} LP(\theta) &= - \sum_{p=0}^{P-1} \log(|\lambda_\eta(p)|) + P \log(K) - \frac{\gamma}{2} \sum_{p=0}^{P-1} \left| \frac{\hat{x}_p}{\lambda_\eta(p)} - \mu \hat{\mathbb{1}}_p \right|^2 \\ &\quad + \log(\mathbb{1}_{[\mu_m, \mu_M] \times [0, \gamma_M] \times [\eta_m, \eta_M]}(\theta)) \\ &\quad + \log(\mathbb{1}_+(F^\dagger \Lambda_\eta^{-1} \hat{x})) \end{aligned}$$

Pseudo code

```

1: repeat
2:   Sample  $\theta_0$  from  $\pi_{\Theta}$ 
3: until  $\mathbb{1}_+(F^\dagger \Lambda_{\eta_0}^{-1} \hat{x}) = 0$ 
4: for  $k = 1$  to  $K$  do
5:   Sample  $\theta^p$  from  $\pi_{\Theta}$ 
6:   if  $\mathbb{1}_+(F^\dagger \Lambda_{\eta^p}^{-1} \hat{x}) = 0$  do
7:      $\theta_k = \theta_{k-1}$ 
8:   else
9:     Compute acceptance ratio  $\alpha = \exp(\min(0, LP(\theta^p) - LP(\theta_{k-1})))$ 
10:    Sample  $u$  from Uniform(0, 1)
11:    if  $u < \alpha$  do
12:       $\theta_k = \theta^p$ 
13:    else
14:       $\theta_k = \theta_{k-1}$ 
15:    end if
16:  end if
17: end for
    
```

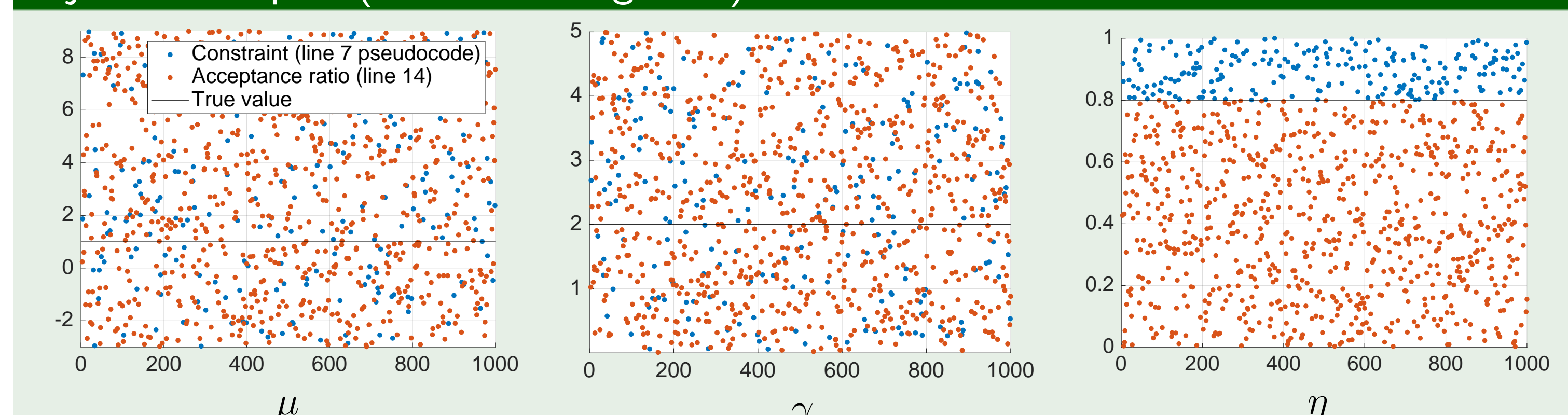
Simulated chains



Obtained samples for θ

Issue: low acceptance rate (0.6%) \rightsquigarrow lack of diversity.

Rejected samples (under investigation)



η appears to play a key role.

Perspectives

- Analysing $\mathbb{1}_+(F^\dagger \Lambda_{\eta^p}^{-1} \hat{x}) = \mathbb{1}_+(F^\dagger \Lambda_{\eta^p}^{-1} \Lambda_{\eta^*} \hat{u}) \rightsquigarrow$ new filter $\Lambda_{\eta^p}^{-1} \Lambda_{\eta^*}$
- Random Walk Metropolis $\theta^p = \theta_{k-1} + \varepsilon$ with $\varepsilon \sim \mathcal{N}(0, \sigma^2 I)$
- Another filtering: $x = \frac{1}{\sqrt{\alpha}} A_\eta u + \beta \mathbb{1}$ (with $\mu = 0$ and $\gamma = 1$)
- Application to images in the astronomical, medical or industrial field.

Bibliography

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